



# HyTech Racing BMS: Presentation 2

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# Order of Presentation

1. Updated Requirements and Engineering Design Specifications
2. Concept and Component Selection
3. Embedded Systems Design
4. Electrical and PCB Design
5. Mechanical Design
6. Thermal Analysis
7. Schedule
8. Future Work



# Updated Customer Requirements

| Category                      | Customer Requirements  |
|-------------------------------|--|
| 1) Function                   | a) Charge 9 LiCoO <sub>2</sub> pouch battery cells with a nominal capacity of 18Ah |
|                               | b) Record and store current and voltage data for every cell                        |
|                               | c) Must be compatible with Melasta SLPBA580183 battery cells                       |
| 2) Electrical Characteristics | a) Charging current of 9-10A (0.5C rate)   |
|                               | b) Must have a cell balancing algorithm  |
|                               | c) Powered from a regular electrical wall outlet                                   |
| 3) Mechanical Characteristics | a) Minimal risk of environmental damage to batteries (ex. water)                   |
|                               | b) Modular design (adaptable to changes in dimensions or geometry)                 |
|                               | c) Relatively lightweight and easy to transport                                    |
|                               | d) Keep battery cells below 45 degrees celsius                                     |
| 4) Safety                     | a) Must be easy and safe for someone trained to operate the device                 |
| 5) Reliability                | a) The device must be able to withstand regular use for 2-3 years                  |

# Engineering Design Specifications

- ~38V and ~10A needed to charge nine battery cells in series at 0.5C
  - max voltage of one battery cell is around 4.2V
- Safe battery temperature range is between 10-45 degrees Celsius
- Required I/O includes a temperature sensor, current sensor, local data storage, a keypad for user input, and a screen for user output
- Physical stress on battery cell tabs need to be considered



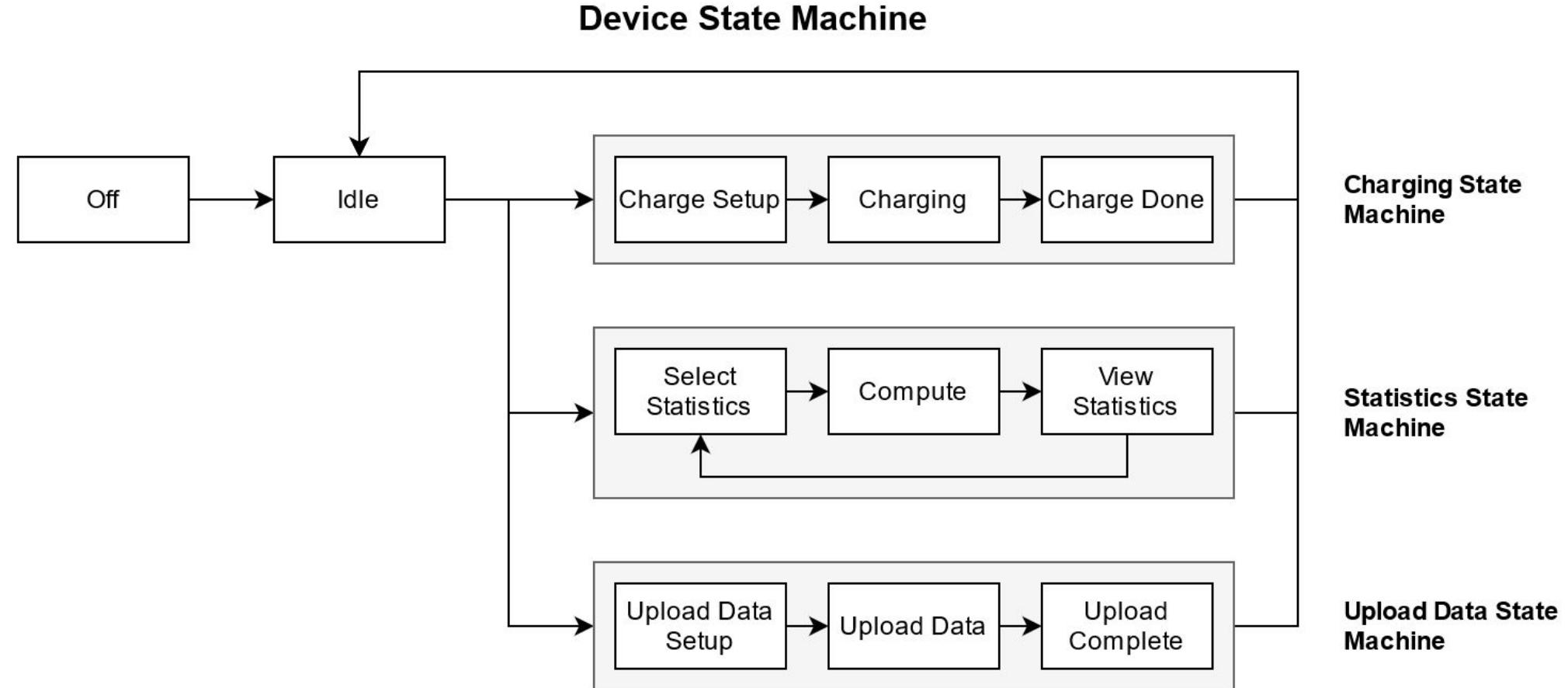
# Concept and Component Selection

- Clamping mechanism chosen to secure battery terminals to the charger (discussed more later on)
- **Teensy 4.1 Microcontroller**
  - HyTech already uses the Teensy 4.1
  - Integrated SD card reader (used for data logging)
- **LTC6811 Battery Stack Monitor**
  - LTC6811-2 already implemented by HyTech
  - Used for cell voltage measurement and cell balancing
- **Power Supply (BK Precision 9104)**
  - HyTech already has this power supply unit
- Thermistors for measuring individual cell temperatures
- Keypad and LCD screen for user input/output

# Embedded System Design - Updates

- Current parts we have / are prototyping with
  - LCD screen
  - Teesny
- Parts arriving soon (~Friday)
  - Current sensor
  - Thermistor
  - Keypad
- Working on writing and testing code for state machine and LCD screen (needs to be pushed to repo)
- A little behind schedule but the pace we are right now will line up with when the PCBs arrive

# Embedded System Design - State Machine



# Electrical and PCB Design - Cell Charger BMS

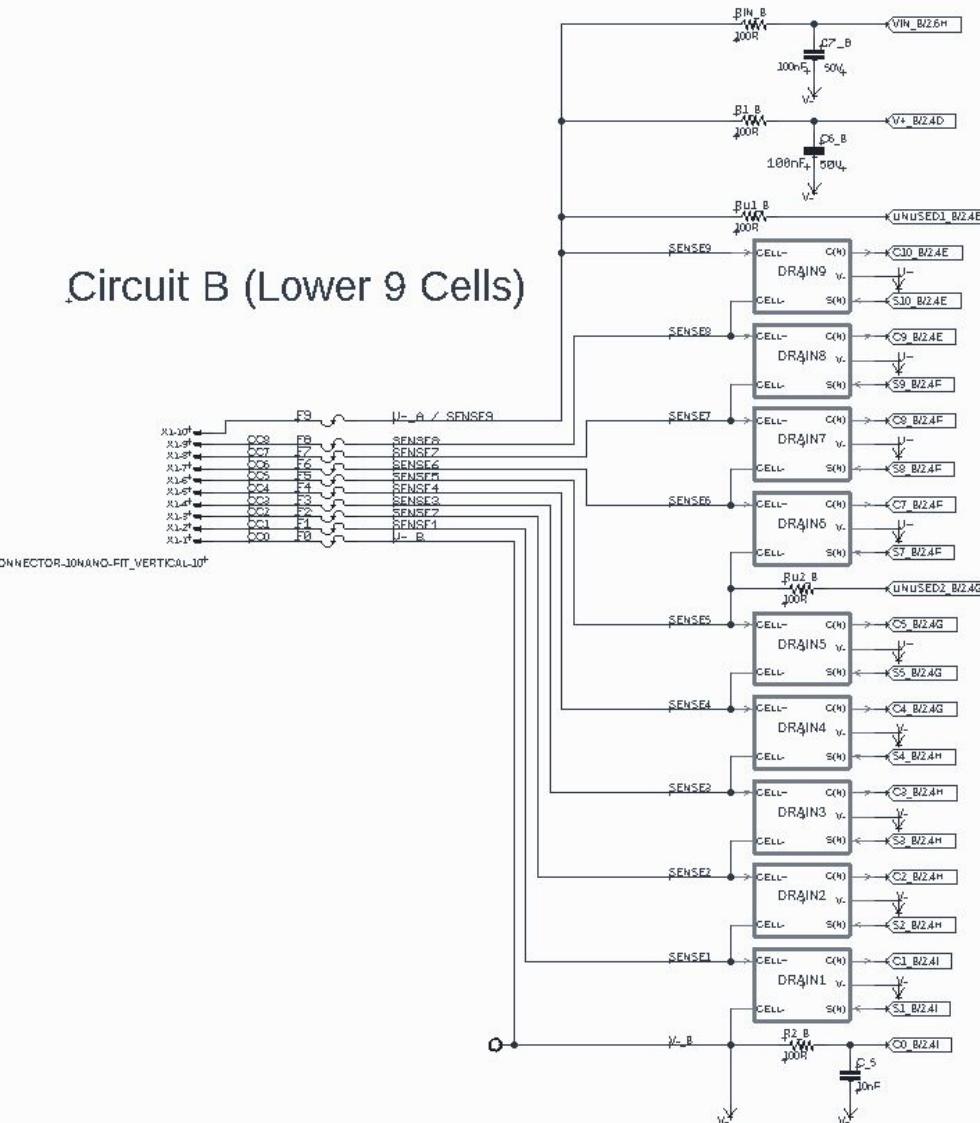
## Purpose of Cell Charger BMS Board:

