

# HW5-Q1

November 14, 2019

```
[1]: import numpy as np
import matplotlib.pyplot as plt
import random
from sklearn.datasets import make_spd_matrix, make_sparse_spd_matrix
from scipy.stats import unitary_group
```

```
[2]: class LossFunc:

    # initialization
    def __init__(self, Q, b, lam, eg):

        self.Q = Q
        self.b = b
        self.lam = lam
        self.eg = eg

    def g(self, x):
        return 0.5*np.dot(x.T.dot(self.Q), x) - np.dot(self.b, x)
    def g2(self, x):
        # print((0.5*(self.eg*(x**2)) - self.b*x).shape)
        return 0.5*np.dot(self.eg, (x**2)) - np.dot(self.b, x)

    def h(self, x):
        return self.lam*np.linalg.norm(x, 1)

    def gGrad(self, x):
        return self.Q.dot(x) - self.b
    def g2Grad(self, x):
        # print((self.eg*x - self.b).shape)
        return self.eg*x - self.b

    def obj(self, x):
        return self.g2(x) + self.h(x)

    def Gt(self, x, t, idx):
        x_0 = x.copy()
        x[idx] = self.prox(x[idx] - t*self.g2Grad(x)[idx], t)
```

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    return (x_0 - x)/t

def soft_threshold(self,b,a):
    if (np.abs(a)<=b):
        return 0
    if(a<-b):
        return a+b
    if(a>b):
        return a-b

def prox(self,x,t):
    return self.soft_threshold(x,self.lam*t)

```

## 1 Experiment Setup

- We would like to compare exact step coordinate proximal GD with fixed step coordinate proximal GD.
- For comparison, we will run them on the specific convex problems for several times
- After preliminary experiments, we found two factors which will affect how much exact step helps: dimension of variables  $X$  and the distribution of the eigen value of  $Q$
- So we set 2 hyperparameters for our experiment:  $X$ 's dimension and  $Q$ 's condition number
- For other settings, we choose  $\lambda = 0.1$  and fixed step size  $t_{fixed} = 1/\max(Q[i, i])$ .

```

[40]: def exact_vs_fixed(n,cond,trial=10):
    # n is the dimesion of x,Q,b
    # cond is the Q_eigen_value_max / Q_eigen_value_min
    # trial is the number of repeated tests

    plt.figure(figsize=(24,2*trial))
    epi = 1e-6
    flops_fx = []
    flops_ex = []

    for z in range(trial):
        x_0 = np.zeros(n)
        min_eg = np.abs(np.random.randn(1)[0])
        max_eg = cond*min_eg
        eg = np.append(np.array([min_eg,max_eg]),np.random.
→uniform(low=min_eg,high=max_eg,size=n-2))
        # eg = np.random.uniform(low=0.001,high=1,size=n)
        lam = 0.1
        random.shuffle(eg)
        Q = np.diag(eg)
        W = unitary_group.rvs(n)

```

```

Q = np.dot(W.T.dot(Q),W)
b = np.random.randn(n)

# Fixed Step Coordinate Proximal GD
# cot_fx = []
obj_fx = []

L = LossFunc(Q.copy(),b.copy(),lam,eg.copy())
x = x_0.copy()
obj_0 = L.obj(x)
# obj_record = []
# cot = 0
obj_fx.append(obj_0)
t = 1/max_eg

while(True):
    for i in range(n):
        x[i] = L.prox(x[i]-t*L.g2Grad(x)[i],t)
        # cot = cot+1
        obj_1 = L.obj(x)
        obj_fx.append(obj_1)
        if (obj_0 - obj_1) < epi:
            break
    obj_0 = obj_1

# cot_fx.append(cot)
# obj_fx.append(obj_record)

# Exact Step Coordinate Proximal GD
# cot_ex = []
obj_ex = []

L = LossFunc(Q,b,lam,eg)
x = x_0.copy()
obj_0 = L.obj(x)
# obj_record = []
# cot = 0
obj_ex.append(obj_0)

while(True):
    for i in range(n):
        t = 1/eg[i]
        x[i] = L.prox(x[i]-t*L.g2Grad(x)[i],t)
        # cot = cot+1
        obj_1 = L.obj(x)
        obj_ex.append(obj_1)
        if (obj_0 - obj_1) < epi:

```

```

        break
    obj_0 = obj_1

    # cot_ex.append(cot)
    # obj_ex.append(obj_record)

    plt.subplot(trial/4,4,z+1)
    plt.xlabel('Flops')
    plt.ylabel('Criterion')
    fx = np.array(obj_fx)
    plt.plot(fx,label='Fixed')
    ex = np.array(obj_ex)
    plt.plot(ex,label='Exact')
    plt.legend()

