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CS3331 Concurrent Computing Exam 2 Fall 2015

100 points – 8 pages

- Most of the following questions only require short answers. Usually a few sentences would be sufficient. Please write to the point. If I don't understand what you are saying, I believe, in most cases, you don't understand the subject.
- To minimize confusion in grading, please write <u>readable</u> answers. Otherwise, it is likely I may interpret your unreadable handwriting in my way.
- Justify your answer with a convincing argument. An answer <u>must</u> include a convincing justification. You will receive no point for that question even though you have provided a correct answer. I consider a good and correct justification more important than just providing a right answer. Thus, if you provide a very vague answer without a convincing argument to show your answer being correct, you will likely receive a low to very low grade.
- You must use execution sequences to answer a problem if you are asked to do so. In addition, you must include a convincing argument. You will receive <u>zero</u> point if you do not provide a needed execution sequence, you do not elaborate your answer, and your answer is not clear or vague.
- Repeated/Recycled problems are marked with * and will be graded with a nearly all-or-nothing principle.
- The syntax of semaphores is unimportant. You may declare and initialize a semaphore S with "Sem S = 1" and use Wait (S) and Signal (S) for semaphore wait and semaphore signal.
- Do those problems you know how to do first. Otherwise, you may not be able to complete this exam on time.

1. Synchronization Basics

(a) [15 points] The following is a solution to the critical section problem. It has two shared variables Flag[] and turn and a process Scheduler started before processes P_1 and P_2 . Process Scheduler waits until turn becomes 0. Then, the repeat-until loop searches for a j such that Flag[j] is TRUE. Finally, turn is set to the value of j and loops back.

```
Boolean Flag[1..2] = { FALSE, FALSE } // note that there is no Flag[0]
       turn = 0;
Process Scheduler
int j;
j = 0;
                         // repeat forever
repeat
  while (turn != 0)
                         // wait if turn is not 0
                         //
     ;
                         // now turn = 0
  repeat
     j = (j \% 2) + 1;
                         // search for a j such that
  until Flag[j];
                         // Flag[j] is TRUE
                         // set turn to j
  turn = j;
until FALSE;
                         // loops back
```

Processes P_1 and P_2 are shown below. Both have very simple entry and exit sections.

```
Process P_1 Process P_2

Flag[1] = TRUE;  // interested Flag[2] = TRUE;  // interested while (turn != 1)  // wait if not my turn while (turn != 2)  // wait if not my turn;  // Critical Section  // Critical Section Flag[1] = FALSE;  // no more interested turn = 0;  // release my turn turn = 0;  // release my turn
```

Show rigorously that this solution satisfies the mutual exclusion and bounded waiting conditions. Moreover, state the *bound* first and prove the bounded waiting condition. A vague and/or unconvincing proof receives no point.

(b) [10 points]* Define the meaning of a *race condition*? Answer the question first and use an execution sequence with a clear and convincing argument to illustrate your answer. You must explain step-by-step why your example causes a race condition.

2. Synchronization

(a) [10 points] Consider the following implementation of mutual exclusion with a semaphore X.

Semaphore X = 1;

Show rigorously that the above implementation satisfies the mutual exclusion condition. A vague and/or unconvincing proof receives no point.

(b) [10 points] A programmer designed a FIFO semaphore so that the waiting processes can be released in a first-in-first-out order. This FIFO semaphore has an integer counter Counter, a queue of semaphores, and procedures FIFO_Wait() and FIFO_Signal().

A semaphore Mutex with initial value 1 is also used. FIFO_Wait() uses Mutex to lock the procedure and checks Counter. If Counter is positive, FIFO_Wait() decreases Counter by one, unlocks the procedure, and returns. If Counter is zero, a semaphore X with initial value 0 is allocated and added to the end of the queue of semaphores. Then, FIFO_Wait() releases the procedure, and lets the caller wait on X.

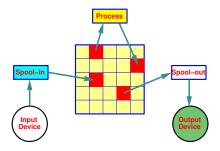
Procedure FIFO_Signal() first locks the procedure, and checks if the semaphore queue is empty. If the queue is empty, FIFO_Signal() increases Counter by one, unlocks the procedure, and returns. If there is a waiting process in the queue, the head of the queue is removed and signaled so that the *only* waiting process on that semaphore can continue. Then, this semaphore node is freed and the procedure is unlocked.