- Includes:
  - LTC6811-2 Multicell Battery Stack Monitor Chip (measures voltages)
  - Fuses
  - Battery connections
- Adapted from HyTech's previously existing BMS circuit

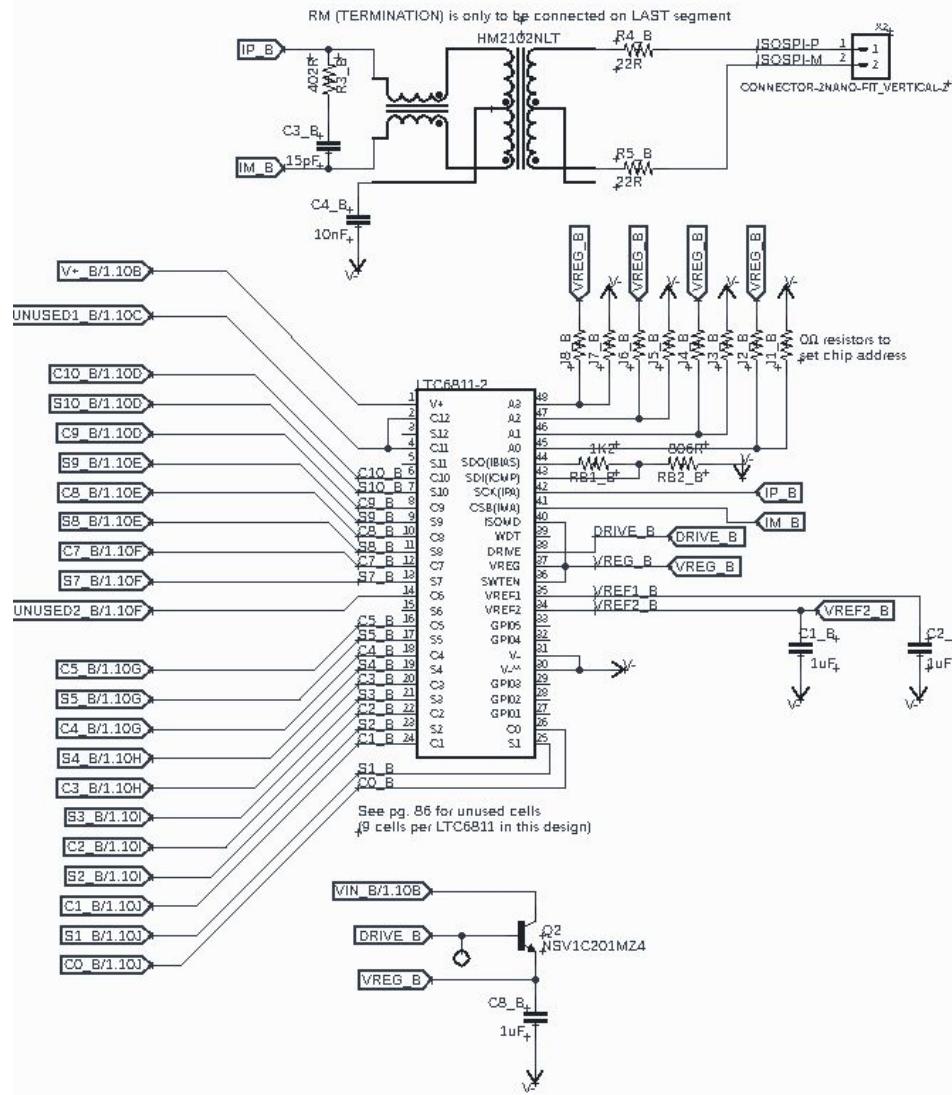
# Electrical and PCB Design - Cell Charger BMS

| Design Change   | Justification/Reasoning   |
|---|---|
| Include the appropriate number of battery cells             | Our design specification only requires the charger to be equipped for 9 cells, whereas HyTech's previous BMS circuit was designed for 18 cells. |
| Remove thermistors from existing design                     | Temperatures now measured on separate controller board  |
| Change the contact method of the board to the battery cells | Spring pad contacts swapped out for 10-pin connector  |

# Electrical and PCB Design - Cell Charger BMS



Cell Connections, Drains, and Fuses



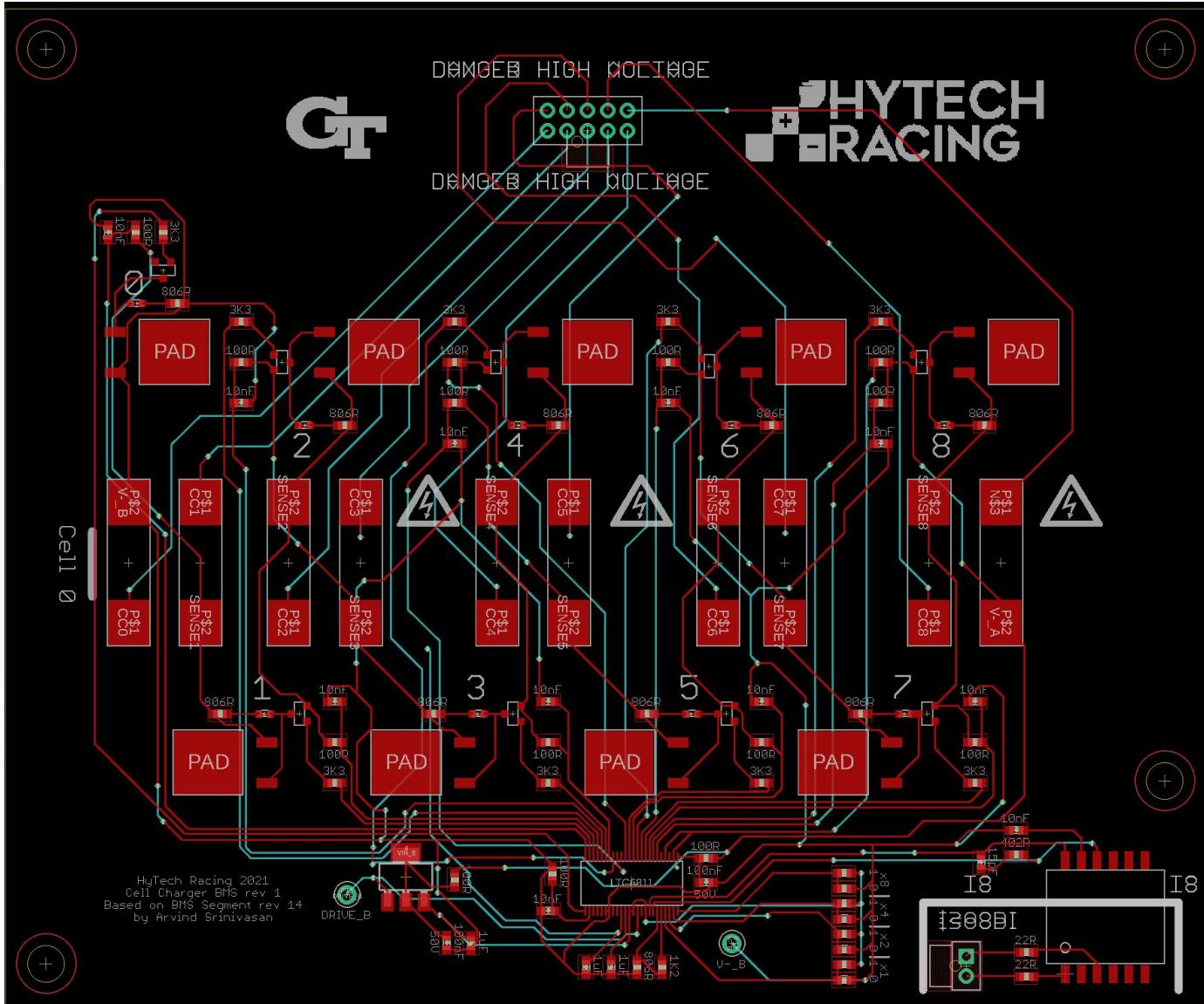
LTC 6811-2 Multicell Battery Stack Monitor Chip