    flops_fx.append(len(obj_fx))
    flops_ex.append(len(obj_ex))
    return np.array(flops_fx).mean(),np.array(flops_ex).mean()

```

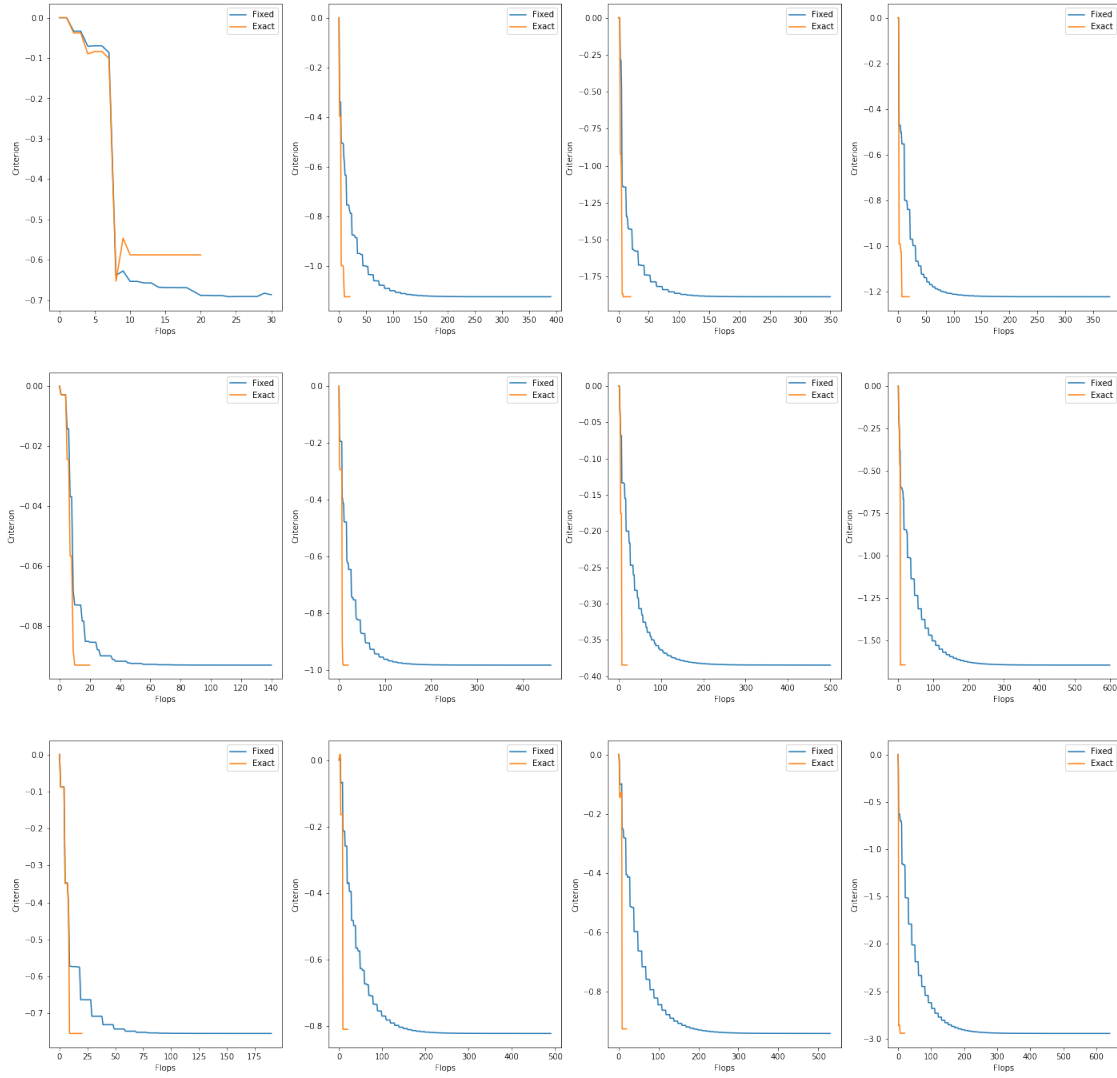
## 2 Result

### 2.1 How dimension affects

#### 2.1.1 $n = 10$

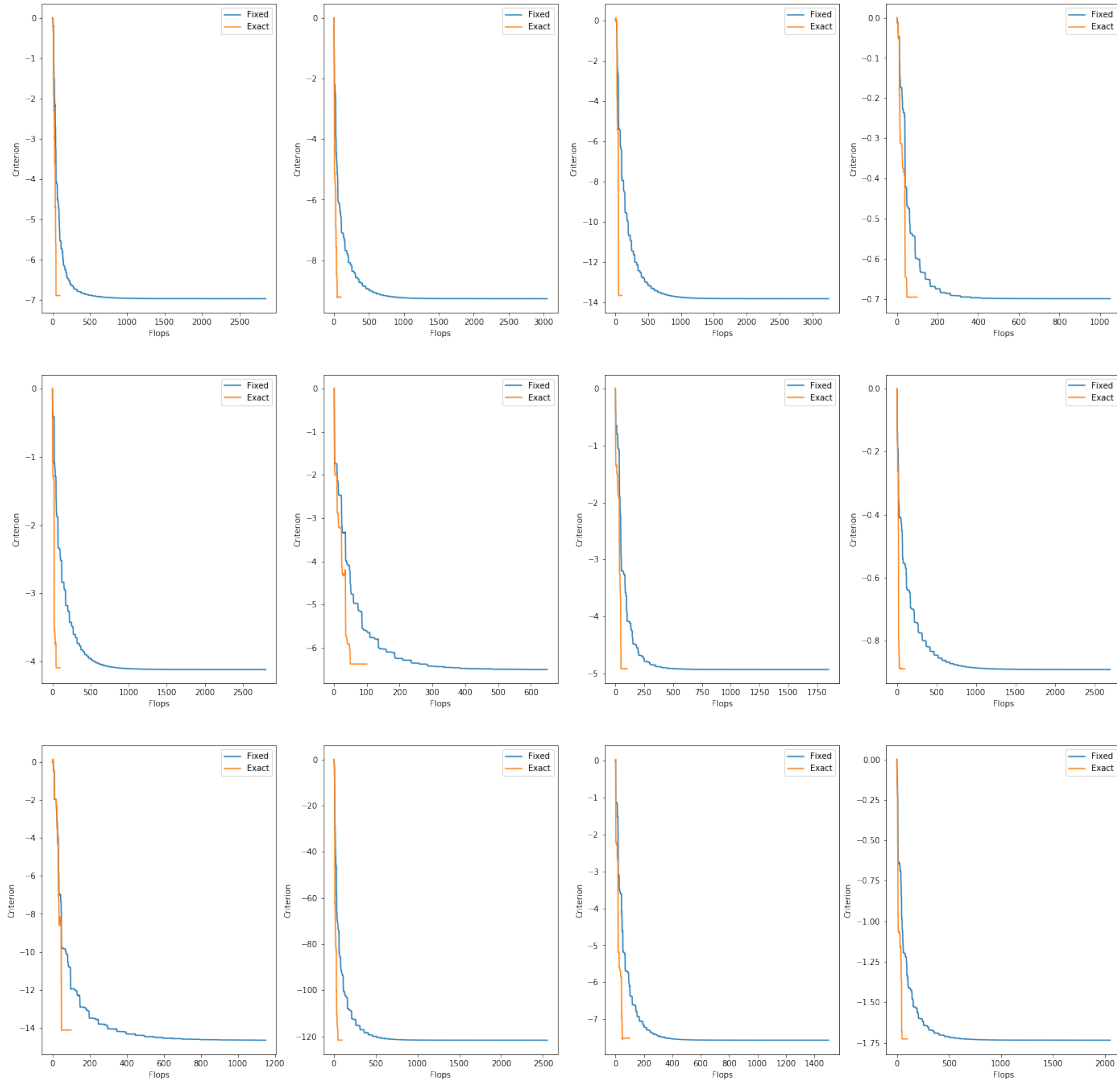
```
[60]: flop_until_convergence_fx = []
      flop_until_convergence_ex = []
```

