

Metropolis Adjusted Langevin Trajectories: a robust alternative to Hamiltonian Monte-Carlo.

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Joint work with



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Hamiltonian dynamics

- Goal: approximate sampling from a target with density

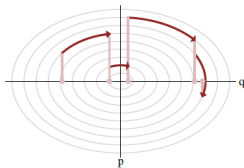
$$\Pi(\mathbf{x}) \propto \exp\{-\Phi(\mathbf{x})\}, \quad \mathbf{x} \in \mathbb{R}^d.$$

- **A1:** The potential $\Phi \in C^1(\mathbb{R}^d)$ has a Lipschitz gradient

$$\exists M > 0, \quad |\nabla\Phi(\mathbf{x}) - \nabla\Phi(\mathbf{y})| \leq M|\mathbf{x} - \mathbf{y}|, \quad \mathbf{x}, \mathbf{y} \in \mathbb{R}^d.$$

- Hamiltonian dynamics for $t \geq 0$:

$$d \begin{bmatrix} \mathbf{X}_t \\ \mathbf{V}_t \end{bmatrix} = \begin{bmatrix} \mathbf{V}_t \\ -\nabla\Phi(\mathbf{X}_t) \end{bmatrix} dt.$$



- Invariant measure: $\Pi \otimes \mathcal{N}_d(\mathbf{0}_d, \mathbf{I}_d)$ with density

$$\Pi_*(\mathbf{x}, \mathbf{v}) \propto \exp\{-\Phi(\mathbf{x}) - |\mathbf{v}|^2/2\}, \quad (\mathbf{x}, \mathbf{v}) \in \mathbb{R}^{2d}.$$

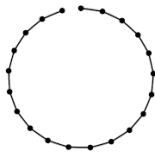
Leapfrog integrator

- Leapfrog: a standard integrator for Hamiltonian dynamics.
- For a time step $h > 0$, define $\theta_h : (\mathbf{x}_0, \mathbf{v}_0) \mapsto (\mathbf{x}_h, \mathbf{v}_h)$ as

$$\mathbf{v}_{h/2} = \mathbf{v}_0 - (h/2)\nabla\Phi(\mathbf{x}_0)$$

$$\mathbf{x}_h = \mathbf{x}_0 + h\mathbf{v}_{h/2}$$

$$\mathbf{v}_h = \mathbf{v}_{h/2} - (h/2)\nabla\Phi(\mathbf{x}_h).$$



- A trajectory is composed of $L = \lceil T/h \rceil$ steps: $\theta_h^L = \theta_h \circ \dots \circ \theta_h$.

Hamiltonian Monte Carlo

- Duane et al. 1987
- HMC for $h > 0$, $T > 0$. Set $L = \lceil T/h \rceil$.
 - refresh the momentum $\mathbf{V}' \leftarrow \boldsymbol{\xi} \sim \mathcal{N}_d(\mathbf{0}_d, \mathbf{I}_d)$
 - propose a trajectory $(\mathbf{X}_L, \mathbf{V}_L) = \boldsymbol{\theta}_h^L(\mathbf{X}_0, \mathbf{V}')$
 - accept with probability $\pi_*(\mathbf{X}_L, \mathbf{V}_L)/\pi_*(\mathbf{X}_0, \mathbf{V}')$
 - if rejected, flip the momentum $(\mathbf{X}_L, \mathbf{V}_L) \leftarrow (\mathbf{X}_0, -\mathbf{V}')$
- Remark: full refreshments erase the momentum flips.

Generalized Hamiltonian Monte Carlo

- Horowitz 1991
- GHMC for $h > 0$, $T > 0$, and **persistence** $\alpha \in [0, 1)$. Set $L = \lceil T/h \rceil$.
 - refresh the momentum $\mathbf{V}' \leftarrow \alpha \mathbf{V}_0 + \sqrt{1 - \alpha^2} \boldsymbol{\xi} \sim \mathcal{N}_d(\mathbf{0}_d, \mathbf{I}_d)$.
 - propose a trajectory $(\mathbf{X}_L, \mathbf{V}_L) = \boldsymbol{\theta}_h^L(\mathbf{X}_0, \mathbf{V}')$
 - accept with probability $\pi_*(\mathbf{X}_L, \mathbf{V}_L) / \pi_*(\mathbf{X}_0, \mathbf{V}')$
 - if rejected, flip the momentum $(\mathbf{X}_L, \mathbf{V}_L) \leftarrow (\mathbf{X}_0, -\mathbf{V}')$
- Remark: **momentum flips are only partially erased.**

