第二次习题课:复合函数的链式法则、高阶偏导数、方向导数

(1) 多元复合函数的链式法则

设二元函数 z=f(u,v) 在点 (u_0,v_0) 处可微,二元函数 u=u(x,y),v=v(x,y) 在点 (x_0,y_0) 处存在偏导数,并且 $u_0=u(x_0,y_0),v_0=v(x_0,y_0)$,则复合函数 z=f(u(x,y),v(x,y)) 在点 (x_0,y_0) 处存在偏导数,且

$$\frac{\partial z}{\partial x}\Big|_{(x_0,y_0)} = \frac{\partial f(u_0,v_0)}{\partial u} \cdot \frac{\partial u(x_0,y_0)}{\partial x} + \frac{\partial f(u_0,v_0)}{\partial v} \cdot \frac{\partial v(x_0,y_0)}{\partial x},$$

$$\frac{\partial z}{\partial y}\Big|_{(x_0, y_0)} = \frac{\partial f(u_0, v_0)}{\partial u} \cdot \frac{\partial u(x_0, y_0)}{\partial y} + \frac{\partial f(u_0, v_0)}{\partial v} \cdot \frac{\partial v(x_0, y_0)}{\partial y}$$

(2) 多元函数一阶微分形式的不变性: 设 z = f(u,v), u = u(x,y), v = v(x,y) 均连续可微, 则将 z 看成 x,y 的函数,有 $dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy$.

另一方面,由复合函数的链式法则, $\frac{\partial z}{\partial x} = \frac{\partial f}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial f}{\partial v} \frac{\partial v}{\partial x}$, $\frac{\partial z}{\partial y} = \frac{\partial f}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial f}{\partial v} \frac{\partial v}{\partial y}$, 代入

$$dz = \frac{\partial z}{\partial x}dx + \frac{\partial z}{\partial y}dy, \quad \text{(4)}$$

$$dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy = \left(\frac{\partial f}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial f}{\partial v} \frac{\partial v}{\partial x}\right) dx + \left(\frac{\partial f}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial f}{\partial v} \frac{\partial v}{\partial y}\right) dy$$
$$= \frac{\partial f}{\partial u} \left(\frac{\partial u}{\partial x} dx + \frac{\partial u}{\partial y} dy\right) + \frac{\partial f}{\partial v} \left(\frac{\partial v}{\partial x} dx + \frac{\partial v}{\partial y} dy\right)$$
$$= \frac{\partial f}{\partial u} du + \frac{\partial f}{\partial v} dv$$

我们将 $dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial v} dy = \frac{\partial f}{\partial u} du + \frac{\partial f}{\partial v} dv$ 称为一阶微分的形式不变性。

1. 已知函数 z = z(x, y) 由方程 $x^2 + y^2 + z^2 = a^2$ 决定,求 $\frac{\partial^2 z}{\partial x \partial y}$.

解: 方程 $x^2 + y^2 + z^2 = a^2$ 两边分别对 x, y 求偏导, 得 $2x + 2z \frac{\partial z}{\partial x} = 0$, $2y + 2z \frac{\partial z}{\partial y} = 0$,

故
$$\frac{\partial z}{\partial x} = -\frac{x}{z}$$
, $\frac{\partial z}{\partial y} = -\frac{y}{z}$, 这样 $\frac{\partial^2 z}{\partial x \partial y} = \frac{y}{z^2} \cdot \frac{\partial z}{\partial x} = -\frac{xy}{z^3}$.

2. 设 $g(x) = f(x, \varphi(x^2, x^2))$, 其中函数 f 和 φ 的二阶偏导数连续, 求 $\frac{d^2g(x)}{dx^2}$.

解: 由 $g(x) = f(x, \varphi(x^2, x^2))$ 两边对x求导,得

$$\frac{dg(x)}{dx} = f_x'(x,\phi(x^2,x^2)) + 2f_\phi'(x,\phi(x^2,x^2))(\phi_1'(x^2,x^2) + \phi_2'(x^2,x^2))x,$$

两边再对x求导,得

$$\frac{d^2g(x)}{dx^2} = f_{xx}^{"} + 4f_{x\phi}^{"}(\phi_1 + \phi_2)x + 4f_{\phi\phi}^{"}(\phi_1 + \phi_2)^2x^2 + 4f_{\phi}^{"}(\phi_{11} + 2\phi_{12}^{"} + \phi_{22}^{"})x^2 + 2f_{\phi}^{"}(\phi_1 + \phi_2),$$

其中符号 ϕ_1 , ϕ_2 分别表示 ϕ 对其第一个中间变量和第二个中间变量求偏导。

3. 设
$$z = z(x, y)$$
 二阶连续可微, 并且满足方程 $A \frac{\partial^2 z}{\partial x^2} + 2B \frac{\partial^2 z}{\partial x \partial y} + C \frac{\partial^2 z}{\partial y^2} = 0$.

