

# Image Segmentation

Computer Vision

Assignment

# Overview

- Task 1: implement Mean-Shift to segment image (40 pts).
- Task 2: implement simplified SegNet on multi-digit MNIST dataset (60 pts).

# Mean-Shift

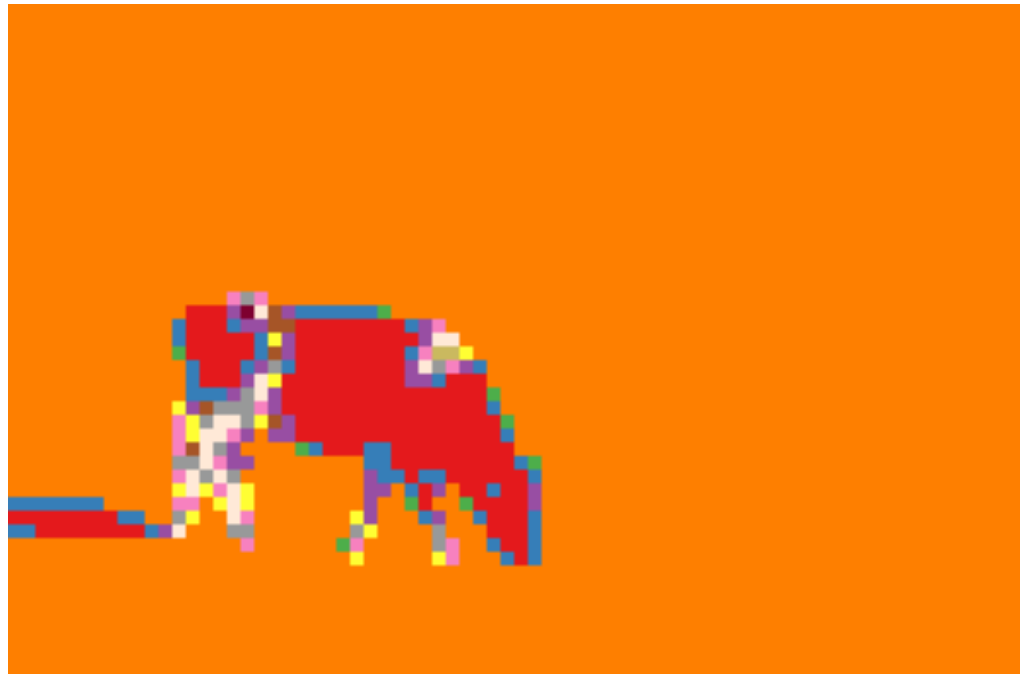
- Input image



Input Image

# Mean-Shift

- Goal – segment the image in CIELAB color space (preprocessing already provided in code)



Expected Segments

# Mean-Shift

- In each step, for each point:
  - Compute the distances from this point to all points (including current point) within a radius. In this assignment we set this radius to positive infinity so that you can have an easier implementation
  - Compute weight of every point as a Gaussian kernel function of distance, with bandwidth=2.5
  - Compute weighted mean of all points (including current point), then update current point with this weighted mean

# Mean-Shift – Implementation Details

- Within each mean-shift step, you should update all points **out of place**, i.e the order of update should not affect the final output.
- Run 20 steps.
- After implementing the basic mean-shift algorithm, try to accelerate it by taking advantage of batch processing.