# Electrical and PCB Design - Cell Charger BMS

10-pin connector

Fuses

Multicell Battery Stack  
Monitor Chip



# Electrical and PCB Design - Controller Board

## Purpose of Controller Board:

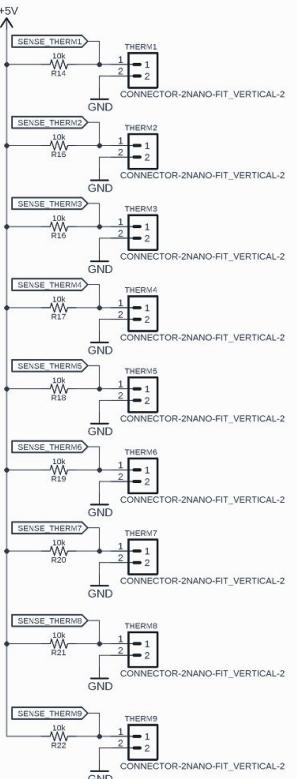
- Measures charging current
- Communicates with BMS via isoSPI
- Monitors cell temperatures
- Implements user interface with a keypad and a screen

# Electrical and PCB Design - Controller Board

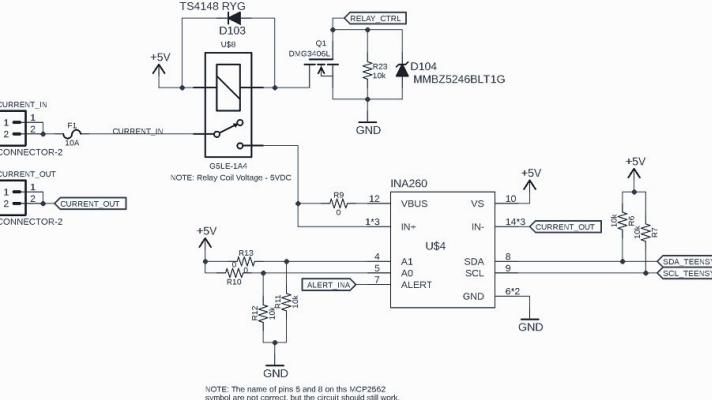
| Feature                  | Implementation  |
|--------------------------|---|
| Fusing                   | 10A replaceable mini-blade fuse   |
| Current switching        | Omron G5LE-1A4 SPST Relay with 5VDC coil voltage  |
| Current sensing          | TI INA260 current sensor in TSSOP-16 package  |
| Microcontroller          | Teensy 4.1 microcontroller is compatible with Arduino toolchain, includes a powerful Cortex-M7 (600 MHz), integrated SD card slot, SPI, I2C, and CAN ports.   |
| isoSPI communication     | LTC6820 isolated communications interface with HM2102NLT transformer  |
| CAN communication        | MCP2551 CAN transceiver connected to the Teensy allows for use of programmable power supplies or future module additions.   |
| User interface           | 3x4 Matrix keypad coupled with 240x320 TFT display  |
| Cell temperature sensing | Nine 2-pin Molex Nano-fit connectors allow for use of 10 KOhm thermistors such as Vishay NTCALUG02A103F. The thermistors are connected in a voltage divider configuration.  |
| Board power              | The controller board is powered with a 12V power supply through a 2-pin Molex Mini-Fit Jr. connector. 12V is converted down to 5V using Murata OKI-78R-5 voltage regulator. The 3.3V rail is supplied by the Teensy 4.1 on-board regulator. |