若令
$$\begin{cases} u = x + \alpha y \\ v = x + \beta y \end{cases}$$
 、试确定 α , β 为何值时原方程可变为 $\frac{\partial^2 z}{\partial u \partial v} = 0$.

解:因为z = z(x, y)二阶连续可微,因此二阶混合偏导与求导次序无关。将x, y看成自变量,u, v看成中间变量,利用链式法则得

$$\frac{\partial z}{\partial x} = \frac{\partial z}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial z}{\partial v} \frac{\partial v}{\partial x} = \frac{\partial z}{\partial u} + \frac{\partial z}{\partial v}, \quad \frac{\partial z}{\partial v} = \frac{\partial z}{\partial u} \frac{\partial u}{\partial v} + \frac{\partial z}{\partial v} \frac{\partial v}{\partial v} = \alpha \frac{\partial z}{\partial u} + \beta \frac{\partial z}{\partial v},$$

$$\frac{\partial^2 z}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial z}{\partial u} + \frac{\partial z}{\partial v} \right) = \frac{\partial^2 z}{\partial u^2} + 2 \frac{\partial^2 z}{\partial u \partial v} + \frac{\partial^2 z}{\partial v^2},$$

$$\frac{\partial^2 z}{\partial y^2} = \frac{\partial}{\partial y} \left(\alpha \frac{\partial z}{\partial u} + \beta \frac{\partial z}{\partial v} \right) = \alpha^2 \frac{\partial^2 z}{\partial u^2} + 2\alpha \beta \frac{\partial^2 z}{\partial u \partial v} + \beta^2 \frac{\partial^2 z}{\partial v^2},$$

$$\frac{\partial^2 z}{\partial x \partial y} = \frac{\partial}{\partial x} \left(\alpha \frac{\partial z}{\partial u} + \beta \frac{\partial z}{\partial v} \right) = \alpha \frac{\partial^2 z}{\partial u^2} + (\alpha + \beta) \frac{\partial^2 z}{\partial u \partial v} + \beta \frac{\partial^2 z}{\partial v^2},$$

由
$$0 = A \frac{\partial^2 z}{\partial x^2} + 2B \frac{\partial^2 z}{\partial x \partial y} + C \frac{\partial^2 z}{\partial y^2}$$
 得到

$$\left(A + 2B\alpha + C\alpha^{2}\right)\frac{\partial^{2}z}{\partial u^{2}} + 2\left(A + B\left(\alpha + \beta\right) + C\alpha\beta\right)\frac{\partial^{2}z}{\partial u\partial v} + \left(A + 2B\beta + C\beta^{2}\right)\frac{\partial^{2}z}{\partial v^{2}} = 0 \quad \cdots (*)$$

故只要选取
$$\alpha, \beta$$
使得 $\begin{cases} A + 2B\alpha + C\alpha^2 = 0 \\ A + 2B\beta + C\beta^2 = 0 \end{cases}$,即得 $\frac{\partial^2 z}{\partial u \partial v} = 0$.

这样问题转化为方程 $A+2Bt+Ct^2=0$ 有两不同实根,即要求 $B^2-AC>0$.

令
$$\alpha = \frac{-B + \sqrt{B^2 - AC}}{C}$$
, $\beta = \frac{-B - \sqrt{B^2 - AC}}{C}$. 将其代入方程(*),可知 $\frac{\partial^2 z}{\partial u \partial v}$ 的系数不为

零,从而
$$\frac{\partial^2 z}{\partial u \partial v} = 0$$
.

