

# Homework 4

**Due: December 14, 2018 in class**

**Note: No late homework will be accepted.** You may discuss with your classmates but **you may not plagiarize.** You need to turn in **your analysis and also your code** (printout) written in Octave or Matlab.

Part A. (30%)

**A.1** Show the discrete orthogonality of cosines

$$\sum_{j=0}^N \frac{1}{c_j} \cos k x_j \cos k' x_j = \begin{cases} 0 & \text{if } k \neq k' \\ \frac{1}{2} c_k N & \text{if } k = k' \end{cases}$$

where  $x_j = \pi j/N$ ,  $j = 0, 1, 2, \dots, N$  and

$$c_k = \begin{cases} 2 & \text{if } k = 0, N \\ 1 & \text{otherwise.} \end{cases}$$

(Hint: by substituting complex exponential representations for cosines.)

A.2 The discrete cosine series is defined by

$$f_j = \sum_{k=0}^N a_k \cos k x_j \quad j = 0, 1, 2, \dots, N,$$

where  $x_j = \pi j/N$ .

Prove that the coefficients of the series are

$$a_k = \frac{2}{N} \frac{1}{c_k} \sum_{j=0}^N \frac{1}{c_j} f_j \cos k x_j \quad k = 0, 1, 2, \dots, N.$$

Part B. (20%)

Differentiate the following functions using two methods: FFT and central difference formula

$$f'_j = \frac{f_{j+1} - f_{j-1}}{2h}.$$

When you use the central difference formula, compute the derivative only at the interior points but not at the boundary points. **For each method, use  $N = 16$  and  $N = 32$ .** Plot your results based on FFT and central difference formula as symbols (for example, squares or triangles) and the exact derivative as a continuous line.

B.1

$$f(x) = \sin 3x + 3 \cos 6x \quad 0 \leq x < 2\pi$$

B.2

$$f(x) = 6x - x^2 \quad 0 \leq x < 2\pi$$

Which method works better in B.1? Which method works better in B.2? Can you explain the reason?

### Part C. (30%)

Here are two functions  $f(x)$  and  $g(x)$  defined in the interval  $(0, 2\pi)$ , i.e.

$$f(x) = \sin(2x) + 0.1\sin(15x),$$

$$g(x) = \sin(2x) + 0.1\cos(15x).$$

C.1 Use  $N = 32$  grid points, i.e.  $x_j = 2\pi j/N$ ,  $j = 0, 1, 2, \dots, N-1$ . Compute  $f_j = f(x_j)$ ,  $g_j = g(x_j)$  and  $H_j = f_j g_j$ . Compute the FFT of  $H_j$ , i.e.  $\hat{H}_k$ ,  $k = -N/2, -N/2 + 1, \dots, -1, 0, 1, \dots, N/2 - 1$ ? What is the real function that  $\hat{H}_k$  represents?

C.2 Use  $N = 32$  grid points and compute the FFT of  $f_j$ , i.e.  $\hat{f}_k$ , and the FFT of  $g_j$ , i.e.  $\hat{g}_k$ . Compute  $\hat{h}_m$  using the convolution sum

$$\hat{h}_k = \sum_{m=-N/2}^{N/2-1} \hat{f}_m \hat{g}_{k-m},$$

where  $k = -N/2, -N/2 + 1, \dots, -1, 0, 1, \dots, N/2 - 1$ . What is the real function that  $\hat{h}_k$  represents?

C.3 Use trigonometric identities to show the exact result of  $E(x) = f(x)g(x)$ . Use  $N = 32$  grid points and compute  $E_j = E(x_j)$  and the FFT of  $E_j$ , i.e.  $\hat{E}_k$ . Does  $\hat{E}_k$  represent  $E(x)$  correctly? Do you see any difference among  $\hat{E}_k$ ,  $\hat{H}_k$  and  $\hat{h}_k$ ? Which is correct? Why?

### Part D. (20%)

We use the Chebyshev derivative matrix operator to differentiate  $u(x) = 4(x^2 - x^4)e^{-x/2}$  in the range  $-1 \leq x \leq 1$ . Let vector  $\mathbf{x}$  represent the collocation points  $x_j = \cos(\pi j/N)$ ,  $j = 0, 1, 2, \dots, N$ , and vector  $\mathbf{u}$  represent the values of  $u(x)$  at the collocation points. Construct the  $(N+1) \times (N+1)$  Chebyshev collocation derivative matrix  $\mathbf{D}$  using (6.46) or (6.47) in the textbook.

D.1 For  $N = 7$ , write down the vectors  $\mathbf{x}$  and  $\mathbf{u}$ , the derivative matrix  $\mathbf{D}$ , and the first derivative of  $u(x)$  at the collocation points, i.e.  $\mathbf{u}'$ , via  $\mathbf{u}' = \mathbf{D}\mathbf{u}$ . Plot the first derivative  $\mathbf{u}'$  at the collocation points using symbols and the exact first derivative using a continuous line.

D.2 For  $N = 7$ , write down the vectors  $\mathbf{x}$  and  $\mathbf{u}$ , the second derivative matrix  $\mathbf{D}_2$ , and the second derivative of  $u(x)$  at the collocation points, i.e.  $\mathbf{u}''$ , via  $\mathbf{u}'' = \mathbf{D}_2\mathbf{u}$ . Plot the second derivative  $\mathbf{u}''$  at the collocation points using symbols and the exact second derivative using a continuous line.