```
[61]: nf,ne = exact_vs_fixed(10,10,trial=12)
      flop_until_convergence_fx.append(nf)
      flop_until_convergence_ex.append(ne)
```



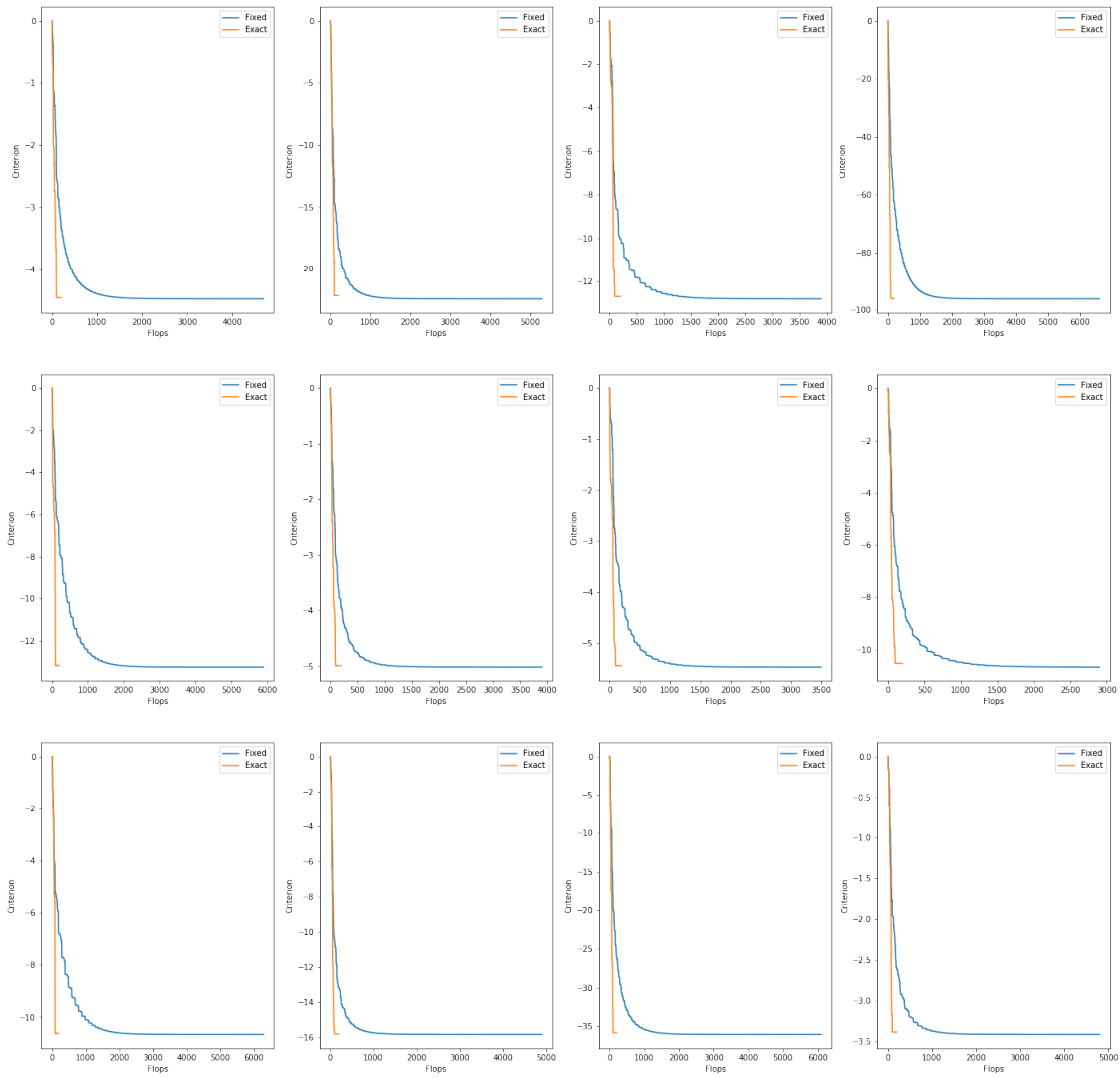
### 2.1.2 $n = 50$

```
[62]: nf,ne = exact_vs_fixed(50,10,trial=12)
      flop_until_convergence_fx.append(nf)
      flop_until_convergence_ex.append(ne)
```



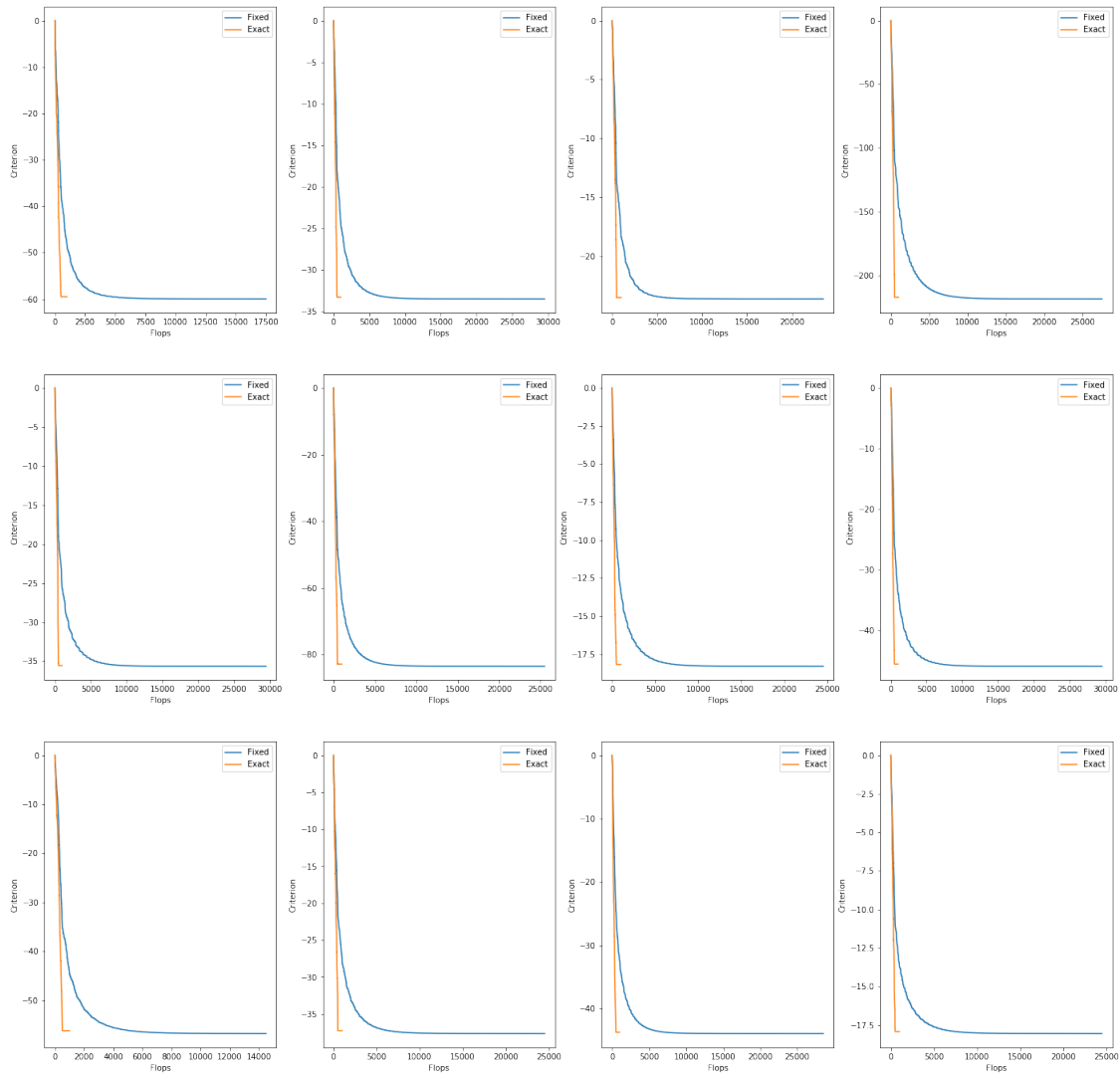
### 2.1.3 $n = 100$