# Electrical and PCB Design - Controller Board

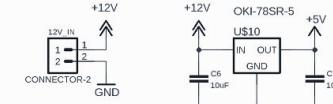
Thermistor connections



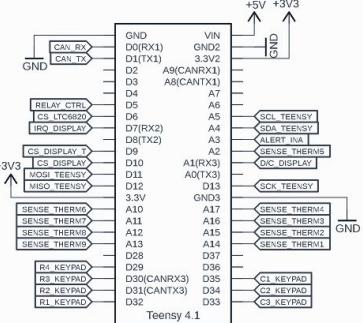
Current sensing and main relay



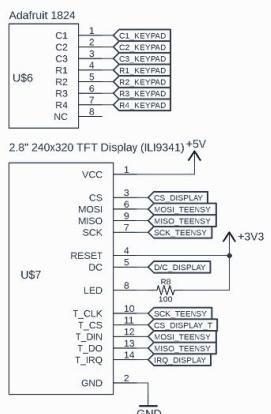
Board power



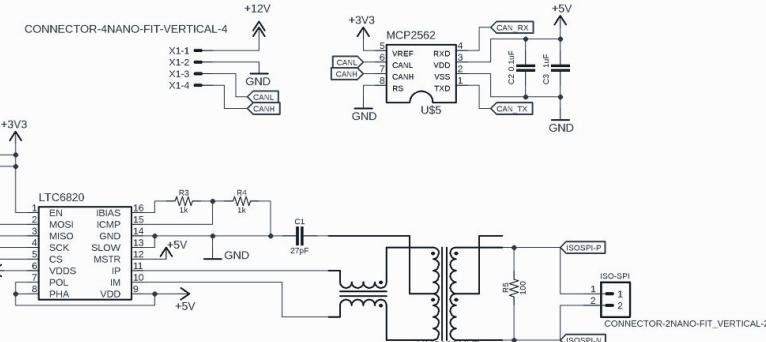
Microcontroller



User interface



isoSPI and CAN communications

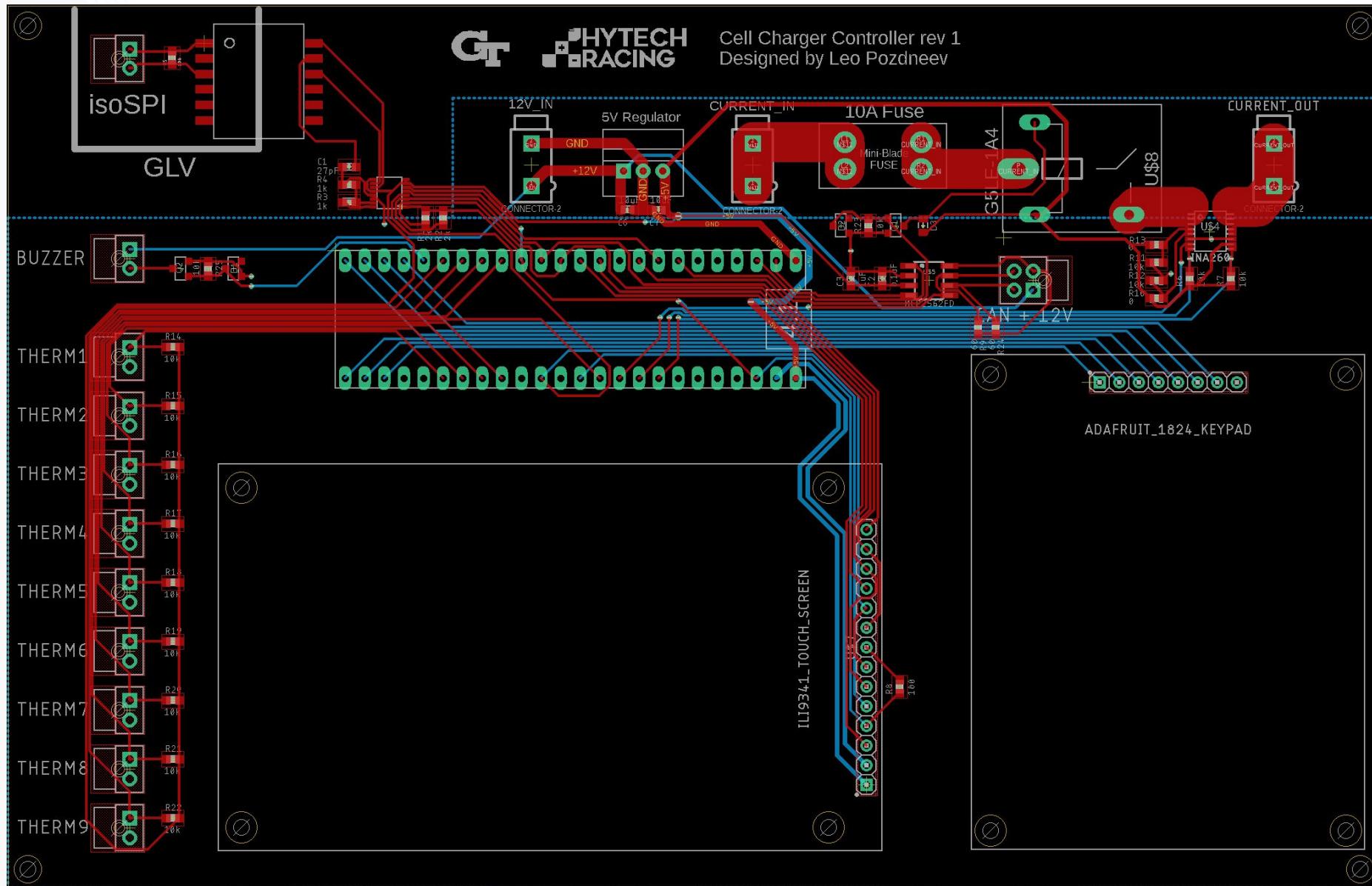


Engineer: Leonid Pozdneev

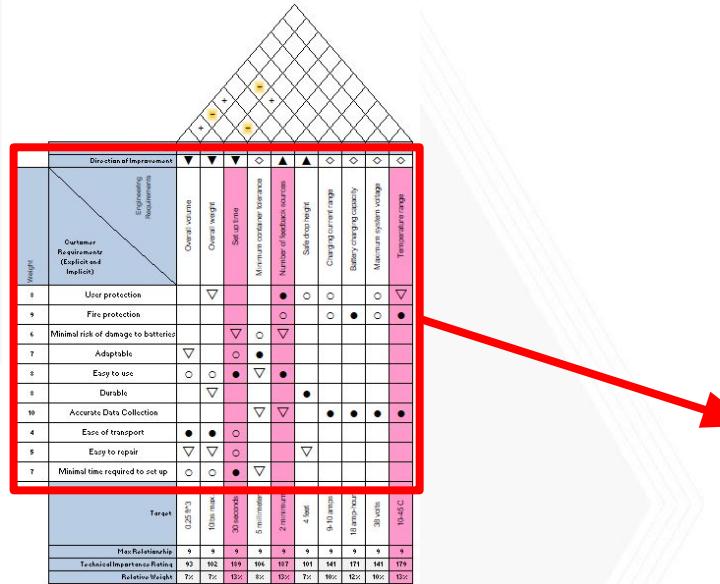
Document Name: Cell Charger Controller rev1

Description: Schematic for HyTech Racing battery cell charger controller board.

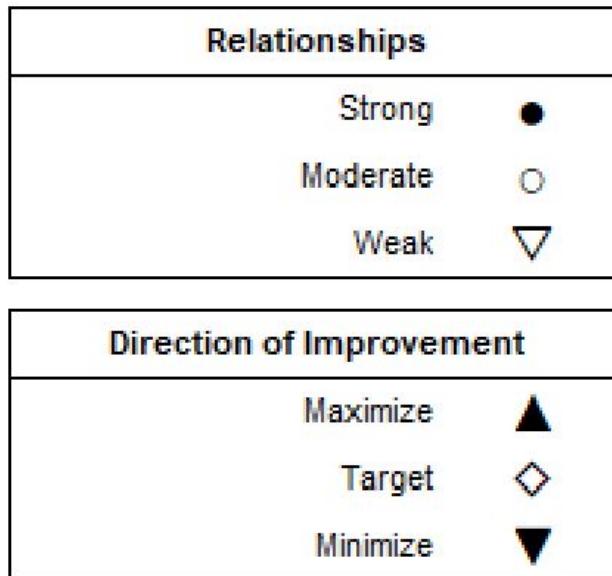
# Electrical and PCB Design - Controller Board



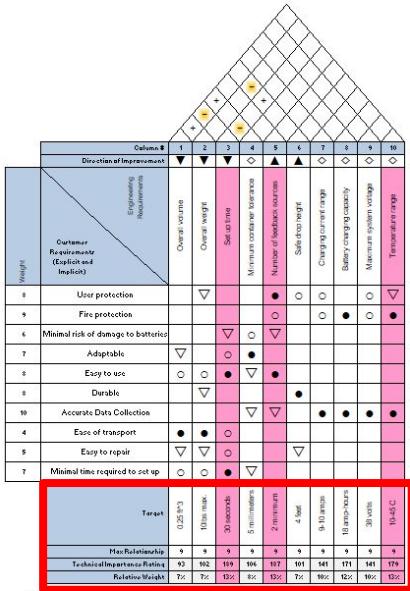
# Mechanical Design (House of Quality-Correlation)



| Column #                            | 1   | 2              | 3           | 4                           | 5                          | 6                | 7                      | 8                         | 9                      | 10                |
|-------------------------------------|---|----------------|-------------|-----------------------------|----------------------------|------------------|------------------------|---------------------------|------------------------|-------------------|
| Direction of Improvement            | ▼   | ▼              | ▼           | ◊                           | ▲                          | ▲                | ◊                      | ◊                         | ◊                      | ◊                 |
| Engineering Requirements            | Customer Requirements (Explicit and Implicit) | Overall weight | Set up time | Minimum container tolerance | Number of feedback sources | Safe drop height | Charging current range | Battery charging capacity | Maximum system voltage | Temperature range |
| Overall volume                      |   |                |             |                             |                            |                  |                        |                           |                        |                   |
| User protection                     | ▽   |                |             |                             | ●                          | ○                | ○                      | ○                         | ○                      | ▽                 |
| Fire protection                     |   |                |             |                             | ○                          | ○                | ○                      | ●                         | ○                      | ●                 |
| Minimal risk of damage to batteries | ▽   | ○              | ○           | ○                           | ▽                          |                  |                        |                           |                        |                   |
| Adaptable                           | ▽   | ○              | ●           | ●                           | ●                          |                  |                        |                           |                        |                   |
| Easy to use                         | ○   | ○              | ●           | ▽                           | ●                          |                  |                        |                           |                        |                   |
| Durable                             | ▽   | ●              |             |                             | ●                          |                  |                        |                           |                        |                   |
| Accurate Data Collection            |   |                | ▽           | ▽                           |                            | ●                | ●                      | ●                         | ●                      | ●                 |
| Ease of transport                   | ●   | ●              | ○           |                             |                            |                  |                        |                           |                        |                   |
| Easy to repair                      | ▽   | ▽              | ○           |                             |                            | ▽                |                        |                           |                        |                   |
| Minimal time required to set up     | ○   | ○              | ●           | ▽                           |                            |                  |                        |                           |                        |                   |



# Mechanical Design (House of Quality-Targets)



|                             | Target    |            |            |               |           |        |           |              |          |         |
|-----------------------------|-----------|------------|------------|---------------|-----------|--------|-----------|--------------|----------|---------|
|                             | 0.25 ft^3 | 10lbs max. | 30 seconds | 5 millimeters | 2 minimum | 4 feet | 9-10 amps | 18 amp-hours | 38 volts | 10-45 C |
| Max Relationship            | 9         | 9          | 9          | 9             | 9         | 9      | 9         | 9            | 9        | 9       |
| Technical Importance Rating | 93        | 102        | 189        | 106           | 187       | 101    | 141       | 171          | 141      | 179     |
| Relative Weight             | 7%        | 7%         | 13%        | 8%            | 13%       | 7%     | 10%       | 12%          | 10%      | 13%     |

