

# CSE 3100 Exam 3

## Review

# POSIX Threads

- Thread creation
- Thread joining
- Synchronization Methods
  - Mutex
  - Condition variables
  - Barriers

# Creating/Joining With Threads

```
int pthread_create(pthread_t *thread, const pthread_attr_t *attr,  
                  void *(*start_routine) (void *), void *arg);
```

- Threads always receive a void\* and return a void\*
  - Why is this?
- We usually package thread arguments in a struct

```
int pthread_join(pthread_t thread, void **retval);
```

- We must know which thread we want to join with
- Notice the slight difference in types

# Creating/Joining With Threads Example

```
✓ typedef struct thread_arg_tag {  
    int num;  
    double data[16];  
    // we can put whatever we want here  
} thread_arg_t;  
  
✓ void* thread_func(void* arg) {  
    // Do things!!  
    return NULL; // or some value in a void*  
}  
  
✓ int main() {  
    pthread_t my_thread;  
    thread_arg_t my_arg;  
    // set values in the my_arg struct  
    pthread_create(&my_thread, NULL, thread_func, &my_arg);  
    // ...  
    pthread_join(my_thread, NULL); // if we don't care about the return value, use NULL  
}
```

# Mutexes

```
int pthread_mutex_destroy(pthread_mutex_t *mutex);  
int pthread_mutex_init(pthread_mutex_t *restrict mutex,  
const pthread_mutexattr_t *restrict attr);
```

- We usually initialize mutexes with default attributes (NULL)
- You can only destroy an *unlocked* mutex!
- Use mutexes to protect shared data/resources
- We need to avoid **data races**

# Mutex Rules of Thumb

We should use a mutex when:

- We need to “protect” a certain value
- Multiple threads are writing and/or reading this same value
- When only one thread should be executing a section of code at a certain time
  - “Critical Section”

We should NOT use a mutex when:

- Multiple threads are only reading a value (no data races)
- Threads are guaranteed not to interfere with one another

# Mutex Design Example

Let's say we want to count the number of prime numbers between 2 and 1000. We split the work between two threads.

Thread 1 takes numbers 2-500, and thread 2 takes 501-1000

Let's come up with some pseudocode for these threads

# Mutex Design Example (Counting Primes)

## Design 1:

```
for i between [min, max]:  
    if i is prime:  
        lock mutex  
        shared_prime_count++  
        unlock mutex
```

## Design 2:

```
for i between [min, max]:  
    if i is prime:  
        local_count++  
  
lock mutex  
shared_prime_count += local_count  
unlock mutex
```

Which design is better?



# Condition Variables

```
int pthread_cond_destroy(pthread_cond_t *cond);  
int pthread_cond_init(pthread_cond_t *restrict cond,  
const pthread_condattr_t *restrict attr);
```

- Again, initialize with default attributes (NULL)
- Each cond is associated with only one mutex

```
int pthread_cond_wait(pthread_cond_t *restrict cond,  
pthread_mutex_t *restrict mutex);
```

```
int pthread_cond_broadcast(pthread_cond_t *cond);  
int pthread_cond_signal(pthread_cond_t *cond);
```

# Condition Variables

```
typedef struct thread_arg_tag {
    int num;
    pthread_mutex_t mutex;
    pthread_cond_t cond;
} thread_arg_t;

void* thread_func(void* arg) {
    thread_arg_t* thread_arg = arg;
    pthread_mutex_lock(&thread_arg->mutex);
    while(thread_arg->num < 100) {
        pthread_cond_wait(&thread_arg->cond, &thread_arg->mutex);
    }
    // Do things
    pthread_mutex_unlock(&thread_arg->mutex);

    // ...

    return NULL;
}
```

- Always in a while loop
- Should be predicated on some condition
  - Perhaps a status variable
- Unlocks the mutex while waiting
- Has the mutex when we wake up

# Barriers

```
int pthread_barrier_destroy(pthread_barrier_t *barrier);  
int pthread_barrier_init(pthread_barrier_t *restrict barrier,  
const pthread_barrierattr_t *restrict attr, unsigned count);
```

- Again, initialize with default attributes (NULL)
- Initialize with a *count*, the number of threads to hit a barrier before they are unblocked

```
int pthread_barrier_wait(pthread_barrier_t *barrier);
```

- Note that `barrier_wait` calls do not take a mutex
- Typically barriers are used independent of mutexes

