VIETNAM NATIONAL UNIVERSITY, HANOI UNIVERSITY OF ENGINEERING AND TECHNOLOGY

SOCIALIST REPUBLIC OF VIETNAM Independence – Freedom – Happiness

EXAMINATION QUESTIONS AND EXERCISES

1. Course Information

Course title: Signals and Systems

Course ID: ELT2035Number of credits: 03

- Number of credit hours (Lec/Lab/Prep): 45 (42/3/0)

- Presiquisite: MAT1095

- Course group: Compulsory **■** Elective □

2. Lecturer's Information

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3. List of Questions and Exercises

3.1. Multiple-choice questions

<u>Question 1</u>. Which one of the following statements is INCORRECT?

- A. An energy signal can not be periodic.
- B) A power signal can not have finite energy.
- C. A sinusoidal is a power signal.
- D. A finite-length signal can be a power signal.

Question 2. Which one of the following statements is INCORRECT?

- A. The impulse response of a causal LTI system is a causal signal.
- B. The impulse response of a stable LTI system is an energy signal.
- C. The impulse response of a stable LTI system is a finite-length signal.
- D. The frequency response of a discrete-time stable LTI system is a continuous-frequency function.
- E. The frequency response of a discrete-time LTI system is periodic.

Question 3. Given a system described by the equation y(n)-y(n-1) = x(n), which one of the following statements is INCORRECT about this system?

- A. The system is linear.
- B. The system is time-invariant.
- C. The system is stable.
- D. The system is causal.

Types of credit hours: Lecture hours; Tutorial/Lab hours; Self preparatory hours.

Question 4. Which one of the following statements is INCORRECT?

- A. All poles of a stable continuous-time causal LTI system must be in the right half of the s-plane.
- B. All poles of a stable discrete-time causal LTI system must be inside the unit circle in the z-plane.
- C. The region of convergence (ROC) of the transfer function of a stable continuoustime LTI system must contain the $j\omega$ axis of the s-plane.
- D. The region of convergence (ROC) of the transfer function of a stable discretetime LTI system must contain the unit circle in the z-plane.

Question 5. Which one of the following signals is NOT periodic:

A.
$$x(t) = [\cos(2\pi t)]^2$$

B.
$$x(t) = \sum_{k=-\infty}^{+\infty} w(t-3k)$$
, where $w(t) = \begin{cases} 0 & (t \le -1 \lor t > 1) \\ 1+t & (-1 < t \le 0) \\ 1-t & (0 < t \le 1) \end{cases}$

B.
$$x(t) = \sum_{k=-\infty}^{+\infty} w(t-3k)$$
, where $w(t) = \begin{cases} 0 & (t \le -1 \lor t > 1) \\ 1+t & (-1 < t \le 0) \\ 1-t & (0 < t \le 1) \end{cases}$

C. $x(t) = \sum_{k=-5}^{5} w(t-2k)$, where $w(t) = \begin{cases} 0 & (t \le -1 \lor t > 1) \\ 1+t & (-1 < t \le 0) \\ 1+t & (-1 < t \le 0) \\ 1-t & (0 < t \le 1) \end{cases}$

D.
$$x(n)=(-1)^n$$

<u>Ouestion 6</u>. Which one of the following signals is NOT periodic:

$$A. x(n) = \cos(2n)$$

B.
$$x(n) = \cos(2\pi n)$$

C.
$$x(n) = \sum_{k=-\infty}^{+\infty} \{ (-1)^k [\delta(n-2k) + \delta(n+3k)] \}$$

D.
$$x(n) = 2\sin(4\pi n/19) + \cos(10\pi n/19) + 1$$

Question 7. Which of the systems described by the following impulse responses is memoryless?

$$h(t) = \cos(\pi t)$$

B.
$$h(t) = e^{-2t}u(t-1)$$

B.
$$h(t) = e^{-2t}u(t-1)$$

C. $h(t) = u(t+1)$

$$h(t) = 3\delta(t)$$

Question 8. Which of the systems described by the following impulse responses is memoryless?

A.
$$h(n) = (-1)^n u(-n)$$

B.
$$h(n)=(1/2)^{|n|}$$

C.
$$h(n)=2^{n}[u(n)-u(n-1)]$$

D.
$$h(n) = \cos(\pi n/8)[u(n) - u(n-10)]$$

Question 9. Which of the systems described by the following impulse responses is causal?

2

A.
$$h(t) = \cos(\pi t)$$

B.
$$h(t) = e^{-2t}u(t-1)$$

$$h(t) = u(t+1)$$

Question 10. Which of the systems described by the following impulse responses is causal?

