Lillian Chin

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Education

Massachusetts Institute of Technology (MIT) **June 2017**
B.S. in Electrical Engineering and Computer Science *Cambridge, MA*
Minors in Mechanical Engineering, Comparative Media Studies *GPA: 4.9/5.0*

Work and Research Experience

MIT Computer Science & Artifical Intelligence Lab, Distributed Robotics Group **Sept. 2016 – present**
Researcher with Dr. Daniela Rus *Cambridge, MA*

- Will be designing a self-deploying robot that uses novel auxetic materials to interlock and create foldable structures

Apple **June – Aug. 2016**
iPad Hardware Systems Integration, Electrical Engineering Intern *Cupertino, CA*

- Designed schematic layout and PCB board in Cadence for internal project board involving high-speed signals.
- Wrote TCL scripts to validate functionality of SoCs. Deployed this test suite on SMT, FATP and REL lines in China.
- Performed power validation and signal integrity measurements on low and high speed signals, including I2C and SPI.
- Wrote Python scripts to conduct thermal experiments on battery life and power output.

Massachusetts Institute of Technology, Department of Mechanical Engineering **Feb. 2014 – Jun. 2016**
Researcher with Dr. John Hart *Cambridge, MA*

- Created machine vision algorithms in C++ for dynamic photolithography system, increasing speed of tracking, detection and encapsulation by 300% with multithreading, Kalman filters and bit plane splicing.
- Performed encapsulation experiments on liver hepatocytes in photopolymers for tissue engineering applications.
- Adapted photolithographic system to a robot arm, enabling accurate micropatterning on macro-scale objects. Improved scanning system's accuracy and designed mechanical enclosures for electronic / optical systems.
- Designed and printed NFC circuits to test capabilities of photolithography system for flexible circuits
- Analyzed performance of various particle detection and tracking algorithms in simulated and actual conditions.

Square **June – Aug. 2015**
Electrical Engineering Intern *San Francisco, CA*

- Wrote C code for NFC card proximity detection that interfaced with 2 microcontrollers, an FPGA, ADC/DACs, and a voltage regulator. Key part of firmware needed to pass contactless payment certification
- Tuned NFC antennas with VNA and SMT rework skills, enabling proposal of new antenna design directions
- Wrote Python script to send HCI commands to Bluetooth chip, validating results with spectrum analyzer
- Supported EVT build in China, conducting failure analysis for SMT and FATP factory lines and providing translation
- Created preliminary schematics and PCB layout for new NFC board in Altium

MIT Media Lab, Biomechatronics Group **Jan. – May 2015**
Researcher with Dr. Hugh Herr *Cambridge, MA*

- Created thin-wire electrodes and Matlab script to stimulate rat sciatic nerve and measure response
- Wrote automated particle analysis in ImageJ to measure neuron size, count and g-ratio to quantify nerve regrowth

Projects

For pictures and more detailed information, please go to http://lillych.in

2.72 - Elements of Machine Design **Spring 2016**
Desktop lathe that maintained 50 micron precision even after being dropped. Won first place for highest accuracy

MIT Mobile Autonomous Systems Laboratory **Jan. 2016**
Cube-stacking autonomous robot. Won first place, best software, best wiki and "most likely to be staff" award

MakeMIT 2014 **Feb. 2014**
Guitar-playing robot that uses solenoids to strum and a rack-and-pinion setup to fret. Won first place.

Publications

1 first-author bioengineering paper; 1 co-author mathematics paper; 3 mechanical engineering manuscripts in preparation

Skills and Activities

Languages – *Fluent:* Python, Java, C/C++, LaTeX, Matlab, TCL; *Familiar:* Javascript, SQL, HTML/CSS, Bash, Chinese
Proficiencies – Git, Cadence, Adobe Photoshop, Adobe Illustrator, Django, EAGLE, Altium, MasterCAM, Solidworks