4.
$$\forall u(x,y) \in C^2$$
, $\forall \frac{\partial^2 u}{\partial x^2} - \frac{\partial^2 u}{\partial y^2} = 0$, $u(x,2x) = x$, $u'_x(x,2x) = x^2$, $\forall u''_{xx}(x,2x)$,

$$u''_{xy}(x,2x), \quad u''_{yy}(x,2x).$$

解: 因为 $\frac{\partial u}{\partial x}(x,2x) = x^2$, 两边对 x 求导, 得

$$\frac{\partial^2 u}{\partial x^2}(x,2x) + \frac{\partial^2 u}{\partial y \partial x}(x,2x) \cdot 2 = 2x. \tag{1}$$

由 u(x,2x) = x, 两边对 x 求导, 得 $\frac{\partial u}{\partial x}(x,2x) + \frac{\partial u}{\partial y}(x,2x) \cdot 2 = 1$,

所以, $\frac{\partial u}{\partial y}(x,2x) = \frac{1-x^2}{2}$. 此式两边再对 x 求导, 得

$$\frac{\partial^2 u}{\partial x \partial y}(x, 2x) + \frac{\partial^2 u}{\partial y^2}(x, 2x) \cdot 2 = -x. \tag{2}$$

由己知,
$$\frac{\partial^2 u}{\partial x^2}(x,2x) - \frac{\partial^2 u}{\partial y^2}(x,2x) = 0$$
, (3)

因为 $u(x,y) \in C^2$, 因此 $\frac{\partial^2 u}{\partial x \partial y}(x,2x) = \frac{\partial^2 u}{\partial y \partial x}(x,2x)$. 现在 (1), (2), (3) 联立解得:

$$\frac{\partial^2 u}{\partial x^2}(x,2x) = \frac{\partial^2 u}{\partial y^2}(x,2x) = -\frac{4}{3}x, \quad \frac{\partial^2 u}{\partial x \partial y}(x,2x) = \frac{5}{3}x.$$

5. 设
$$f$$
 可微,且 $z = x^3 f\left(xy, \frac{y}{x}\right)$,求 $\frac{\partial z}{\partial x}, \frac{\partial z}{\partial y}$.

解:
$$dz = f \cdot 3x^2 dx + x^3 df = 3x^2 f dx + x^3 \left[f_1' d(xy) + f_2' d \left(\frac{y}{x} \right) \right]$$

$$= 3x^2 f dx + x^3 \left[f_1' (x dy + y dx + f_2' \frac{x dy - y dx}{x^2} \right]$$

$$= \left(3x^2 f + x^3 y f_1' - x y f_2' \right) dx + \left(x^4 f_1' + x^2 f_2' \right) dy$$

由一阶微分的形式不变性。

$$dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy = \left(3x^{2} f + x^{3} y f_{1}' - x y f_{2}'\right) dx + \left(x^{4} f_{1}' + x^{2} f_{2}'\right) dy$$

故
$$\frac{\partial z}{\partial x} = \left(3x^2f + x^3yf_1' - xyf_2'\right), \quad \frac{\partial z}{\partial y} = \left(x^4f_1' + x^2f_2'\right).$$

其中符号 f_1 , f_2 分别表示函数 f(x,y) 分别对第一个中间变量和第二个中间变量求偏导。

6. 若 $f_x(x,y)$, $f_y(x,y)$ 在 $P_0(x_0,y_0)$ 的 邻 域 内 存 在 , 且 在 $P_0(x_0,y_0)$ 可 微 , 则 $f_{xy}(P_0) = f_{yx}(P_0).$

证明: 令 $g(h) = f(x_0 + h, y_0 + h) - f(x_0 + h, y_0) - f(x_0, y_0 + h) + f(x_0, y_0)$. 对某个充分 小的固定的 $h \neq 0$,令 $\varphi(x) = f(x, y_0 + h) - f(x, y_0)$. 则条件表明 $\varphi(x)$ 可导。 由一元函数的微分中值定理,存在 $0 < \theta_1 < 1$ 使得

$$g(h) = \varphi(x_0 + h) - \varphi(x_0) = \varphi'(x_0 + \theta_1 h)h = [f_x(x_0 + \theta_1 h, y_0 + h) - f_x(x_0 + \theta_1 h, y_0)]h.$$

又因为 $f_x(x,y)$ 在 $P_0(x_0,y_0)$ 可微,故

$$f_{x}(x_0 + \theta_1 h, y_0 + h) = f_{x}(x_0, y_0) + f_{xx}(x_0, y_0)\theta_1 h + f_{xy}(x_0, y_0)h + o(h)$$
 \coprod

$$f_x(x_0 + \theta_1 h, y_0) = f_x(x_0, y_0) + f_{xx}(x_0, y_0)\theta_1 h + o(h)$$
, 从而

$$g(h) = f_{yy}(x_0, y_0)h^2 + o(h^2) \cdots (1)$$

令 $\psi(y) = f(x_0 + h, y) - f(x_0, y)$. 则 $\psi(y)$ 可导,且存在 $0 < \theta_2 < 1$ 使得

$$g(h) = \psi(y_0 + h) - \psi(y_0) = \psi'(y_0 + \theta_2 h)h = [f'_y(x_0 + h, y_0 + \theta_2 h) - f'_y(x_0, y_0 + \theta_2 h)]h. \quad 2$$