A.
$$h(n)=(-1)^n u(-n)$$

B.
$$h(n)=(1/2)^{|n|}$$

C.
$$h(n)=u(n)-2u(n-5)$$

D.
$$h(n) = \sin(\pi n/2)$$

Question 11. Which of the systems described by the following impulse responses is stable?

A.
$$h(t) = \cos(\pi t)$$

B.
$$h(t) = e^{-2t}u(t-1)$$

C.
$$h(t) = u(t+1)$$

D.
$$h(t) = \cos(\pi t) u(-t)$$

Question 12. Which of the systems described by the following impulse responses is stable?

A.
$$h(n) = \sin(\pi n/2)$$

B.
$$h(n)=(-1)^n u(-n)$$

C.
$$h(n)=u(n)-2u(n-5)$$

D.
$$h(n) = \sum_{k=0}^{+\infty} \delta(n-2k)$$

Question 13. Which of the following systems is a causal linear time-invariant system?

A.
$$y(t) = (t-1)x(t)$$

B.
$$y(t)=x(t)-2x(t/2)$$

C.
$$y(n) = x(n) + y(n-1)$$

D.
$$y(n) = |x(n) - x(n-1)|$$

Question 14. What is the appropriate Fourier representation of the following signal:

$$x(t) = e^{-t} \cos(2\pi t) u(t)$$

Question 15. What is the appropriate Fourier representation of the following signal:

$$x(n) = \begin{cases} \cos(\pi n/10) + j\sin(\pi n/10) & (|n| < 10) \\ 0 & (|n| \ge 10) \end{cases}$$

- A. The continuous-time Fourier transform (FT).
- B. The discrete-time Fourier transform (DTFT).
- C. The continuous-time Fourier series (FS).
- The discrete-time Fourier series (DTFS).

Question 16. What is the appropriate Fourier representation of the following signal:

$$x(t) = e^{1+t}u(2-t)$$

- A The continuous-time Fourier transform (FT).
- B. The discrete-time Fourier transform (DTFT).
- C. The continuous-time Fourier series (FS).
- D. The discrete-time Fourier series (DTFS).

Question 17. What is the appropriate Fourier representation of the following signal:

$$x(t) = |\sin(2\pi t)|$$

- A. The continuous-time Fourier transform (FT).
- B. The discrete-time Fourier transform (DTFT).
- C. The continuous-time Fourier series (FS).
- D. The discrete-time Fourier series (DTFS).

Question 18. What is the appropriate description of the system described by the following impulse response:

$$h(t) = \delta(t) - 2e^{-2t}u(t)$$

- A. A low-pass filter.
- B. A high-pass filter.
- C. A band-pass filter.
- D. A band-reject filter.

Question 19. What is the appropriate description of the system described by the following impulse response:

$$h(t) = 4e^{-2t}\cos(50t)$$

- A. A low-pass filter.
- B. A high-pass filter.
- C. A band-pass filter.
- D. A band-reject filter.

Question 20. What is the appropriate description of the system described by the following impulse response:

$$h(n) = \frac{1}{8} \left(\frac{7}{8}\right)^n u(n)$$

- A. A low-pass filter.
- B. A high-pass filter.
- C. A band-pass filter.
- D. A band-reject filter.

Question 21. What is the appropriate description of the system described by the following impulse response:

$$h(n) = \begin{cases} (-1)^n & (|n| \le 10) \\ 0 & (|n| > 10) \end{cases}$$

- A. A low-pass filter.
- B. A high-pass filter.
- C. A band-pass filter.
- D. A band-reject filter.
- Question 22. What is the initial value of the signal x(t), given its Laplace transform as follows:

$$X(s) = \frac{1}{s^2 + 5s - 2}$$



- **-**. 0
- B. 1
- C. 2
- D. -1
- Question 23. What is the initial value of the signal x(t), given its Laplace transform as follows:

$$X(s) = \frac{s+2}{s^2 + 2s - 3}$$

- A. 0
- **B** 1
- C. 2
- D. -1
- Question 24. What is the initial value of the signal x(t), given its Laplace transform as follows:

$$X(s) = e^{-2s} \frac{6 s^2 + s}{s^2 + 2 s - 2}$$



- B
- C. 2
- D. -1

Question 25. What is the final value of the signal x(t), given its Laplace transform as follows:

$$X(s) = \frac{2 s^2 + 3}{s^2 + 5 s + 1}$$



- B. 2
- C. 1/2
- D. 1/4

Question 26. What is the final value of the signal x(t), given its Laplace transform as follows:

$$X(s) = \frac{s+2}{s^3 + 2 s^2 + s}$$

- A. 0
- B. 2



D. 1/4

Question 27. What is the final value of the signal x(t), given its Laplace transform as follows:

$$X(s) = e^{-3s} \frac{2 s^2 + 1}{s (s+2)^2}$$

- A. 0
- B. 2
 - C. 1/2
 - D. 1/4

Question 28. Which one of the systems described by the following transfer functions can NOT be both causal and stable?

