

## Chapter 1

# week1

### 1.1 Introduction and Recap

- In Kaggle competitions, looks for **Kernels** and/or **Notebooks** people share code that way and you can learn from them.
- IMPORTANT: Insight is more important than algorithm
- IMPORTANT: Don't limit yourself use advanced feature enginnering; run huge greedy calculations over night.
- Recap of models/methods:
  - Linear Methods
    - \* Logistic Regression; Support Vector Machine
    - \* GOOD FOR: Sparse, high dimensional data
    - \* BAD: Often linear separability is not a good approximation
  - Tree Based Methods
    - \* Decision Tree; Random Forrest; Gradient Boosted Decision Trees (GBDT)
    - \* GOOD FOR: good default method for tabular data; good for non-linear relationships
    - \* BAD FOR: hard to capture linear separation (say diagonal line in a 2D plane)

from sklearn: can create over-complex trees that do not generalise data well - that is they are prone to overfitting

trees can't extrapolate trends - they are good at interpolation not extrapolation

- \* Sklearn has good random forrest; xgboost has good GBDT
- K-Nearest neighboors (KNN)

good for feature building

- Neural Networks (NN)

good for images, sounds, texts and sequences very good framework is *pytorch* 

- Most powerfull methods currently are GBDS and NN
- No free lunch theorem there is no single methods that beats all other methods for all applications
- TODO: Look into H20 open source, in-memory, distributed, fast and scalable machine learning and predictive analytics platform.

Looks quite interesting!

Hardware: SSD is critical; use cloud computing for anything too big.

## 1.2 Feature Preprocessing

- VIP: Strong connection between preprocessing and model choice
- Scaling:  $x_i \to \alpha x_i$ 
  - decision trees are not affected by a scaling tx, but non-tree based methods like NN, kNN and regularized linear models are very affected

in KNN -  $x \to 0 * x$  means ignore x, while  $x \to \infty x$  means x dominates

Any methods that relies on gradient descent is sensitive to scaling (logistic regression, SVM, neural networks, etc. etc)

- appraoch 1: Normalization (map to [0,1])

$$x \rightarrow (x - x.min())/(x.max() - x.min)$$

 ${\bf code:\ sklearn.preprocessing.MinMaxSaler}$ 

- approach 2: standardization (to  $\mu = 0, \sigma = 1$ )

$$x \rightarrow (x - x.mean())/x.std()$$

code: sklearn.preprocessing.StandardScaler

- Can use scaling to boost or attenuate signals - so scaling can be thought as just another hyperparameter to tune

In general, start with all features in the same scale and explore changing that.

#### Outliers

- linear models extremely sensitive
- approach 1:  ${\bf Winsorization}$  clip values between percentiles

```
code: UPPER, LOWER = np.percentile(x, [1,99]); y = np.clip(x, UPPER, LOWER) very common in finance
```

- approach 3: Rank

good for knn and linear models when you don't have time to handle outliers by hand

- approach 3: Other transformation

 $\log$  transformation; raising to power; 1 - these have the benefit of bringing outliers in closer, and spreading things around zero apart

#### • Missing values

- can be Nans, empty strings, outliers like -1, or -999
- identifying when a value actually represents a missing value can be challenging. Main tool: Histogram.
- Sometimes missing values contain alot of useful info there might be a reason the value is missing So it is good to create new features like 'isMissing' or something like that.
- 3 main imputation techniques
  - \* NaN  $\rightarrow$  value outside range

Gives trees possibilities to use this; Performance for linear models suffers greatly Curated data often comes with somethign like this already (as described above)

\* NaN  $\rightarrow$  mean, median or mode.

good for linear methods; not good for trees

- \* Try to reconstruct NaN
  - not easy; need to know something about the data generating process.
- WARNING: be vary careful with early NaN imputation if you then build features based on imputed feature
  for exampl if you fill a cyclic feature with median values, and then construct diff as new feature will lead
  to prominent discontinuities and flat zones.
- some libraries, like XGBoost can handle NaNs automatically
- For all all of these, you must learn the transformation from training data, and then apply the same one on testing. Sklearn Transformation API (used by the transformations above) allows you to do this. VERY GOOD.
- USEFUL TRICK: create different predictors from same feature using different preprocessing techniques.
- USEFUL TRICK: Mix models that are trained on different preprocessed versions of the data

## 1.3 External reading

#### FROM SKLEARN

- when data is sparse, you don't want a scaler that moves zeros. Think about nature of your data to chose scalar.
- Transfromer API: scaler = sklearn.Preprocessing.StandardScaler().fit(X\_train); x\_test\_scaled = scaler(X\_test)
- many estimators in sklearn expect features to look more or less  $\sim N(0,1)$
- VIP: Note 11 and 12 regularizes assume all features centered around zero and have variance in the same order.