# Common Mistakes

```
enum {S_INIT, S_READY};

typedef struct thread_arg_tag {
    int num;
    int status;
    pthread_mutex_t mutex;
    pthread_cond_t cond;
} thread_arg_t;

void* some_func(void* arg) {
    thread_arg_t* thread_arg = arg;

    if(thread_arg->status == S_READY) {
        pthread_mutex_lock(&thread_arg->mutex);
        thread_arg->num += 100;
        pthread_mutex_unlock(&thread_arg->mutex);
    }

    // ...

    return NULL;
}
```

# Common Mistakes

```
enum {S_INIT, S_READY};

typedef struct thread_arg_tag {
    int num;
    int status;
    pthread_mutex_t mutex;
    pthread_cond_t cond;
} thread_arg_t;

void* some_func(void* arg) {
    thread_arg_t* thread_arg = arg;

    if(thread_arg->status == S_READY) {
        pthread_mutex_lock(&thread_arg->mutex);
        thread_arg->num += 100;
        pthread_mutex_unlock(&thread_arg->mutex);
    }

    // ...

    return NULL;
}
```

## Correct Approach

```
enum {S_INIT, S_READY};

typedef struct thread_arg_tag {
    int num;
    int status;
    pthread_mutex_t mutex;
    pthread_cond_t cond;
} thread_arg_t;

void* better_func(void* arg) {
    thread_arg_t* thread_arg = arg;

    pthread_mutex_lock(&thread_arg->mutex);
    while(thread_arg->status != S_READY) {
        pthread_cond_wait(&thread_arg->cond, &thread_arg->mutex);
    }
    thread_arg->num += 100;
    pthread_mutex_unlock(&thread_arg->mutex);

    // ...

    return NULL;
}
```

# Common Mistakes

```
enum {S_INIT, S_READY};

typedef struct thread_arg_tag {
    int num;
    int status;
    pthread_mutex_t mutex;
    pthread_cond_t cond;
} thread_arg_t;

void* slow_func(void* arg) {
    thread_arg_t* thread_arg = arg;
    pthread_mutex_lock(&thread_arg->mutex);
    do_one_million_calculations(thread_arg->num);
    pthread_mutex_unlock(&thread_arg->mutex);
}
```

# Common Mistakes

```
enum {S_INIT, S_READY};

typedef struct thread_arg_tag {
    int num;
    int status;
    pthread_mutex_t mutex;
    pthread_cond_t cond;
} thread_arg_t;

void* slow_func(void* arg) {
    thread_arg_t* thread_arg = arg;
    pthread_mutex_lock(&thread_arg->mutex);
    do_one_million_calculations(thread_arg->num);
    pthread_mutex_unlock(&thread_arg->mutex);
}
```

## Correct Approach

```
enum {S_INIT, S_READY};

typedef struct thread_arg_tag {
    int num;
    int status;
    pthread_mutex_t mutex;
    pthread_cond_t cond;
} thread_arg_t;

void* faster_func(void* arg) {
    thread_arg_t* thread_arg = arg;
    int temp;
    pthread_mutex_lock(&thread_arg->mutex);
    temp = thread_arg->num;
    pthread_mutex_unlock(&thread_arg->mutex);
    do_one_million_calculations(temp);
    return NULL;
}
```

