

ECE 411 - HW3 & HW4 Exam Cheat Sheet (Lipo-Novotny Conventions)

1) Frames & Conventions

- q-axis $\parallel \alpha$ at $\theta=0$; d is -90° from q (clockwise).
- θ_e : electrical angle ($\alpha \rightarrow q$, CCW); $\omega_e = d\theta_e/dt$.
- $q = \text{Real}\{\cdot\}$, $d = -\text{Imag}\{\cdot\}$; $\beta = -\text{Imag}\{\alpha\beta\}$ for plotting.

2) Clarke & Park Transforms

Clarke: $\alpha = (2/3)[V_a - 0.5V_b - 0.5V_c]$

$$\beta = (2/3)(\sqrt{3}/2)(V_c - V_b)$$

$$\text{Park: } q = \alpha \cos\theta - \beta \sin\theta$$

$$d = \alpha \sin\theta + \beta \cos\theta$$

$$\text{Inverse: } \alpha = q \cos\theta + d \sin\theta; \quad \beta = -q \sin\theta + d \cos\theta$$

3) Phasor Definitions

$$a = e^{j2\pi/3}; \quad x_{\alpha\beta} = (2/3)(x_a + a x_b + a^2 x_c)$$

$$\text{Park: } x_{qd} = x_{\alpha\beta} e^{-j\theta_e}; \quad q = \text{Re}\{x_{qd}\}, \quad d = -\text{Im}\{x_{qd}\}$$

$$E_0 = \omega_e \Lambda_0; \quad \Lambda_0 = E_0 / \omega_e$$

4) Base Quantities (per-unit)

$$V_B = V_{dc}/\sqrt{3}, \quad I_B = I_{max}, \quad Z_B = V_B/I_B$$

$$P_B = 1.5 V_B I_B, \quad \omega_B = 2\pi f_B, \quad T_B = P_B/\omega_m B$$

5) Voltage Equations

$$\text{Round-rotor: } V_q = R_s I_q + \omega_e L_s I_d + E_q$$

$$V_d = R_s I_d - \omega_e L_s I_q + E_d$$

$$\text{Salient-pole: } V_q = R_s I_q + \omega_e L_d I_d + E_q$$

$$V_d = R_s I_d - \omega_e L_q I_q + E_d$$

6) Torque & Power

$$P = 1.5(V_q I_q + V_d I_d)$$

$$T_e = P / \omega_e$$

$$T_e = (E_q I_q)/\omega_e + ((L_d - L_q) I_d I_q)/\omega_e$$

Salient-pole:

$$T_{field} = -(E_0 V_0)/(\omega_e L_d) \sin\delta$$

$$T_{rel} = -(V_0^2(L_d - L_q))/(2\omega_e L_d L_q) \sin(2\delta)$$

One-page review — HW3 & HW4 core equations under Lipo-Novotny convention.

$$T_e = T_{field} + T_{rel}$$

7) Field Weakening

$$\text{Voltage limit (R_s=0): } V_0^2 = (\omega_e \Lambda_0)^2 - (\omega_e L_s I_0)^2$$

$$\Lambda_0 = \sqrt{[(V_0/\omega_e)^2 + (L_s I_0)^2]}$$

$$T_{max} = V_0 I_0 / \omega_e; \quad P_{max} = V_0 I_0$$

$$\text{Flux ratio} = \Lambda_{new} / \Lambda_{rated}$$

8) $R_s \neq 0$ Effects

$$Z_s = \sqrt{(R_s^2 + (\omega_e L_s)^2)}$$

$$T_{max} = (V_0 E_0)/(\omega_e Z_s) - (E_0^2 R_s)/(\omega_e Z_s^2)$$

$$\delta_{max} = \sin^{-1}(R_s/Z_s) - \pi/2$$

9) Saliency & Ratios

$$\text{Saliency ratio } \xi = L_d / L_q$$

$$T_{rel,max} = T_{field,max} \rightarrow L_q = (V_0 L_d)/(2E_0 + V_0 R_s)$$

10) Quick Reference (exam tips)

- Open-circuit: $v_q \approx \omega_e \Lambda_0$, $v_d \approx 0$ (confirm q- α alignment).

- Generator: $P_{mech} = -P_{elec}$; motoring $\rightarrow +T_e$.

- δ increases with load torque; small $\delta \approx$ linear region.

- Keep per-unit bases consistent (V_B , I_B , L in pu).

- q = torque-producing axis; d = flux (field) axis.