- other useful tx:
  - \* preprocessing.Normalizer() scaling individual samples to have unit norm (useful when estimating pair similarity via dot prod)
  - \* preprocessing.OneHotEncoder(), preprocessing.OrdinalEncoder()
  - \* preprocessing.KBinDiscretizer(n\_bins, encode).fit() different strategies available histograms focus on counting features in particular bin, whereas dsicretizers focus on labeling features with bin
- Sebastian Raschka
  - Tree based classification is probably the only scale invariant algo
  - VIP: when using PCA, it is better to standardize (mean 1, std 0) than just normalize (map to [0,1]) scaling affects covariance

cool example doing PCA and then bayes classifier on top - compar prediction score.

- Jason Brownlee Discover feature engineering: "Most algorithms are standard we spend most of our efforts on feature engineering"
- Rahul Agarwal Best practices in feature engineering
  - LogLoss clipping technique: clip prediction prob to [0.05, 0.95] when using log loss metric it penalizes heavily being very certain and wrong
  - Use PCA for rotation, not only dim rec
  - sometimes add interaction features, A\*B, A/B, A+B, A B

#### 1.4 Feature Generation

- encodings categorical/ordinal
  - label encoding: map categories to 1,2,3,4...

good for tree based methods, not good for knn or linear (because it assume order and proportionality in labels - moreover dependence is likely not-linear)

 ${\bf code:}\ {\bf sklearn.preprocessing.LabelEncoder()}\ {\bf or}\ {\bf pd.factorize()}$ 

- Frequency encoding: map to numerical value representing frquency of category

can help trees use less splits

this is even sometimes useful in linear models

- one-hot encoding: create indicator variable for each category

these can be good for linear methods, but in general slow down methods (explosion of features) and might not help (specially trees)

though will help tree if target depends on lbael encoded feature in a very non linear way code: pd.get\_dummies() or sklearn.preprocessing.OneHotEncoder()

- Datetime and coordinates
  - Very different than simple numerical or categorical because we can interpret their meaning they have much context
  - dates and times can lead to two main types of features
    - \* moments in a period (ie using periodicity of datetime)
      ex: day of week, day of month, month in year, etc. Or minute value, hour value, etc.
      useful to capture repetitive pattern in data
    - \* time since/to event

can be row independent: years since 2000, for all rows (so all rows have same reference) row dependent: days since last holiday (or till next holiday) - two rows can be referring to different holidays

- very useful to diffs between two date columns
- once you generate new features, numerical or categorical, preprocess them accordingly
- coordinates
  - \* typically you want to calculate distance to points of interest (nearest hospital, school, etc)
  - \* very useful to calculate aggregated statistics for objects around an area
    - ex: # of flats around a point -; proxy for popularity of area

ex: mean price of flats around a point -; gives sense of price of area.

- Collection of tricks
  - separte price into integer part and fractional part can utilize differences in peoples perception of a price
  - Create feature, 'isRoundNumber' people often use numers like 5 and 10, while robots can use many decimals.
  - One-hot encode interaction between categorical features [just concatenate strings and OHE result]
     Not so useful in tree based models, because they can easily approximate this with individual categories.
  - Sometimes simple multiplication, or division of features makes a huge difference.
    - linear models can't approximate these, and trees have a very hard time approximating them.
  - sometimes useful to add slightly rotated coordinate system particularly when using trees.
    - ex: if a particular street happens to be a good division, but that street is not algined with coordinates, then tree uses many split to approximate.

hard to know what rotation to use a priori - so add several and check effect.

### 1.5 Feature Extraction From Texts and Images

- For Text...
- Preprocessing: 1) lowercase, 2) lemmatization, 3) stemming, 4) remove stopwords
- feature extraction: Bag of words column per word in corpus, row perd doc, count ocurrences can extend to n-grams, of either words of letters
- Post processing: TFiDF (Term Frequency and Inverse document frequency)
- OR ...
- embeddings (word2vec, or others)
  - Still use preprocessing
  - create vector representation of words in text
  - uses nearby words (unsupervised)
  - often resulting vector space has interpretable operations
  - training can take a long time check for pretrained
- BOW and Word2Vec often give very different results use bott together
- for images
  - look for pretained models and do some fine tunning
  - use image augmentation to increase training samples (crops, rotations, adding noise, etc.)
     reduces overfitting

### 1.6 Questions

• in GBM\_drop\_tree notebook - why are raw predictions - the output of the staged\_decision\_function - approaching ±8? (I assume it has to do with depth 3 choice of trees, but still, shouldn't output be close to ±1 which is actual y-values?

## Chapter 2

## Week 2

### 2.1 EDA

• VIP: EDA is key

Kaggle CEO says two apporaches: 1) is EDA other is 2) deep NN and pass everything. They have different domains in which they work better.

