Estimation of Respiration Rate from Three-Dimensional Acceleration Data Based on Body Sensor Network

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Abstract

Respiratory monitoring is widely used in clinical and healthcare practice to detect abnormal cardiopulmonary function during ordinary and routine activities. There are several approaches to estimate respiratory rate, including accelerometer(s) worn on the torso that are capable of sensing the inclination changes due to breathing. In this article, we present an adaptive band-pass filtering method combined with principal component analysis to derive the respiratory rate from three-dimensional acceleration data, using a body sensor network platform previously developed by us. In situ experiments with 12 subjects indicated that our method was capable of offering dynamic respiration rate estimation during various body activities such as sitting, walking, running, and sleeping. The experimental studies also suggested that our frequency spectrum-based method was more robust, resilient to motion artifact, and therefore outperformed those algorithms primarily based on spatial acceleration information.

Key words: dynamic respiratory monitoring, body sensor network, acceleration-derived respiration rate, home health monitoring

Introduction

he necessity for early diagnosis of potentially dangerous conditions, such as sleep apnea¹, sudden infant death syndrome², and chronic obstructive pulmonary disease³ has fostered the development of several methods for measuring respiratory activity, especially in ambulatory settings. As the gold standard, the capnograph device was routinely used in hospital and critical care centers to monitor patients' respiratory status.⁴ Other well-accepted respiratory monitoring techniques and devices are respiratory inductive plethysmograph (RIP)⁵, electrical impedance tomography⁶, thermistors for airflow measurements⁷, piezoelectric transducers, and micro-electromechanical systems (MEMS) accelerometers. Empowered by body sensor network

(BSN) technology these methods became more easily to deploy while being less obtrusive to patients.^{8,9} More recently, Baltag and Popa¹⁰ designed a microwave Doppler transducer and Li et al.¹¹ proposed a radarbased approach for noninvasive respiratory monitoring, but their attempts are still premature for clinical employments.

Accelerometers have been increasingly used in recently years to derive respiration rate. Accelerometers worn on the torso are capable of measuring inclination and angular changes during breathing, and then respiratory rate can be estimated using digital signal processing technology. Hung et al.12 proposed a new approach based on a chest biaxial accelerometer to derive respiratory rate during static body conditions (e.g., sitting, standing and lying down). 13 Anmin et al. 14 suggested a hybrid principal component analysis (PCA) method (using full angles and the PCA) to derive respiratory rate with a three-dimensional (3D) accelerometer during static body conditions. Bates et al. 15 presented a wireless 3D accelerometer device to derive respiration rate, which tracked the axis of rotation and obtained regular rates of breathing motion. The aforementioned methods mainly used spatial acceleration information. Therefore, when the subject was changing position, the respiration rate estimation inevitably deteriorated because the magnitude of the movement-induced signal greatly exceeds that due to breathing, and the posture and orientation of the 3D accelerometer shifted during the disturbance. To cancel these problems, these authors simply removed the acceleration signal episodes that were contaminated by motion artifacts. 14,15

On another side of the spectrum, different frequency spectrum analysis algorithms were developed to derive respiration rate from various physiological signals such as electrocardiograph (ECG), piezoelectric pulse signal, and photoplethymograph (PPG). Band-pass filter¹⁶ and Wavelet transform^{17–19} were applied to derive respiratory rates from single-a lead ECG signal. Dash et al.²⁰ used a time-frequency analysis method to estimate the respiration rate from ECG, PPG, and piezoelectric pulse transducer signals. Chon et al.²¹ used a time-frequency spectral method to estimate respiratory rate from PPG data. It is logical to attempt the spectrum analysis approach for respiration rate estimation from wearable acceleration signals.

This article briefly described a wearable device to sense the 3D acceleration. The device was based on a BSN platform developed by us in previous studies. A novel spectrum analysis method was presented to derive respiration rate from 3D acceleration signals. Consequently, experimental studies were carried out to verify our method and conclusion was given at the end.

