

# CellSeg2

# Main Algorithmic Steps

- Identify Background
- Identify Points within Cells
- Segment Cells

# Identify Background

Why?

- Needed for robustness against artefacts / etc.

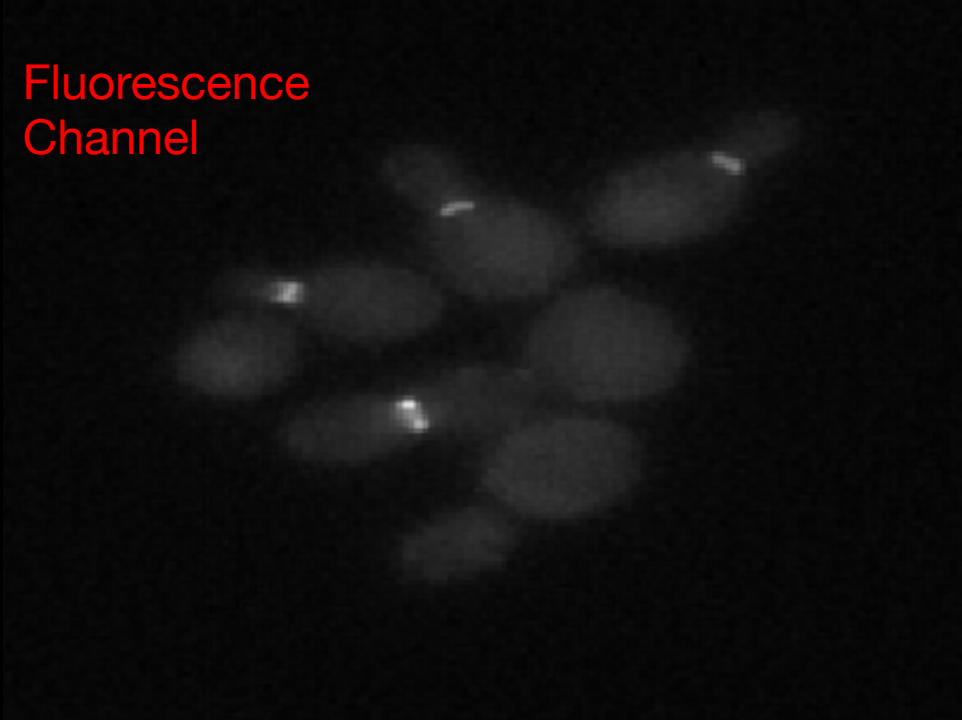
How?

- Based on fluorescence channel with high background fluorescence of cells
- Blur image with high radius
- Otsu thresholding
- Dilate thresholded image
- Invert

# Otsu Thresholding

- Divide Pixels into foreground and background
- Create histogram of Pixel intensities, which is assumed to be bimodal
- Finds threshold in “valley” between two modes, by minimizing the variance within the two clusters

Fluorescence  
Channel



Otsu  
thresholding



Dilated,  
inverted



# Point in Cell Identification

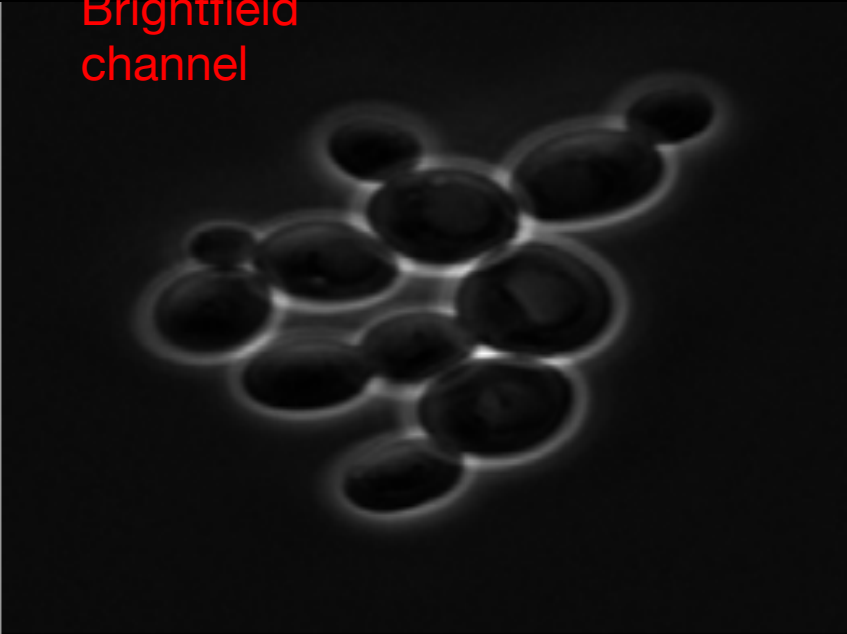
Why?