An example program

Check the Exam 3 Review Session Folder in HuskyCT

Download *workshop.c* and setup your environment

We will code along together

Solutions will be posted after the review session



# Problem Description

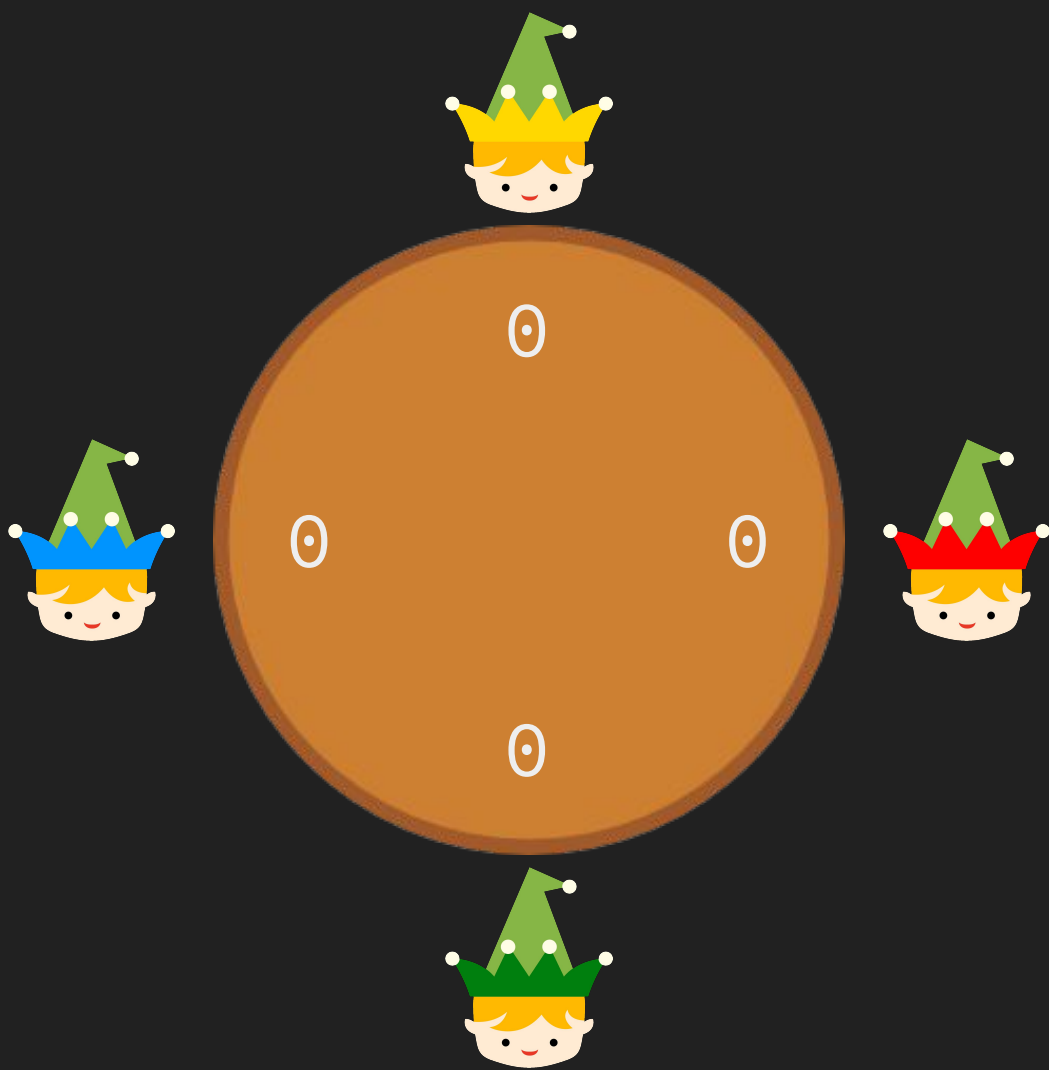
- We will simulate elves in a workshop making toy cars.
- Each car needs a certain number of parts to function
- Let's say we have four elves and four parts in a car