System and Methods

The complete system was comprised of hardware modules for 3D acceleration signal acquisition, signal processing algorithms for

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LIU ET AL.

energy expenditure (EE) estimation, and respiration rate estimation, as detailed below.

HARDWARE MODULES

The BSN platform included the node boards that serve as the primary BSN components; the RIP sensor interface board that interfaces with an RIP belt sensor, the ECG interface board that was capable of detecting heart rate from non-contact electrodes, a PPG sensor interface board that interfaces with a generic PPG sensor, a base station board that connects with a personal computer or a personal digital device; a battery board with a wireless charger that provides power supply for the node and sensor boards; and several prototyping boards for debugging purpose. A low-power microprocessor, a radio transceiver, a memory integrated circuit (IC), a 3D accelerometer, a power regulator, a 20-pin expansion port, and affiliated discrete components were integrated on the BSN node. An improved media access control (MAC) protocol was presented to facilitate wireless data communications, which solved collision voidance, message recovery, and power consumption bottlenecks. All the boards, except the base station board, were designed in a uniform form factor that is 23 mm in diameter. There are well-defined expansion ports in all, but the base station board so the boards could be easily stacked. As shown later the BSN modules were assembled as a waistband device for 3D acceleration signal monitoring. Figure 1 illustrated the node board, the resiration belt, the mask, and the experiment setup for 3D acceleration data acquisition.

ACCELEROMETER

The detection of body motions is important for behavior profiling and biofeedback training. 22 A digital built-in 3-axis accelerometer SCA3000

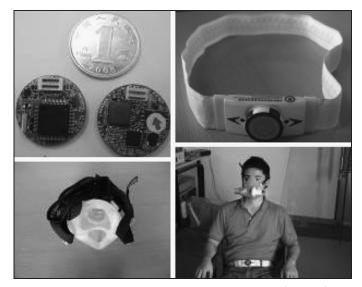


Fig. 1. The node boards for 3D acceleration detection (top, left); the abdomen belt for respration detection (top, right); a mask for BIOPAC $\rm CO_2$ 100C module (bottom, left), the experiment setup (bottom, right). 3D, three-dimensional.

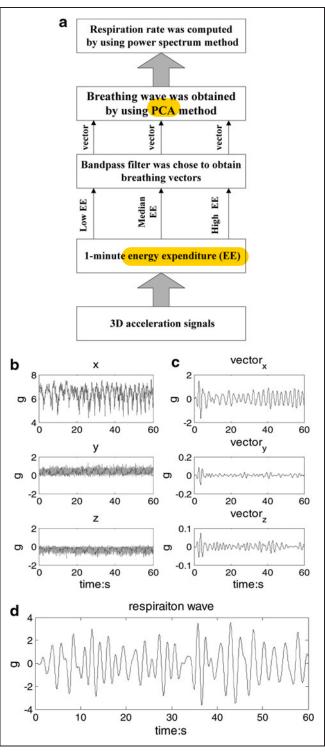


Fig. 2. (a) The step-by-step procedures for motion-derived respiratory rate estimation, (b) raw 3D acceleration signals for 1 min episode, (c) the three vectors derived from 3D acceleration signals by using the band-pass filter based on 1-minute EE, and (d) the respiration wave derived from three vectors by using the PCA method. EE, energy expenditure; PCA, principal component analysis.

DERIVED RESPIRATION RATE FROM 3D ACCELERATION

was equipped in the node board. This device incorporates a 3D MEMS element and a signal conditioning application-specific integrated circuit (ASIC). With its integrated design, the BSN node became more compact and immune to the noises induced by cables and connectors.