```
[63]: nf,ne = exact_vs_fixed(100,10,trial=12)
      flop_until_convergence_fx.append(nf)
      flop_until_convergence_ex.append(ne)
```



### 2.1.4 $n = 500$

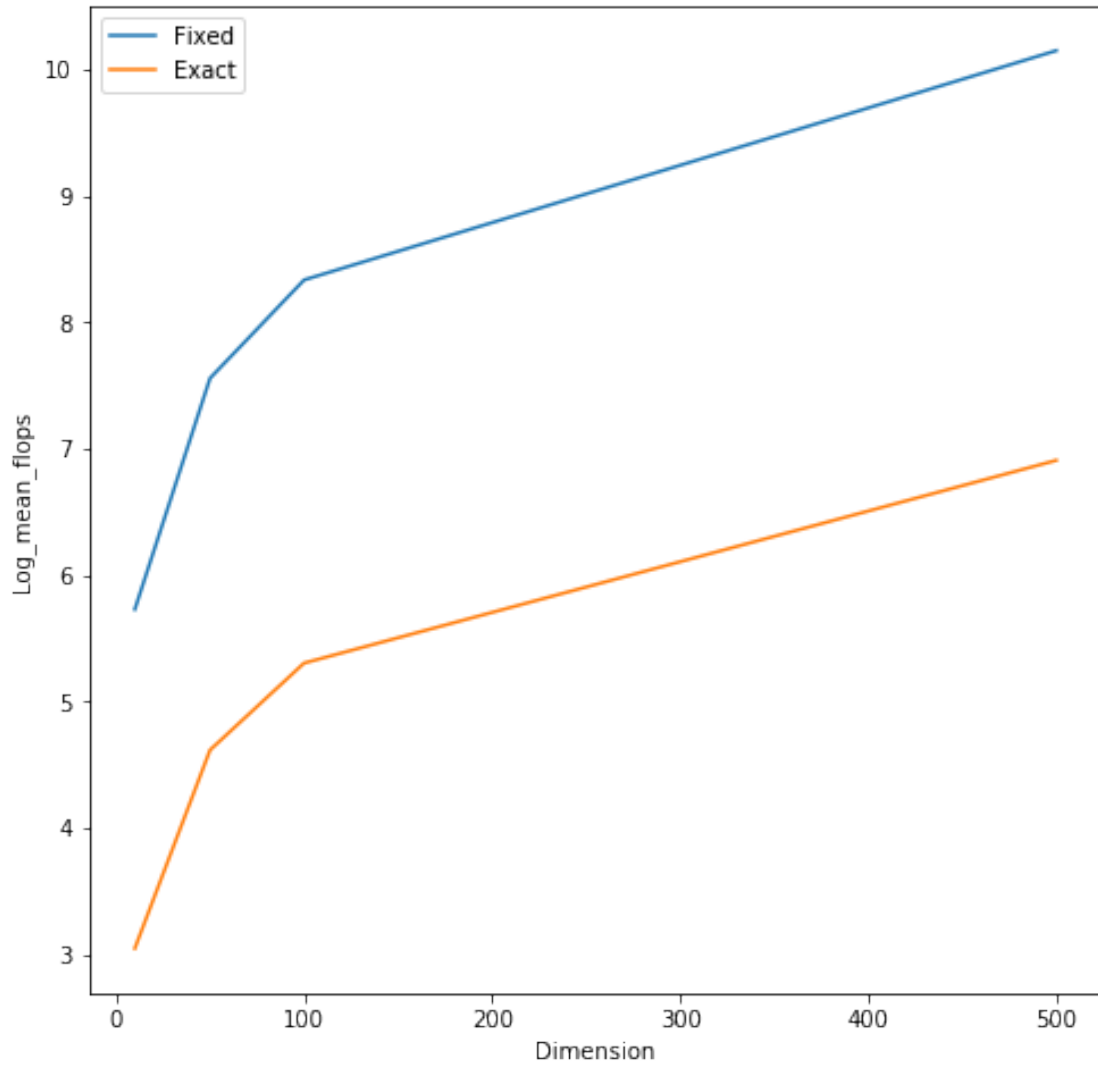
```
[64]: nf,ne = exact_vs_fixed(500,10,trial=12)
      flop_until_convergence_fx.append(nf)
      flop_until_convergence_ex.append(ne)
```



## 2.2 Dimension VS Flops Until Convergence