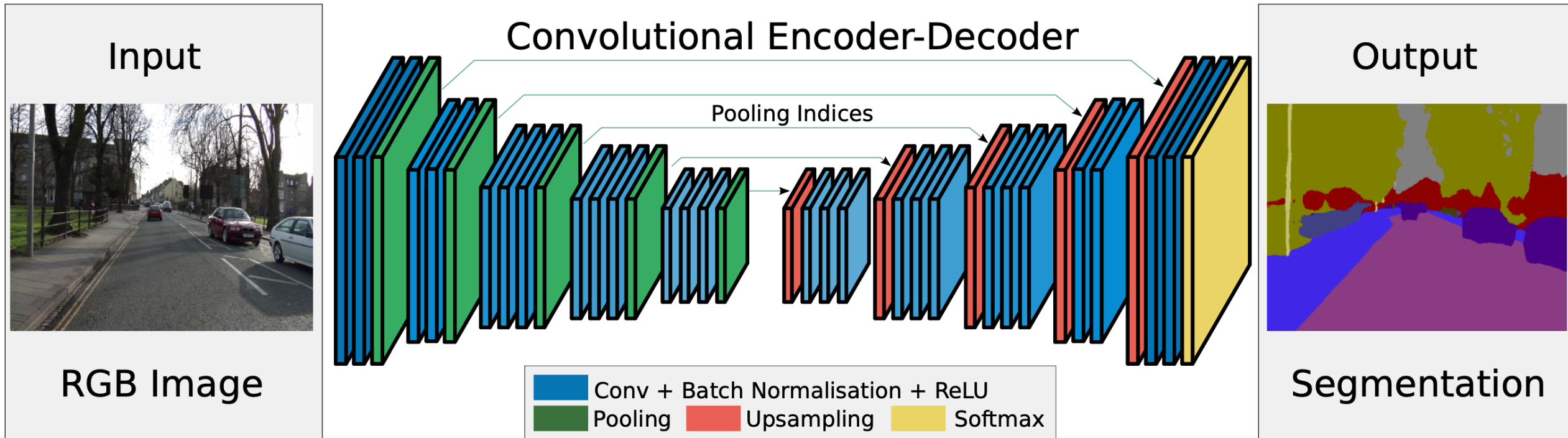
# Mean-Shift

- Pseudo code

```
while not_converged():  
    for i, point in enumerate(points):  
        # distance for the given point to all points  
        distances = distance(point, points)  
  
        # turn distance into weights using a gaussian  
        weights = gaussian(dist, bandwidth=2.5)  
        # update the point by calculating weighted mean of all points  
        points[i] = update_point(weight, X)  
  
return points
```