3D ACCELERATION-DERIVED RESPIRATION RATE

3D acceleration signals were monitored by the waist-worn device (*Fig. 1*) during various body activities. In general, abdomen motion includes body motion and respiration motion, and the frequency band for respiration ranged from 0.1 to 0.6 Hz during various body activities. The parameters of the band-pass filter were set, according to the EE for every minute, Consequently, the adaptive filter was used to obtain three respiration vectors from *x*, *y*, and *z* coordinates of the 3D acceleration signal, respectively. A PCA method was used to obtain the weight of each vector and to extract the respiration waveform. Finally, the respiration rate was estimated by power spectrum analysis. *Figure 2* demonstrated the procedures that respiration rate was derived from abdomen 3D acceleration signals during different body activities. The algorithm was detailed step by step, as below.

EE CALCULATION

Acceleration signals from the three axes were acquired at a sampling rate of 25 samples per second (Sps). Typically, the acceleration of a moving object consists of two parts: the gravity and acceleration caused by movements, which were called static accelerations and dynamic accelerations, respectively. It is the latter that was primarily concerned in our experiments. A high-pass filter (-3dB bandwidth was 1 Hz) was employed to eliminate the static portions. The acceleration signal Ai was defined as²⁴:

$$\Delta A(i) = \left[(x(i+1) - x(i))^2 + (y(i+1) - y(i))^2 + (z(i+1) - z(i))^2 \right]^{1/2} \tag{1}$$

The **EE** for the abdomenal part was calculated as:

$$EE = \sum \Delta A(i) \text{ over 1 min} \tag{2}$$

The routine activities were classified based on EE as: If EE < 100, the activity was considered to be with low EE; If $100 \le EE < 400$, the activity was considered to be with median EE; If $EE \ge 400$, the activity was considered to be with high EE;

Table 1. Bandpass Digital Filter Parameters							
ABDOMEN MOTION EE	BODY ACTIVITIES	FREQUENCY BAND (HZ)	STOP BAND (HZ)	COEFFICIENT			
Low EE	Sitting: 30 min sitting with minor movements Strict sitting: 5 min	0.2-0.4	0.15–0.45	Rp=6 Rs=15			
	Sleeping: normal sleeping for a night	0.2-0.4	0.15-0.45	Rp=6 Rs=15			
Median EE	Walking: 3 min slow walk with 2.5 km/h	0.2-0.6	0.15-0.65	Rp=9 Rs=15			
High EE	Running: 5 min run with 6.0 km/h	0.3-0.7	0.2-0.8	Rp=3 Rs=15			
EE, energy expenditure.							

ADAPTIVE DIGITAL FILTER

The respiratory rate is approximately 0.1 to 0.6 Hz during different body activities. According to the different EE values conducted from abdomen motions, the parameters of Butterworth band-pass filter were adaptively selected to derive respiration vectors from x, y, and z co-ordinates of 3D acceleration signals, separately. The parameters of Butterworth digital filter are shown in *Table 1*; the pass-band ripple Rp denotes the maximum permissible pass-band loss in decibels, and the stop-band attenuation Rs denotes the number of decibels that the stop-band is down from the pass-band.

PRINCIPLE COMPONENT ANALYSIS

Because of the unpredicted posture changes during routine activities and the geometric deployment of the accelerometer, a PCA-based method was proposed to obtain the weight of the respiration vectors from the *x*-, *y*-, and *z*-axis accelerations.

Table 2. Motion-Derived Respiratory Rate Experiments with Abdomen Accelerometer								
ACTIVITIES	PROTOCOL	GOLDEN STANDARD	MAINLY MOTION					
Stationary activity	Strict sitting quietly for 5min	CO ₂ analysis with Biopic CO ₂ 100C	abdomen motion					
	Sitting with minor movements for 30 min	module	Body/abdomen					
Dynamic activity	Walking for 3 min with 2 km/h		Body motion					
	Running for 5 min with 6 km/h		Body motion					
Sleeping	Sleeping for above 6 h		Body/Abdomen					

LIU ET AL.

