

Task 1.1: Gradient and Differentiability

Assume that $f: \mathbb{R} \rightarrow \mathbb{R}$ is differentiable and define $F: \mathbb{R}^2 \rightarrow \mathbb{R}$ by setting

$$F(x, y) = f(x + 2y) + f(7y - 3x)$$

for all $x, y \in \mathbb{R}$. Is F differentiable? In that case, compute ∇F .

Set $g_1(x, y) = x + 2y$ and $g_2(x, y) = 7y - 3x$. As differentiability is a linear property, we know that g_1 and g_2 are differentiable on \mathbb{R}^2 . Given f , g_1 and g_2 are differentiable, both $f \circ g_1$ and $f \circ g_2$ are differentiable, and thus through linearity, F is as well.

$$\begin{aligned}\nabla F &= \frac{\partial F}{\partial \mathbf{x}} = \begin{bmatrix} \frac{\partial F}{\partial x} \\ \frac{\partial F}{\partial y} \end{bmatrix} \\ \frac{\partial F}{\partial x} &= \frac{\partial f \circ g_1}{\partial x} + \frac{\partial f \circ g_2}{\partial x} = \frac{\partial f}{\partial g_1} \frac{\partial g_1}{\partial x} + \frac{\partial f}{\partial g_2} \frac{\partial g_2}{\partial x} = f' \circ g_1 - 3f' \circ g_2 \\ \frac{\partial F}{\partial y} &= \frac{\partial f \circ g_1}{\partial y} + \frac{\partial f \circ g_2}{\partial y} = \frac{\partial f}{\partial g_1} \frac{\partial g_1}{\partial y} + \frac{\partial f}{\partial g_2} \frac{\partial g_2}{\partial y} = 2f' \circ g_1 + 7f' \circ g_2 \\ \Rightarrow \nabla F &= \begin{bmatrix} f' \circ g_1 - 3f' \circ g_2 \\ 2f' \circ g_1 + 7f' \circ g_2 \end{bmatrix} \Rightarrow \nabla F(\mathbf{x}) = \begin{bmatrix} f'(g_1(\mathbf{x})) - 3f'(g_2(\mathbf{x})) \\ 2f'(g_1(\mathbf{x})) + 7f'(g_2(\mathbf{x})) \end{bmatrix}\end{aligned}$$

Task 1.2: Absolute Value

Define $F: \mathbb{R}^2 \rightarrow \mathbb{R}$ by setting $F(x, y) = \sqrt{|xy|}$. Is F differentiable in $\mathbf{0}$? Justify your answer.

Let $f_1(x) = \sqrt{x}$, $f_2(x) = |x|$ and $f_3(x, y) = xy$, then $F = f_1 \circ f_2 \circ f_3$. Given f_2 is not differentiable at $x = 0$, F is not differentiable at $\mathbf{0}$.

Recall on the **Banach-Fixed-Point** theorem. Let (X, d) be a non-empty complete metric space and $F: X \rightarrow X$. We say F is a *contraction* if there exists a constant $C \in [0, 1)$ such that

$$d(F(z_1), F(z_2)) \leq Cd(z_1, z_2)$$

for all $z_1, z_2 \in X$. We say that \bar{z} is a *fixed point* for F if $F(\bar{z}) = \bar{z}$. The Banach-Fixed-Point theorem states that if F is a contraction, then F admits a unique fixed point. Recall that \mathbb{R}^n is a complete metric space with the euclidean distance.

Task 1.3: Banach-Fixed-Point Theorem

Let (X, d) be a non-empty complete metric space. Prove the Banach-Fixed-Point theorem stated above.