HMC: tuning the time step

- Choosing h for a given T , when $\alpha = 0$ (full refreshments).
- **A2:** The potential writes $\Phi(\mathbf{x}) = \sum_{i=1}^d \phi(x_i)$ where $\phi \in C^4(\mathbb{R})$

$$\int_{\mathbb{R}} x^8 \exp\{\phi(x)\} dx < \infty, \quad \|\phi^{(k)}\|_{\infty} < \infty, \quad k = 2, 3, 4.$$

- Beskos et al. 2013: optimal scaling of the acceptance rate, as $d \rightarrow \infty$.
- Choose $h = \ell_T d^{-1/4}$ to get an asym. acceptance rate $a(\ell_T) \approx 65\%$.

HMC: tuning the integration time

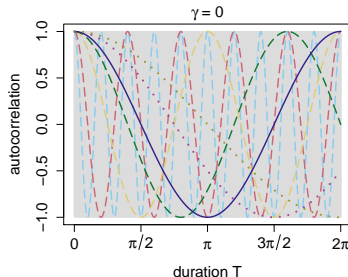
- Auto-Correlation Functions: $\rho_i(T) \triangleq \text{Corr}(X_i(T), X_i(0))$, $i = 1, \dots, d$.

- Heterogeneity of scales, Gaussian

$$\Phi(\mathbf{x}) = \sum_{i=1}^d x_i^2 / (2\sigma_i^2).$$

- Periodic ACFs

$$\rho_i(T) = \cos(T/\sigma_i).$$



- The worst ACF $\max_{i \in \llbracket 1, d \rrbracket} |\rho_i(T)|$ can be arbitrarily erratic and close to 1.
- Bou-Rabee and Sanz-Serna 2017: $T \sim \text{Exp}(\lambda)$, Randomized HMC.
- Smoothing effect: $\mathbb{E}[\rho_i(T)] = \frac{\sigma_i^2}{\sigma_i^2 + \lambda^{-2}} \leq \frac{\sigma_{\max}^2}{\sigma_{\max}^2 + \lambda^{-2}} \Rightarrow \text{monotonic}.$

Langevin diffusion

- Damping parameter $\gamma \geq 0$, a.k.a friction.

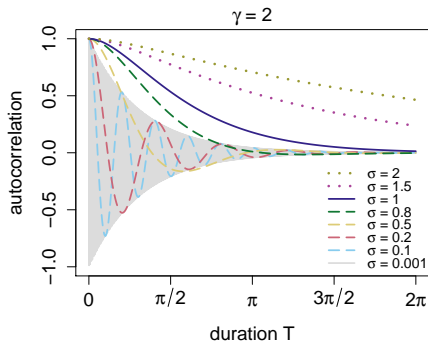
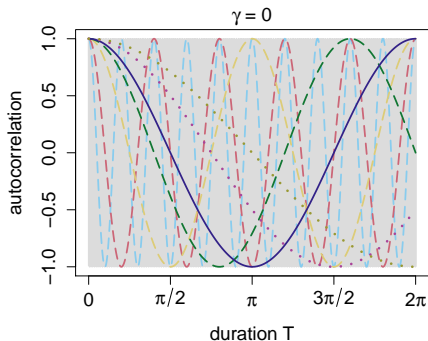
- Langevin SDE for $t \geq 0$:

$$d \begin{bmatrix} \mathbf{X}_t \\ \mathbf{V}_t \end{bmatrix} = \begin{bmatrix} \mathbf{V}_t \\ -\nabla \Phi(\mathbf{X}_t) \end{bmatrix} dt + \begin{bmatrix} \mathbf{0}_d \\ -\gamma \mathbf{V}_t dt + \sqrt{2\gamma} d\mathbf{W}_t \end{bmatrix}.$$

- Langevin dynamics = Hamiltonian dynamics with momentum refreshment continuously induced by a Brownian Motion $(\mathbf{W}_t)_{t \geq 0}$.
- Same invariant measure: $\Pi \otimes \mathcal{N}_d(\mathbf{0}_d, \mathbf{I}_d)$.

Control of the worst ACF

- ACF for HMC and the Langevin diffusion ($\gamma = 2$), for various $\sigma_i > 0$.