PCA is generally used for dimension reduction of multivariate datasets.²⁵ In this article the implementation is as follows:

First, denoting the three co-ordinate acceleration vectors time series as matrix $\sum = \{\text{vector}_x(k); \text{vector}_y(k); \text{vector}_z(k)\}.$

Second, the eigenvectors and corresponding eigenvalues $(\lambda_1, \lambda_2, \lambda_3)$ of \sum was computed based on classic PCA method.

Third, the weights for three co-ordinate acceleration vectors were obtained as the following equations:

$$\eta_i = \frac{\lambda_i}{\lambda_1 + \lambda_2 + \lambda_3} \qquad (i = 1, 2, 3) \tag{3}$$

At last, the x_0 represents the respiratory time sequence by

$$x_0 = \eta_1 vector_x + \eta_2 vector_y + \eta_3 vector_z$$
 (4)

Where the $vector_x$, $vector_y$, and $vector_z$ denote the vectors from x, y, and z co-ordinates of 3D acceleration filtered using adaptive band-pass filter, respectively.

SPECTRUM ANALYSIS

Respiratory rate was estimated by using the power spectrum for every 1-min episode.

Experiment

PROTOCOL OF THE EXPERIMENT

Twelve healthy subjects with a mean age of 23.5 years (between 21 and 32) have participated in experiment 1 as shown in *Table 2*. All subjects were chosen randomly. The experiment protocol was illustrated in *Figure 3*:

The reference signal (being golden standard in our experiments) was obtained by the airflow CO_2 analysis with a BIOPAC CO_2 100C module (Fig. 1).

3D-ACCELERATION DERIVED RESPIRATION METHODS

To derive respiration rate from 3D acceleration signals, different methods based on wavelet decompositions acceleration-derived respiration (ADR)1-2 and nonadaptive band-pass filters (ADR3-4) were used, based on the indications in the literature of their potential merits and preliminary review of their implemented results.

- (1) ADR1: respiration rate was derived by using wavelet decomposition, scale 6, and power spectrum from the 3D acceleration signals.
- (2) ADR2: respiration rate was derived by wavelet decomposition, scale 5 plus scale 6, and power spectrum from the 3D acceleration signals.

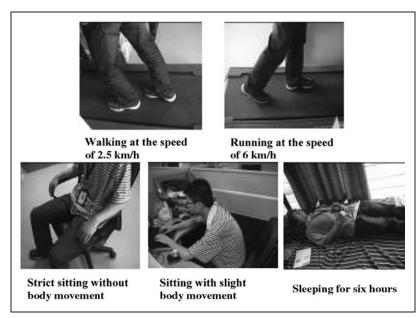


Fig. 3. The experiment circuit.

- (3) ADR3: respiration rate was derived with band-pass 0.2-0.8 Hz and power spectrum, from 3D acceleration signals.
- (4) ADR4: respiration rate was derived with band-pass 0.2–0.6 Hz and power spectrum, from 3D acceleration signals.
- (5) ADR5: our method, as detailed in the previous session.

STATISTICAL ANALYSIS

The accuracy of each method was estimated by the average percentage error of the measurements in comparison with the reference

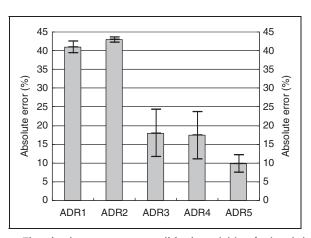


Fig. 4. The absolute error across all body activities (strict sitting, sitting with minor movement, walking, and running). Mean ± one standard deviation was plotted. ADR1-2 meant 3D-ADR rate based on wavelet; ADR3-4 meant 3D-ADR rate based on band-pass filter; ADR5 as detailed in the previous article. ADR, acceleration derived respiration.