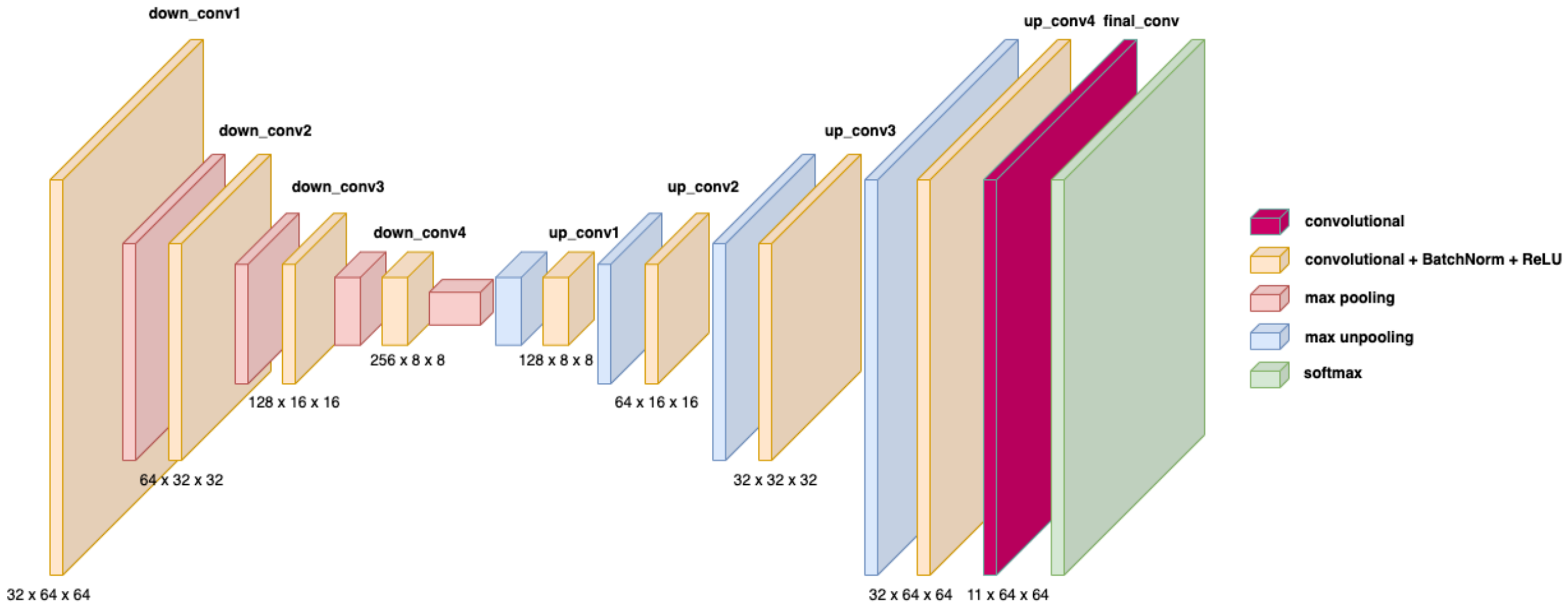
Standard deviation for Gaussian

# SegNet – From the Lecture





# SegNet – Simplified Version



# Basic Modules

- Conv2d, BatchNorm2d, MaxPool2d and MaxUnpool2d

# Basic Modules – BatchNorm2d

<https://pytorch.org/docs/stable/generated/torch.nn.BatchNorm2d.html>

```
CLASS torch.nn.BatchNorm2d(num_features, eps=1e-05, momentum=0.1, affine=True,  
                             track_running_stats=True, device=None, dtype=None) [SOURCE]
```

Applies Batch Normalization over a 4D input (a mini-batch of 2D inputs with additional channel dimension) as described in the paper [Batch Normalization: Accelerating Deep Network Training by Reducing Internal Covariate Shift](#).

$$y = \frac{x - \mathbf{E}[x]}{\sqrt{\mathbf{Var}[x] + \epsilon}} * \gamma + \beta$$

The mean and standard-deviation are calculated per-dimension over the mini-batches and  $\gamma$  and  $\beta$  are learnable parameter vectors of size  $C$  (where  $C$  is the input size). By default, the elements of  $\gamma$  are set to 1 and the elements of  $\beta$  are set to 0. The standard-deviation is calculated via the biased estimator, equivalent to `torch.var(input, unbiased=False)`.

Also by default, during training this layer keeps running estimates of its computed mean and variance, which are then used for normalization during evaluation. The running estimates are kept with a default `momentum` of 0.1.

If `track_running_stats` is set to `False`, this layer then does not keep running estimates, and batch statistics are instead used during evaluation time as well.

# Basic Modules – MaxUnpool2d

<https://pytorch.org/docs/stable/generated/torch.nn.MaxUnpool2d.html>

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**CLASS** `torch.nn.MaxUnpool2d(kernel_size, stride=None, padding=0)` [\[SOURCE\]](#)

Computes a partial inverse of `MaxPool2d`.

`MaxPool2d` is not fully invertible, since the non-maximal values are lost.

`MaxUnpool2d` takes in as input the output of `MaxPool2d` including the indices of the maximal values and computes a partial inverse in which all non-maximal values are set to zero.

