

**Task 1.1: Gradient and Differentiability**

Assume that  $f: \mathbb{R} \rightarrow \mathbb{R}$  is differentiable and define  $F: \mathbb{R}^2 \rightarrow \mathbb{R}$  by setting

$$F(x, y) = f(x + 2y) + f(7y - 3x)$$

for all  $x, y \in \mathbb{R}$ . Is  $F$  differentiable? In that case, compute  $\nabla F$ .

Set  $g_1(x, y) = x + 2y$  and  $g_2(x, y) = 7y - 3x$ . As differentiability is a linear property, we know that  $g_1$  and  $g_2$  are differentiable on  $\mathbb{R}^2$ . Given  $f$ ,  $g_1$  and  $g_2$  are differentiable, both  $f \circ g_1$  and  $f \circ g_2$  are differentiable, and thus through linearity,  $F$  is as well.

$$\begin{aligned} \nabla F &= \frac{\partial F}{\partial \mathbf{x}} = \begin{bmatrix} \frac{\partial F}{\partial x} \\ \frac{\partial F}{\partial y} \end{bmatrix} \\ \frac{\partial F}{\partial x} &= \frac{\partial f \circ g_1}{\partial x} + \frac{\partial f \circ g_2}{\partial x} = \frac{\partial f}{\partial g_1} \frac{\partial g_1}{\partial x} + \frac{\partial f}{\partial g_2} \frac{\partial g_2}{\partial x} = f' \circ g_1 - 3f' \circ g_2 \\ \frac{\partial F}{\partial y} &= \frac{\partial f \circ g_1}{\partial y} + \frac{\partial f \circ g_2}{\partial y} = \frac{\partial f}{\partial g_1} \frac{\partial g_1}{\partial y} + \frac{\partial f}{\partial g_2} \frac{\partial g_2}{\partial y} = 2f' \circ g_1 + 7f' \circ g_2 \\ \Rightarrow \nabla F &= \begin{bmatrix} f' \circ g_1 - 3f' \circ g_2 \\ 2f' \circ g_1 + 7f' \circ g_2 \end{bmatrix} \Rightarrow \nabla F(\mathbf{x}) = \begin{bmatrix} f'(g_1(\mathbf{x})) - 3f'(g_2(\mathbf{x})) \\ 2f'(g_1(\mathbf{x})) + 7f'(g_2(\mathbf{x})) \end{bmatrix} \end{aligned}$$

**Task 1.2: Absolute Value**

Define  $F: \mathbb{R}^2 \rightarrow \mathbb{R}$  by setting  $F(x, y) = \sqrt{|xy|}$ . Is  $F$  differentiable in  $\mathbf{0}$ ? Justify your answer.

Let  $f_1(x) = \sqrt{x}$ ,  $f_2(x) = |x|$  and  $f_3(x, y) = xy$ , then  $F = f_1 \circ f_2 \circ f_3$ . Given  $f_2$  is not differentiable at  $x = 0$ ,  $F$  is not differentiable at  $\mathbf{0}$ .

Recall on the **Banach-Fixed-Point** theorem. Let  $(X, d)$  be a non-empty complete metric space and  $F: X \rightarrow X$ . We say  $F$  is a *contraction* if there exists a constant  $C \in [0, 1)$  such that

$$d(F(z_1), F(z_2)) \leq Cd(z_1, z_2)$$

for all  $z_1, z_2 \in X$ . We say that  $\bar{z}$  is a *fixed point* for  $F$  if  $F(\bar{z}) = \bar{z}$ . The Banach-Fixed-Point theorem states that if  $F$  is a contraction, then  $F$  admits a unique fixed point. Recall that  $\mathbb{R}^n$  is a complete metric space with the euclidean distance.

**Task 1.3: Banach-Fixed-Point Theorem**

Let  $(X, d)$  be a non-empty complete metric space. Prove the Banach-Fixed-Point theorem stated above.

