



Length: Maximum of 2 pages, including references.

TITLE (TIMES NEW ROMAN, UPPERCASE, font size 11)

Author(s) Full name in Times New Roman Bold 11

Institution, country, and email in Times New Roman 11

(Include this information for each author)

Abstract: 100 words. Times New Roman 11. Line spacing 1.5

Keywords: Maximum of four.

1. Introduction

Times New Roman 11. Line spacing 1.5

2. Methods

Times New Roman 11. Line spacing 1.5

3. Results

Times New Roman 11. Line spacing 1.5. Tables and figures must follow APA format

4. Discussion

Times New Roman 11. Line spacing 1.5

5. Conclusions

Times New Roman 11. Line spacing 1.5

6. References

[APA](#) Format. List only those cited in alphabetical order. Examples: [1] and [2].

- [1] M. A. Gomes, G. L. M. Silveira, and A. A. G. Siqueira. Gait pattern adaptation for an active lower-limb orthosis based on neural networks. *Advanced Robotics*, 25(1):1903–1925, 2011.



- [2] J C Perez Ibarra, W M Santos, H I Krebs, and A A G Siqueira. Adaptive impedance control for robot-aided rehabilitation of ankle movements. In 5th IEEE RAS & EMBS International Conference on Biomedical Robotics and Biomechatronics, pages 664–669, São Paulo, Brazil, 2014.