Online version:





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Computer vision scientist (M. A. Sc.) specialized in medical imaging. I define myself as a **curious** and **autonomous** person with ease in **communication**.

Professional profile _____

Epipolar geometry, optical calibration, image/volume registration and reconstruction, metrology procedures, AI, statistical analysis, tracking, ultrasound, 3D rendering, GPGPU, camera and computer hardware.

Education

ÉTS (École de technologie supérieure) Montréal (include McGill course)

M. A. Sc. in Electrical Engineering, graduated with honors, GPA: 4.1/4.3 Sept. 2014 - Aug. 2016

Lyon INSA (National Institute of Applied Sciences of Lyon)

M. Eng. in Electrical Engineering

Sept. 2012 - Aug. 2016

IUT (University Institutes of Technology) Lyon 1

TECHNICAL DEGREE IN INDUSTRIAL ENGINEERING AND MAINTENANCE, GRADUATED WITH HONORS

Lyon, FRANCE

Lyon, FRANCE

Montréal, CANADA

Sept. 2010 - Jun. 2012

Skills

Low-level programming C++11 (OpenCV, Ceres, Boost, Eigen), C (GSL, MEX), CUDA, Assembly

High-level programming Python (Matplotlib, Numpy, Plotly, jupyter, TensorFlow), MATLAB (statistical and machine learning toolbox)

Softwares VS 2017, TortoiseGit, Redmine, Spyder, ET_FX, Blender, cMake, make

Operating systems Windows, GNU/Linux

Languages French (mother tongue), Polish (fluent), English (professional, TOEIC 925), Spanish (basics)

Work Experience ____

Dental Wings/Straumann Group, Digital Business Unit

Montréal, CANADA Dec. 2016 - PRESENT

C++ COMPUTER VISION DEVELOPPER: 3D SOLUTIONS FOR DIGITAL DENTISTRY.

· Algorithms for optical calibration, 3D scanning/reconstruction, dental metrology, with state of the art technology.

Prototyping in Python (Numpy, plotly, jupyter notebooks)

Agile development in C++ (OpenCV, Ceres, Eigen, Boost)

Building and versioning (VS 2017, Git)

- Conception of a virtual scanner for hardware/software experimentation and validation.
- Camera (and other devices) hardware validation. CMOS and camera integration.
- Conferences attendance (CVPR 2018, Agile Tour 2017), open days for recruiting interns (Concordia university, Polytechnique, McGill).

LATIS, ÉTS Montréal Montréal, CANADA

RESEARCH ASSISTANT (*): GRAPH-BASED ESTIMATION OF PROBE TRAJECTORY FOR SENSORLESS FREEHAND 3D US.

Jan. 2015 - Nov. 2016

- Calibration of optical and electromagnetic probes for freehand 3D US. Development in C++ (3rd party lib, SVN) and compilation (CMake).
- · Image registration from echographic sequence using speckle-decorrelation. Trajectory estimation by a directed graph with uncertainty (gaussian process regression and Lie Algebra). https://link.springer.com/chapter/10.1007/978-3-319-47157-0_25

Programming in C/C++ (GSL, OpenCV, Boost, Eigen), compilation under GNU/Linux (make) Quantitative and qualitative analysis (MATLAB)

• Poster presentation at Colloque REPARTI 2016. Accepted paper for MICCAI/MLMI 2016 conference.

Thales Group, Thales Air Systems

Limours, FRANCE Feb. 2014 - Aug. 2014

INTERN (*): FAST INITIALIZATION OF CARTESIAN TRACK USING FM BAND

- Track initialization in cartesian coordinates with range measurements, using a custom non-linear filter and statistical methods. Implementation on MATLAB.
- Validation on aircraft records.

Validation on MATLAB (MEX function) and C++ (Eigen).

Relevant Projects

- Blog about comuter science (html, jupyter notebooks). https://ltetrel.github.io/.
- Automatic row counting for kniting. Image processing and edge detectors (Python).
- Stock market indicator analysis for best investment (Matlab, TensorFlow).
- Design of an autonomous robot's detection system for an international competition. Programming (C) and PCB design (Altium).

McGill, ÉTS Montréal Montréal, CANADA

SHOOL PROJECTS

2014 - 2016

- · Registration of MRI and CT images using Gaussian Process interpolation with uncertainty.
- GPGPU and GPU architecture introduction, Sobel filtering development using CUDA (NPP) on Nvidia GTX.
- Automatic classification and prediction models for early Parkinson disease. Features extracted from MRI images of patient's brain.

Lvon INSA Lvon, FRANCE

SHOOL PROJECT MANAGER: BUSINESS CREATION SIMULATION FOR ELECTRONIC SHOES.

Sept. 2012 - Jun. 2013

· Team management of 10 people with establishment of project plan, functional analysis and marketing mix.

Volunteer Experience

Hacking Health Montreal Montréal, CANADA

EVENT VOLUNTEER Oct. 2016 - Dec. 2016

· Promote innovations between health and science. Helped the organization of HIP Ottawa 2016 in CHEO-OCTC.

Big Band ÉTS Montréal, CANADA

EVENT COORDINATOR AND GUITARIST Sept. 2015 - Aug. 2016

YES (Young Employees Society) Thales

Limours, FRANCE

Feb. 2014 - Aug. 2014 MEMBER

• Young professional events. Thales trainees forum day.

ClubElek (Lyon INSA) Lyon, FRANCE

BEGINNER TEAM MANAGER Sept. 2012 - Jun. 2013

Conception of an autonomous robot. Coordinator assistant for InnoRobo Lyon 2013.

IUT Lyon 1 Lyon, FRANCE

FREE TUTORING IN MATHEMATICS Sep. 2010 - Jun. 2012

Conferences & Awards

Salt Lake City (UT), Jun, 2018 **CVPR 2018**, Attendance to promote computer vision research for Staumann. USA

Nov, 2017 Agile Tour 2017, Training for agile development. Montréal, CANADA

Grant, Bourse interne ÉTS: merit scholarship for graduate students (3.000 CAD). Montréal, CANADA 2016

Oct, 2016 MICCAI 2016, Poster presentation of thesis work. Athens, GREECE

May, 2015 **1st place**, 24h de l'innovation : Mobile app to teach science for children. Montréal, CANADA

2014 Grant, Explora'sup: regional merit scholarship for undergraduate students (2.000 EUR). Lyon, FRANCE

March, InnoRobo 2013, Volunteer work as an event coordinator. Lyon, FRANCE 2013

La Ferté Bernard, 2013 Qualification phase, Eurobot: international robotic contest with autonomous robots.

FRANCE

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March,

Europe (France, Poland, England, Spain, Germany, Greece, Switzerland), USA (UT, FL, CA, NV, NY), Canada (QC, ON, BC), Asia (Thailand) **Travels**

Hobbies IT (video games, computer vision, blockchain), politics, reading books (fantasy, SF), playing music (rock, jazz)

Sports Weight training, ski, salsa dance