```
[53]: plt.figure(figsize=(8,8))
plt.plot([10,50,100,500],np.log(np.
    ↪array(flop_until_convergence_fx)),label='Fixed')
plt.plot([10,50,100,500],np.log(np.
    ↪array(flop_until_convergence_ex)),label='Exact')
plt.xlabel('Dimension')
plt.ylabel('Log_mean_flops')
plt.legend()
plt.show()
```



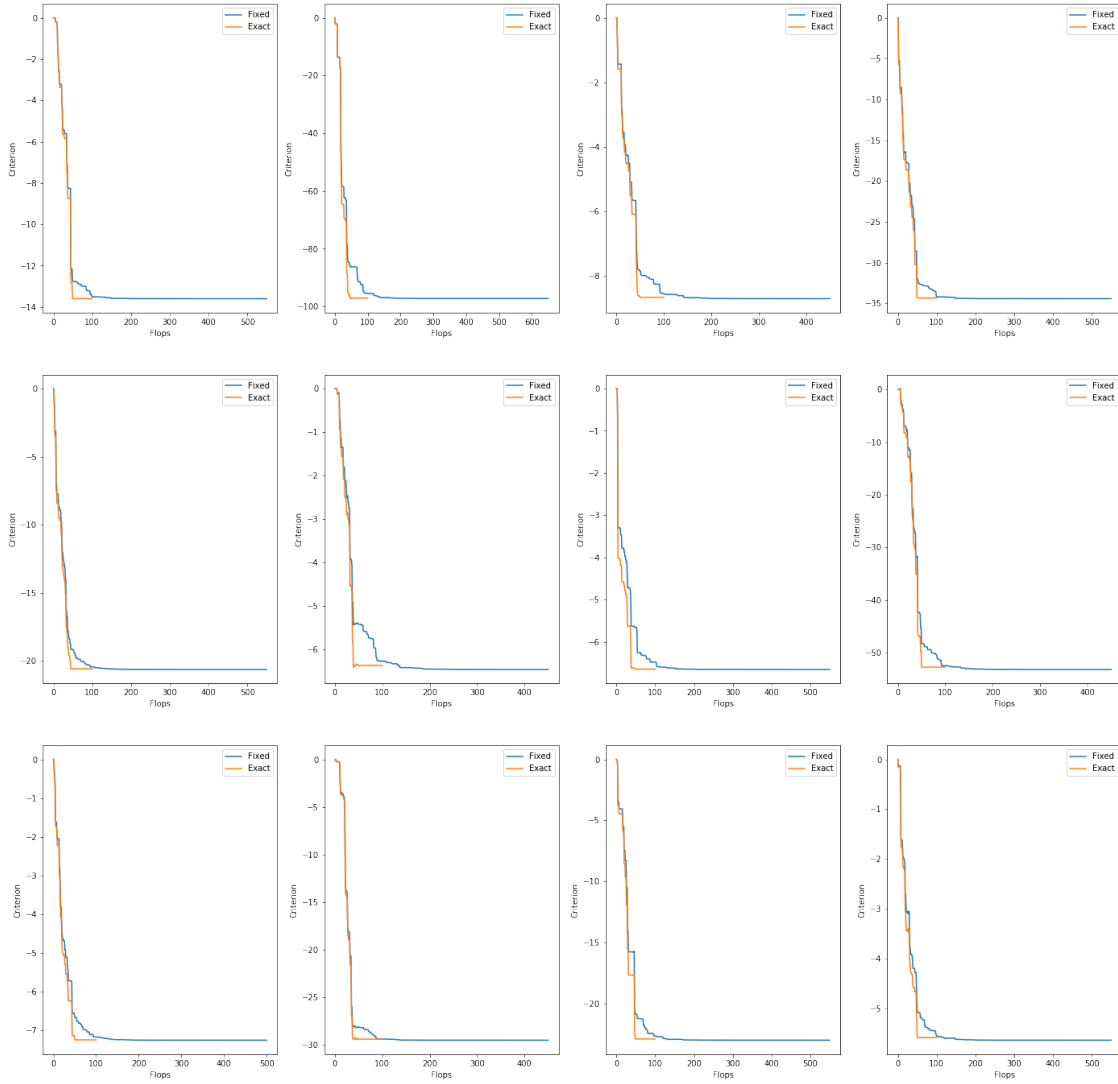


## 2.3 How condition number of $Q$ affects

### 2.3.1 $\text{cond} = 2$

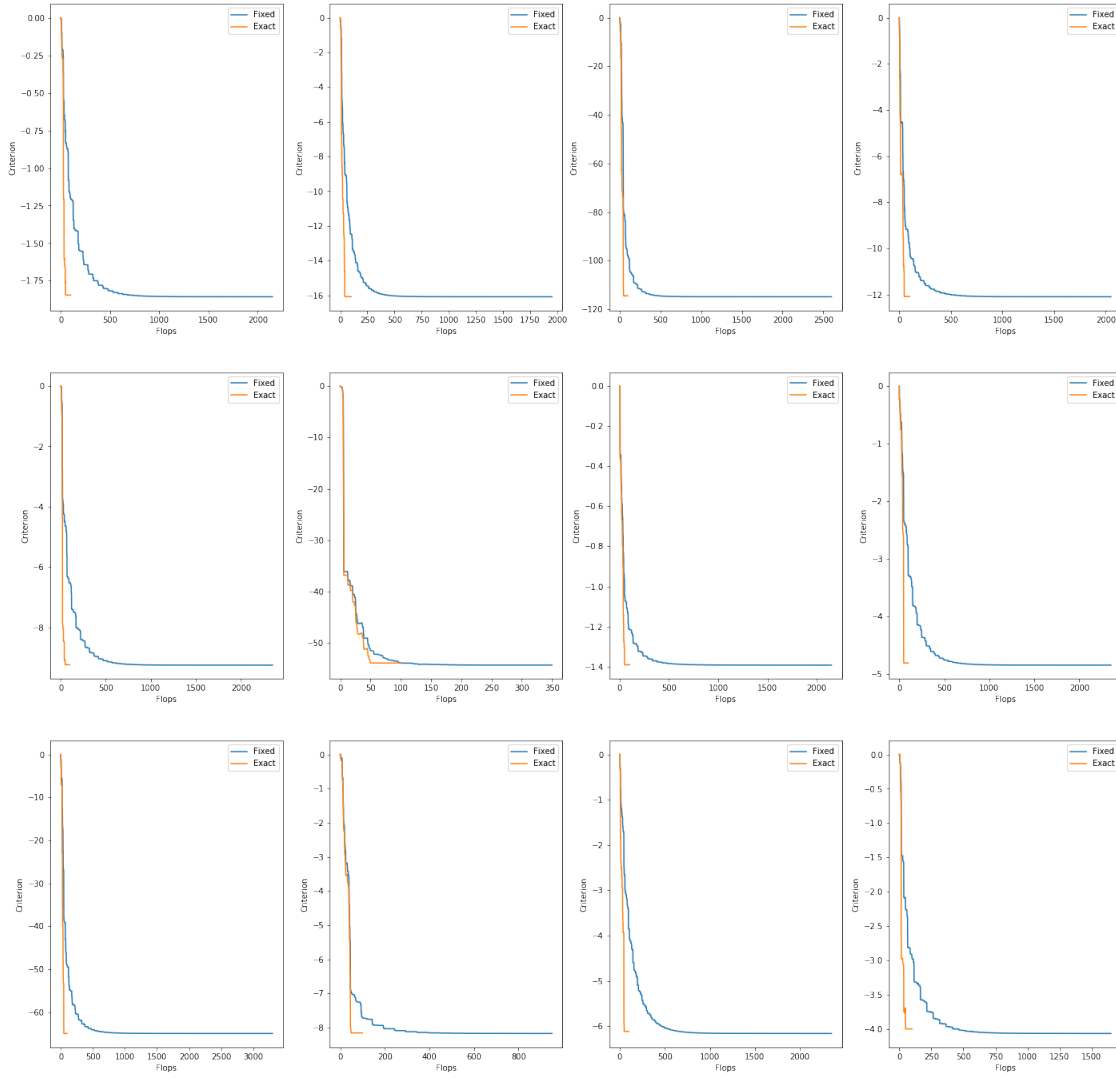
```
[66]: flop_until_convergence_fx = []  
      flop_until_convergence_ex = []
```