- Used for segmentation later on

How?

- Based on (blurred) brightfield image
- Otsu thresholding, series of binary image transformation to give good approximation of where the cell borders are
- Calculate distance transform
- Find maxima of smoothed distance transform that aren't within background

Brightfield  
channel



Otsu  
thresholding



Erode image,  
remove noise



Dilate, make  
border area  
larger

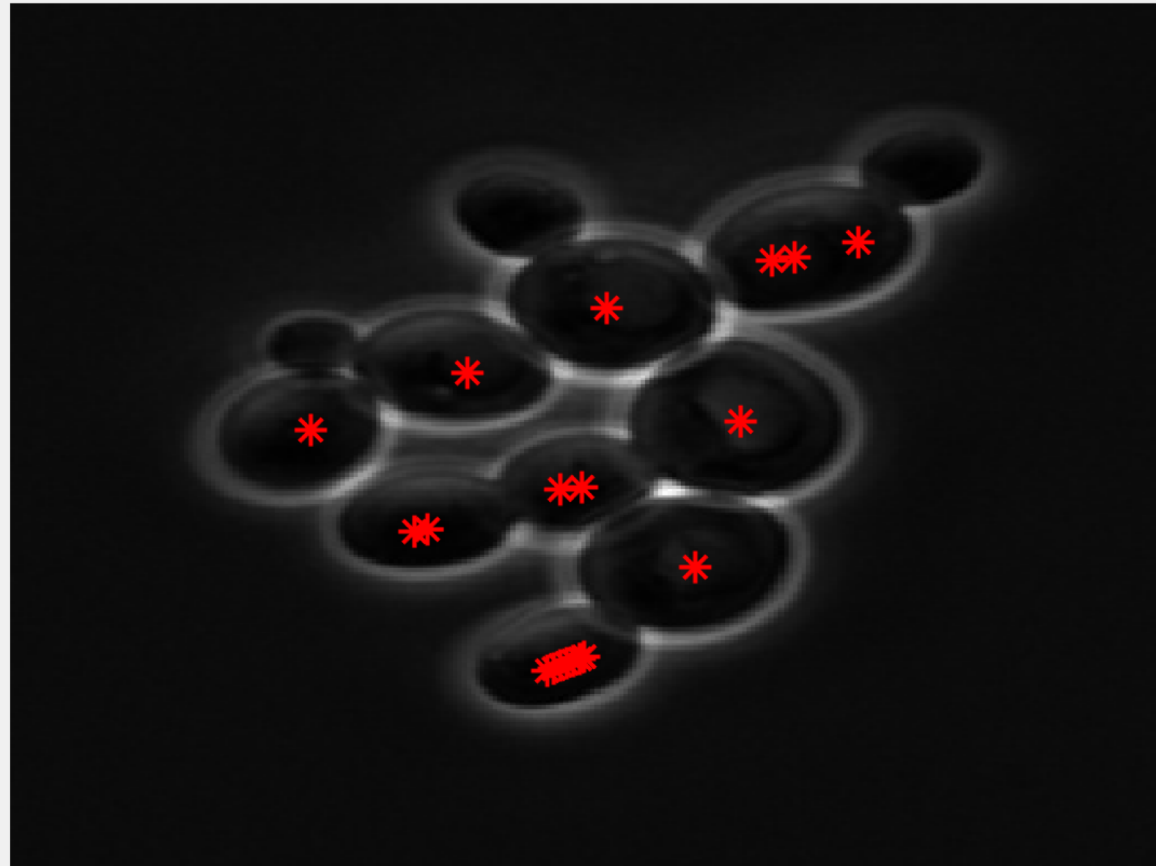


