Calculus of Variations

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1 Introduction

The objects of calculus of variations are so-called functionals, i.e. functions of functions. The main interests are the critical points of these functionals. Since such critical points are often solutions to (elliptic) PDEs. We will therefore look for minima and saddle points.

Example 1.1 (soap bubbles). *Which object encloses a fixed volume and has smallest surface area?*
Formulation:

$$\mathcal{F} : \{\textit{surfaces enclosing volume } v_0\} \to \mathbb{R}_{\geq 0}$$

The minimizer is a sphere.

1.1 mathematical formulation

Let X be a Banach space. Let $\varnothing \neq U \subset X$ and

$$E : U \to \mathbb{R}$$

be a functional.
Now, if E is bounded from below (i.e. $\exists M > 0 : E(u) \geq -M \ \forall u \in U$), is there a $u \in U$ s.t. $E(u) = \inf_{v \in U} E(v)$? Are there other critical points?
There are two ways to approach the first question.

1. if U is open and E is differentiable then look for a solution to

   $$E'(u) = 0$$

   (called the classical method in CV). This will lead us to u being a solution to a PDE.

2. take a sequence $(u_n)_{n \in \mathbb{N}} \subset U$ s.t. $E(u_n) \to \inf_{v \in U} E(v)$ (a minimizing sequence).

   (a) Find a topology s.t. $\exists (u_{n_k})_{k \in \mathbb{N}}, u \in U$ with

   $$u_{n_k} \to u$$

   in this topology.

   (b) check if $E(u) \leq \liminf_{k \to \infty} E(u_{n_k})$.

2 First variation and convexity

2.1 First variation

We fix X to be a Banach space

Definition 2.1. Let $\varnothing \neq V \subset X$ be open. Let $E : V \to \mathbb{R}$. We say that E is Fréchet differentiable at $u \in V$ if $\exists A \in L(X, \mathbb{R})$ (a linear bounded map) s.t.

$$\lim_{||\varphi||_x \to 0} \frac{E(u+\varphi) - E(u) - A\varphi}{||\varphi||_x} = 0$$

A is called the Fréchet derivative of E at u denoted by $E'(u)$.

Definition 2.2 (First variation)**.** Let $\varnothing \neq V \subset X$, $E : V \to \mathbb{R}$ and $u \in V$. Let $\varphi \in X$ s.t.

$$\exists \delta > 0 \text{ s.t. } u + t\varphi \in V \; \forall t \in (-\delta, \delta)$$

If

$$(-\delta, \delta) \ni t \mapsto E(u + t\varphi) \in \mathbb{R}$$

is differentiable at $t = 0$ we say that E has first in variation u in direction φ and write

$$\delta E(u)(\varphi) = \frac{d}{dt} E(u + t\varphi)|_{t=0}$$

Theorem 2.3 (Fundamental Lemma of CV)**.** *Let $\Omega \subset \mathbb{R}^n$ open, $w \in L^1_{loc}(\Omega)$ (i.e. $\forall K \subset \Omega$ compact, $w \in L^1(K)$). If*

$$\int_\Omega w\varphi \, dx = 0 \; \forall \varphi \in C_0^\infty(\Omega)$$

then $w = 0$ a.e.

Corollary 2.4. *Let $n \in \mathbb{N}$, $u \in L^1_{loc}((a,b))$ s.t.*

$$\int_a^b u \frac{d^n}{dx^n} \varphi \, dx = 0 \; \forall \varphi \in c_0^\infty((a,b))$$

Then $\exists a_1, ..., a_n \in \mathbb{R}$ s.t.

$$u(x) = \sum_{i=0}^{n-1} a_i x^i$$

Definition 2.5. Let $u \in L^1_{loc}(\Omega)$. We say that u is once weakly differentiable if $\forall i \in$

$\{1, 2, ..., n\}$ $\exists v_i \in L^1_{loc}(\Omega)$ s.t.

$$\int_\Omega u \partial_{x_i} \varphi \, dx = - \int_\Omega v_i \varphi \, dx \; \forall \varphi \in C_0^\infty(\Omega)$$

In that case $\partial_i u = v_i$.
Similarly, if $\alpha \in \mathbb{N}_0^n$ we say u is α-weakly differentiable if

$$\exists v_\alpha \in L^1_{loc} \text{ s.t. } \int_\Omega u D^\alpha \varphi \, dx = (-1)^{|\alpha|} \int v_\alpha \varphi \, dx$$