# Loss – Per-pixel Cross-Entropy Loss

```
class CrossEntropy2D(nn.Module):
    def __init__(self, ignore_index, reduction='mean', weight=None):
        """Initialize the module

        Args:
            ignore_index: specify which the label index to ignore.
            reduction (str): reduction method. See torch.nn.functional.cross_entropy for details.
            output_dir (str): output directory to save the checkpoint
            weight: weight for samples. See torch.nn.functional.cross_entropy for details.
        """
        super(CrossEntropy2D, self).__init__()
        self.weight = weight
        self.ignore_index = ignore_index
        self.reduction = reduction

    def forward(self, output, target, resize_scores=True):
        """Forward pass of the loss function

        Args:
            output (torch.nn.Tensor): output logits, i.e. network predictions w.o. softmax activation.
            target (torch.nn.Tensor): ground truth labels.
            resize_scores (bool): if set to True, when target and output have different widths or heights,
                upsample output bilinearly to match target resolution. Otherwise, downsample
                target using nearest neighbor to match input.

        Returns:
            loss (torch.nn.Tensor): loss between output and target.
        """
        _assert_no_grad(target)

        b, c, h, w = output.size()
        tb, th, tw = target.size()

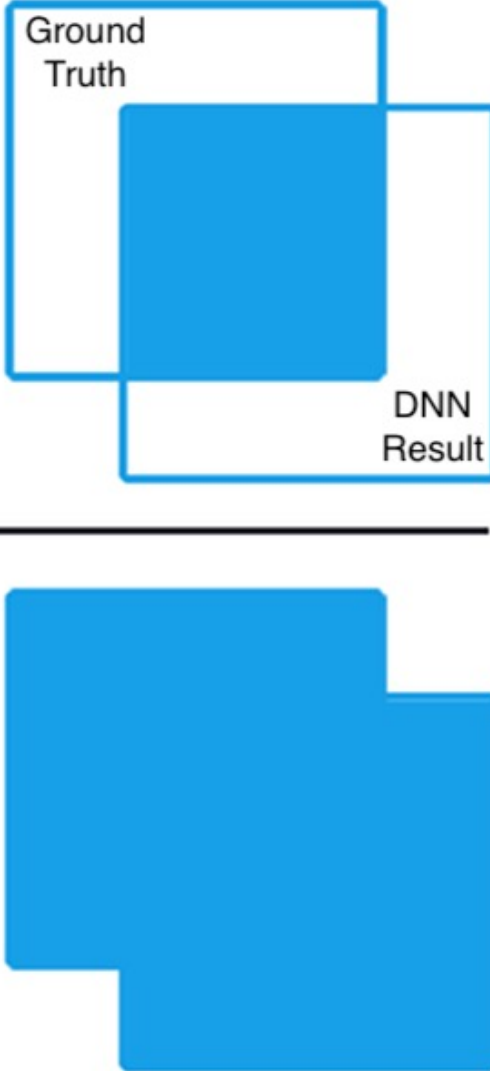
        assert(b == tb)

        # Handle inconsistent size between input and target
        if resize_scores:
            if h != th or w != tw: # upsample logits
                output = nn.functional.interpolate(output, size=(th, tw), mode="bilinear", align_corners=False)
            else:
                if h != th or w != tw: # downsample labels
                    target = nn.functional.interpolate(target.view(b, 1, th, tw).float(), size=(h, w), mode="nearest").view(b, h, w).long()

        loss = nn.functional.cross_entropy(
            output, target, weight=self.weight, ignore_index=self.ignore_index, reduction=self.reduction
        )

        return loss
```

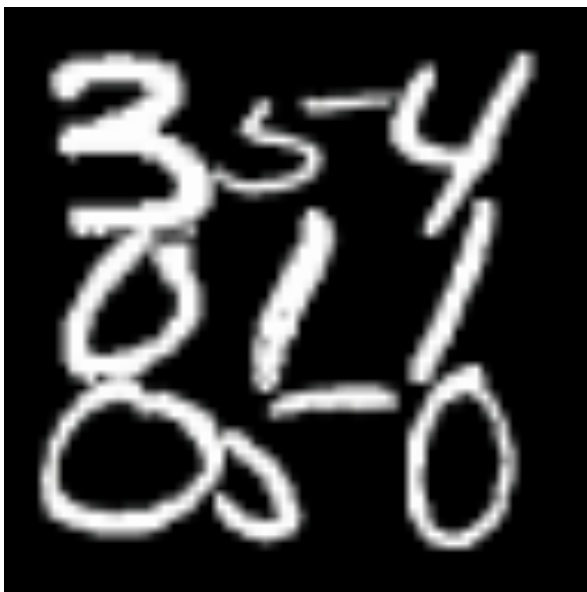
# Evaluation Metric – Intersection Over Union

$$\text{IoU} = \frac{\text{Area of Overlap}}{\text{Area of Union}}$$


The diagram illustrates the Intersection Over Union (IoU) metric. It shows two overlapping rectangles: a 'Ground Truth' rectangle (top-left) and a 'DNN Result' rectangle (bottom-right). The intersection of the two rectangles is shaded blue. Below the rectangles, the union of the two rectangles is also shaded blue, representing the 'Area of Union'.

# SegNet

- Dataset – multi-digit MNIST



Input Image (64x64)



GT Labels

# Summary

- Materials will be available later today.
- Assignment is due 22.11.2024 at midnight (11:59pm)
- If you have questions about the assignment, please post on the moodle forum. We will check it regularly.