```
[67]: nf, ne = exact_vs_fixed(50, 2, trial=12)  
      flop_until_convergence_fx.append(nf)  
      flop_until_convergence_ex.append(ne)
```



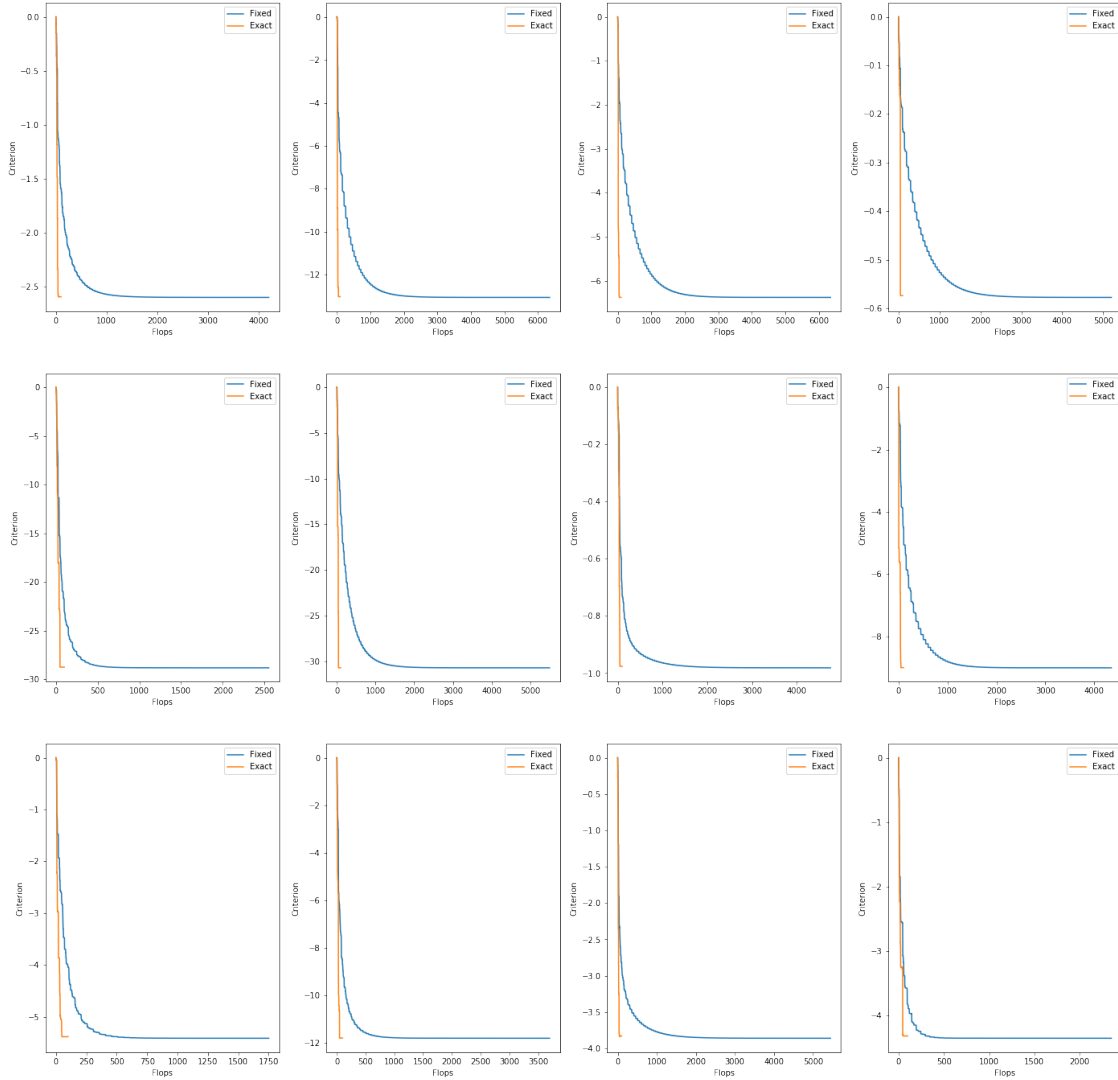
### 2.3.2 $\text{cond} = 10$

