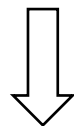
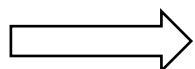


Image Pairs



Undistortion and
Key point detection

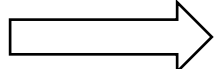
Key points



Feature descriptor
match

Feature
matches

Sparse Matching



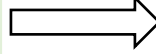
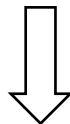
Rectified
images

Rectification



Camera
parameters

Estimated camera
position/fundamental
matrix

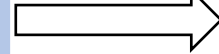


Dense
Matching

Disparity
Map



Depth
Map



Triangulation

Mesh

