```
def compute innovations(self, z raw, Q raw):
        Given lines extracted from the scanner data, tries to associate each one
        to the closest map entry measured by Mahalanobis distance.
        Inputs:
               z_raw: np.array[2,I] - I lines extracted from scanner data in
                                                                          columns representing (alpha, r) in the scanner frame.
                Q raw: np.array[I,2,2] - I covariance matrices corresponding
                                                                          to each (alpha, r) column of z raw.
        Outputs:
               vs: np.array[M,2I] - M innovation vectors of size 2I
                                                                   (predicted map measurement - scanner measurement).
        ######## Code starts here ########
        # TODO: Compute vs (with shape [M x I x 2]).
                                                                          # Num of particles. M.
                 = self.M
        n lin = self.map_lines.shape[1] # Num of known lines on map. J.
                                                                         # Num of scanned lines. I.
        n mea = z raw.shape[1]
        z raw = z_raw.T
                                                                                    # shape(n mea, 2)
                                                                                    # shape(n mea, 2, 2)
        # Q raw
        hs = self.compute_predicted_measurements().transpose(0, 2, 1) # shape(n, n lin, 2)
        h mat = hs[:, :, None, :]
                                                                                    # shape(n, n lin, 1, 2)
        d mat = np.matmul(v fat.transpose(0, 1, 2, 4, 3), Q inv)
        d = np.matmul(d = np.matmul(
        d_mat = d_mat.reshape((n,n_lin,n_mea)) # shape(n, n_lin, n_mea)
        # For each particle, for each scanned line, this returns the index
        # of the best known line.
        d argmin = np.argmin(d mat, axis=1)
                                                                                                                     # shape(n, n mea)
        d_argmin = d_argmin[:, None, :, None]
                                                                                                                     # shape(n, 1, n mea, 1)
        vs = np.take_along_axis(v_mat, d_argmin, axis=1) # shape(n, 1, n_mea, 2)
vs = vs.reshape((n, n mea, 2)) # shape(n, n_mea, 2)
        ######## Code ends here #########
        # Reshape [M x I x 2] array to [M x 2I]
        return vs.reshape((self.M,-1)) # [M x 2I]
```