#3. LIE ALGEBRAS (\$ 13-1.4 OF THE)

Last time: For a matrix group
$$G \subset GL_n(\mathbb{R})$$
we have
$$T_{1d} G = \left\{ A \in M_m(\mathbb{R}) \middle| e^{tA} \in G \mid H \in \mathbb{R} \right\}$$

$$E \times AMP \times S$$

$$T_{1d} GL_n(\mathbb{R}) = M_m(\mathbb{R})$$

$$T_{1d} SL_n(\mathbb{R}) = \left\{ A \in M_n(\mathbb{R}) \middle| t_1 A = 0 \right\}$$

$$O_n(\mathbb{R}) = \left\{ A \in M_n(\mathbb{R}) \middle| AA = 1d \right\}$$

$$O_{\mathcal{N}}(\mathbb{R}) = \{A \in \mathcal{M}_{\mathcal{N}}(\mathbb{R}) \mid AA^{t} = 1d \}$$

$$T_{1d} O_{M}(\mathbb{R}) = \left\{ A \in M_{M}(\mathbb{R}) \mid A = -A^{+} \right\}$$

$$X \qquad e^{tX} \left(e^{tX} \right) = id$$

$$\frac{d}{dt}\left(t^{x}t^{x}\right)=0$$

$$\frac{d}{dt} \left(e^{tX} \right) e^{0} + e^{0} \frac{d}{dt} \left(e^{tX} \right)$$

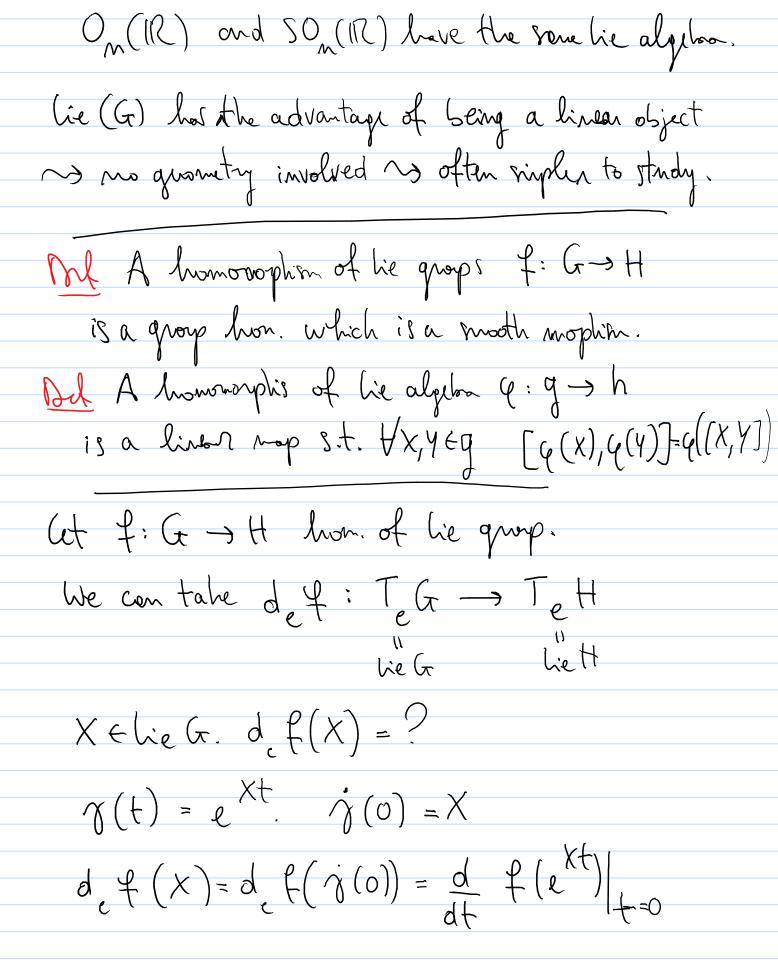
$$\frac{d}{dt} \left(e^{tX} \right) e^{0} + e^{0} \frac{d}{dt} \left(e^{tX} \right)$$

$$\frac{d}{dt} \left(e^{tX} \right) e^{0} + e^{0} \frac{d}{dt} \left(e^{tX} \right)$$

To show 2 Want to show Ltxtxt e e = id Vt X = -X. ex -tx e e = id We can define a natural action of Gron Tid Gr. G C G(M(R) $int(g): M_n(\mathbb{R}) \to M_n(\mathbb{R})$ it's a linear $X \mapsto g \times g^{-1}$ rep. int(g) (G) CG. because ghg EG WhEG didint(g): TeG > TeG So for $X \in T_eG$ d int $(g)(X) = gXg^{-1}$ (!) Ad(g)GXTeG TeG wa upresentation (g, X) D g Xg of G called the adjoint representation