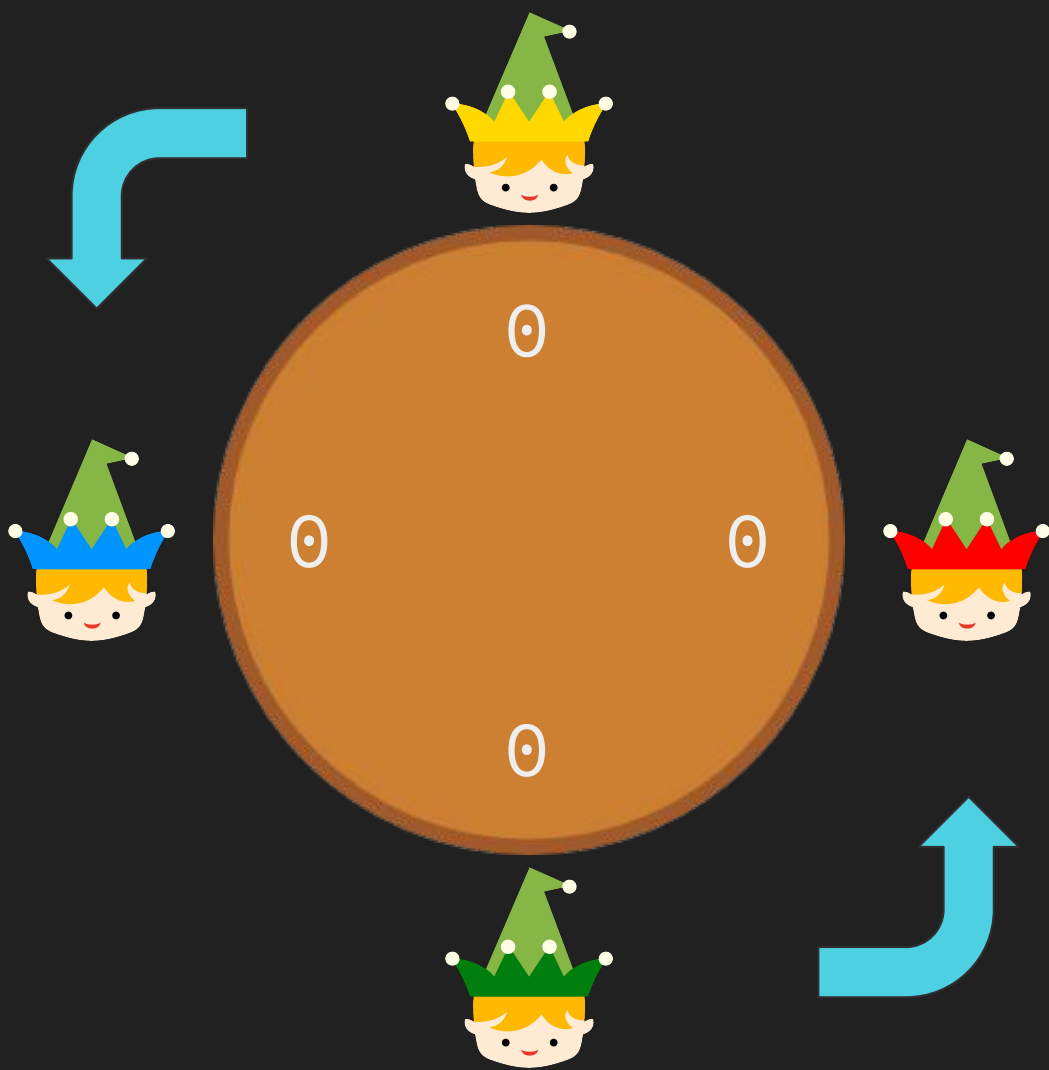
## **Restriction:**

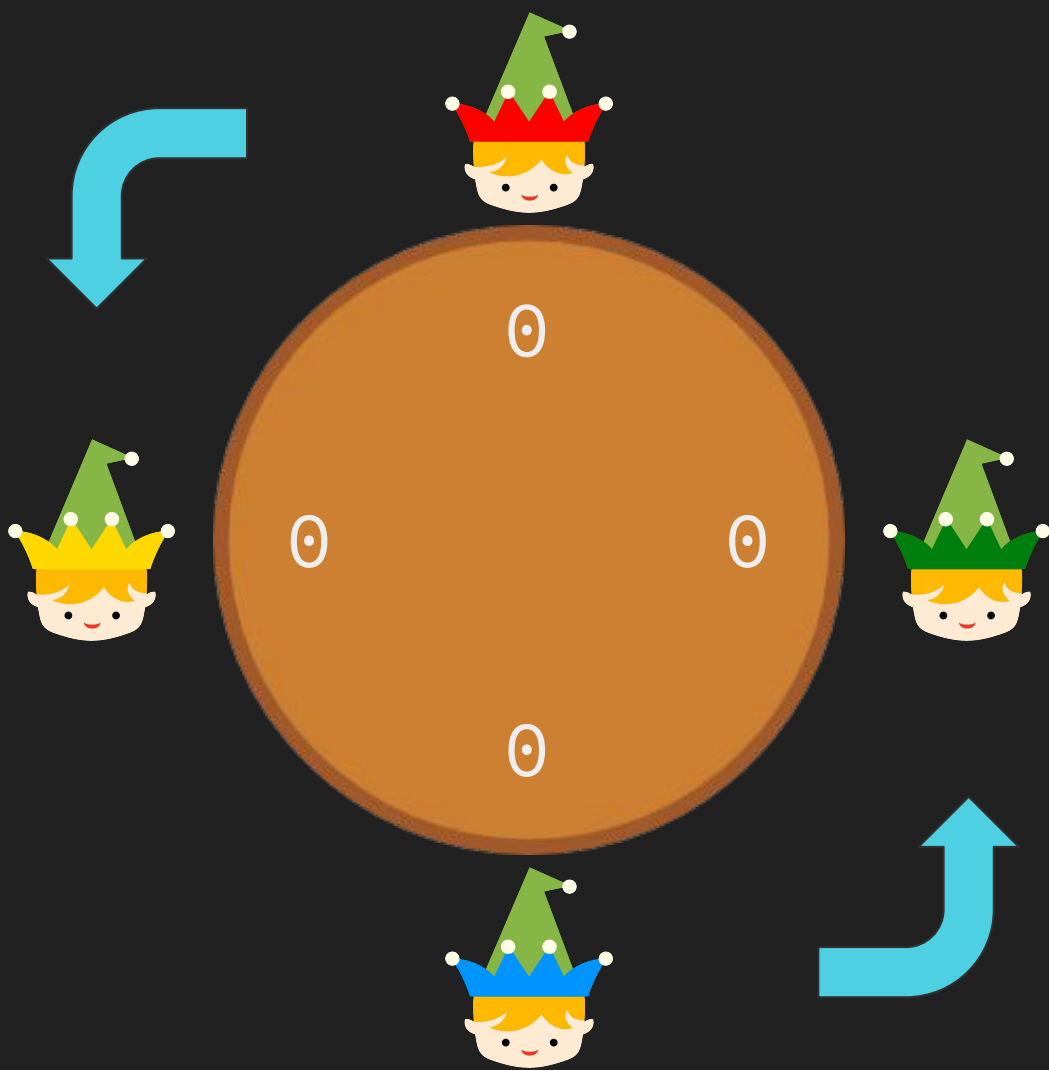
Elves love teamwork, so each elf must add exactly one part to each car.