Let $x_0 \in X$ be arbitrary and F a contraction on X with constant $C \in [0, 1)$. We define a sequence $(x_n)_{n \in \mathbb{N}}$ inductively where $x_{n+1} = F(x_n)$. We prove $(x_n)_{n \in \mathbb{N}}$ is a Cauchy-sequence. Since X is complete under d , if $(x_n)_{n \in \mathbb{N}}$ is a Cauchy-sequence, it converges:

$$d(x_l, x_{l+1}) = d(g(x_{l-1}), g(x_l)) \leq Cd(x_{l-1}, x_l) \leq C^2 d(x_{l-2}, x_{l-1}) \leq \dots \leq C^l d(x_0, x_1)$$

Therefore for some $l \in \mathbb{N}$ with $l \geq 1$, we know that $d(x_l, x_{l+1}) \leq C^l d(x_0, x_1)$, i.e. the distance between subsequent entries becomes 0 as $n \rightarrow \infty$. We now prove that $(x_n)_{n \in \mathbb{N}}$ is in fact a Cauchy-sequence. Let $n, m \in \mathbb{N}$ be arbitrary indices:

$$d(x_{n+m}, x_n) \leq d(x_n, x_{n+1}) + d(x_{n+1}, x_{n+2}) + \dots + d(x_{n+m-1}, x_{n+m})$$

$$\begin{aligned} &\leq C^n d(x_0, x_1) + C^{n+1} d(x_0, x_1) + \cdots + C^{n+m-1} d(x_0, x_1) \\ &= C^n d(x_0, x_1) \sum_{j=0}^{m-1} C^j \leq C^n d(x_0, x_1) \sum_{j=0}^{\infty} C^j = d(x_0, x_1) \frac{C^n}{1-C} \end{aligned}$$

Given $d(x_n, x_{n+m}) \leq d(x_0, x_1) \frac{C^n}{1-C} < \varepsilon$ we get

$$C^n < \frac{\varepsilon(1-C)}{d(x_0, x_1) + 1}$$

As $C < 1$, we can choose n arbitrarily large, hence $(x_n)_{n \in \mathbb{N}}$ is a Cauchy-sequence, as the distance of any two entries for large n diminishes. Given F is Lipschitz-continuous with Lipschitz-constant C , we can apply the sequence-criterion:

$$\lim_{n \rightarrow \infty} F(x_n) = F(\bar{x})$$

Let \bar{x}, \bar{y} be fixed-points of F , then

$$d(\bar{x}, \bar{y}) = d(F(\bar{x}), F(\bar{y})) \leq Cd(\bar{x}, \bar{y}) \Rightarrow d(\bar{x}, \bar{y}) = 0 \Leftrightarrow \bar{x} = \bar{y}$$

Task 1.4: Unique Zero with Banach-Fixed-Points

Define $\mathbf{F}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by setting:

$$\mathbf{F}(x, y) = \begin{bmatrix} x + \frac{y}{2} \\ \frac{x}{2} + y + 1 \end{bmatrix}$$

Define the map $\mathbf{G}(\mathbf{x}) = \mathbf{x} - \mathbf{F}(\mathbf{x})$. Using the Banach-Fixed-Point theorem on \mathbf{G} , prove that \mathbf{F} admits a unique zero, i.e. $\exists \bar{\mathbf{x}} \in \mathbb{R}^2: \mathbf{F}(\bar{\mathbf{x}}) = \mathbf{0}$.

We begin by showing that \mathbf{G} is Lipschitz-continuous with a Lipschitz-constant $C \in [0, 1)$:

$$\begin{aligned} \|\mathbf{G}(\mathbf{x}) - \mathbf{G}(\mathbf{y})\| &= \|\mathbf{x} - \mathbf{F}(\mathbf{x}) - \mathbf{y} + \mathbf{F}(\mathbf{y})\| \\ &= \sqrt{\left(x_1 - x_1 - \frac{x_2}{2} - y_1 + y_1 + \frac{y_2}{2}\right)^2 + \left(x_2 - \frac{x_1}{2} - x_2 - 1 - y_2 + \frac{y_1}{2} + y_2 + 1\right)^2} \\ &= \sqrt{\left(\frac{y_2}{2} - \frac{x_2}{2}\right)^2 + \left(\frac{y_1}{2} - \frac{x_1}{2}\right)^2} = \frac{1}{2}\|\mathbf{y} - \mathbf{x}\| = \frac{1}{2}\|\mathbf{x} - \mathbf{y}\| \end{aligned}$$