The The tangent space Tid to is closed under comtator i.e. A,B & Te G [A,B] := AB-BA E TId G. Pf. A,BETeG. eAteG HTER. $g(t) = Ad(e^{At})(B) \in T_eG$ e de be J(O) = AB·e0 + e0B(-A) = AB-BA Det We call lie to the vector space Te Go together with the operation [,]: TeGxTeG > TeG $X, Y \mapsto XY - YX$ the lie algebre of G Det A lie algebon over a field his a vector space gh together u/a hibilinear operation [,]: 9 x g > g St. [x,x] =0 (antisympty) SACOBI — (x,x)] + (y,z)] + (y,(z,x)) + (z,x)] =0 $\forall x,y$; + (z,x)] =0 $\forall x,y$; + (z,x)]

Chich the Sacdsi identity for Tet. EXAMPLE tie St_m = sl_m $D_3(\mathbb{R}) = \left\{ A \in M_3(\mathbb{R}) \mid A = -A^{\dagger} \right\}$ $\begin{pmatrix}
0 & a & b \\
-a & 0 & c
\end{pmatrix}
\begin{vmatrix}
a, b, c \in \mathbb{R} \\
-b & -c & 0
\end{vmatrix}$ this hor a baris given by $\begin{bmatrix}
E_1 = \begin{pmatrix} 0 & 0 & 0 \\
0 & 0 & -1 \\
0 & 1 & 0
\end{bmatrix}, E_2 = \begin{pmatrix} 0 & -1 \\
-1 & 0 \\
0 & 0
\end{pmatrix}, E_3 = \begin{pmatrix} 0 & -1 \\
0 & 0 \\
0 & 0
\end{pmatrix}$ $[E_1,E_2]=E_3, [E_2,E_3]=E_1, [E_3,E_1]=E_2$ The lie algebra lie & contains a lot of infonction about & We can alrost noon a from lie to Nucle H CG susper that contains a mold of Id, + G conneted =) H= G exp: U ~, V TeG G (exp (TeG)) is a subgroup of G containg (=) Gr is greated by exp(TeG)



The coll
$$\gamma: \mathbb{R} \to \mathbb{R}^n$$
 e^{∞} cave.

 $A \in M_n(\mathbb{R})$ thun

 $\int \gamma(t) = A \gamma(t)$ for every $t \in \mathbb{R}$
 $\gamma(0) = \gamma_0$

VORDINARY CINEAR DIFFERENTIAL EQUATION.

It has exactly one solution $\gamma(t) = e^{At} \gamma_0$

Pf of iniqueness For verice let $||v|| = \sum |v_i| \in \mathbb{R}$
 $A = (a_{ij}) \in M_n(\mathbb{R})$

We have $||Av|| \leq (\sum_{i,j} |a_{ij}|) ||v||$

Arm we have two soles γ_1, γ_2 of the eq.

 $\gamma(t) = A\gamma(t), \gamma(0) = \gamma_0 \in \mathbb{R}^n$

Ut $\gamma(t) = \gamma_1(t) - \gamma_2(t)$. $\gamma(0) = \gamma_0 \in \mathbb{R}^n$

Ut $\gamma(t) = \gamma_1(t) - \gamma_2(t)$. $\gamma(0) = \gamma_0 \in \mathbb{R}^n$

Ut $\gamma(t) = \gamma_1(t) - \gamma_2(t)$. $\gamma(0) = \gamma_0 \in \mathbb{R}^n$

Ut $\gamma(t) = \gamma_1(t) - \gamma_2(t)$. $\gamma(0) = \gamma_0 \in \mathbb{R}^n$

Ut $\gamma(t) = \gamma_1(t) - \gamma_2(t)$. $\gamma(0) = \gamma_0 \in \mathbb{R}^n$

Ut $\gamma(t) = \gamma_1(t) - \gamma_2(t)$. $\gamma(0) = \gamma_0 \in \mathbb{R}^n$

Ut $\gamma(t) = \gamma_1(t) - \gamma_2(t)$. $\gamma(0) = \gamma_0 \in \mathbb{R}^n$

Ut $\gamma(t) = \gamma_1(t) - \gamma_2(t)$. $\gamma(0) = \gamma_0 \in \mathbb{R}^n$