We can have the elves move in a circle!

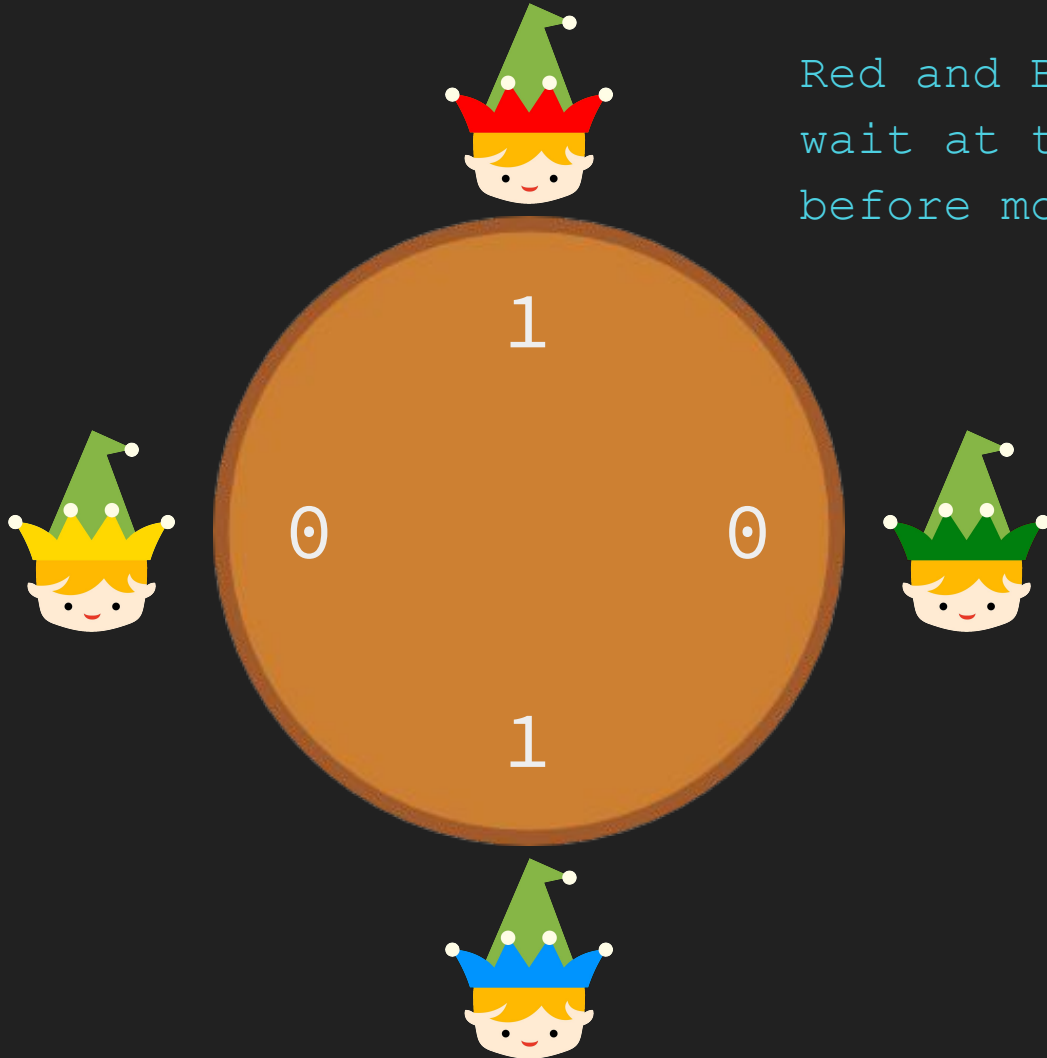




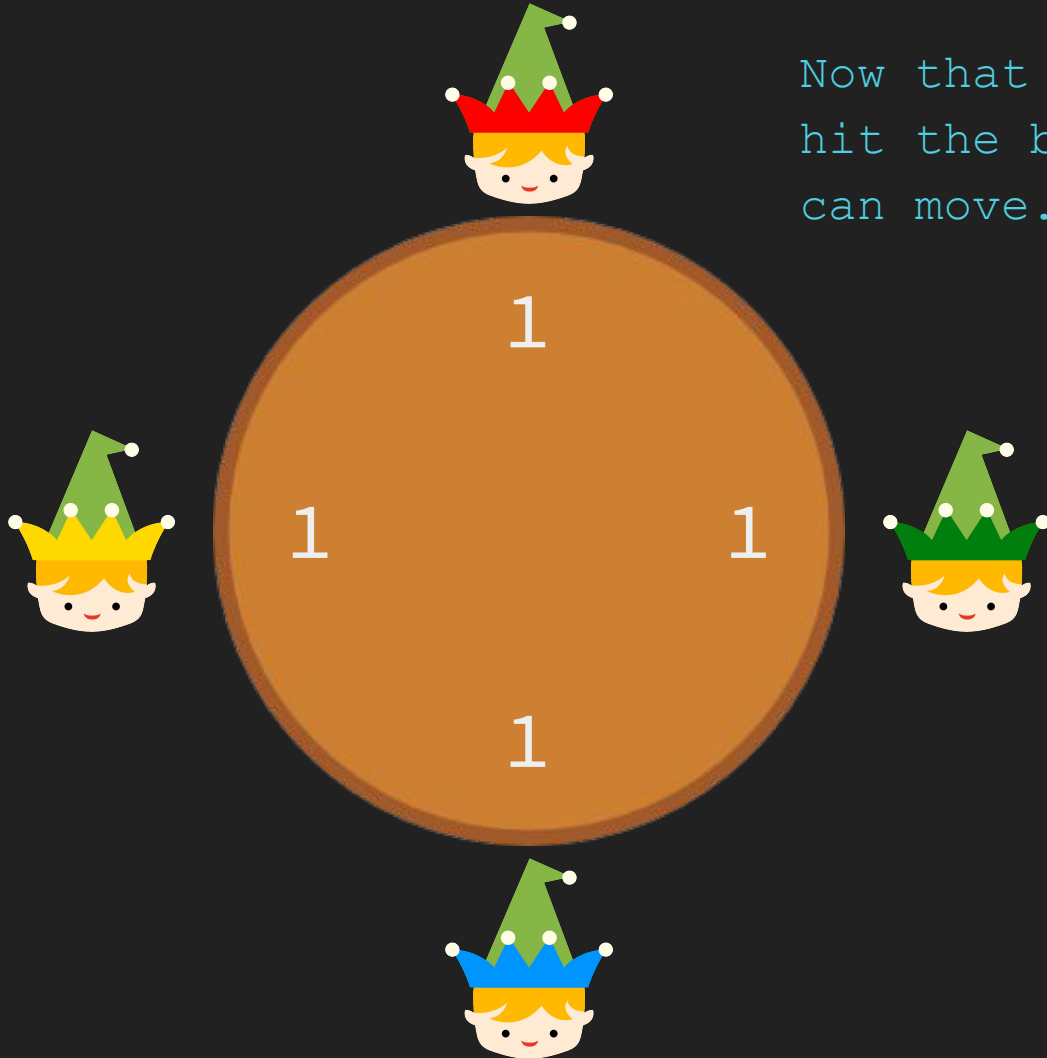


