# **ACQUISITION PROTOCOL**

 ${\color{blue} \textbf{code used for this purpose:}}\ {\color{blue} \textbf{acquisitions\_training\_classifier.ipynb}}$ 

# **Prerequisites**

- Right-handed players only.
- Position of the PCB within the case for acquisitions as shown in the picture below (IMU facing the game net in the forehand grip).





# **Training phase**

Number of subjects: 4

Duration of each acquisition: about 5 seconds

Gestures acquired and related labels set:

Forehand: '0'Backhand: '1'Serve: '2'No shot: '3'

Number of acquisitions for each shot ('forehand', 'backhand', 'serve')  $\rightarrow$  10 for each subject. Number of acquisitions for the 'no shot' gesture  $\rightarrow$  20 acquisitions for 1 subject only. Number of acquisition files  $\rightarrow$  140 (in the "acquisitions\_for\_TRAINING" folder of the GitHub repository)

# Features engineering

For each acquisition\_file.csv, containing 400 rows and 7 columns (6 IMU measurement + 1 label), we computed the most significant statistic parameters of every IMU measurement:

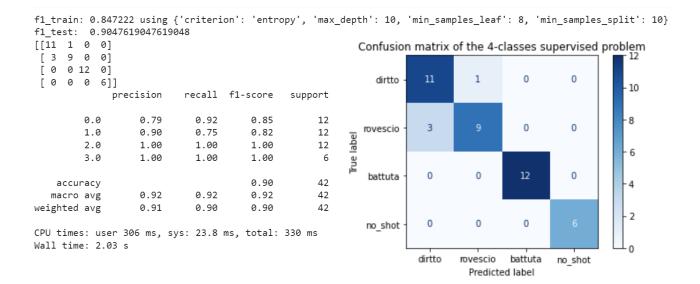
- 1° quantile (0.25)
- Median
- 3° quantile (0.75)

In this way, we summarized each acquisition file.csv in 19-dimensional array.

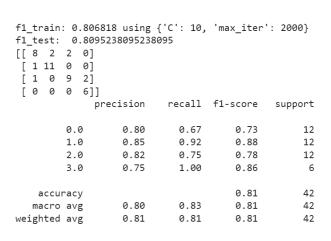
Having 140 acquisition file.csv, the resulting training dataset is a (140, 19) dataframe.

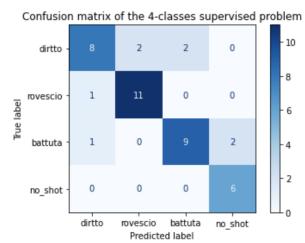
### **Trained classifiers**

Decision Tree:



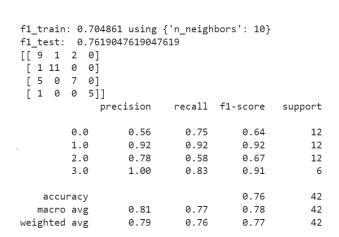
# Logistic Regression:

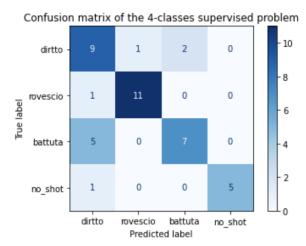




#### Electronic Technologies and Biosensors Lab – Project 3 Academic Year 2021/2022 – Il Semester

### KNN:

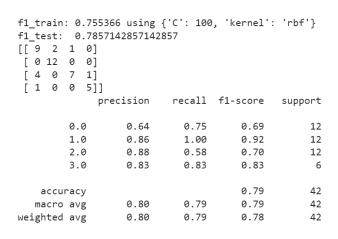


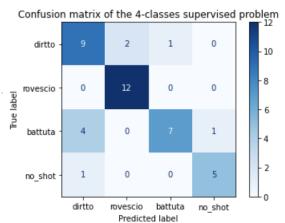


## Random Forest:

f1\_train: 0.969381 using {'criterion': 'gini', 'max\_depth': 15, 'min\_samples\_leaf': 2, 'min\_samples\_split': 3, 'n\_estimators': 10} f1\_test: 0.9523809523809523 [[10 2 0 0] Confusion matrix of the 4-classes supervised problem [ 0 12 0 0] [ 0 0 12 0] 10 [0006]] dirtto 0 0 precision recall f1-score support 8 0 0 rovescio 2 label 0.0 1.00 0.83 0.91 12 6 1.0 0.86 1.00 0.92 12 Free 1.00 1.00 2.0 1.00 12 0 0 battuta - 4 3.0 1.00 1.00 1.00 6 2 0.95 42 accuracy 5 no shot 1 0 0 0.96 42 0.96 0.96 macro avg 0.95 42 weighted avg 0.96 0.95 - 0 dirtto rovescio battuta no shot Predicted label

## SVM





### Electronic Technologies and Biosensors Lab – Project 3 Academic Year 2021/2022 – II Semester

Scaling the data did not lead to significant improvement in the performance of the classifiers, despite improving over fitting in Logistic Regression and KNN; thus, we decided to use the unscaled dataset.

Among the classifiers, we chose **Random Forest** because of:

- √ High F1 score for both training set and test set.
- ✓ Similar F1 scores for training sets and test sets, meaning no overfitting problems.
- ✓ Interpretability of the classifier.