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import aruco_script
import pyproj

def position_correction():
    marker_location = aruco_position()
    drone_pos = read(flight_log_last_line)
    drone_pos = latlong2cartesian(drone_pos)
    new_pos = marker_location - drone_pos
    new_pos = cartesian2latlong(new_pos)
    return new_pos

def main():
    new_pos = position_correction()
    flight_log.write(new_pos)

main()
```