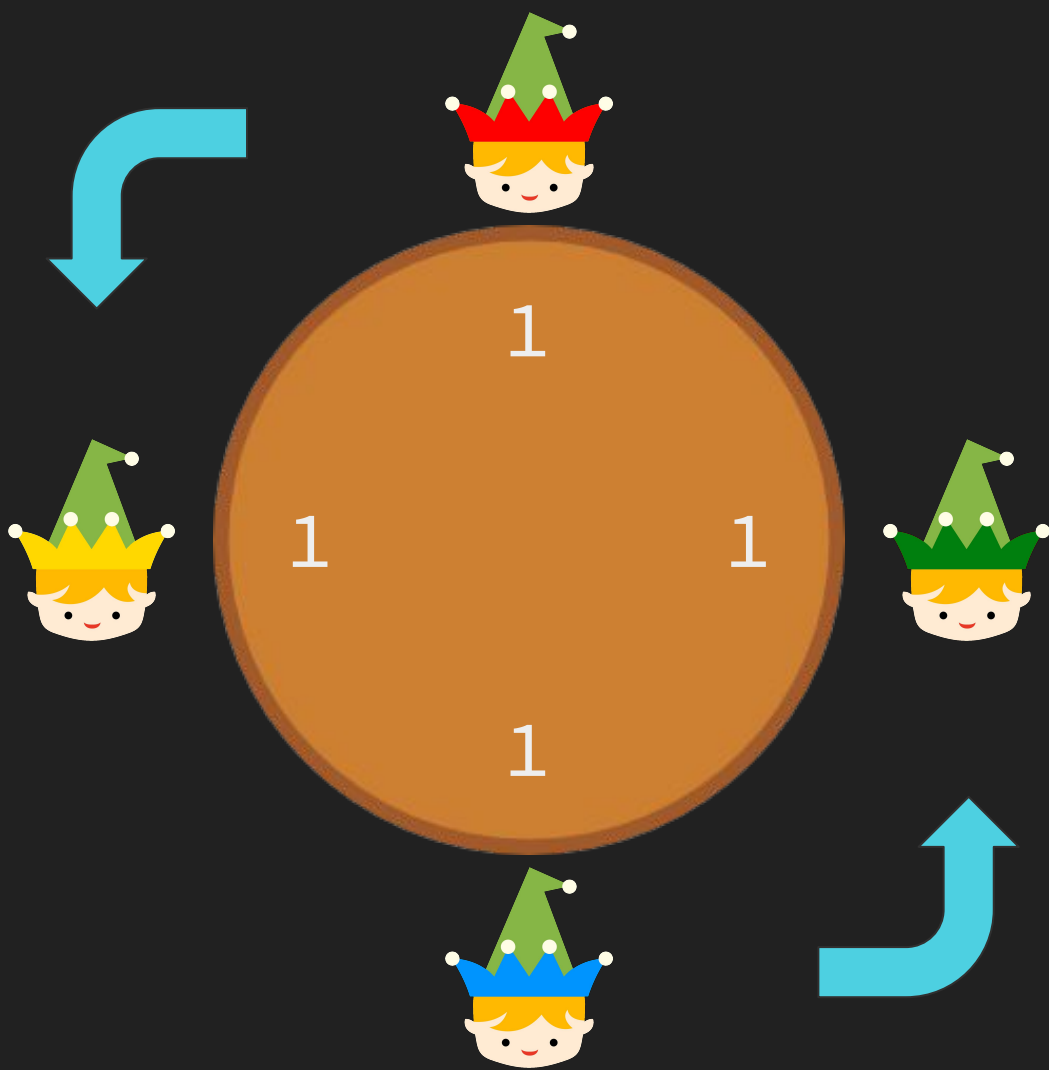


Red and Blue must  
wait at the barrier  
before moving!