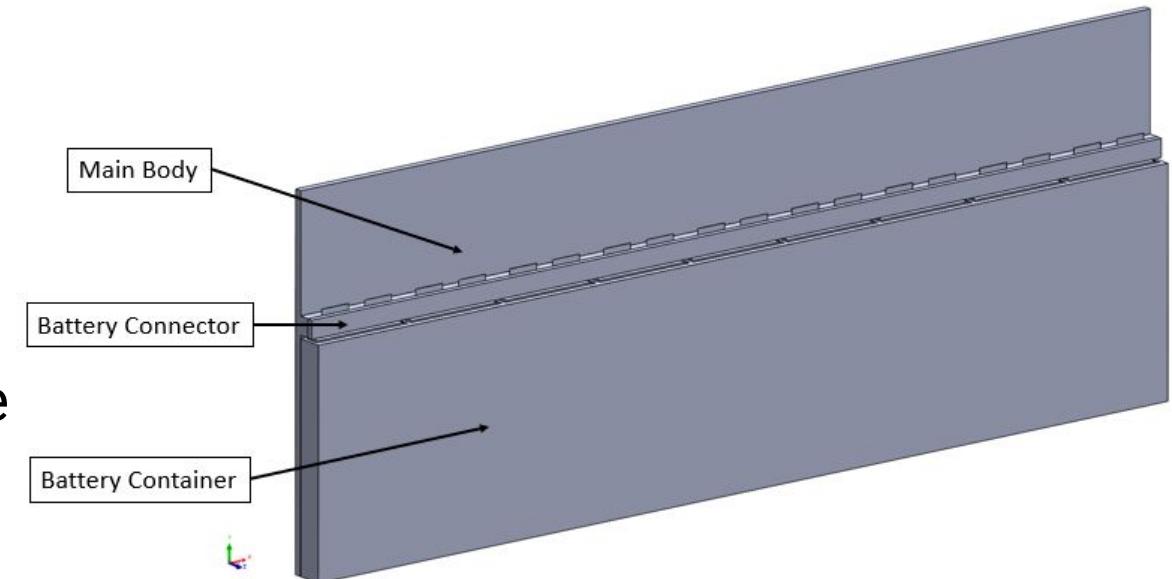
- Results indicate the engineering requirements with the highest priority is set-up time, number of feedback sources, and the cell temperature range.
- Last four requirements are highly prioritized as they are specified ranges by HyTech Racing

# Mechanical Design (Spec Sheet)

| Specification                             | Want(W) / Demand(D) | Requirement                           | Responsibility | Validation  |
|---|---------------------|---------------------------------------|----------------|---|
| <b>Physical Device</b>                    |                     |                                       |                |   |
| Overall Volume                            | W                   | < 0.25 ft^3                           | Mechanical     | CAD   |
| Overall Weight                            | W                   | <= 10 lbs                             | Mechanical     | Sum of overall material and weighing of assembled device  |
| Safe Drop Height                          | D                   | 4 ft (average table height)           | Mechanical     | Impact testing of dummy components (FEA if there is time) |
| Storage Capacity                          | D                   | 9 batteries                           | Mechanical     | CAD   |
| Container Tolerances                      | D                   | > 5 mm                                | Mechanical     | CAD   |
| <b>Battery/Electrical Characteristics</b> |                     |                                       |                |   |
| Electrical Input                          | D                   | Wall outlet                           | Electrical     | Power supply specifications                               |
| Charging Current Range                    | D                   | 9-10 A                                | Electrical     | BMS design  |
| Battery Charging Capacity                 | D                   | 18 A h                                | Electrical     | BMS design  |
| Battery Operating Temperature             | D                   | 10-45C                                | ME and EE      | Cell temperature sensors and insulative material          |
| Maximum System Voltage                    | D                   | 38 V                                  | Electrical     | BMS design  |
| <b>Usability</b>                          |                     |                                       |                |   |
| Set Up Time                               | W                   | < 30 s                                | Mechanical     | Timed trial runs of setup                                 |
| Number of Feedback Sources                | D                   | at least 2 (one audio and one visual) | Electrical     | Combination of user interface and sensor feedback         |

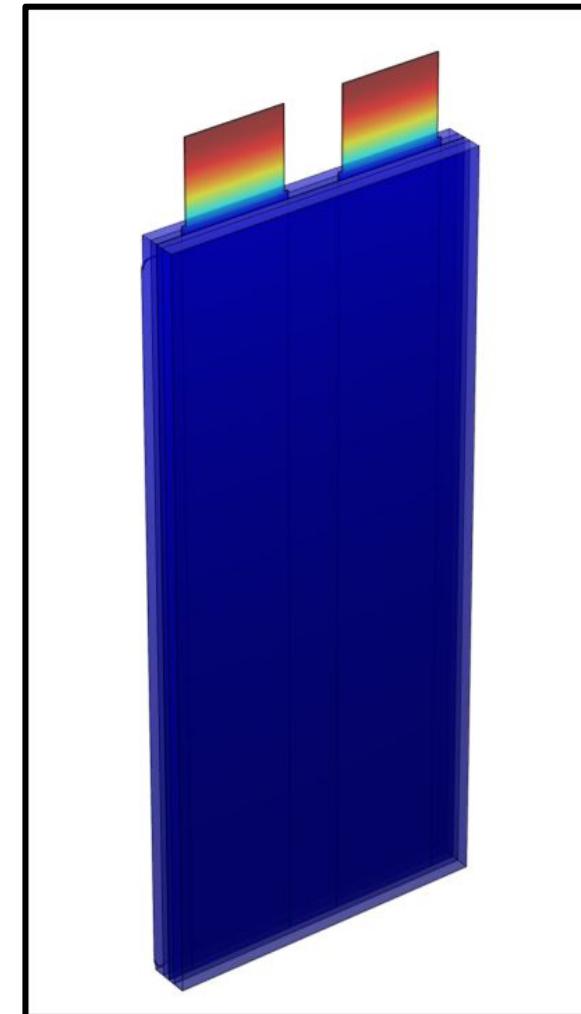
# Mechanical Design (CAD)

- Physical Design is currently generalized, will get more specific when mechanical members meet later this week
- Overall very simple design, should take less than a week to manufacture
- Composed of three main assemblies:
  - Main body: mounting board for all other sub-components
  - Battery connector: single, adjustable piece that connects all of the batteries
  - Battery container: easily-manufacturable container with large tolerances