Hence $\forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^2: \|\mathbf{G}(\mathbf{x}) - \mathbf{G}(\mathbf{y})\| \leq \frac{1}{2}\|\mathbf{x} - \mathbf{y}\|$, i.e. \mathbf{G} is Lipschitz-continuous with Lipschitz-constant $C = \frac{1}{2}$. As $0 \leq C < 1$, \mathbf{G} is a contraction on \mathbb{R}^2 under the euclidean norm, thus we can apply the Banach-Fixed-Point theorem, which states $\exists \bar{\mathbf{x}} \in \mathbb{R}^2: \mathbf{G}(\bar{\mathbf{x}}) = \mathbf{0}$. Hence:

$$\mathbf{G}(\bar{\mathbf{x}}) = \bar{\mathbf{x}} = \bar{\mathbf{x}} - \mathbf{F}(\bar{\mathbf{x}}) \Leftrightarrow \mathbf{0} = \mathbf{F}(\bar{\mathbf{x}})$$

Solving the equation yields the unique zero $\bar{\mathbf{x}}^T = [\frac{4}{6} \quad -\frac{4}{3}]$.

Task 1.5: Local Invertibility

Define $\mathbf{F}: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ by

$$\mathbf{F}(x, y, z) = \begin{bmatrix} x + y + z \\ xy + yz + xz \\ xyz \end{bmatrix}$$

Determine all the points in \mathbb{R}^3 in which \mathbf{F} is locally invertible.

Recall that \mathbf{F} is locally invertible in $\mathbf{x}_0 \in \mathbb{R}^3$ if $\det\left(\frac{\partial \mathbf{F}}{\partial \mathbf{x}}(\mathbf{x}_0)\right) \neq 0$, where $\frac{\partial \mathbf{F}}{\partial \mathbf{x}}$ is the Jacobian of \mathbf{F} :

$$\begin{aligned}\frac{\partial \mathbf{F}}{\partial \mathbf{x}} &= \begin{bmatrix} \frac{\partial F_1}{\partial x} & \frac{\partial F_1}{\partial y} & \frac{\partial F_1}{\partial z} \\ \frac{\partial F_2}{\partial x} & \frac{\partial F_2}{\partial y} & \frac{\partial F_2}{\partial z} \\ \frac{\partial F_3}{\partial x} & \frac{\partial F_3}{\partial y} & \frac{\partial F_3}{\partial z} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ y+z & x+z & x+y \\ yz & xz & xy \end{bmatrix} \\ \det\left(\frac{\partial \mathbf{F}}{\partial \mathbf{x}}\right) &= (x+z)xy - xz(x+y) - (y+z)xy + yz(x+y) + (y+z)xz - yz(x+z) \\ &= x^2y + xyz - (x^2z + xyz) - (xy^2 + xyz) + xyz + y^2z + xyz + xz^2 - xyz - yz^2 \\ &= x^2y - x^2z - xy^2 + y^2z + xz^2 - yz^2 = J(\mathbf{x})\end{aligned}$$

One obvious non-invertible point is $\mathbf{0}$, as $J(\mathbf{0}) = 0$. Additionally, the lines $(\lambda, 0, 0)$, $(0, \xi, 0)$ and $(0, 0, \mu)$ provide subspaces, for $\lambda, \xi, \mu \in \mathbb{R}$, where \mathbf{F} is not locally-invertible. Additionally we notice $J((\lambda, \lambda, \lambda)) = 0$, as the first and last row of $\frac{\partial \mathbf{F}}{\partial \mathbf{x}}$ become linearly dependent.

Let $x = 0$ and $y, z \neq 0$, then $\frac{\partial \mathbf{F}}{\partial \mathbf{x}}$ has the following form:

$$\begin{bmatrix} 1 & 1 & 1 \\ y+z & z & y \\ yz & 0 & 0 \end{bmatrix}$$

Setting $z = -y$ yields $J(\mathbf{x}) = -2y^3$, however for $z = y$ we get $J(\mathbf{x}) = 0$. Hence \mathbf{F} is locally invertible on:

$$\mathbb{R}^3 \setminus (\text{span}(\mathbf{e}_2, \mathbf{e}_3) \cup \text{span}(\mathbf{e}_1, \mathbf{e}_3) \cup \text{span}(\mathbf{e}_1, \mathbf{e}_2) \cup \text{span}(\mathbf{1}_3))$$

where

$$\mathbf{1}_k = \sum_{i=1}^k \mathbf{e}_i \in \mathbb{R}^k$$