Definition 2.6 (Sobolev spaces)**.** For $m \in \mathbb{N}$, $p \in (1, \infty)$, define

$$W^{m,p}(\Omega) = \{u \in L^p(\Omega) \text{ s.t. } D^\alpha u \in L^p(\Omega) \; \forall \alpha \in \mathbb{N}_0^n, \; |\alpha| \leq m\}$$

This is a vector space and can be equipped with the norm

$$||u||_{W^{m,p}} = \left(\sum_{(\alpha) \leq m} ||D^\alpha u||^p_{L^p(\Omega)} \right)^{\frac{1}{p}}$$

Theorem 2.7. *$(W^{m,p}(\Omega), || \cdot ||_{W^{m,p}})$ is a Banach space and for $p = 2$ it's a Hilbert space. Finally, $C^\infty(\Omega) \cap W^{m,p}(\Omega)$ is dense in $W^{m,p}(\Omega)$.*

Definition 2.8. $W_0^{m,p}(\Omega) = \overline{C_0^\infty(\Omega)}^{W^{m,p}(\Omega)}$, i.w. $f \in W_0^{m,p}(\Omega)$ if

$$\exists (f_n)_{n \in \mathbb{N}} \subset C_0^\infty(\Omega)$$

s.t.

$$||f - f_n||_{W^{m,p}} \to 0, \, n \to \infty$$

Remark 2.9. $W_0^{m,p}(\Omega) \subset W^{m,p}(\Omega)$

Definition 2.10 (weak solution of Poisson equation)**.** We say that u is a <u>weak solution</u> of

$$\begin{cases} -\nabla u & = f, \text{ in } \Omega \\ u & = 0, \text{ on } \partial\Omega \end{cases}$$

if $u \in W_0^{1,2}(\Omega)$ and

$$\int_\Omega (\nabla u \nabla \varphi - f\varphi) \, dx = 0 \; \forall \varphi \in C_0^\infty(\Omega)$$

3 Direct Methods

Lemma 3.1 (Poincaré-inequality)**.** *$\exists C = C(\Omega)$ s.t.*

$$||u||_{L^2} \leq C||\nabla u||_{L^2} \; \forall u \in W_0^{1,2}(\Omega)$$

Lemma 3.2. *Define $||u||_{W_0^{1,2}(\Omega)} = ||\nabla u||_{L^2}$, then $||\cdot||_{W^{1,2}}$ and $||\cdot||_{W_0^{1,2}}$ are equivalent in $W_0^{1,2}(\Omega)$.*

Theorem 3.3. *Every bounded sequence in a Hilbert space admits a weakly convergent subsequence. That means given $(v_k)_{k\in\mathbb{N}} \subset H$ bounded in Hilbert space H $\exists (v_{k_l})_{l\in\mathbb{N}} \exists v \in H$ s.t.*

$$\langle v_{k_l}, w\rangle_H \to \langle v, w\rangle_H \; \forall w \in H$$

Theorem 3.4. *If $(u_k)_{k\in\mathbb{N}}$ converges weakly to u in H, then*

$$||u||_H \leq \liminf_{k\to\infty} ||u_k||_H$$

Remark 3.5. A functional $T : X \to Y$ is compact if $\forall (x_k)_{k\in\mathbb{N}}$ bounded in X, the sequence $(Tx_n)_{n\in\mathbb{N}} \subset Y$ admits a convergent subsequence.

Theorem 3.6. *The inclusion map $W_0^{1,2} \to L^2(\Omega)$ that maps $u \mapsto u$ is compact.*

3.1 Some concepts from functional analysis

Let X be a $\mathbb{R}$-Banach space.

Definition 3.7. We define the dual space

$$X' = L(X, \mathbb{R}) = \{T : X \to \mathbb{R} \text{ linear and continuous}\}$$

Lemma 3.8. *For linear maps, the following are equivalent:*

1. *continuity*
2. *continuity at 0*
3. *boundedness*

Definition 3.9. Similarly, the bidual space

$$X'' = L(X', \mathbb{R})$$

is also a Banach space. There exists a canonical map

$$i_X : X \to X''$$

For $x \in X$ we define the canonical map

$$i_x : X \to X''$$

by

$$i_X(x)(T) = Tx \text{ for } T \in X'$$

i_X is well-defined and $i_X(x)$ is an element of the bidual space. Moreover, the map is injective and an isometry. Spaces X where i_X is also surjective are also called reflexive spaces.