- Positive damping enables a uniform control of the correlations

$$\gamma = 2/\sigma_{\max} \Rightarrow \max_{i \in \llbracket 1, d \rrbracket} |\rho_{i,\gamma}(T)| \leq e^{-T/\sigma_{\max}} (1 + T/\sigma_{\max}).$$

Quantitative mixing rates

- Randomized HMC with parameters (λ, α) , a jump-type SDE for $t \geq 0$:

$$d \begin{bmatrix} \mathbf{X}_t \\ \mathbf{V}_t \end{bmatrix} = \begin{bmatrix} \mathbf{V}_t \\ -\nabla \Phi(\mathbf{X}_t) \end{bmatrix} dt + \begin{bmatrix} \mathbf{0}_d \\ (\alpha \mathbf{V}_{t-} + \sqrt{1-\alpha^2} \boldsymbol{\xi}_{N_{t-}} - \mathbf{V}_{t-}) dN_t \end{bmatrix}.$$

- **A3**: the potential $\Phi \in C^2(\mathbb{R}^d)$, such that for some $M \geq m > 0$

$$m\mathbf{I}_d \preceq \nabla^2 \Phi(\mathbf{x}) \preceq M\mathbf{I}_d, \quad \mathbf{x} \in \mathbb{R}^d.$$

- **Theorem**: Let $\lambda = \frac{2\sqrt{M+m}}{1-\alpha^2}$, then for any $\alpha \in [0, 1)$ we have

$$W_2((\nu \mathbf{P}^t)_{\mathbf{x}}, \Pi) \leq C e^{-rt} W_2(\nu_{\mathbf{x}}, \Pi), \quad \nu = \nu_{\mathbf{x}} \otimes \mathcal{N}_d(\mathbf{0}_d, \mathbf{I}_d)$$

$$\|\mathbf{P}^t f\| \leq C' e^{-rt} \|f\|, \quad f \in \mathbb{L}_0^2(\Pi)$$

where

$$r = \frac{1+\alpha}{2} \left(\frac{m}{\sqrt{M+m}} \right), \quad C, C' \leq 1.56$$

Quantitative mixing rates

- Interpolation of Deligiannidis et al. 2018 and Dalalyan and R-D 2020.
- Randomized HMC and Langevin diffusion generators, for $f \in C_c^\infty(\mathbb{R}^{2d})$.

$$\begin{aligned}\mathcal{L}_{\lambda,\alpha}^{\text{RH}} &\triangleq \mathcal{L}^{\text{H}} + \lambda \mathcal{R}_\alpha^{\text{PP}} & \mathcal{L}^{\text{H}} f(\mathbf{x}, \mathbf{v}) &\triangleq \mathbf{v}^\top \nabla_{\mathbf{x}} f(\mathbf{x}, \mathbf{v}) - \nabla \Phi(\mathbf{x})^\top \nabla_{\mathbf{v}} f(\mathbf{x}, \mathbf{v}) \\ \mathcal{L}_\gamma^{\text{LD}} &\triangleq \mathcal{L}^{\text{H}} + \gamma \mathcal{R}^{\text{BM}} & \mathcal{R}_\alpha^{\text{PP}} f(\mathbf{x}, \mathbf{v}) &\triangleq \mathbb{E} \left[f(\mathbf{x}, \alpha \mathbf{v} + \sqrt{1 - \alpha^2} \boldsymbol{\xi}) \right] - f(\mathbf{x}, \mathbf{v}) \\ & & \mathcal{R}^{\text{BM}} f(\mathbf{x}, \mathbf{v}) &\triangleq -\mathbf{v}^\top \nabla_{\mathbf{v}} f(\mathbf{x}, \mathbf{v}) + \Delta_{\mathbf{v}} f(\mathbf{x}, \mathbf{v}).\end{aligned}$$

- **Proposition:** If $\lambda = \frac{2\gamma}{1-\alpha^2}$ then $\|\mathcal{L}_{\lambda,\alpha}^{\text{RH}} f - \mathcal{L}_\gamma^{\text{LD}} f\|_\infty \rightarrow 0$ as $\alpha \rightarrow 1$.
- The Langevin diffusion is a limit of Randomized HMC that achieves the fastest exponential mixing rate for strongly log-concave targets.
- Motivates the construction of a sampler drawing Langevin trajectories.

