

Increasing the tractability of occupancy models

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Abstract

place holder

NIMBLE, Markov chain Monte Carlo, latent states, block sampling, dynamic occupancy,
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5 Introduction

6 Estimating the proportion of sites occupied by a species is common challenge for many
7 subdisciplines ecology and evolution including metapopulation, engangered and inva-
8 sion biology. Greater acceptance of the biases of imperfect detection has lead to the devel-
9 opment and proliferation of occupancy models, which model the occurrence of a species
10 at a site as a latent state layered underneath a detection process (e.g., MacKenzie *et al.*,
11 2006; Royle & Kéry, 2007). Now only a little over a decade after occupancy models were
12 introduced to ecology, they are being used to model the occurence of everything from
13 bees (M’Gonigle *et al.*, 2015) to tigers (Hines *et al.*, 2010) in an endless variety of complex-
14 ity.

15 Occupancy models are part of a larger class of models known as Hidden Markov Mod-
16 els. For discrete Hidden Markov Models like occupancy models where a species is either
17 present or absent from a site, likelihood calculation involves summing over the distri-
18 bution of latent states. Because estimating the effect of explanatory variables on site oc-
19 cupancy or shared variation of in occupancy across species is often of greatest interest
20 to ecologists (e.g., Iknayan *et al.*, 2014), the Hidden Markov Models are embedded in a
21 larger hierarchical model. In such cases, practitioners may rely on Markov chain Monte
22 Carlo (MCMC) to perform a Bayesian analysis. Such models are computationally inten-
23 sive, and large models requiring hundreds or thousands of dimensions which require
24 MCMC can be computationally impractical. To ensure occupancy models are accessible
25 to practitioners, more efficient methods for estimating these models are necessary.

Materials & Methods

Results

Discussion

Acknowledgments

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