Finally, the initialization procedure FIFO_Init(), not shown below, sets the counter to an initial value and the queue to empty.

```
Semaphore Mutex = 1;
int
           Counter;
FIFO_Wait(...)
                                               FIFO_Signal(...)
     Wait (Mutex);
                                                    Wait (Mutex);
     if (Counter > 0) {
                                                     if (queue is empty) {
          Counter--;
                                                          Counter++;
          Signal (Mutex);
                                                          Signal (Mutex);
     else { /* must wait here */
                                                     else { /* someone is waiting */
          allocate a semaphore node, X=0;
                                                          remove the head X;
          add X to the end of queue;
                                                          Signal(X);
          Signal (Mutex);
                                                          free X;
          Wait(X);
                                                          Signal (Mutex);
                                                     }
     }
}
```

Discuss the correctness of this solution. If you think it correctly implements a first-in-first-out semaphore, provide a convincing argument to justify your claim. Otherwise, discuss why it is wrong with an execution sequence.

(c) [15 points] A simplified SPOOL system has three processes: Spool-in, Spool-out and Process. They share a spool device, say a disk. Spool-in reads in input from a slow input device and copies it to the spool device, Spool-out sends the print output from the spool device to a slow output device, and Process is a user program that reads in its input from and writes its output to the spool device. To be more efficient, the spool device is divided into a number of slots and each read and write operation reads and writes exactly one slot. Once a slot is read (by Process) or printed (by Spool-out) the space occupied by this slot is considered free and can be re-used.



The following are the "rules" for performing a spooling operation:

- Initially, the spool device is empty.
- As long as the spool device has an empty slot, *Spool-in* will read the input and copy it to the spool device. If all slots are used, *Spool-in* blocks until there are free slots.
- *Process* reads its input from the spool device if there are slots that have been filled with input data by *Spool-in*; otherwise, *Process* blocks until new input data become available. After reading an input, *Process* will generate some output, one slot at a time. *Process* also blocks until there are empty slots for output.
- As long as the spool device has output slots, *Spool-out* will read and send them to the output device. *Spool-out* blocks until output data become available.
- Reading from and writing into a slot is guaranteed to be mutually exclusive.

Under what condition(s) this system will have a deadlock. You should provide an execution sequence that can lead to a deadlock. Elaborate your answer; otherwise, you may receive <u>low</u> or even **no** credit.

3. Problem Solving:

(a) [20 points] A multithreaded program has two global arrays and a number of threads that execute concurrently. The following shows the global arrays, where n is a constant defined elsewhere (e.g., in a #define):

```
int a[n], b[n];
```

Thread T_i ($0 < i \le n-1$) runs the following (pseudo-) code, where function f () takes two integer arguments and returns an integer, and function g () takes one integer argument and returns an integer. Functions f () and g () do not use any global variable.

```
while (not done) {
    a[i] = f(a[i], a[i-1]);
    b[i] = g(a[i]);
}
```

More precisely, thread T_i passes the value of a[i-1] computed by T_{i-1} and the value of a[i] computed by T_i to function f() to compute the new value for a[i], which is then passed to function g() to compute b[i].

Declare semaphores with initial values, and add Wait() and Signal() calls to thread T_i so that it will compute the result correctly. Your implementation should not have any busy waiting, race condition, and deadlock, and should aim for **maximum parallelism**.

A convincing correctness argument is needed. Otherwise, you will receive <u>no</u> credit for this problem.

- (b) [20 points] Design a class Group in C++, a constructor, and method Group_wait () that fulfill the following specification:
 - The constructor Group (int n) takes a positive integer argument n, and initializes a private int variable in class Group to have the value of n. The value of n will not change in the execution of the program.
 - Method Group_wait (void) takes no argument. A thread that calls Group_wait() blocks if the number of threads being blocked is less than n-1. Then, the n-th calling thread releases all n-1 blocked threads and all n threads continue. Note that the system has more than n threads. For example, suppose n is initialized to 3. The first two threads that call Group_wait() block. When the third thread calls Group_wait(), the two blocked threads are released, and all three threads continue. Note that your solution cannot assume n to be 3. Otherwise, you will receive zero point.

Use semaphores only to implement class Group and method Group_wait(). Otherwise, you will receive **zero** point. Use Sem for semaphore declaration and initialization (e.g., "Sem S = 0;"), Wait(S) on a semaphore S, and Signal(S) to signal semaphore S.

Your implementation should not have any busy waiting, race condition and deadlock. You should explain why your implementation is correct in detail. A vague discussion or no discussion receives <u>no</u> credit.

Grade Report

Problem		Possible	You Received
1	a	15	
	b	10	
2	a	10	
	b	10	
	С	15	
3	a	20	
	b	20	
Total		100	