似地, 由 $f_{v}(x,y)$ 在 $P_{0}(x_{0},y_{0})$ 可微, 得到

$$g(h) = f_{yx}(x_0, y_0)h^2 + o(h^2) \cdots (2)$$

由(1)与(2),得
$$f_{xy}(P_0) = \lim_{h \to 0} \frac{g(h)}{h^2} = f_{yx}(P_0)$$
.

7. 设z(x,y)是定义在矩形区域 $D = \{(x,y) | 0 \le x \le a, 0 \le y \le b\}$ 上的可微函数。证明:

(1)
$$z(x, y) = f(y) \Leftrightarrow \forall (x, y) \in D, \frac{\partial z}{\partial x} \equiv 0$$
;

(2)
$$z(x,y) = f(y) + g(x) \Leftrightarrow \forall (x,y) \in D, \frac{\partial^2 z}{\partial x \partial y} \equiv 0$$
.

证明:(1) "⇒"显然.

" \leftarrow " 任取 $x_0 \in [0,a]$. 任意固定 $y \in [0,a]$,关于 x 的一元函数 z(x,y) 在以 x

与 x_0 为端点的区间上应用微分中值定理,故存在 ξ 使得

$$z(x, y) - z(x_0, y) = \frac{\partial z}{\partial x} (\xi, y)(x - x_0) = 0$$
, $\dot{z} \notin z(x, y) = z(x_0, y)$, \dot{z}

$$z(x, y) = f(y)$$
与 x 无关.

(2) ⇒: 显然.

$$\Leftarrow$$
: 因为 $\frac{\partial^2 z}{\partial x \partial y} \equiv 0$, $\frac{\partial z}{\partial y} = h(y)$ 与 x 无关. 故

$$z(x,y) = \int h(y)dy + g(x) = f(y) + g(x).$$

8. 设n为整数,若对任意的t > 0, $f(tx,ty) = t^n f(x,y)$,则称f是n次齐次函数。证明:

可微函数
$$f(x, y)$$
 是零次齐次函数的充要条件是 $x \frac{\partial f}{\partial x} + y \frac{\partial f}{\partial y} = 0$.

证明: 先证必要性。由条件, f(tx,ty) = f(x,y) ($\forall t > 0$).

若 f 在坐标原点处有定义,则由 f 的连续性可知 f(x,y) = f(0,0), $(\forall (x,y))$.

结论显然成立。现在假设f在坐标原点处没有定义。则由复合函数的链式法则,

两边对
$$t$$
求导,得 $x\frac{\partial f}{\partial x}(tx,ty)+y\frac{\partial f}{\partial y}(tx,ty)=0$.

令
$$t=1$$
,即得 $x\frac{\partial f}{\partial x}(x,y)+y\frac{\partial f}{\partial y}(x,y)=0$. 必要性得证。

$$\frac{\partial f}{\partial r} = \frac{\partial f}{\partial x} \cdot \cos \theta + \frac{\partial f}{\partial y} \cdot \sin \theta = \frac{1}{r} \left(x \frac{\partial f}{\partial x} + y \frac{\partial f}{\partial y} \right) = 0.$$

上式说明 f 在极坐标系中只是 $\theta = \arctan \frac{y}{x}$ 的函数,这等价于只是 $\frac{y}{x}$ 的函数。可记 $f(x,y) = \phi(\frac{y}{x})$ 。显然 ϕ 是零次齐次函数。

9. 设 f(x,y) 定义在 R^2 上, 若对 x 连续, 对 y 的偏导数在 R^2 上有界, 证明 f(x,y) 是连续函数.

