

Task week 2: Servo motor

```
#include <Servo.h>
```

```
Servo moto; //any name should do
```

```
void setup(){
```

```
    moto .attach(7);
```

```
}
```

```
void loop(){
```

```
    moto .write(0);
```

```
    delay(1000);
```

```
    moto .write(120);
```

```
    delay(2000);
```

```
}
```