

view_frames Result

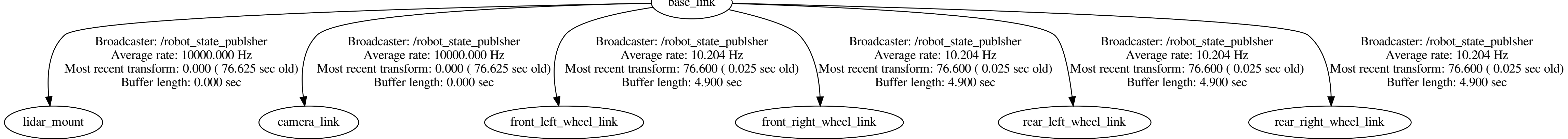
Recorded at time: 76.625

base_footprint



Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (76.625 sec old)
Buffer length: 0.000 sec

base_link



Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (76.625 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (76.625 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 76.600 (0.025 sec old)
Buffer length: 4.900 sec

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Average rate: 10.204 Hz
Most recent transform: 76.600 (0.025 sec old)
Buffer length: 4.900 sec

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Most recent transform: 76.600 (0.025 sec old)
Buffer length: 4.900 sec

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Average rate: 10.204 Hz
Most recent transform: 76.600 (0.025 sec old)
Buffer length: 4.900 sec

lidar_mount

camera_link

front_left_wheel_link

front_right_wheel_link

rear_left_wheel_link

rear_right_wheel_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (76.625 sec old)
Buffer length: 0.000 sec

lidar