证明: 对 $\forall (x_0, y_0) \in R^2$,

$$|f(x,y) - f(x_0, y_0)| = |[f(x,y) - f(x,y_0)] + [f(x,y_0) - f(x_0, y_0)]|$$

$$\leq |f(x,y) - f(x,y_0)| + |f(x,y_0) - f(x_0, y_0)|$$

因为
$$f(x,y)$$
对 x 连续,所以 $\lim_{x\to x_0} [f(x,y_0)-f(x_0,y_0)]=0$ 。

又因为 f(x,y) 对 y 的偏导数在 R^2 上有界,故存在 M>0 使得 $\left|\frac{\partial f}{\partial y}(x,y)\right| \leq M$. 所以存在 η 使得

$$|f(x,y)-f(x,y_0)| = \left|\frac{\partial f}{\partial y}(x,\eta)(y-y_0)\right| \le M |y-y_0| \to 0, \quad y \to y_0.$$

这样

$$\begin{split} &\lim_{(x,y)\to(x_0,y_0)} \left(f(x,y) - f(x_0,y_0) \right) \\ &= \lim_{(x,y)\to(x_0,y_0)} \left[f(x,y) - f(x,y_0) \right] + \lim_{(x,y)\to(x_0,y_0)} \left[f(x,y_0) - f(x_0,y_0) \right] = 0, \end{split}$$

即 f(x, y) 是连续函数.

10. 设
$$f(x,y)$$
 在 $P_0(x_0,y_0)$ 可 微 。 已 知 $\vec{v} = \vec{i} - \vec{j}$, $\vec{u} = -\vec{i} + 2\vec{j}$, 且 $\frac{\partial f(P_0)}{\partial \vec{v}} = 2$,

$$\frac{\partial f(P_0)}{\partial \vec{u}} = 1$$
, $\vec{x} f(x, y) \in P_0(x_0, y_0)$ 的微分。

解: 因为 $\vec{v} = \vec{i} - \vec{j} = (1, -1)$, $\vec{u} = -\vec{i} + 2\vec{j} = (-1, 2)$, 且 f(x, y) 在 $P_0(x_0, y_0)$ 可微, 因此

$$2 = \frac{\partial f(P_0)}{\partial \vec{v}} = (f_x'(P_0), f_y'(P_0)) \cdot (\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}) = \frac{1}{\sqrt{2}} (f_x'(P_0) - f_y'(P_0)),$$

$$1 = \frac{\partial f(P_0)}{\partial \vec{u}} = (f_x(P_0), f_y(P_0)) \cdot (-\frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}}) = \frac{1}{\sqrt{5}} (-f_x(P_0) + 2f_y(P_0)),$$

由此解出 $f_x(P_0) = 4\sqrt{2} + \sqrt{5}$, $f_y(P_0) = 2\sqrt{2} + \sqrt{5}$.

所以 f(x, y) 在 $P_0(x_0, y_0)$ 的微分 $df(P_0) = (4\sqrt{2} + \sqrt{5})dx + (2\sqrt{2} + \sqrt{5})dy$.

11. 设 f(x,y) 为可微函数, $\vec{l_1}$, $\vec{l_2}$ 是 \mathbb{R}^2 上的一组线性无关的向量。试证: f(x,y) 在任一点 P(x,y) 沿任意向量 \vec{l} 的方向导数 $f_{\vec{l_1}}(P)$ 必定能用 $f_{\vec{l_2}}(P)$ 与 $f_{\vec{l_2}}(P)$ 线性表示。

证明: 令 $\vec{l}_1 = (\cos \alpha_1, \cos \beta_1)$, $\vec{l}_2 = (\cos \alpha_2, \cos \beta_2)$.

因为f(x,y)可微,故

$$\begin{cases} f_{\vec{l}_1}(P) = f_x(P) \cos \alpha_1 + f_y(P) \cos \beta_1 = d_1 \\ f_{\vec{l}_2}(P) = f_x(P) \cos \alpha_2 + f_y(P) \cos \beta_2 = d_2. \end{cases}$$

由于
$$\vec{l}_1$$
, \vec{l}_2 线性无关,因此由上式解出 $\begin{pmatrix} f_x'(P) \\ f_y'(P) \end{pmatrix} = \begin{pmatrix} \cos \alpha_1 & \cos \beta_1 \\ \cos \alpha_2 & \cos \beta_2 \end{pmatrix}^{-1} \begin{pmatrix} d_1 \\ d_2 \end{pmatrix}$.