Let  $x_0 \in X$  be arbitrary and  $F$  a contraction on  $X$  with constant  $C \in [0, 1)$ . We define a sequence  $(x_n)_{n \in \mathbb{N}}$  inductively where  $x_{n+1} = F(x_n)$ . We prove  $(x_n)_{n \in \mathbb{N}}$  is a Cauchy-sequence. Since  $X$  is complete under  $d$ , if  $(x_n)_{n \in \mathbb{N}}$  is a Cauchy-sequence, it converges:

$$d(x_l, x_{l+1}) = d(g(x_{l-1}), g(x_l)) \leq Cd(x_{l-1}, x_l) \leq C^2d(x_{l-2}, x_{l-1}) \leq \dots \leq C^ld(x_0, x_1)$$

Therefore for some  $l \in \mathbb{N}$  with  $l \geq 1$ , we know that  $d(x_l, x_{l+1}) \leq C^ld(x_0, x_1)$ , i.e. the distance between subsequent entries becomes 0 as  $n \rightarrow \infty$ . We now prove that  $(x_n)_{n \in \mathbb{N}}$  is in fact a Cauchy-sequence. Let  $n, m \in \mathbb{N}$  be arbitrary indices:

$$d(x_{n+m}, x_n) \leq d(x_n, x_{n+1}) + d(x_{n+1}, x_{n+2}) + \dots + d(x_{n+m-1}, x_{n+m})$$

$$\begin{aligned} &\leq C^n d(x_0, x_1) + C^{n+1} d(x_0, x_1) + \dots + C^{n+m-1} d(x_0, x_1) \\ &= C^n d(x_0, x_1) \sum_{j=0}^{m-1} C^j \leq C^n d(x_0, x_1) \sum_{j=0}^{\infty} C^j = d(x_0, x_1) \frac{C^n}{1-C} \end{aligned}$$

Given  $d(x_n, x_{n+m}) \leq d(x_0, x_1) \frac{C^n}{1-C} < \varepsilon$  we get

$$C^n < \frac{\varepsilon(1-C)}{d(x_0, x_1) + 1}$$

As  $C < 1$ , we can choose  $n$  arbitrarily large, hence  $(x_n)_{n \in \mathbb{N}}$  is a Cauchy-sequence, as the distance of any two entries for large  $n$  diminishes. Given  $F$  is Lipschitz-continuous with Lipschitz-constant  $C$ , we can apply the sequence-criterion:

$$\lim_{n \rightarrow \infty} F(x_n) = F(\bar{x})$$

Let  $\bar{x}, \bar{y}$  be fixed-points of  $F$ , then

$$d(\bar{x}, \bar{y}) = d(F(\bar{x}), F(\bar{y})) \leq C d(\bar{x}, \bar{y}) \Rightarrow d(\bar{x}, \bar{y}) = 0 \Leftrightarrow \bar{x} = \bar{y}$$

#### Task 1.4: Unique Zero with Banach-Fixed-Points

Define  $\mathbf{F}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  by setting:

$$\mathbf{F}(x, y) = \begin{bmatrix} x + \frac{y}{2} \\ \frac{x}{2} + y + 1 \end{bmatrix}$$

Define the map  $\mathbf{G}(\mathbf{x}) = \mathbf{x} - \mathbf{F}(\mathbf{x})$ . Using the Banach-Fixed-Point theorem on  $\mathbf{G}$ , prove that  $\mathbf{F}$  admits a unique zero, i.e.  $\exists \bar{\mathbf{x}} \in \mathbb{R}^2: \mathbf{F}(\bar{\mathbf{x}}) = \mathbf{0}$ .

We begin by showing that  $\mathbf{G}$  is Lipschitz-continuous with a Lipschitz-constant  $C \in [0, 1)$ :

$$\begin{aligned} \|\mathbf{G}(\mathbf{x}) - \mathbf{G}(\mathbf{y})\| &= \|\mathbf{x} - \mathbf{F}(\mathbf{x}) - \mathbf{y} + \mathbf{F}(\mathbf{y})\| \\ &= \sqrt{\left(x_1 - x_1 - \frac{x_2}{2} - y_1 + y_1 + \frac{y_2}{2}\right)^2 + \left(x_2 - \frac{x_1}{2} - x_2 - 1 - y_2 + \frac{y_1}{2} + y_2 + 1\right)^2} \\ &= \sqrt{\left(\frac{y_2}{2} - \frac{x_2}{2}\right)^2 + \left(\frac{y_1}{2} - \frac{x_1}{2}\right)^2} = \frac{1}{2} \|\mathbf{y} - \mathbf{x}\| = \frac{1}{2} \|\mathbf{x} - \mathbf{y}\| \end{aligned}$$