Ut $\gamma(t) = \gamma_1(t) - \gamma_2(t)$. $\gamma(0) = \gamma_0 \in \mathbb{R}^n$

Ut $\gamma(t) = \gamma_1(t) - \gamma_2(t)$. $\gamma(0) = \gamma_0 \in \mathbb{R}^n$

Ut $\gamma(t) = \gamma_1(t) - \gamma_2(t)$. $\gamma(0) = \gamma_0 \in \mathbb{R}^n$

Ut $\gamma(t) = \gamma_1(t) - \gamma_2(t)$. $\gamma(0) = \gamma_0 \in \mathbb{R}^n$

Ut $\gamma(t) = \gamma_1(t) - \gamma_2(t)$. $\gamma(0) = \gamma_0 \in \mathbb{R}^n$

=)
$$|| S(t) || \le ct \max_{M \in [1,t]} || S(M) ||$$
. Fix $t_0 = \frac{1}{2c}$
 $\forall t \in [0,t_0]$ we have

 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || \le ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || = ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || = ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || = ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || = ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || = ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || = ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || = ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || = ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || = ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || = ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || = ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || = ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || = ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || = ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $|| S(t) || = ct_0 \max_{M \in [0,t_0]} || S(M) || =)$
 $| S(t) || =$

Pf. For
$$x \in ke$$
 G e $dq(x) = q(e^{x}) \in H$

$$\gamma(t) = q(e^{tx})$$

$$\gamma(t) = \frac{d}{dt} q(e^{tx}) = \frac{d}{ds} q(e^{(t+s)x})|_{s=0}$$

$$= \frac{d}{ds} q(e^{tx}) q(e^{sx})|_{s=0} = q(e^{tx}) dq(x) = q(e^{tx}) dq(x)$$

$$= \gamma(t) dq(x)$$
So γ is a γd . of the diff. equation
$$\gamma(t) = \gamma(t) dq(x) \qquad \gamma(0) = ld$$

$$q(t) = e^{tdq(x)} q(e^{tx}) q(e^{tx}) = q(f) dq(x)$$

$$q(t) = e^{tdq(x)} q(e^{tx}) q(e^{tx}) = q(f) dq(x)$$

$$q(t) = \delta(t) \forall t \in \mathbb{R}^{t-1} \qquad q(e^{tx}) = e^{dq(x)}$$
Prop deq : where $deq(x)$ is a home of his algebras
$$\forall x, y \in ke$$
 $deq(x)$, $dq(y) = dq((x, y))$.

X, y & he G Fix f Ell? $\gamma(s) = \varphi(e + x + sy - tx)$ 6(ex)6(esx)6(e-tx) etder(x) esder(Y) -tder(x) j(0) = etde (x) de (x) -t de (x) -dq(exye-tx) Ht EIR $d\varphi(XYe^{o}+e^{o}Y(-X))=d_{e}\varphi(X)d_{e}\varphi(Y)e+$ $+e^{\circ}d_{e}(Y)(-d_{e}(X))$ dq (XY-YX) $d_{e}(x)d_{e}(y)-d_{e}(y)d_{e}(x)$ ol 6 ((X, Y)) $[d_{\varphi}(x), d_{\varphi}(Y)]$

Prop Gisconected. q:G+H, q:G+H lie group hon. Thun G=G2 (=) dq, = d42. Pf. "=" Trivial "=" G: (ex) = edq:(x) +x+lie f 9, and 92 coincide on e lie G =) G, and Gz coincide on a subgroup which contains a subship of 1. =) q = q · Dul A one-parameter subgroup of Gis or smooth group hon $J: (IR, t) \rightarrow G$ Cor lie & parametrises one-parametrishprops of & Y y one-par. Subgroup 3!X Elie Gr S.t. 7(t)=etx HtER.

Pf Uniqueess follows g(0) = XA one par subporp satisfies g(s+t)=g(s)g(t) \(\forall s,t\)

$$\begin{aligned}
\tilde{J}(t) &= \frac{d}{dS} \, \mathcal{J}(s+t) \Big|_{s=0} = \frac{d}{dS} \, \mathcal{J}(t) \, \tilde{J}(s) \Big|_{s=0} = \\
&= \mathcal{J}(t) \, \mathcal{J}(0) \, . \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) \, . \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) \, . \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(0) = \mathcal{J}(t) \quad \text{which how} \\
&\approx \mathcal{J}(t) \, \mathcal{J}(t) \, \mathcal{J}(t) \quad \mathcal{J}$$