Close, better handling  
at cell connections



Smooth distance  
transform





Pan Zoom

#### Frame Selection

Region

Z

Timeframe

Channel

Position Nbr

#### Point Detection

Add Point

Remove Point

☒ Show Points

#### Plot Fluorescence

Plot Selected

#### Segmentation

Segment

Add to Region

Merge Regions

☐ Show Cell Numbers

#### Labeling

Redo Labels

Change Label

New Cell in Area



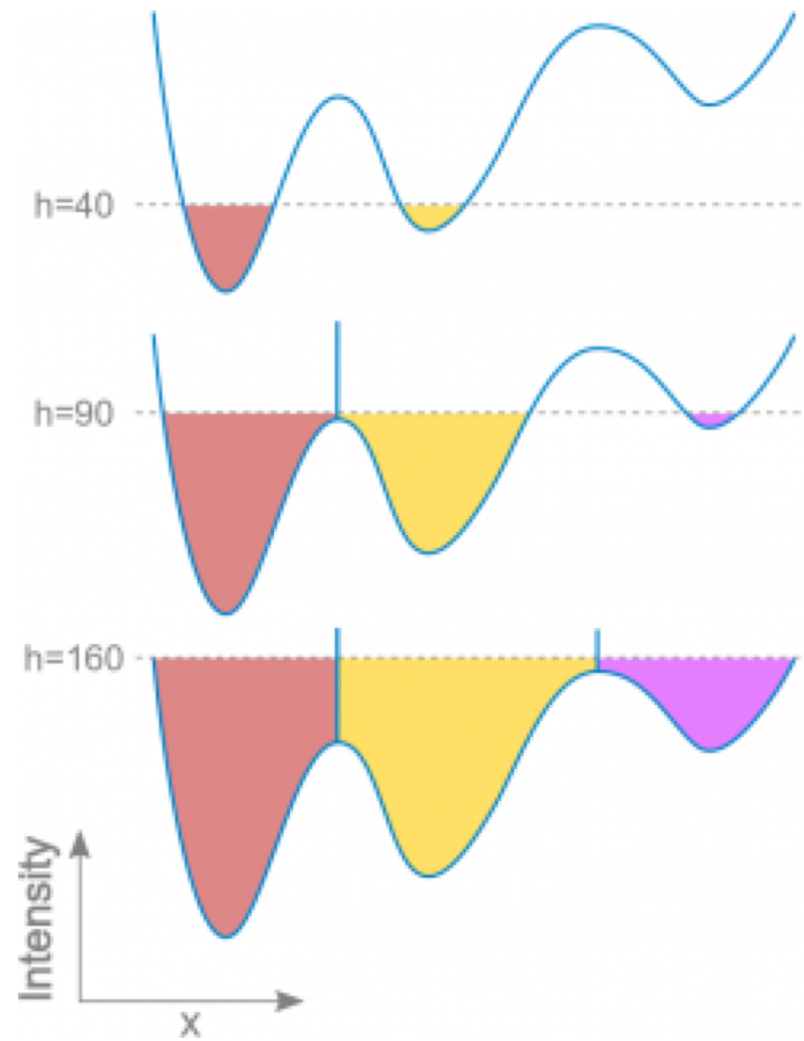
# Segment Cells

Why?