DERIVED RESPIRATION RATE FROM 3D ACCELERATION

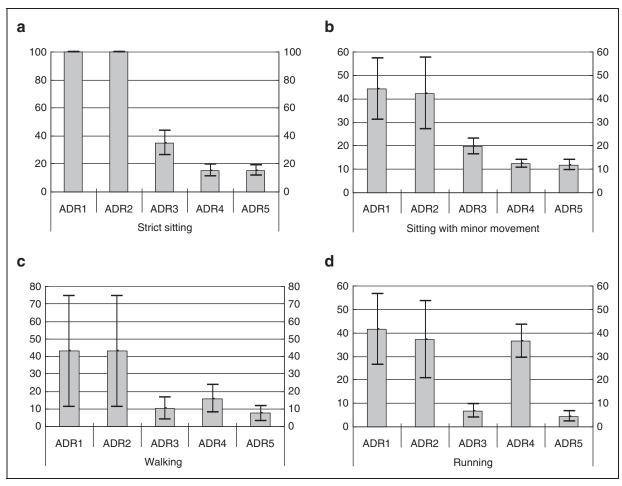


Fig. 5. The mean absolute errors of five methods during various body activates (e.g., strict sitting (a), sitting with minor movement (b), walking (c), and running (d)); Mean ± one standard deviation were plotted. ADR1-2 meant 3D-ADR rate based on wavelet; ADR3-4 meant 3D-ADR rate based on band-pass filter; ADR5 meant 3D-ADR rate based on PCA and band-pass filter that we designed in the article.

value, calculated by subtracting the test value from the reference value and dividing the results by the reference value of each measurement. Absolute value was used in our study to minimize error offset between each experiment.

Error =	$\frac{ (Derived - reference) }{ (Derived - reference) } \times 100 (\%)$	(5)
LIIII -	Observed (70)	(5)

If
$$Error > 100$$
, $Error = 100$ (6)

Table 3. Difference in Derived Respiratory Rate for Controlled 0.5-h Test							
	DERIVED RESPIRATION METHODS: MEAN±ONE STANDARD						
ACTIVITIES	ADR1	ADR2	AD3	ADR4	ADR5		
Quiet	100±0	100±0	34.86±17.43	15.36±8.10	15.46 ± 7.67		
Sitting	44.26±26.03	42.36±30.67	19.85±15.45	12.39±3.38	11.79 ± 4.35		
Walking	43.03 ± 63.22	42.83 ± 63.03	10.35 ± 12.63	15.86±15.59	7.45 ± 8.62		
Running	41.52 ± 30.29	37.32±32.82	6.79 ± 5.61	36.62 ± 14.22	4.52 ± 4.34		

Mean absolute error difference with the reference value in breaths per minute (Bold values if significant difference with the reference value at α = 0.05).

ADR, acceleration derived respiration.

We did the statistical tests (with SPSS v17.0) for all the experiments. Mean and standard deviations were used to evaluate the mean absolute error between the derived results and the reference values. Where two datasets were compared, we performed two sample t-tests for each individual method. The significance level was chosen as α =0.05.

Results

OVERALL PERFORMANCE OF ALL ACTIVITIES

Figure 4 depicts the mean absolute errors for the derived values and the

LIU ET AL.

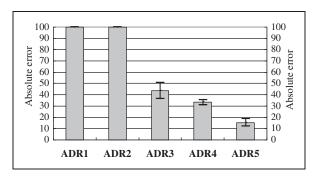


Fig. 6. The mean absolute error of ADR1-5 during sleeping. Mean±one standard deviation were plotted. ADR1-2 meant 3D ADR rate based on wavelet; ADR3-4 meant 3D ADR rate based on band-pass filter; ADR5 meant 3D ADR rate based on PCA and band-pass filter in this article.

reference value during different body activities (strict sitting, sitting with minor movement, walking, and running). The result demonstrated that the ADR5 method achieved the least mean absolute error against the reference value at 10% approximately. The wavelet-based method (ADR1–2), which had the mean absolute error at 30%, had more significant difference with the reference value. The band-pass-based method (ADR3–4) had the mean absolute error at approximate 20%. This demonstrated that our method (ADR5) improved the measure accuracy, comparing with other methods.

