Input $\mathbf{I}_t$	<u>.</u>																		
Ø	0	0	O	0	Ø	0	O	0	0	O	0	0	0	0	O	0	0	0	O
Prediction $\mathbf{U}\overline{\mathbf{r}}_t$																			
	œ,	5	0	0	Ø	0	ø	0	0	0	0	0	0	0	O	0	0	0	0
Predicti	Prediction Error $\mathbf{I}_t - \mathbf{U}\overline{\mathbf{r}}_t$																		
Ø	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	O	0
After C	After Correction $\mathbf{U}\mathbf{\hat{r}}_t$																		
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
									Time										