2022 Future Computing Summer Internship Project: Detecting if Simulated Oscillators are Following the Kuramoto Model by Determining if the Oscillators Experience Synchronization.

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Abstract

The primary focus in this research is to find a metric that determines if a set of similar oscillators are synchronized or not. The Kuramoto Model is a mathematical model that describes how coupled oscillators may synchronize over time. If a system architect creates a system involving coupled oscillators and are unaware of this model, unintended behavior will occur if the oscillators synchronize over time. In this case, effort is put forward to creating an algorithm that results in a metric to detect which oscillators in a set are synchronized and which are not. The current algorithm results in a metric that measures the difference in time between the first peak in harmonic oscillators and a reference harmonic oscillator of the same frequency. The difference in time is multiplied by 2π to measure the phase difference between the set of oscillators and the reference oscillators. Detecting synchronization is done by comparing the phase difference between the oscillators. If the oscillators are in-phase (phase difference of zero) or anti-phase (phase difference of π) and share the same frequency, they are synchronized. More work needs to be put forward on expanding this metric, testing its correctness, or determining a more effective metric for detecting oscillator synchronization.

1 Project Description

The challenge addressed by this work is to determine a correct and efficient way to analyze multiple oscillators and determine which oscillators are synchronized and which are not. The purpose for this is to detect synchronization of oscillators in simulation. This problem is being looked at due to the Kuramoto Model, which is a mathematical model that describes how coupled oscillators may synchronize over time. If this behavior is unintended and system architects are unaware of it, this can create unintended behavior. In this case, an effort is put forward to detecting which oscillators are synchronized in a set and which are not.

2 Motivation

This work is helpful for networking and quantum computing. For networking, it is useful to determine if communication from multiple clients are synchronously sending messages or not. If a large number of clients transfer messages synchronously, then the problem such as thundering herd can occur in the network. In this case, it is useful for network architects to be able to simulate network traffic and determine if the clients' traffic is synchronized. In quantum computing, if coupled oscillators are used in the production of quantum systems then they can potentially follow the Kuramoto Model and synchronize over time. It will be useful to measure and detect for oscillator synchronization if it is undesired behavior.

3 Prior work

Detecting synchronization in signals appears to be largely researched in the neuroscience field. Different methods for detecting synchronization have been researched. Biswas, Khamaru, and Majumdar research a method to determine a signal synchronization measurement based on measuring signal peaks [1]. Similarly,

Quian, Kreuz, Grassberger, defined a method to analyzing signal synchronization through the use of defining events [2]. The authors use peaks as their event in which to analyze for signal synchronization. They measure for synchronization by comparing when events occur in multiple signals. Their idea to focus on peaks in signal was used in the implementation for oscillator synchronization detection in discrete-event simulators.

4 Result

Due to the Structural Simulation Toolkit (SST) discrete-event simulator's (DES) limitations, it was not feasible to implement the algorithm for detecting oscillator synchronization in the DES. This is due to component frequencies being set at the beginning of the simulation and unable to be changed or offset during runtime. In this case, the current implementation was written in Python. The process for measuring for synchronization can be copied over to a discrete-event simulator.

The current implementation for detecting oscillator synchronization is to sample when peaks occur in a set of signals during a sample of one period for all signals. This implementation assumes that the frequency of all signals are tracked and ignores signal amplitudes. Since frequency is given, we will assume that the set of oscillators being compared all share the same frequency. The goal now is to determine if they are all in phase or in anti-phase. The algorithm for synchronization detection works as follows:

- 1. During runtime, begin sampling the set of oscillators for one period. As they share the same frequency, one period is enough to determine if they are synchronized.
- 2. While sampling, when the first peak is encountered, store which oscillator it is associated with and the time it occurred. This will be the reference oscillator peak.
- 3. Continue sampling for the period and store each time the first peak has occurred for all other oscillators.
- 4. After sampling for one period, calculate the differences in time between the reference oscillator's first peak and all other oscillators' first peaks.
- 5. Multiply the differences in time by 2π to give the phase difference between the reference oscillator and all other oscillators.
- 6. Compare the phases of the oscillators with each other to determine if they are in-phase (phase difference of zero) or anti-phase (phase difference of π).

The psuedocode for the algorithms for detecting oscillator synchronization:

Algorithm 1 Oscillator Sampling

```
1: for length(Period) do
       if peaks detected == number of oscillators then
 2:
 3:
           Break
       end if
 4:
 5:
       for each signal do
 6:
           if current signal's first peak has already been found then
              Continue
 7:
           end if
 8:
           if signal's value == signal's amplitude then
9:
              if reference peak found == false then
10:
11:
                  Store current signal as reference oscillator
                  Store current time as reference oscillator's first peak
12:
                  Reference peak found equals true
13:
                  Set current signals first peak found to be true
14:
                 Increment peaks detected
15:
16:
              else
                  Store current signals time subtracted from the time of the reference oscillator's first peak
17:
                  multiplied by 2\pi
18:
                  Set current signals first peak found to be true
19:
                 Increment peaks detected
20:
21:
              end if
22:
           end if
       end for
23:
24: end for
```

Algorithm 2 Oscillator Synchronization Comparison

The algorithm was written in python and only tested on oscillators with simple harmonic motion such as sine and cosine function. It worked as intended but it has not been tested on more non-harmonic oscillators.

5 Future Work

Due to time constraints, researching and coming up with an implementation for detecting oscillator synchronization was rushed. Due to this, the implementation explained above was only tested on oscillators with simple harmonic motion. The algorithm should be tested against more complicated oscillators that share the same frequencies to see if the metric is still accurate.

A different promising direction is to look for research related to phase synchronization, phase clustering, and phase correlation. These terms all relate to calculating the phases of signals and comparing them with other signals to extract information about the pair. Similar to the above, researching these measurements was cut short due to time constraints.

References

- [1] Rahul Biswas, Koulik Khamaru, and Kaushik K. Majumdar. A peak synchronization measure for multiple signals. $IEEE\ Transactions\ on\ Signal\ Processing,\ 62(17):4390-4398,\ 2014.$
- [2] R. Quian Quiroga, T. Kreuz, and P. Grassberger. Event synchronization: A simple and fast method to measure synchronicity and time delay patterns. *Phys. Rev. E*, 66:041904, Oct 2002.