```
[68]: nf,ne = exact_vs_fixed(50,10,trial=12)
      flop_until_convergence_fx.append(nf)
      flop_until_convergence_ex.append(ne)
```



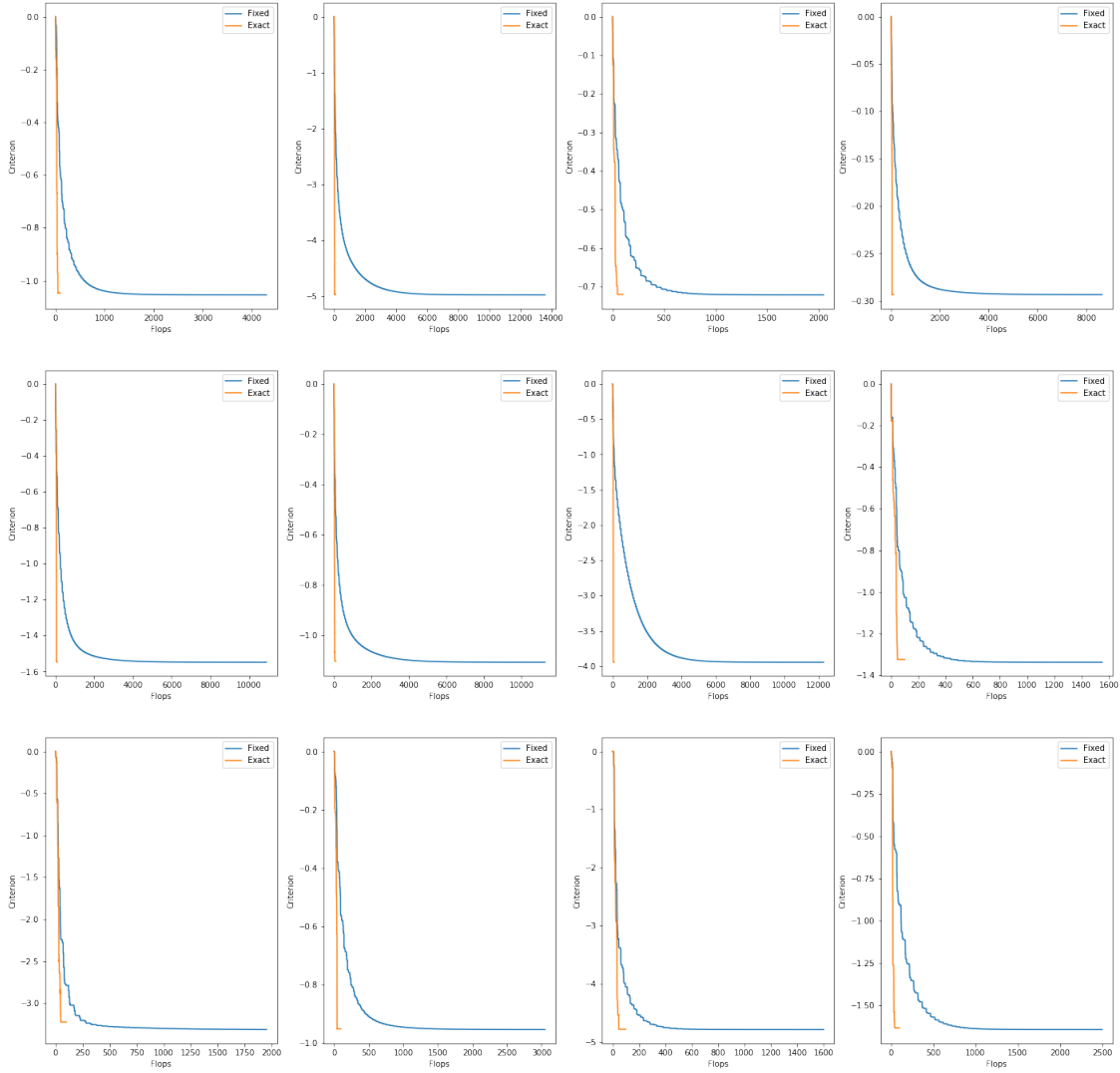
### 2.3.3 $\text{cond} = 20$

```
[69]: nf,ne = exact_vs_fixed(50,20,trial=12)
      flop_until_convergence_fx.append(nf)
      flop_until_convergence_ex.append(ne)
```



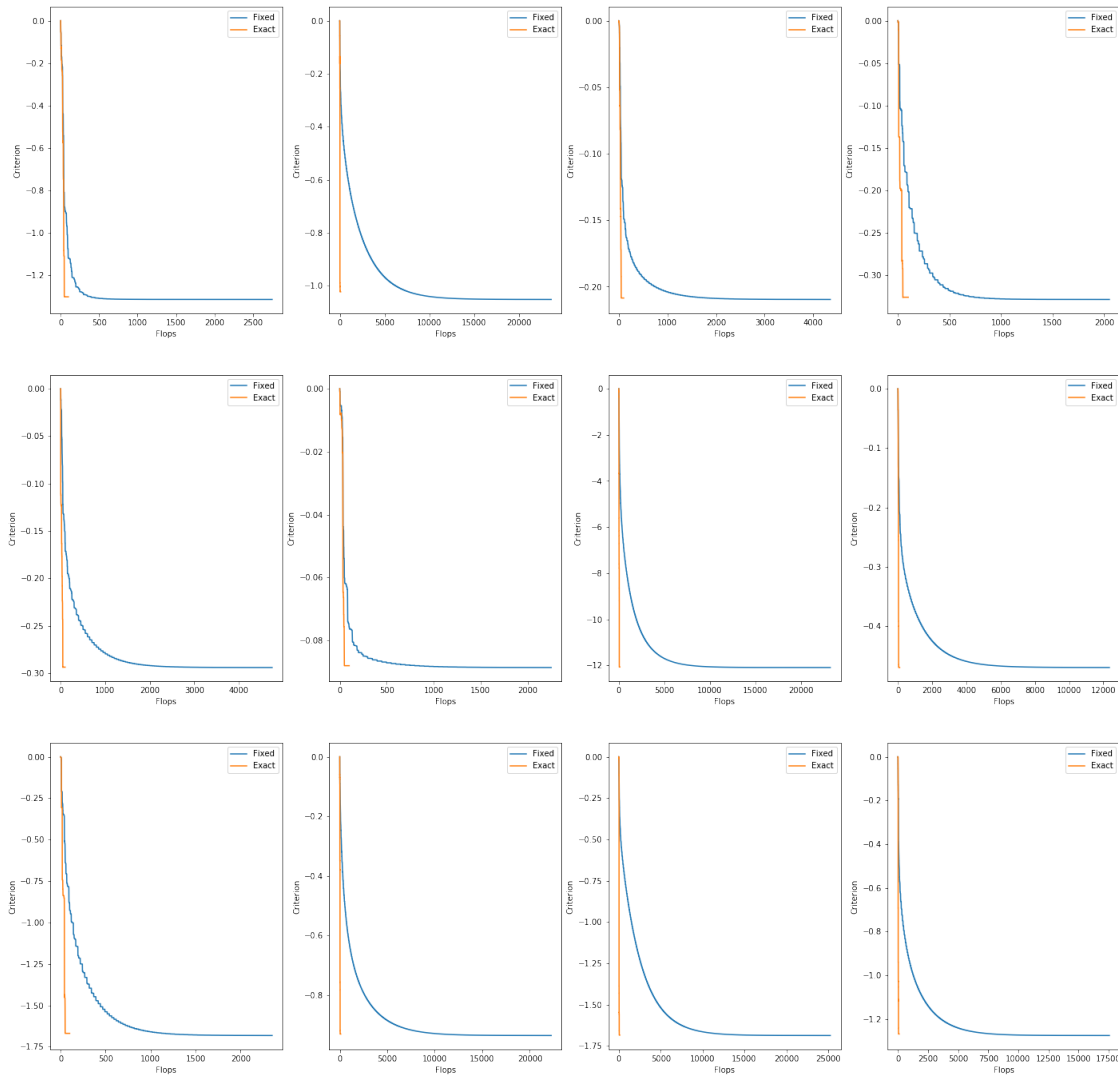
### 2.3.4 $\text{cond} = 50$