- Steps:
  - 1. Get Domain knowledge google, read wiki, read state of the art (put in the time!)
  - 2. Check whether values in data set agree with domain knowloedge var ranges, typos, etc. (systematic errors can be very useful info)
  - 3. KEY: figure out the generation process used in the data must try to mimic to set up proper validation scheme.

perhaps they did random sample; perhaps they over sampled a class to balance out; some times train and test set are produce very differently. INVESTIGATE

- Exploring Anonimized data
  - anonimized data is data which organizers intentionally change so as to not reveal some information (ex: replace words with hash values, or col names with x1, x2..)
  - Things to try:
    - \* try to decode (very difficult, and most of the time, can't do it)
    - $\ast$  guess the meaning of the column
      - cool example was trying to unstardadize a numerical column, by reverse engineering the mean and std dev, to find out original column was year born
    - \* guess the type: numeric, categorical, etc. this is generally doable
    - \* find out how feature relate to each other find pairwise relationships (scatter plots) or even groups (correlatio plots, etc)
  - tip: label encode using pandas factorize (encodes based on order of appearance)

```
for c in train.columns[train.dtypes == 'object']: x[c] = x[c].factorize()[0]
```

- VIP TIP: fit a random forrest and then use plt.plot(rf.feature\_importances\_ this can tell you which features you should work on most.
- VIP: Linear models can eaily extract sums and differences, but tree based methods cannot!!

#### 2.2 visualizations

- EDA is an art, and visualizations are our tools
- Plots to explore individual features
- VIP: Never make a conclusion from a single plot! if you have a hypothesis, try to come up with several different plots that could disprove it!
  - plt.hist

can be misleading - vary bin nums. Also zoom in.

if see alot of thinks like 12, 24, 26 - i.e. separated by same amount then generate feature x % 12 (or whatever the appropriate number)

```
- plt.plot(x,'.')
```

convenient not to connect points with line segments - just use dots

if horizontal lines appear, then lots of repeated values - IN THIS CASE, CREATE FEATURE THAT COUNTS HOW MANY COLS SAME IN THE GROUP - or feature for more nuanced pattern in group.

if vertical patterns, then data is not shuffled - IN THIS CASE ADD ROW INDEX AS FEATURE

- plt.scatter(range(len(x), x, c=y) very good for looking for separation in the classes based on that feature.
- Explore feature relationships
  - plt.scatter(x1, x1) One of the best tools!

usually color by class label too

for regression used heaptmap type colors, or visualize target value as point size

TIP: useuful to overlap colored train data with uncolored test data

scatter plots can lead to finding mathematical relations between features (like  $x1 \le x2$ ) - use these to generate new features like diff or ratio

if small number of features: pd.scatter\_matrix(df)

- large scale feature similarity: df.corr() and plt.matshow()

instead of corr, try to create matrices like: how many times in one feature greater than the other (this can spot cumulative features), or how many distinct combinations of these two features in data exist (can spot relationships between labels)

really cool algorithm for grouping based on these corr values:  $\mathbf{spectral\ biclustering\ algorithm} - \mathbf{LOOK}$  INTO THIS!

- df.mean().plot(style='.')

particularly if you sort the columns based on that statistic - might see groups

- AND MANY MORE BE CREATIVE
- if you find groups of related features, it is often good to generate new features like a mean value of the group, etc.
- nice code when overlapping values:

```
def jitter(data, stdev):

N = len(data)

return data + np.random.rand(N)*stdev

plt.scatter(jitter(x, sigma), jitter(y, sigma), c=y)
```

## 2.3 Dataset cleaning and things to check

• Find (and discard) features that are constant in train and test

```
traintest.nunique(axis = 1) == 1
```

if constant in training and non-constant in test, still remove

• find and remove duplicate features

```
traintest.T.drop_duplicates()
```

if duplicate categorical but with diff cat names label encode first, using factorize()!! for f in categorical\_feats:

```
\begin{aligned} & train[f] = traintest[f].factorize() \\ traintest.T.drop\_duplicates() \end{aligned}
```

ullet check for duplicate rows

check if duplicate rows have diff targets - if so, understand why!

- check if train and test have common rows if so, why?
- check if data is shuffled (plot feature or target vs row index)

if not shuffled, high chace leakage exists

• Nice code - feature histograms

```
def hist_it(feat):  \begin{array}{ll} plt.figure(figsize=(16,4)) \\ feat[Y == 0].hist(bins=range(int(feat.min()), int(feat.max()+2)), normed=True, alpha=0.8) \\ feat[Y == 1].hist(bins=range(int(feat.min()), int(feat.max()+2)), normed=True, alpha=0.8) \\ plt.ylim((0,1)) \end{array}
```

• Usually convenient to concatenate train and test, and do all feature engineering with result (but not always)

#### 2.4 Validation

- Validation is a piece of test data not used for fitting, but rather checking the value of the model over unseen data.
- Overfliting in general != Overfliting in competitions

former: train quality ¿ test quality

latter: when quality in test is worse than expected

MAIN POINT: have train/validation split mimic the train/test split - THIS IS KEY.

without this, you validation score does not represent your out of sample test score.