于是,对任意的向量 $\vec{l} = (\cos \alpha, \cos \beta)$,

$$f_{\bar{l}}(P) = f_{x}(P)\cos\alpha + f_{y}(P)\cos\beta = (\cos\alpha, \cos\beta) \begin{pmatrix} f_{x}(P) \\ f_{y}(P) \end{pmatrix}$$

$$= (\cos\alpha, \cos\beta) \begin{pmatrix} \cos\alpha_{1} & \cos\beta_{1} \\ \cos\alpha_{2} & \cos\beta_{2} \end{pmatrix}^{-1} \begin{pmatrix} d_{1} \\ d_{2} \end{pmatrix}$$

$$= (a, b) \begin{pmatrix} d_{1} \\ d_{2} \end{pmatrix},$$

$$\exists t t (a, b) = (\cos\alpha, \cos\beta) \begin{pmatrix} \cos\alpha_{1} & \cos\beta_{1} \\ -\cos\alpha_{1} & \cos\beta_{1} \end{pmatrix}^{-1}$$

其中 $(a, b) = (\cos \alpha, \cos \beta) \begin{pmatrix} \cos \alpha_1 & \cos \beta_1 \\ \cos \alpha_2 & \cos \beta_2 \end{pmatrix}^{-1}$.

12. 设在 \mathbb{R}^2 上可微函数 f(x,y)满足 $xf_x + yf_y = 0$,试证: 在极坐标系中 f 只是 θ 的函数。证明: (方法一) 令 z = f(x,y), $x = r\cos\theta$, $y = r\sin\theta$.

因为
$$\frac{\partial z}{\partial r} = f_x \cos \theta + f_y \sin \theta$$
,因此 $r \frac{\partial z}{\partial r} = r \cos \theta f_x + r \sin \theta f_y = x f_x + y f_y = 0$.

当
$$r \neq 0$$
时, $\frac{\partial z}{\partial r} \equiv 0$,因此 $z = f(r\cos\theta, r\sin\theta)$ 与 r 无关。

而当r=0时,由于f在原点连续,故由原点出发的任一射线上函数值相等。故在极坐标系中f只是 θ 的函数。

方法二: 任取 $(x,y) \in \mathbb{R}^2$,并令 $\vec{r} = (x,y)$. 因为 $xf_x + yf_y = 0$,因此 $\frac{\partial f(x,y)}{\partial \vec{r}} = \frac{1}{\|\vec{r}\|} (xf_x + yf_y) = 0$,即 f 沿着任意方向的方向导数都等于零,

从而 f 沿着任意方向的函数值不变。

故在极坐标系中,由原点出发的任一射线上函数值相等。 所以在极坐标系中 f 只是 θ 的函数。

13. 设 $f(x,y) = x^2 - xy + y^2$, $P_0(1,1)$. 试求 $\frac{\partial f(P_0)}{\partial \vec{l}}$, 并问: 在怎样的方向 \vec{l} 上, 方向导数 $\frac{\partial f(P_0)}{\partial \vec{l}}$ 分别有最大值、最小值和零值。

解: 因为 f(x,y) 可微,且 $f_x(P_0) = (2x-y)|_{(1,1)} = 1$, $f_y(P_0) = (2y-x)|_{(1,1)} = 1$,

因此对任意的单位向量 $\vec{l} = (\cos \alpha, \cos \beta)$, $\frac{\partial f(P_0)}{\partial \vec{l}} = \cos \alpha + \cos \beta$.

当 \vec{l} = (1,1) 是梯度方向时, $\frac{\partial f(P_0)}{\partial \vec{l}} = \sqrt{2}$ 达到最大;

当 $\vec{l} = (-1, -1)$ 时, $\frac{\partial f(P_0)}{\partial \vec{l}} = -\sqrt{2}$ 达到最小;

当 $\vec{l} = (1,-1)$ 或 $\vec{l} = (-1,1)$ 时,即 $\alpha = \frac{7\pi}{4}$ 或 $\frac{3\pi}{4}$ 时, $\frac{\partial f(P_0)}{\partial \vec{l}} = 0$.

14. 设 a,b 是实数,函数 $z = 2 + ax^2 + by^2$ 在点 (3,4) 处的方向导数中,沿 $l = -3\mathbf{i} - 4\mathbf{j}$ 的方向

导数最大,最大值为10,求a,b.

解: 因为函数可微,我们有 $\frac{\partial z}{\partial x}\Big|_{(3,4)}=6a$, $\frac{\partial z}{\partial y}\Big|_{(3,4)}=8b$,且函数沿着梯度方向的方向导数达到

最大,因此梯度单位向量
$$\mathbf{l}^o = \frac{1}{5}(-3\mathbf{i} - 4\mathbf{j}) = (\frac{6a}{10}, \frac{8b}{10})$$
. 从而
$$\begin{cases} \frac{6a}{10} = -\frac{3}{5} \\ \frac{8b}{10} = -\frac{4}{5}, \end{cases}$$
 故
$$\begin{cases} a = -1 \\ b = -1. \end{cases}$$