```
[70]: nf,ne = exact_vs_fixed(50,50,trial=12)
      flop_until_convergence_fx.append(nf)
      flop_until_convergence_ex.append(ne)
```



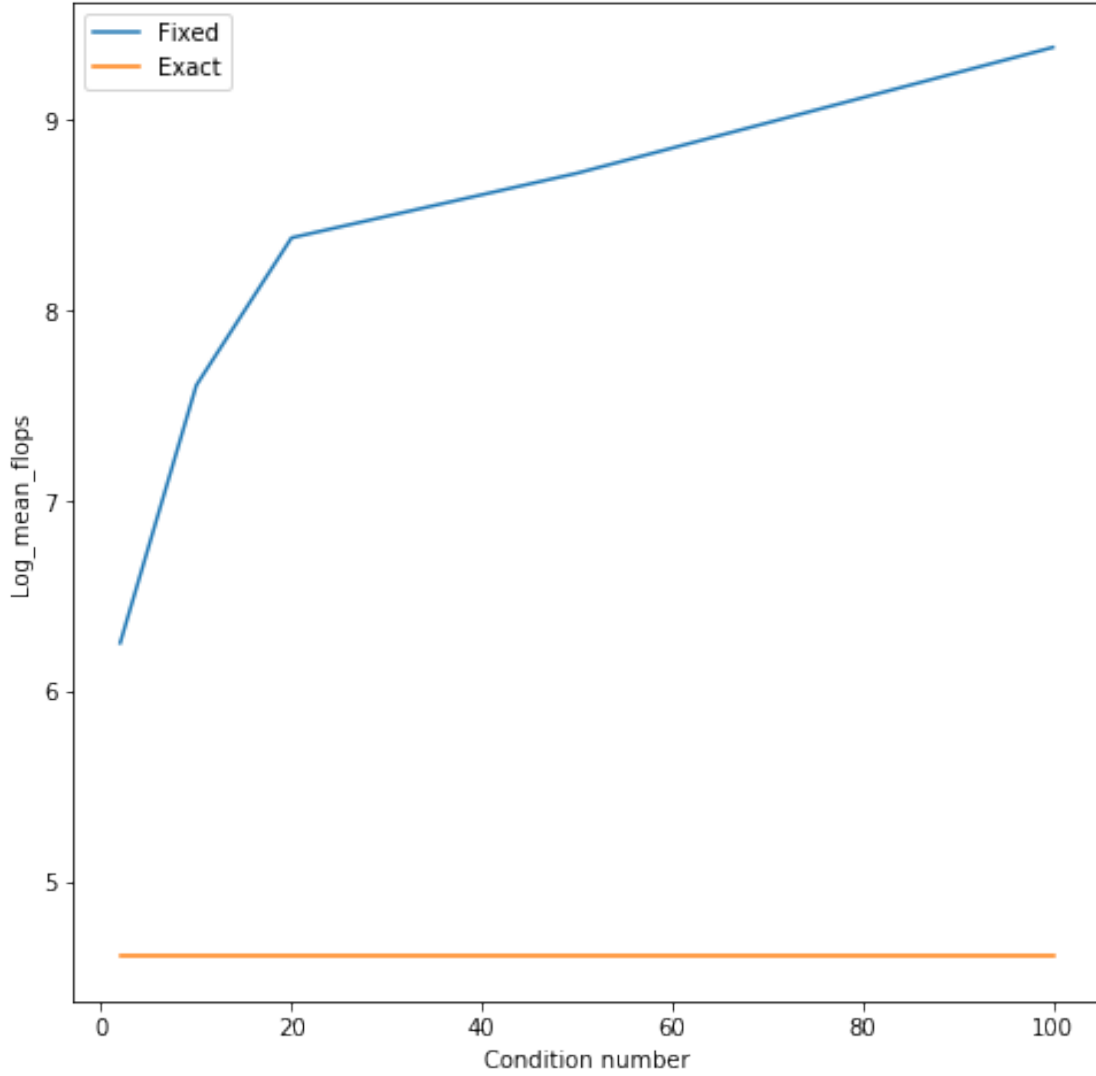
### 2.3.5 $\text{cond} = 100$

```
[71]: nf,ne = exact_vs_fixed(50,100,trial=12)
      flop_until_convergence_fx.append(nf)
      flop_until_convergence_ex.append(ne)
```



## 2.4 Condition Number VS Flops Until Convergence

```
[72]: plt.figure(figsize=(8,8))
plt.plot([2,10,20,50,100],np.log(np.
    ↪array(flop_until_convergence_fx)),label='Fixed')
plt.plot([2,10,20,50,100],np.log(np.
    ↪array(flop_until_convergence_ex)),label='Exact')
plt.xlabel('Condition number')
plt.ylabel('Log_mean_flops')
plt.legend()
plt.show()
```



### 3 Conclusion

- Exact step size coordinate proximal gradient descent (CPGD) always converge faster than fixed step size coordinate proxiaml gradient descent.
- When variable dimension grows, both of them take more flops to converge. Meanwhile, the increase rate of the number of flops they take to converge is almost log-linear as the dimension increase.
- When distribution of eigenvalues of  $Q$  changes, as the condition number of  $Q$  grows, Fixed step size CPGD take more flops to converge but the number of flops that exact step size CPGD takes to converge almost remains.