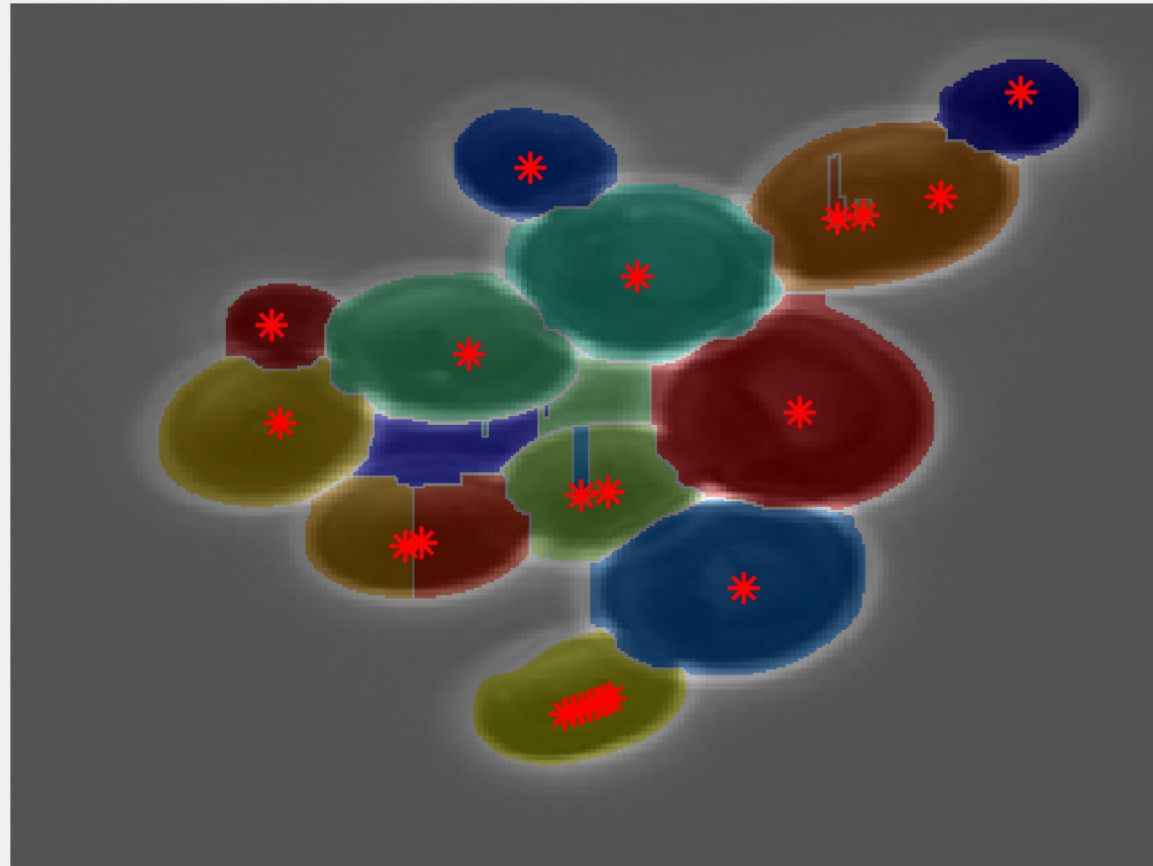
- For every pixel, assign it to a cell

How?

- Watershed algorithm
- Start at identified cell points and identified background
- Look at the image intensity as a landscape. Start filling this landscape up with water at starting points. If two lakes meet, identify this as the border of the cell.



(image from ImageJ)