PERFORMANCE FOR DIFFERENT ACTIVITIES

The dataset was partitioned into the following activity categories: strict sitting, sitting with minor movement, walking, and running. *Figure 5* indicates mean absolute differences for all methods. It is clear that the wavelet decomposition methods (ADR1 and ADR2) have the largest mean absolute error with the reference value during each body activity. However, The ADR5 method we have presented had the least mean absolute error with the reference value during each body activity. The band pass method (ADR3) had the similar performance to the ADR5 during walking and running, and the ADR4 had also the similar performance to the ADR5 during strict sitting and sitting with minor movement. The result demonstrated our algorithm improved the measure accuracy.

Table 3 demonstrates the difference in derived respiratory rate with reference value for all activities. Statistical testing shows that the wavelet methods (ADR1–2) had significant differences with the reference value at α =0.05 during each body activity. The ADR5 method did not have significant difference during each activity. The band-pass methods (ADR3–4) had significant differences with the reference value at α =0.05 during some activities, such as strict sitting (ADR3) and running (ADR4).

PERFORMANCE FOR OVERNIGHT MONITORING

Simultaneous respiratory and acceleration monitoring were performed for 10 subjects for overnight sleep monitoring. The result in *Figure 6* demonstrated that our algorithm outperformed the other data processing methods used in this article.

Discussion

An adaptive and frequency spectrum-based method was designed to estimate respiratory rate, because spatial acceleration information could be easily contaminated during various body activities. For example, Bates et al. 15 used a threshold method to remove contaminated acceleration signals and only 45% of the whole dataset was left for respiration rate estimation. 15 In contrast with Bates et al. 15 our algorithm was able to estimate respiration rate from the complete dataset without data tailoring. *Figure 7* summarized the magnitudes of the movement-induced signals during different body activities.

Denoting the respiration time series as x[k] and the reference signal as y[k], the correlation coefficient ρ_{xy} was calculated as

$$\rho_{xy} = \sum_{k=1}^{N-n} (x(k) - \overline{x(k)})(y(k+n) - \overline{y(k+n)}) / \sqrt{\sum_{k=1}^{N} (x(k) - \overline{x(k)})^2 \sum_{k=1}^{N} (y(k) - \overline{y(k)})^2}$$
(7)

Figure 8 indicates the variance of the correlation coefficient across all body activities, which suggested larger correlation coefficient during walking and running activities. This is because the frequency-domain expression (calculated with our ADR5 method) caused by respirations was enhanced due to physical exercise. This is clearly advantageous against those spatial acceleration-based methods, in which the correlation coefficient was reduced due to physical exercise.

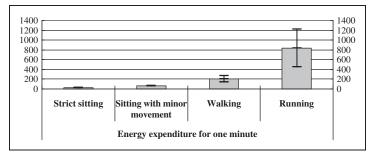


Fig. 7. EEs from abdomen motion during various body activities. Mean \pm one standard deviation were plotted.

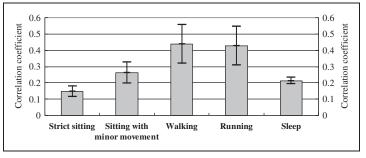


Fig. 8. Correlation coefficients between the outputs from the ADR5 method and the golden standard across all activities.

DERIVED RESPIRATION RATE FROM 3D ACCELERATION

Conclusions

This article presents a respiration rate estimation method based on a generalized BSN development platform. The frequency spectrum-based algorithm, which combined PCA and adaptive band-pass filtering, was designed to derive respiration rate from 3D acceleration signal during various activities. *In situ* experiment results indicated our method was capable of offering pervasive respiration rate monitoring during various body activities. Furthermore, the result demonstrated that our method was more robust, resilient to motion artifact, and, therefore, outperformed those algorithms primarily based on spatial acceleration information. In the future we will investigate the long-term monitoring of the respiration rate using our method.

Disclosure Statement

No competing financial interests exist.

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