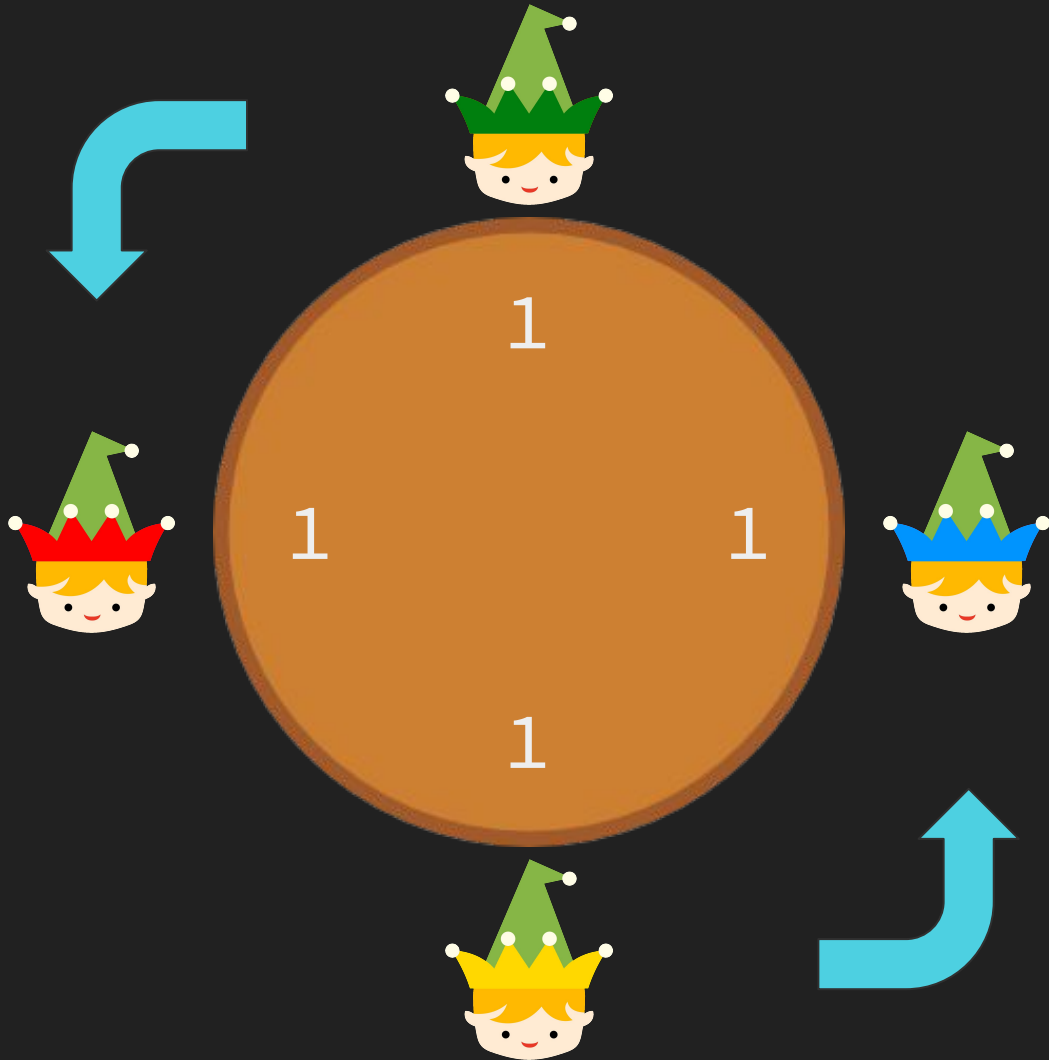


Now that each elf has  
hit the barrier, they  
can move...





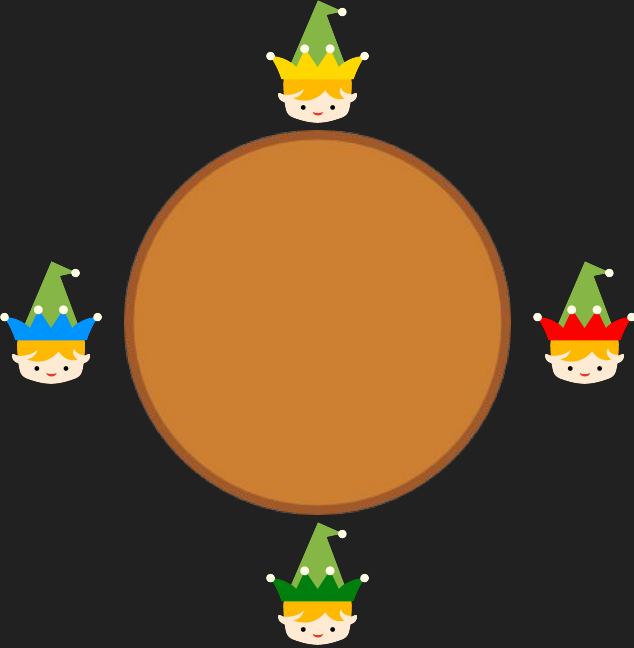






The elves work and wait at the barrier again...

If an elf sees that the car has 4 parts, free it! Then stop.



## Summary:

1. Grab a car
2. Wait at the barrier
3. Move one step
4. If the car has less than 4 parts, add one and repeat from step 2
5. Else, free the car and stop working

```
/*  
 * The elves sit in a circle and take the following steps:  
 * First, each elf grabs a car and places it in the spot corresponding to its id  
 * Next, each elf moves to the next spot around the table. 0->1->2->3->0->...  
 * Once the elves have moved, each elf adds a part to the car  
 * After all the elves complete this task, they move once again (this must be synchronized!)  
 * Eventually, every car will have the necessary number of parts and the elves should send them to santa! (Free them)  
 * Afterwards, the elves will stop working  
 */
```

## Extra Notes:

- It is highly recommended that you run your code locally rather than submit to gradescope to test your code
  - It takes a long time for gradescope to run
- PLEASE make sure your code **compiles**
  - Recommendation: each time you have compiled code, copy it into a notepad so that if your changes are unrecoverable, you always have compiled code to submit
- Helpful tool to find thread errors:

```
valgrind --tool=helgrind executable
```

Questions?