Example 3.10. *All Hilbert spaces, L^p spaces and all Sobolev spaces are reflexive for $1 < p < \infty$.*

Definition 3.11. Let $(x_k)_{k\in\mathbb{N}} \subset X$. x_k converges weakly to $x \in X$ if for all $T \in X'$

$$T(x_k) \to T(x) \text{ for } k \to \infty$$

Theorem 3.12. *Every bounded sequence in a reflexive space admits a weakly convergent subsequence.*

Theorem 3.13. *Let $(X, ||\cdot||)$ be a reflexive Banach space. Let $M \subset X$ and $M \neq \varnothing$ a weakly sequentially closed subset X. Let $E : M \to \mathbb{R}$ s.t.*

1. *$E(y) \to \infty$ if $||y||_X \to \infty$*
2. *E is sequentially weakly lower semi-continuous that is if x_k converges weakly to $x \in X$, than $E(x) \leq \liminf_{k\to\infty} E(x_k)$*

Then, E is bounded from below and $\exists x \in M$ s.t.

$$E(x) = \inf\{E(y) : \ y \in M\}$$

4 A partition problem and functions of bounded variation

Given $\Omega \subset \mathbb{R}^n$ bounded and smooth, is there an $E \subseteq \Omega$ s.t.

$$|E| = |\Omega \setminus E|$$

and $H^{n-1}(\partial E \cap \Omega)$ is minimal?

4.1 Motivation

Definition 4.1. If $E \subset \Omega$ is smooth, then

$$H^{n-1}(\partial E \cap \Omega) = \int_{\partial E \cap \Omega} 1 dS(x) = \int_{\partial E \cap \Omega} \langle v(x), v(x) \rangle dS(x)$$

Let $\varphi \in C : 0^\infty(\Omega; \mathbb{R}^n)$ s.t. $\varphi(x) = \lambda(x) v(x)$ where $\lambda(x) \in [0, 1]$ and $x \in \partial E$. Then

$$H^{n-1}(\partial E \cap \Omega) \geq \int_{\partial E \cap \Omega} \langle \varphi(x), v(x) \rangle dS(x) = \int_{\partial E} \langle \varphi(x), v(x) \rangle dS(x) = \int_\Omega \chi_E div(\varphi(x)) dx$$

Since D is smooth, $\exists \psi : \mathbb{R}^n \to \mathbb{R}^n$ with

- $\psi(x) = v(x)$ on $\partial E \cap \Omega$
- $\psi(x) = 0$ "some bit away from Ω"
- $||\psi(x)||_2 \leq 1 \ \forall x \in \mathbb{R}^n$ and $||\psi||_\infty \leq 1$.

Now, let ξ_ε be the bump function on Ω which converges to χ_Ω for $\varepsilon \to 0$. Then $\varphi_\varepsilon = \xi_\varepsilon \psi$ satisfies $\varphi_\varepsilon \in C_0^\infty(\Omega, \mathbb{R}^n)$ and $||\varphi_\varepsilon||_\infty \leq 1$. Now

$$H^{n-1}(\partial E \cap \Omega) \overset{\varepsilon \searrow 0}{\to} \int_{\partial E \cap \Omega} dS(x) = H^{n-1}(\partial E \cap \Omega)$$

Hence

$$H^{n-1}(\partial E \cap \Omega) = \sup\{ \int_\Omega \chi_E div \varphi dx \mid \varphi \in C_0^\infty(\Omega, \mathbb{R}^n), \ ||\varphi||_\infty \leq 1 \}$$

The idea is to use this expression for non-smooth E.

4.2 Functions of bounded variations

Let $\Omega \subset \mathbb{R}^n$ be open and bounded.

Definition 4.2. We define for $v \in L^1(\Omega)$

$$\int_\Omega |Dv| = \sup\{ \int_\Omega v(x) div \varphi(x) dx \mid \varphi \in C_0^\infty(\Omega; \mathbb{R}^n), \ ||\varphi||_\infty \leq 1 \}$$

the total variation of v.
We say that v is of bounded variation, if

$$\int |Dv| < \infty$$

Finally, we define $BV(\Omega) = \{v \in L^1(\Omega) : \int_\Omega |Dv| < \infty\}$