Pan Zoom

#### Frame Selection

Region 1

Z 1

Timeframe 1

Channel 3

Position Nbr 1

#### Point Detection

Add Point

Remove Point

☒ Show Points

#### Plot Fluorescence

Plot Selected

#### Segmentation

Segment

Add to Region

Merge Regions

☐ Show Cell Numbers

#### Labeling

Redo Labels

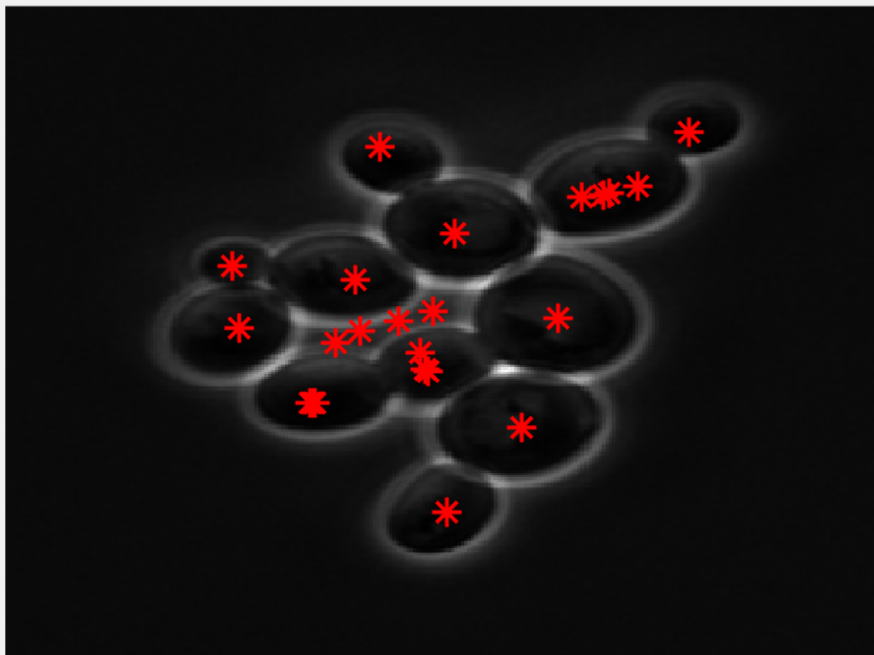
Change Label

New Cell in Area

# Learn from Previous Frame

Two key improvements in the next frame:

- If a cell in the previous frame doesn't have a point within it in the next cell, add the centroid as point
- After segmentation look at previous segmentation to identify cell correspondence.



Pan Zoom

#### Frame Selection

Region

Z

Timeframe

Channel

Position Nbr

#### Point Detection

Add Point

Remove Point

☒ Show Points

#### Plot Fluorescence

Plot Selected

#### Segmentation

Segment

Add to Region

Merge Regions

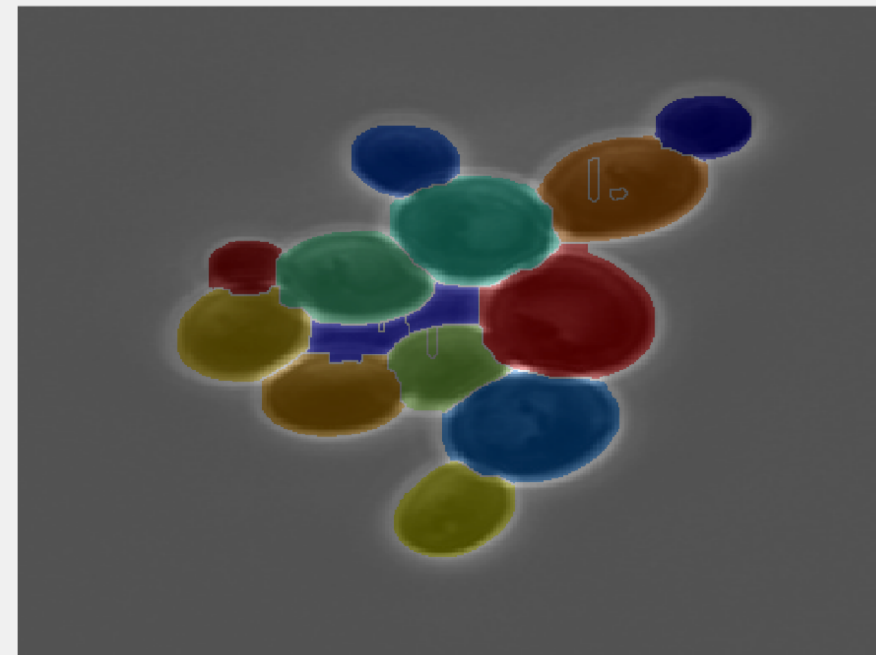
☐ Show Cell Numbers

#### Labeling

Redo Labels

Change Label

New Cell in Area



Pan Zoom

#### Frame Selection

Region

Z

Timeframe

Channel

Position Nbr

#### Point Detection

Add Point

Remove Point

☐ Show Points

#### Plot Fluorescence

Plot Selected

#### Segmentation

Segment

Add to Region

Merge Regions

☐ Show Cell Numbers

#### Labeling

Redo Labels

Change Label

New Cell in Area