A discretization for Langevin Trajectories

- A standard integrator for Langevin dynamics (**A1** \Rightarrow strong accuracy):
- Set $\alpha = e^{-\gamma h/2}$, let $(\mathbf{x}_h, \mathbf{v}_h) \sim \mathbf{Q}_{h,\gamma}((\mathbf{x}_0, \mathbf{v}_0), \cdot)$ such that

$$\mathbf{v}'_0 = \alpha \mathbf{v}_0 + \sqrt{1 - \alpha^2} \boldsymbol{\xi}$$

$$\mathbf{v}_{h/2} = \mathbf{v}'_0 - (h/2) \nabla \Phi(\mathbf{x}_0)$$

$$\mathbf{x}_h = \mathbf{x}_0 + h \mathbf{v}_{h/2}$$

$$\mathbf{v}'_h = \mathbf{v}_{h/2} - (h/2) \nabla \Phi(\mathbf{x}_h)$$

$$\mathbf{v}_h = \alpha \mathbf{v}'_h + \sqrt{1 - \alpha^2} \boldsymbol{\xi}'.$$

- Langevin trajectory, $L = \lceil T/h \rceil$ steps: $(\mathbf{X}_L, \mathbf{V}_L) \sim \mathbf{Q}_{h,\gamma}^L((\mathbf{x}_0, \mathbf{v}_0), \cdot)$

Metropolis Adjusted Langevin Trajectories

- MALT for $h > 0$, $T > 0$, and **damping** $\gamma \geq 0$. Set $L = \lceil T/h \rceil$.
 - **refresh the momentum** $\mathbf{V}_0 \leftarrow \boldsymbol{\xi} \sim \mathcal{N}_d(\mathbf{0}_d, \mathbf{I}_d)$
 - propose $(\mathbf{X}_L, \mathbf{V}_L) \sim \mathbf{Q}_{h,\gamma}^L((\mathbf{X}_0, \mathbf{V}_0), \cdot)$
 - accept with probability

$$\frac{\pi_*(\mathbf{X}_L, \mathbf{V}_L)}{\pi_*(\mathbf{X}_0, \mathbf{V}_0)} \times \prod_{i=1}^L \frac{q_{h,\gamma}((\mathbf{X}_i, -\mathbf{V}_i), (\mathbf{X}_{i-1}, -\mathbf{V}_{i-1}))}{q_{h,\gamma}((\mathbf{X}_{i-1}, \mathbf{V}_{i-1}), (\mathbf{X}_i, \mathbf{V}_i))}$$

- if rejected, flip the momentum $(\mathbf{X}_L, \mathbf{V}_L) \leftarrow (\mathbf{X}_0, -\mathbf{V}_0)$

- Remark: **full refreshments erase the momentum flips.**

Algorithm 1: MALT (h, T, γ) , set $L = \lfloor T/h \rfloor$ and $\alpha = \exp\{-\gamma h\}$

```
1 for  $n \leftarrow 1$  to  $N$  do
2   draw fresh momentum start  $\mathbf{V}' \sim \mathcal{N}_d(\mathbf{0}_d, \mathbf{I}_d)$ 
3   set  $(\mathbf{x}_0, \mathbf{v}_0) \leftarrow (\mathbf{X}^{n-1}, \mathbf{V}')$  and  $\Delta \leftarrow 0$ 
4   for  $i \leftarrow 1$  to  $L$  do
5     draw  $\boldsymbol{\xi} \sim \mathcal{N}_d(\mathbf{0}_d, \mathbf{I}_d)$  and refresh  $\mathbf{v}'_{i-1} = \alpha \mathbf{v}_{i-1} + \sqrt{1 - \alpha^2} \boldsymbol{\xi}$ 
6     perform a Leapfrog step  $(\mathbf{x}_i, \mathbf{v}_i) = \boldsymbol{\theta}_h(\mathbf{x}_{i-1}, \mathbf{v}'_{i-1})$ 
7     update  $\Delta \leftarrow \Delta + (|\mathbf{v}_i|^2 - |\mathbf{v}'_{i-1}|^2)/2$ 
8   end
9   set  $(\mathbf{X}^n, \mathbf{V}^n) \leftarrow (\mathbf{x}_L, \mathbf{v}_L)$  and  $\Delta \leftarrow \Delta + \Phi(\mathbf{x}_L) - \Phi(\mathbf{x}_0)$ 
10  draw a uniform random variable  $U$  on  $(0, 1)$ 
11  if  $U > \exp\{-\Delta\}$  then
12    reject  $\mathbf{X}^n \leftarrow \mathbf{X}^{n-1}$ 
13  end
14 end
15 return  $\mathbf{X}^1, \dots, \mathbf{X}^N$ .
```

} Propose a Langevin trajectory.