Hence  $\forall \mathbf{x}, \mathbf{y} \in \mathbb{R}^2: \|\mathbf{G}(\mathbf{x}) - \mathbf{G}(\mathbf{y})\| \leq \frac{1}{2} \|\mathbf{x} - \mathbf{y}\|$ , i.e.  $\mathbf{G}$  is Lipschitz-continuous with Lipschitz-constant  $C = \frac{1}{2}$ . As  $0 \leq C < 1$ ,  $\mathbf{G}$  is a contraction on  $\mathbb{R}^2$  under the euclidean norm, thus we can apply the Banach-Fixed-Point theorem, which states  $\exists \bar{\mathbf{x}} \in \mathbb{R}^2: \mathbf{G}(\bar{\mathbf{x}}) = \bar{\mathbf{x}}$ . Hence:

$$\mathbf{G}(\bar{\mathbf{x}}) = \bar{\mathbf{x}} = \bar{\mathbf{x}} - \mathbf{F}(\bar{\mathbf{x}}) \Leftrightarrow \mathbf{0} = \mathbf{F}(\bar{\mathbf{x}})$$

Solving the equation yields the unique zero  $\bar{\mathbf{x}}^T = \begin{bmatrix} \frac{4}{6} & -\frac{4}{3} \end{bmatrix}$ .

#### Task 1.5: Local Invertibility

Define  $\mathbf{F}: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  by

$$\mathbf{F}(x, y, z) = \begin{bmatrix} x + y + z \\ xy + yz + xz \\ xyz \end{bmatrix}$$

Determine all the points in  $\mathbb{R}^3$  in which  $\mathbf{F}$  is locally invertible.

Recall that  $\mathbf{F}$  is locally invertible in  $\mathbf{x}_0 \in \mathbb{R}^3$  if  $\det\left(\frac{\partial \mathbf{F}}{\partial \mathbf{x}}(\mathbf{x}_0)\right) \neq 0$ , where  $\frac{\partial \mathbf{F}}{\partial \mathbf{x}}$  is the Jacobian of  $\mathbf{F}$ :

$$\begin{aligned}\frac{\partial \mathbf{F}}{\partial \mathbf{x}} &= \begin{bmatrix} \frac{\partial F_1}{\partial x} & \frac{\partial F_1}{\partial y} & \frac{\partial F_1}{\partial z} \\ \frac{\partial F_2}{\partial x} & \frac{\partial F_2}{\partial y} & \frac{\partial F_2}{\partial z} \\ \frac{\partial F_3}{\partial x} & \frac{\partial F_3}{\partial y} & \frac{\partial F_3}{\partial z} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ y+z & x+z & x+y \\ yz & xz & xy \end{bmatrix} \\ \det\left(\frac{\partial \mathbf{F}}{\partial \mathbf{x}}\right) &= (x+z)xy - xz(x+y) - (y+z)xy + yz(x+y) + (y+z)xz - yz(x+z) \\ &= x^2y + xyz - (x^2z + xyz) - (xy^2 + xyz) + xyz + y^2z + xyz + xz^2 - xyz - yz^2 \\ &= x^2y - x^2z - xy^2 + y^2z + xz^2 - yz^2 = J(\mathbf{x})\end{aligned}$$

One obvious non-invertible point is  $\mathbf{0}$ , as  $J(\mathbf{0}) = 0$ . Additionally, the lines  $(\lambda, 0, 0)$ ,  $(0, \xi, 0)$  and  $(0, 0, \mu)$  provide subspaces, for  $\lambda, \xi, \mu \in \mathbb{R}$ , where  $\mathbf{F}$  is not locally-invertible. Additionally we notice  $J((\lambda, \lambda, \lambda)) = 0$ , as the first and last row of  $\frac{\partial \mathbf{F}}{\partial \mathbf{x}}$  become linearly dependent.

Let  $x = 0$  and  $y, z \neq 0$ , then  $\frac{\partial \mathbf{F}}{\partial \mathbf{x}}$  has the following form:

$$\begin{bmatrix} 1 & 1 & 1 \\ y+z & z & y \\ yz & 0 & 0 \end{bmatrix}$$

Setting  $z = -y$  yields  $J(\mathbf{x}) = -2y^3$ , however for  $z = y$  we get  $J(\mathbf{x}) = 0$ . Hence  $\mathbf{F}$  is locally invertible on:

$$\mathbb{R}^3 \setminus (\text{span}(\mathbf{e}_2, \mathbf{e}_3) \cup \text{span}(\mathbf{e}_1, \mathbf{e}_3) \cup \text{span}(\mathbf{e}_1, \mathbf{e}_2) \cup \text{span}(\mathbf{1}_3))$$

where

$$\mathbf{1}_k = \sum_{i=1}^k \mathbf{e}_i \in \mathbb{R}^k$$