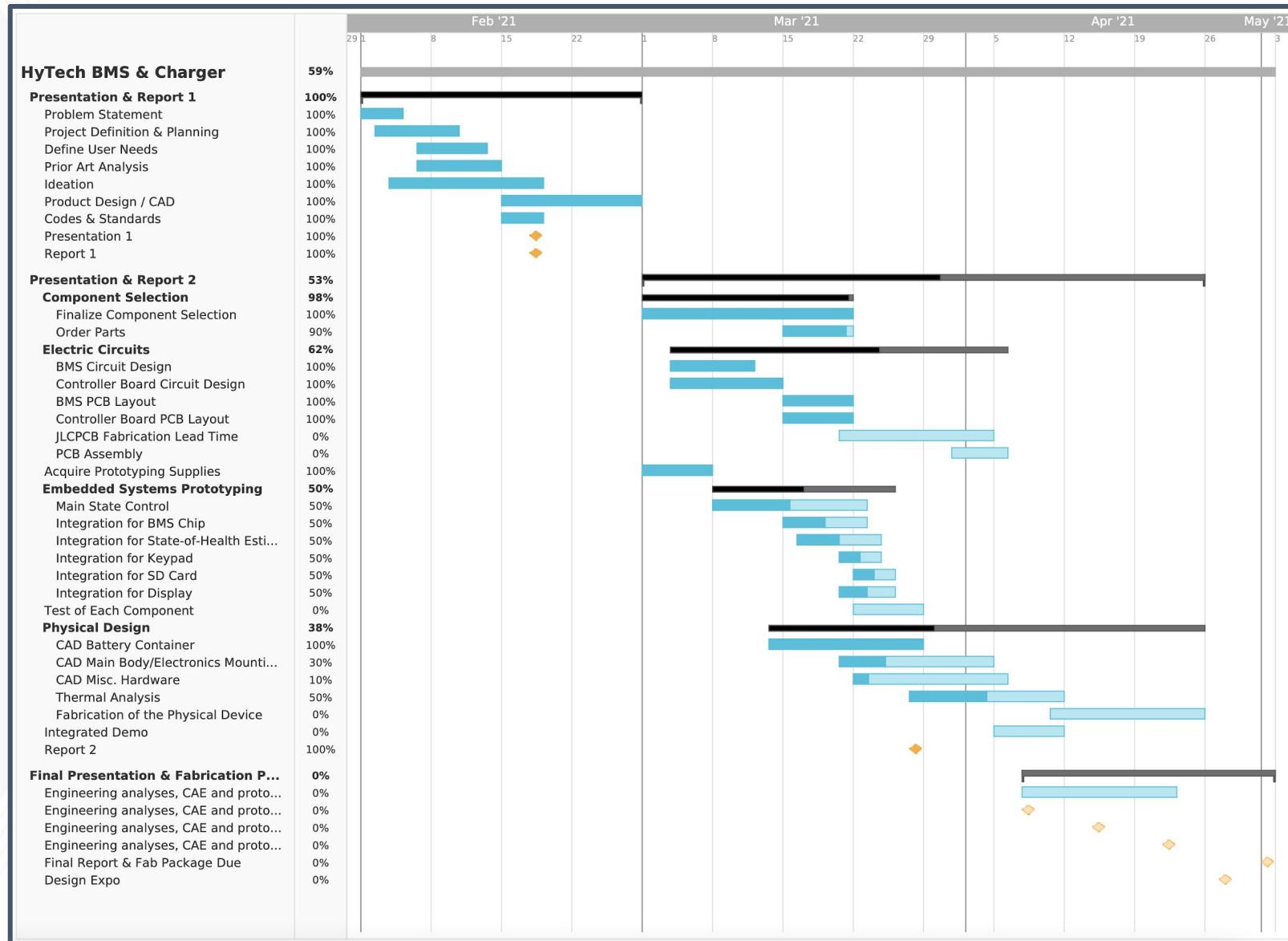


# Thermal Analysis

- Temperature rise of the battery cells should not pose risk to the performance of container
- Material used mostly accounts for concerns
- Attempted to create simulation that models electrochemistry and heat transfer



# Schedule (Gantt Chart)

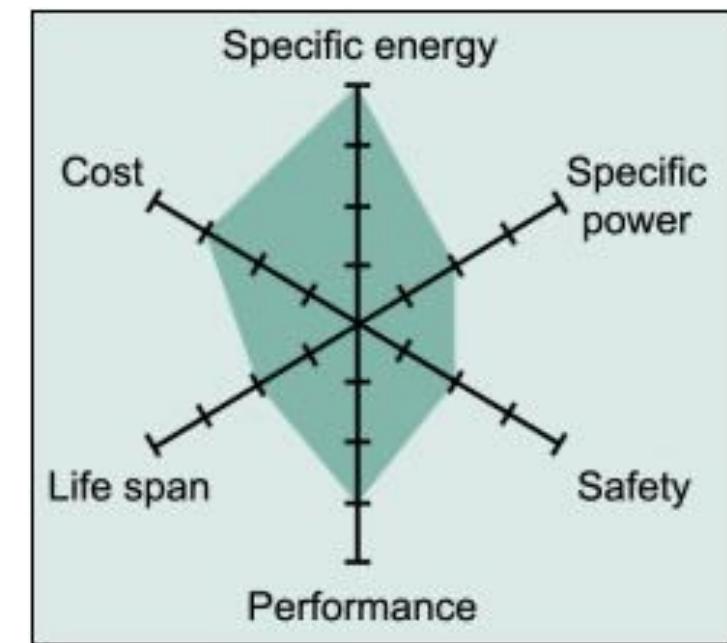


# Future Work

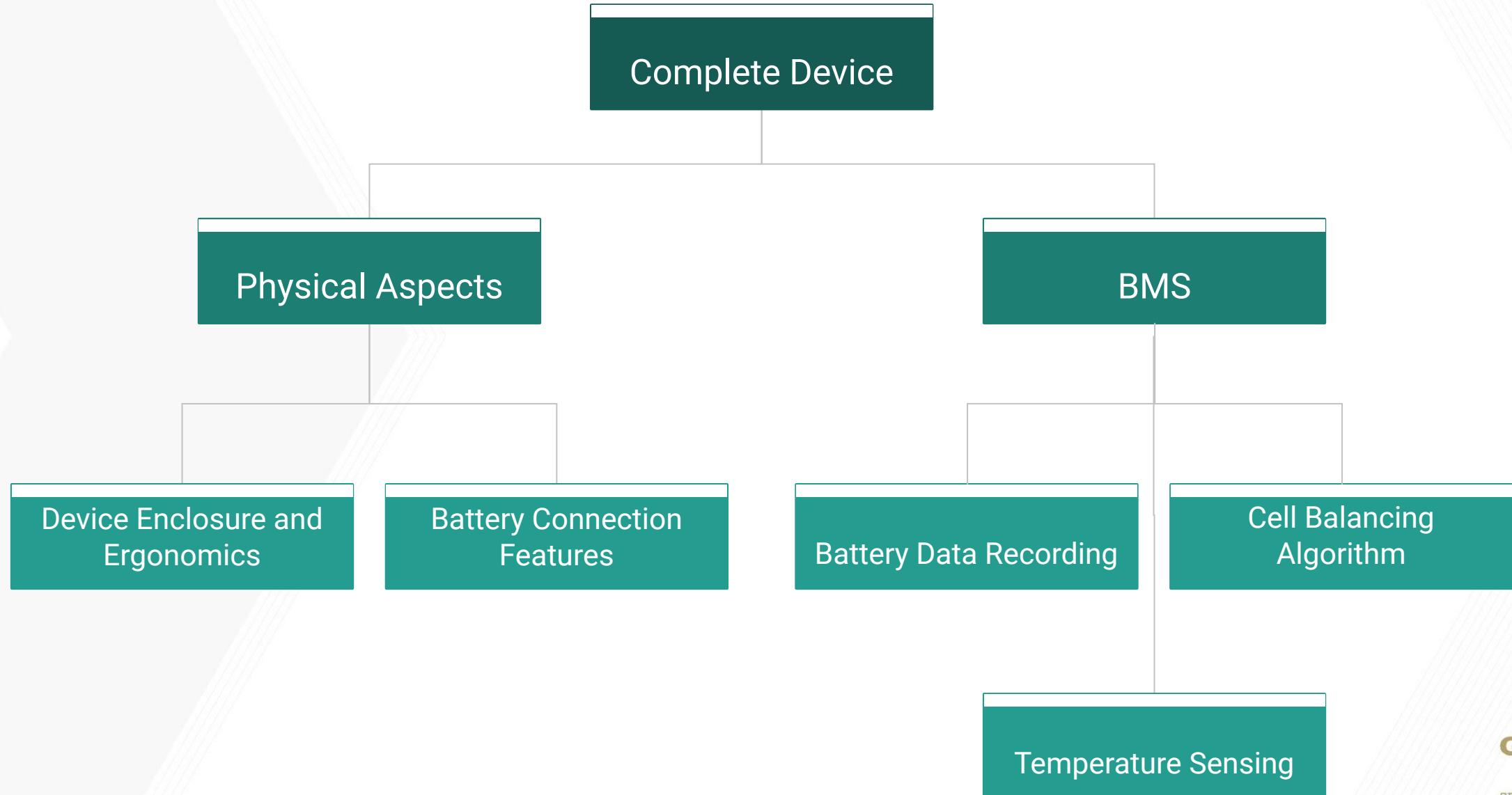
- Finish prototyping embedded systems
- Solder PCBs
- Integrate electrical components
- Detailed CAD
- Fabricate the physical structure
- Assemble and test the final product

# Introduction / Background

- HyTech racing is interested in a custom battery management system, a data recording system, and a user interface for charging Lithium Cobalt Oxide pouch battery cells
- The end goal is efficient battery charging and health estimation
- Lithium Cobalt Oxide batteries are used because of their high specific energy but are limited by short lifespans



# Categories of Prior Art



# Existing Products / Prior Art / Applicable Patents

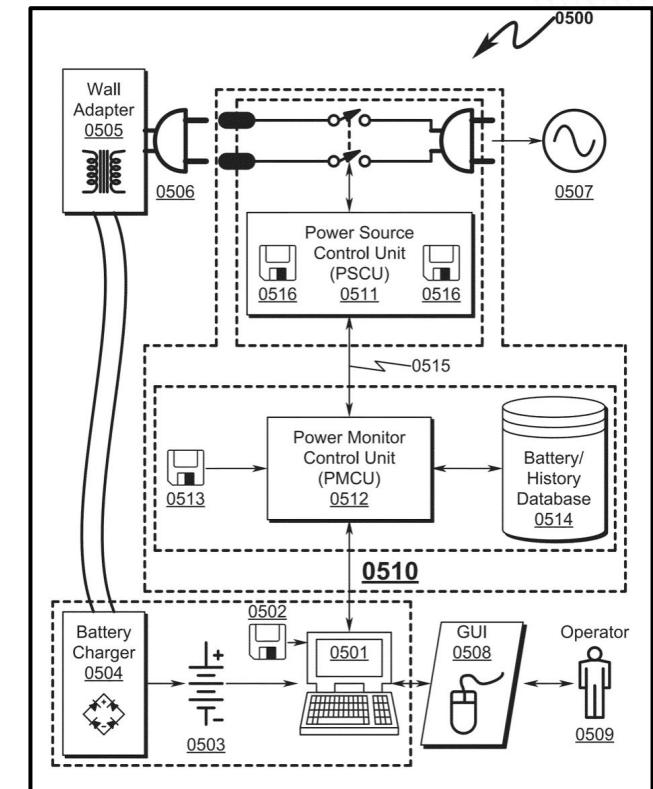
## HyTech Racing:

- Already have a pre-existing BMS design utilizes LTC6804 Multicell Battery Monitors with voltage logging using a Tensey 3.2 microcontroller
- This design has already been thoroughly tested
- More functionality is still to desired (logging storage, temperature monitoring, mechanical design)

## Orion BMS

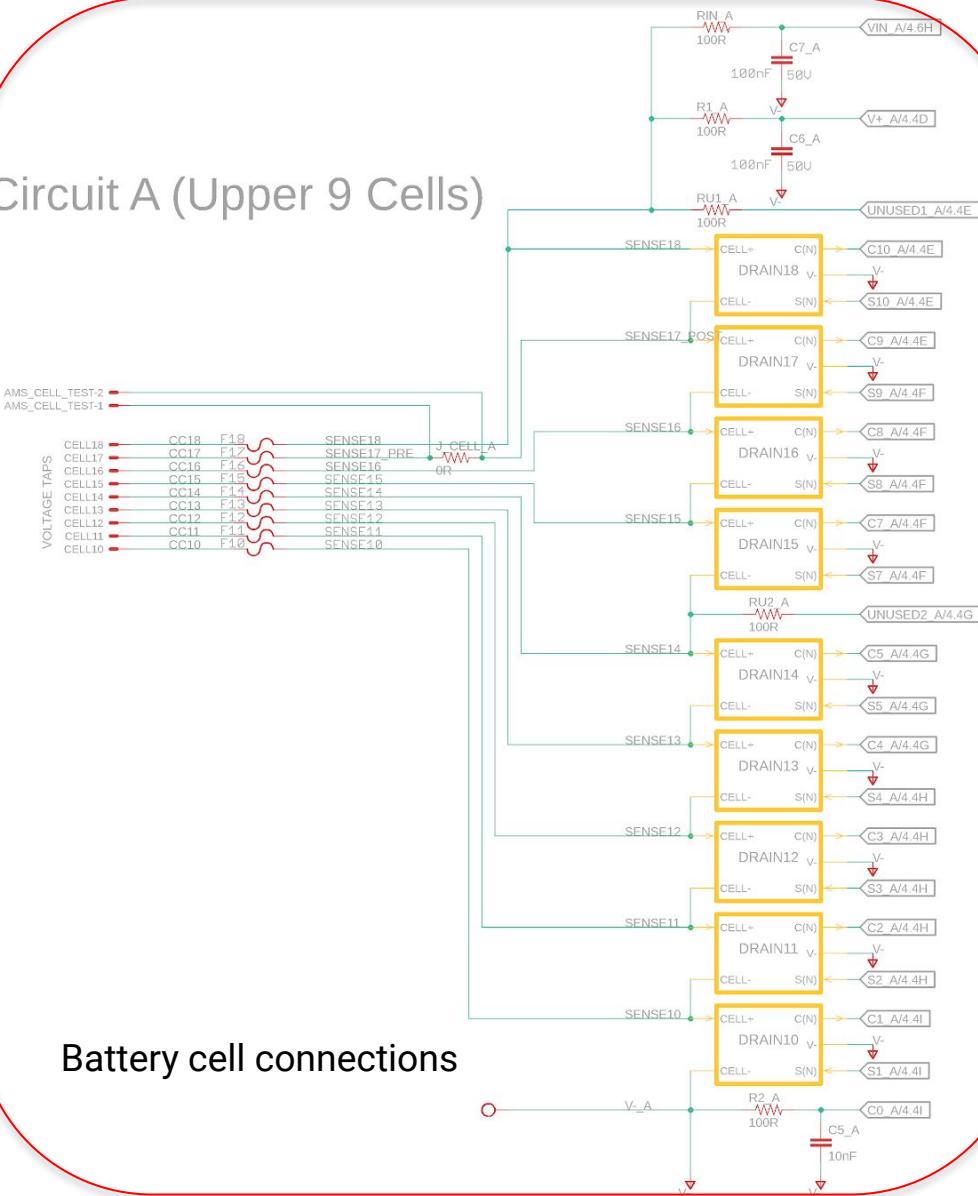
- Was used previously by HyTech
- Has many great features and is field programmable
- Orion BMS in the end was not a desirable solution for HyTech
  - Large size and weight
  - A lot of features that were not needed

## Patents

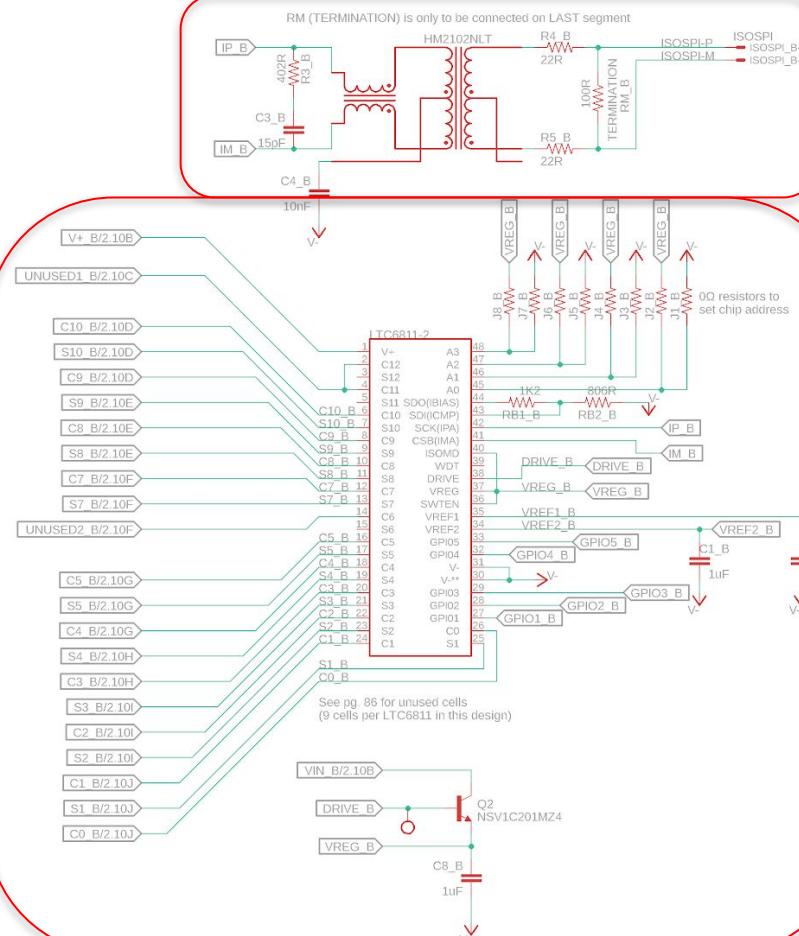


# Prior Art: HyTech BMS Design

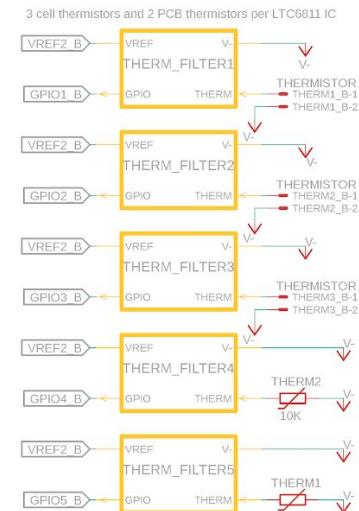
Circuit A (Upper 9 Cells)