Metropolis Adjusted Langevin Trajectories

- A neat Metropolis adjustment for the Langevin diffusion.
- The length of the trajectories can be chosen by the user.
- Momentum flips can be erased by full refreshments.
- For $\gamma > 0$ the trajectories are ergodic \Rightarrow no U-turns.
- Positive damping enables control of the worst ACF.
- A robust extension to HMC: what about tuning & scaling?

Optimal scaling: an extension to positive friction

- Choosing h for a given T and friction $\gamma \geq 0$?

- **A2:** The potential writes $\Phi(\boldsymbol{x}) = \sum_{i=1}^d \phi(x_i)$ where $\phi \in C^4(\mathbb{R})$

$$\int_{\mathbb{R}} x^8 \exp\{\phi(x)\} dx < \infty, \quad \|\phi^{(k)}\|_{\infty} < \infty, \quad k = 2, 3, 4.$$

- **Theorem:** optimal scaling of the acceptance rate, as $d \rightarrow \infty$.
- Choose $h = \ell_T d^{-1/4}$ to get an asym. acceptance rate $a(\ell_T) \approx 65\%$.
- An extension of Beskos et al. 2013 to any friction $\gamma \geq 0$.

Numerical illustration

- Gaussian: $\Phi(\mathbf{x}) = \sum_{i=1}^d x_i^2 / (2\sigma_i^2)$. Heterogeneous scales: $\sigma_i^2 = i/d$.

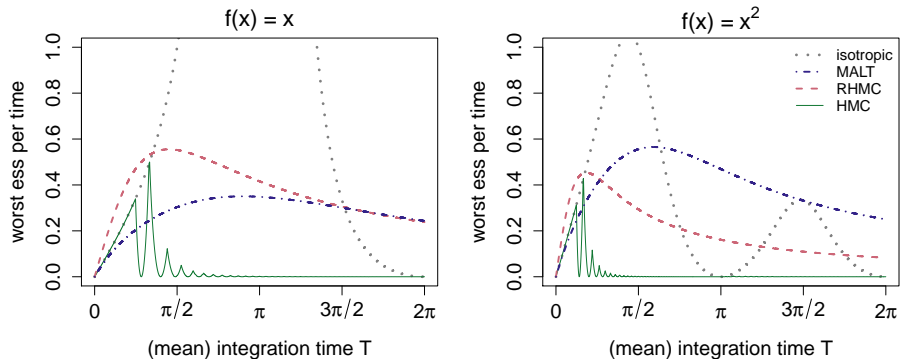


Figure: Gaussian $d=50$. Worst ESS per time for estimating the mean and variance.

Numerical illustration

- Setting: $h > 0$ is fixed to obtain acceptance rates close to 65%.
- Objective: tuning L to obtain good efficiency for every function.

Table: Gaussian $d=50$. Worst ESS per gradient evaluation for various functions.

	odd				even			
$f(x)$	x	x^3	$\text{sgn}(x)$	$\sin(x)$	x^2	x^4	$e^{- x }$	$\cos(x)$
MALT: $L = 8$	0.25	0.31	0.31	0.27	0.40	0.42	0.43	0.40
RHMC: $L = 5$	0.40	0.43	0.45	0.41	0.29	0.31	0.31	0.29
HMC: $L = 3$	0.19	0.25	0.26	0.21	0.00	0.00	0.00	0.00
MALA ($L = 1$)	0.06	0.08	0.09	0.07	0.12	0.12	0.16	0.13

Summary of contributions

- Langevin diffusion is a limit of Randomized HMC that achieves the fastest exponential mixing rate for strongly log-concave targets.
- Positive damping enables control of the worst ACF.
- MALT, a neat Metropolis correction for Langevin trajectories:
 - the length of the trajectories can be chosen by the user
 - momentum flips can be erased by full refreshments
- Optimal scaling, an extension of Beskos et al. 2013: we establish $d^{1/4}$ scaling for any damping, without additional assumptions.

References I

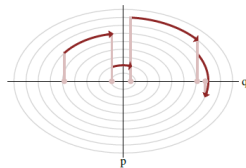
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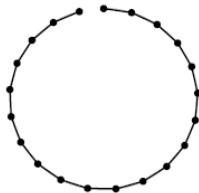
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Pictures

- Hamiltonian dynamics: Betancourt 2017



- Leapfrog integrator: Neal et al. 2011



Thank you !