

2. suppose A has an eigenvector λ . Exercise 1.2.5.

~~and so~~ $(\lambda \in \mathbb{C})$

so ~~A~~ $\text{Ker}(A - \lambda I)$
is an eigenspace of A .

for $\forall v \in \text{Ker}(A - \lambda I)$

$$(A - \lambda I)(Bv)$$

$$= ABv - \lambda Bv$$

consider $AB = BA$

$$(A - \lambda I)(Bv)$$

$$= B(Av - \lambda v)$$

$$= B(A - \lambda I)v = 0.$$

$\therefore Bv \in \text{Ker}(A - \lambda I)$

so $\text{Ker}(A - \lambda I)$ is B -invariant.

according to 1.

B has an eigenvector in $\text{Ker}(A - \lambda I)$

and any vector in $\text{Ker}(A - \lambda I)$
is the eigenvector of A .

so B, A has ^a common eigenvector. \square

$$N_{\infty}(D)$$

$$= \{f \mid f \text{ is a polynomial}\}.$$

conclusion: $N_{\infty}(D - I)$ is NOT
spanned by e^x .

counter example:

$$\text{let } f = (x+1)e^x.$$

$$(D - I)f = e^x.$$

$$(D - I)^2 f = 0.$$

so $f \in N_{\infty}(D - I)$.

but f is not spanned by e^x . \square

under a basis x_1, \dots, x_n .

in which $x_1, \dots, x_{\frac{n+n}{2}}, x_{\frac{n+n}{2}}$.

forms a basis for V_1

and the others form a basis for V_2 .

~~Actually let x_1, \dots, x_n be a basis for V_1 and x_{n+1}, \dots, x_{2n} be a basis for V_2 .~~

Exercise 1.2.3

① consider A_{11} :

for any $v \in \mathbb{R}^n$.

which is equivalent to consider

any $w \in \mathbb{R}^m$, (since: $v = A^T w$)

$$Av = AA^T w.$$

note that $R(AA^T) = R(A)$

$$\text{so } \text{Ran}(A_{11}) = R(AA^T) = R(A)$$

$$\Rightarrow \text{rank}(A_{11}) = \text{rank}(A)$$

② consider A_{12} :

for any $v \in \text{Ker}(A)$

$$Av = 0.$$

$$\text{so } \dim \text{Ran}(A_{12}) = 0$$

$$\Rightarrow \text{rank}(A_{12}) = 0$$

③ consider A_{21} :

from ①: we know that:

~~$\text{Ran}(A_{11})$~~ for any $v \in \mathbb{R}^n$

$$A(v) \in R(AA^T) = R(A)$$

$$\text{note that } R(A) \cap \text{Ker}(A^T) = \{0\}$$

$$\text{so } \text{Ran}(A_{21}) = \{0\}.$$

$$\text{rank}(A_{21}) = 0.$$

④ consider A_{22} :

for any $v \in \text{Ker}(A)$.

$$Av = 0$$

similar to ②: $\text{rank}(A_{22}) = 0$.

Exercise 1.2.4.

1. consider a basis for V :

$\{b_1, \dots, b_k\}$, where $\dim V = k$.

Then:

$$A(\{b_1, \dots, b_k\}) = \{b_1, \dots, b_k\}^T$$

and $T \in M_k(\mathbb{C})$.

~~pick~~ pick $v \in \mathbb{R}^k$ s.t.

$$Tv = \lambda v. (\lambda \in \mathbb{R}).$$

$$\text{and } v = \begin{pmatrix} v_1 \\ \vdots \\ v_k \end{pmatrix}.$$

$$\text{let } u = v_1 b_1 + v_2 b_2 + \dots + v_k b_k.$$

$$\text{Then: } A(u) = A(\{b_1, \dots, b_k\}) \cdot v$$

$$= \{b_1, \dots, b_k\}^T v$$

$$= \lambda \{b_1, \dots, b_k\} v$$

$$= \lambda u.$$

and $u \in V$.

so A has an eigenvector in V .

Exercise 1.2.1.

1. counter example:

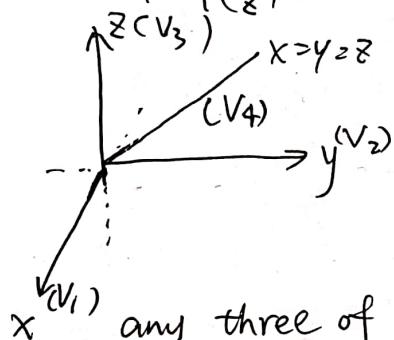
Consider subspaces in \mathbb{R}^3 .

$$V_1: \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} : x \in \mathbb{R}, y = z = 0 \right\}.$$

$$V_2: \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} : y \in \mathbb{R}, x = z = 0 \right\}.$$

$$V_3: \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} : z \in \mathbb{R}, y = x = 0 \right\}$$

$$V_4: \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} : x = y = z; x, y, z \in \mathbb{R} \right\}$$



any three of them are linearly independent.

$$\text{but: } \sum_{i=1}^4 \dim V_i = 4.$$

$$\dim \sum_{i=1}^4 V_i = 3.$$

so they're not linearly independent.

2. counter example:

the same as the previous one.

3. Proof.

~~if~~ V_1, V_2 linearly independent

$$\Rightarrow \dim(V_1 + V_2) = \dim V_1 + \dim V_2.$$

V_3, V_4 linearly independent

$$\Rightarrow \dim(V_3 + V_4) = \dim V_3 + \dim V_4$$

$V_1 + V_2, V_3 + V_4$ linearly independent

$$\Rightarrow \dim(V_1 + V_2 + V_3 + V_4)$$

$$= \dim(V_1 + V_2) + \dim(V_3 + V_4)$$

$$= \dim V_1 + \dim V_2 + \dim V_3 + \dim V_4$$

so, the four subspaces $V_1 \sim V_4$ are linearly independent.