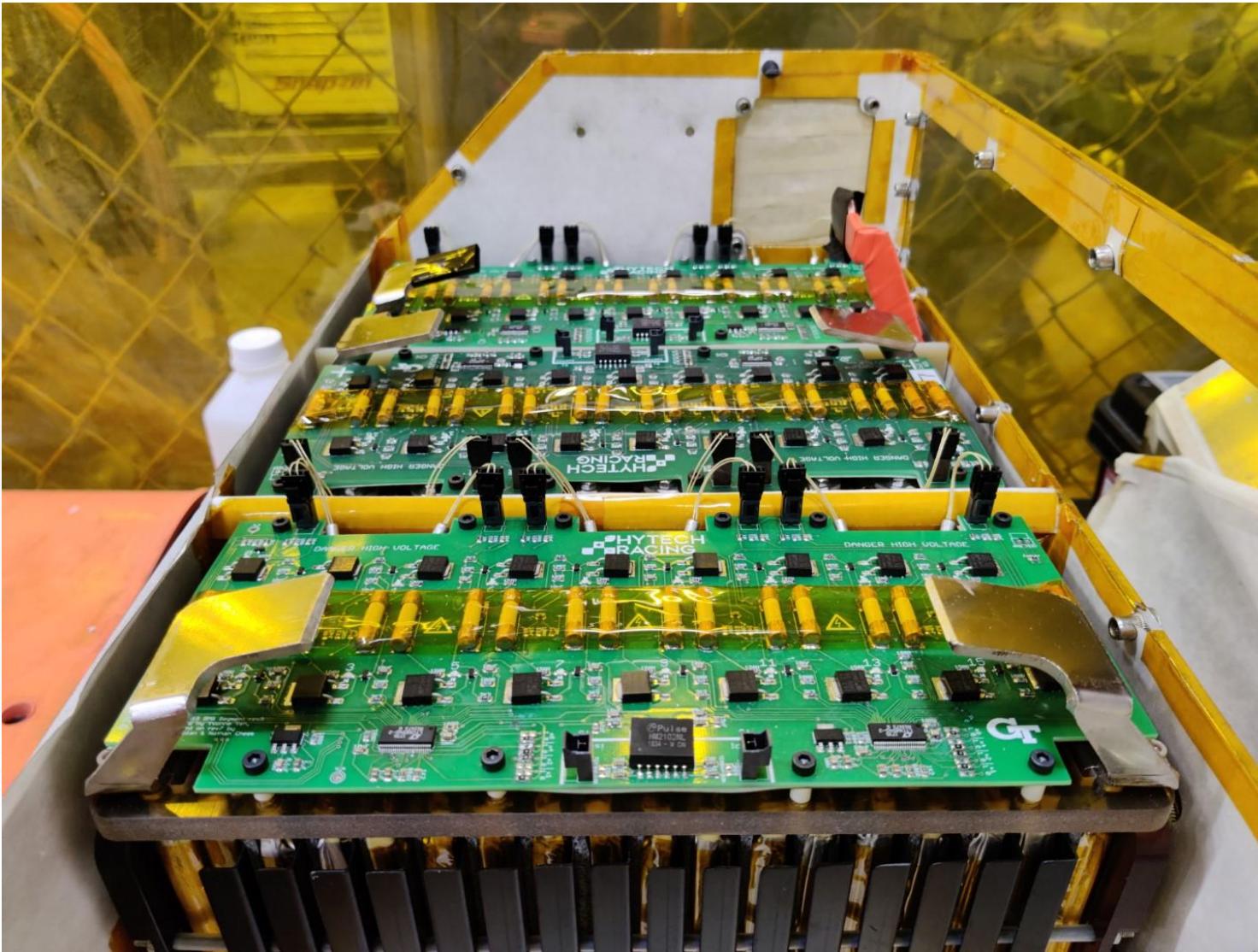
isoSPI transformer



Thermistor connections



# Prior Art: HyTech BMS Design



# Customer Requirements / Design Specifications

- **Function**

- Charge 9 LiCoO<sub>2</sub> Battery Cells with nominal capacity of 18Ah
- Record and store current and voltage data for every cell
- Must be compatible with Melasta SLPBA580183 battery cells

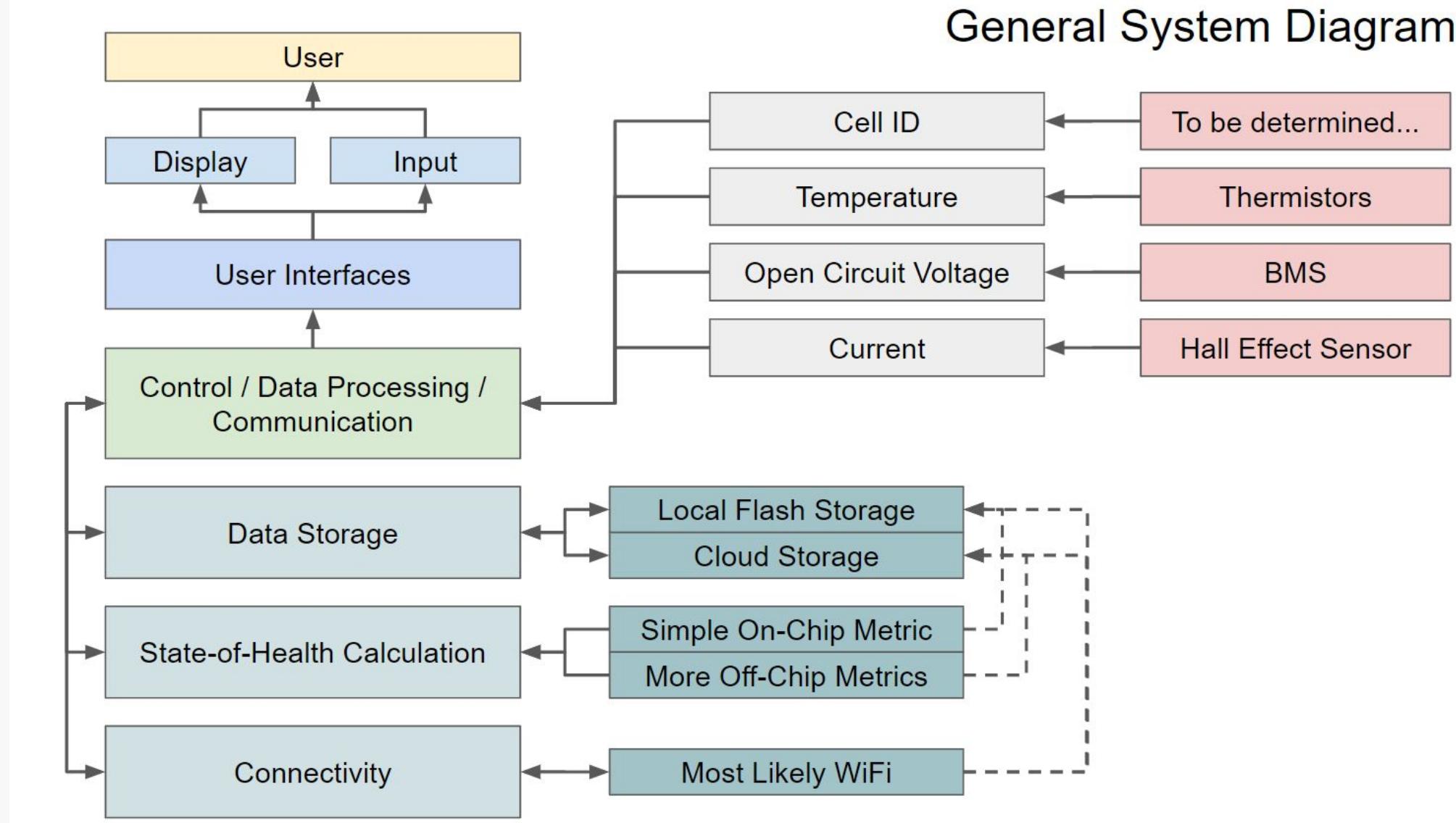
- **Electrical Characteristics**

- Charging current of 9A (0.5C)
- Must have a cell balancing algorithm
- Powered from a regular electrical wall outlet

- **Safety**

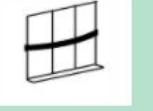
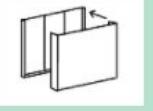
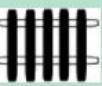
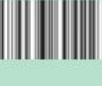
- Must be easy and safe to use

# Design Concept Ideation: General System Diagram



# Design Concept Ideation

## Morphological Chart:

| Sub-Functions                   | Solutions  |   |   |   |
|---------------------------------|--|---|---|---|
|                                 | 1  | 2   | 3   | 4   |
| Multi-Cell(9) Charging          |    |    |    |    |
| record voltage and current data |   | Cloud   |    | flash storage   |
| Power Supply                    |   | Off the shelf   |    | Original Design   |
| Temperature Management          |    |   |   |    |
| User Friendly Interface         |  |  |  | Touch Screen  |
| Cell Tracking ID                |  |  |  |  |

# Design Concept Ideation: Electrical System Diagram