Sometimes it can be very challenging to figure out how train/test split was made. It is worth spending considerable time here if needed.

- validation strategies
  - 3 main: Holdout, K-fold, and leave one out.
  - holdout usually a good choice when there is enough data

no overlap between train and validation

 k-fold - basically repeated holdout, where entire data is partitioned into k validation sets - for each validation set, model is trained on complement. Final measure of performance is average over k folds.

core idea: every sample is used for validation exactly once usually k=5 is a good starting point

- LOO - is k-fold where k = len(train)

used only when there is very little data

- usually houldout and k-fold on shuffled data not good when:
  - unbalanced data sets (as far as classes)
  - multiclass classification with many classes
- in these cases use **stratification** preserve the same target distribution in the different folds
- these methods are also generally not good for time series data
  - you generally need to make a time split so if hold out, don't shuffle.

this emulates how time series data is received, and used

- the time series version of k-fold, is a moving window cross validation this rely on capturing trends
- OTOH, if for competiotn, test/train split did not use a time split, that means you have future data. Then
  USE it! And have your cv emulate (this is generally not the case)
- models/features that rely on trends tend to be very different than those that rely on future data, so it is key
  to get this right.
- main types of splits used in competitions
  - random split (rowwise) done when rows are fairly independent of each other
  - time based split
  - by ID (typically several rows per ID)

test will have IDs not seen in train

- combined ex: date split for each ID independently
- non-trivial
- Typical problems encountered during validation

- Different folds lead to very different values

can happen when different folds are very different in nature: example, in competition, cross-validating with january vs february can be very different (number of holidays is very different) HINT HINT

can also be caused by too little data, or data that is too diverse, or data that is inconsistent (i.e. similar samples with very different target values - error changes if they are both in train, or one and one)

- leaderboard shuffle very different public/ private scores.
- some solutions: increase k. Or redo k-fold with different seeds (can use one to get parameters and one to test)
- submission stage problems: LB consistently higher (lower) than cv; LB uncorrelated with CV

can be caused by train/test data comminb from diff distributions – Best friend EDA: problem is typically that you haven't mimicked split correctly

Other trick: adjust solution based on LB - find optimal constant to add/subtract from your preductions based on public leaderboard score

most often problem comes from imbalanced classes. solution, try to mimic the split.

can also be casued by too little public test data; in this case just trust you CV

### 2.5 Data leakages

- very bad, people get very sensitive, to exploit or not exploit? (shouldn't and often can't in real world)
  When they exist, they tend to dominate
- typical leaks
  - future peaking [incorrect splits]
  - metadata
  - IDS sometimes contain information
  - row ordering
  - LB probing (can be used to extract what they call ground truth

#### 2.6 Additional Material And Links

- CV in sklearn
  - Validation is a way to fit hyperparameters of model without burning data
  - KEY: Preprocessing should also be learned from training, so it is good to use a **pipeline** to combine preprecessing with validation

```
ex: from sklearn.pipeline import make_pipeline clf = make_pipeline(preprocessing.standardScaler(), svm.svc(c=1)) cross_val_score(clf, X, y, cv=cv)
```

- random split: sklearn.model\_selection.train\_test\_split
- k-fold: sklearn.model\_selection.cross\_val\_score(df, x, y, cv=5, scoring='...')

can pass a cross-validation scheme to cv to have more control, or even a custom iterable yielding (test, train) splits

more flexible variant: cross\_validate

- many cross validation iterators that can be used, for iid and not iid (grouped, imbalanced classes, time series)
- Some dude's lessons
  - always cv (not just v)
  - trust good CV method more than LB
  - for final submission picke two very different models (ie. from bagging of SVM, vs Random forrest, vs neural network, vs linear models)
- Kaggle CEO lessons learned
  - Use sklearn pipelines to avoid leakages, peaking, etc.
  - in 2011 random forrest won alot; in 2012 deep NN started dominating (at least vision and time series); in 2015
     XGboost started dominating
  - Two main approaches to dominate

- $\ast\,$  XGBoost with serious EDA
- $\ast\,$  deep NN with very little EDA
- Top Kaggle participant attributes
  - $\ast$  creativity create lots and lots of features
  - \* Tenacity keep working, not get despirited
  - \* very good with statistics [avoid overfitting]
  - \* good software practices [like VC]
- suggestion: look at kaggle public data sets, and use their script forking