Exercise 1.2.2.

$$\text{let } V_1 = \{A: A \in V, A^T = A\}$$

$$V_2 = \{A: A \in V, A^T = -A\}$$

$$\forall X \in V.$$

$$\text{note that: } X = \frac{X + X^T}{2} + \frac{X - X^T}{2}.$$

$$\frac{X + X^T}{2} \in V_1; \frac{X - X^T}{2} \in V_2.$$

$$\text{so } V_1 + V_2 = V.$$

$$\text{let } B \in V_1 \text{ and } B \in V_2$$

$$\text{the } B^T = B = -B \Rightarrow B = 0$$

$$\text{so } V_1 \cap V_2 = \{0\}.$$

$$\therefore V = V_1 \oplus V_2.$$

$$\text{note that: } \dim V_1 = \frac{n^2 + n}{2}$$

$$\dim V_2 = \frac{n^2 - n}{2}$$

so the block form of T

$$\text{is } \begin{bmatrix} I_{\frac{n^2+n}{2}} \\ I_{\frac{n^2-n}{2}} \end{bmatrix}.$$

Ex. 1.2.1

① counter example: $(1,0,0)^T (0,1,0)^T (0,0,1)^T (1,1,1)^T$

② same counter example as above.

$$\begin{aligned} \text{dim}(V_1+V_2+V_3+V_4) &= \text{dim}(V_1+V_2) + \text{dim}(V_3+V_4) - \text{dim}((V_1+V_2) \cap (V_3+V_4)) \\ &= \text{dim}(V_1+V_2) + \text{dim}(V_3+V_4) \\ &= \text{dim } V_1 + \text{dim } V_2 + \text{dim } V_3 + \text{dim } V_4 - \text{dim}(V_1 \cap V_2) - \text{dim}(V_3 \cap V_4) \\ &= \text{dim } V_1 + \text{dim } V_2 + \text{dim } V_3 + \text{dim } V_4 \end{aligned}$$

V_1, V_2, V_3, V_4 are independent.

Ex. 1.2.2

Any $n \times n$ Matrix can be written into the form of symmetric matrix + skew-sym matrix.

$V = \{A\} \oplus \{B\}$ where A satisfy $A = A^T$ and B satisfy $B^T = -B$

considering C . $C = A + B$

$$C^T = A^T + B^T = A - B$$

$$\begin{cases} A = \frac{C+C^T}{2} \\ B = \frac{C-C^T}{2} \end{cases}$$

note that A has $\frac{n+1}{2}$ decisive entry

B has $\frac{n-1}{2}$ decisive entry

$$\text{dim } A = \frac{n+1}{2}, \text{dim } B = \frac{n-1}{2}$$



Ex. 1.2.3

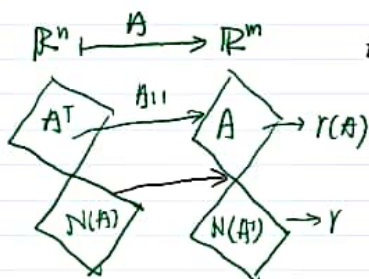
$\mathbb{R}^n \mapsto \mathbb{R}^m$ dim rank is the dim of codomain!

A11 send $\text{Ran}(A^T) \mapsto \text{Ran}(A)$ r(A) → r(A)

A12 send $\text{Ker}(A) \mapsto \text{Ran}(A)$ n-r → r

A21 send $\text{Ran}(A^T) \mapsto \text{Ker}(A)$ r → m-r

A22 send $\text{Ker}(A) \mapsto \text{Ker}(A)$ n-r → m-r



A can only send vectors in \mathbb{R}^n to $\text{Ran}(A)$, so $r(A_{21}), r(A_{22}) = 0$

A send $\vec{v} \in N(A)$ to $\vec{0}$,

so $r(A_{12}) = 0$

A send $\vec{v} \in \text{Ran}(A^T)$ to $\text{Ran}(A)$ $r(A_{11}) = r(A)$

Ex. 1.2.4

① $\text{dim } V = k$, $\vec{v} = c_1 \vec{e}_1 + \dots + c_k \vec{e}_k$ (c_i are not all 0)

$$A\vec{v} = c_1 A\vec{e}_1 + \dots + c_k A\vec{e}_k \in V$$

so $A\vec{v}$ can be written out with a linear combination like:

$$d_1 \vec{e}_1 + \dots + d_k \vec{e}_k, (\vec{e}_1, \dots, \vec{e}_k \text{ are independent})$$

$$A\vec{e}_i = \frac{d_i}{c_i} \vec{e}_i \quad (i=1, \dots, k)$$

so A has at least 1 eigenvector in V

②. suppose $A\vec{v} = \lambda \vec{v}$.

multiply \vec{v} by B : $B\vec{v}$

$$A(B\vec{v}) = AB\vec{v} = BA\vec{v} = \lambda B\vec{v}$$

$B\vec{v}$ is still in the eigenspace for $A(\lambda)$

$$V = \{ \vec{v} \mid (A - \lambda I)\vec{v} = 0 \} \text{ is } B\text{-invariant.}$$

so B has an eigenvector in V .

Ex. 1.2.5

$$N_{\infty}(D) = \{ c_0 x^0 + \dots + c_n x^n \}$$

if $f(x) \in N_{\infty}(D-I)$ then must have

$$\frac{d}{dx} f(x) = f(x)$$

counter example: e^{-x} also satisfies: $(e^{-x})' = -e^{-x}$ $k=2$.

false conclusion.

Collaborator: Ex 1.2.1 ③ & 1.2.2

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