A.
$$H(s) = \frac{(s+1)(s+2)}{(s+1)(s^2+2s+10)}$$

B.
$$H(s) = \frac{s^2 - 3s + 2}{(s+2)(s^2 - 2s + 8)}$$

C.
$$H(s) = \frac{s^2 + 2s - 3}{(s+3)(s^2 + 2s + 5)}$$

D.
$$H(s) = \frac{(s+1)(s^2+2s+10)}{(s+1)(s+2)}$$

Question 29. For which of the following signals does the discrete-time Fourier transform NOT exist?

6

A.
$$x(n) = \delta(n-1)$$

B.
$$x(n) = \delta(n+1)$$

C.
$$x(n)=(2/3)^{|n|}$$

D.
$$x(n)=(1/4)^n u(-n)$$

Question 30. Which one of the systems described by the following transfer functions can be both causal and stable?

A.
$$H(z) = \frac{2z+3}{z^2+z-5/16}$$

B.
$$H(z) = \frac{z^{-1}}{[1-(1/2)z^{-1}](1+3z^{-1})}$$

C.
$$H(z) = \frac{z^2 - 1/4}{6z^2 + 7z + 3}$$

D.
$$H(z) = \frac{z^{-2}}{1 - (1/2)z^{-1} + (1/4)z^{-2}}$$

3.2. Exercises

Exercise 1. Find the fundamental period of the following periodic signal:

$$x(t) = [\cos(2\pi t)]^2$$

Exercise 2. Find the fundamental period of the following periodic signal:

$$x(t) = \sum_{k=-\infty}^{+\infty} w(t-3k) \text{ , where } w(t) = \begin{cases} 0 & (t \le -1 \lor t > 1) \\ 1+t & (-1 < t \le 0) \\ 1-t & (0 < t \le 1) \end{cases}$$

Exercise 3. Find the fundamental period of the following periodic signal:

$$x(n)=(-1)^n$$

Exercise 4. Find the fundamental period of the following periodic signal:

$$x(n) = \cos(2\pi n)$$

<u>Exercise 5</u>. Determine the impulse response of a continuous-time LTI system described by the following equation:

$$y(t) + 3 \frac{dy(t)}{dt} + 2 \frac{d^2 y(t)}{dt^2} = \frac{dx(t)}{dt}$$

<u>Exercise 6</u>. Determine the magnitude response and the phase response of a continuous-time LTI system decsribed by the following equation:

$$y(t)+3\frac{dy(t)}{dt}+2\frac{d^2y(t)}{dt^2}=\frac{dx(t)}{dt}$$

<u>Exercise 7</u>. Determine the transfer function of a causal discrete-time LTI system described by the following equation:

$$y(n)+3y(n-1)+2y(n-2)=x(n-1)$$

<u>Exercise 8</u>. Determine the step response of a causal discrete-time LTI system described by the following equation:

$$y(n)+3y(n-1)+2y(n-2)=x(n-1)$$

Exercise 9. A discrete-time LTI system has the following impulse response:

$$h(n)=2^{-n}u(n)$$

Determine the output of the system when the input signal is:

$$x(n) = \sin(\pi n/3 + \pi/4) + 2$$

Exercise 10. Determine the impulse response of the following causal LTI system:

$$\frac{dy(t)}{dt} - y(t) = x(t) + x(t-1)$$

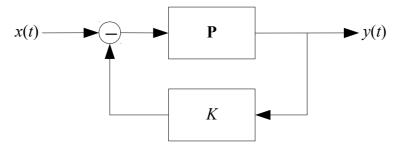
Exercise 11. Determine the impulse response of the following causal LTI system:

$$4y(n)-y(n-2)=x(n)-2x(n-1)$$

Exercise 12. The negative feedback control system shown in figure bellow has a plant $\bf P$ and a feedback coefficient of K, in which the plant $\bf P$ is described by the equation

$$\frac{dy(t)}{dt} - 2y(t) = x(t)$$

and *K* is a real value.

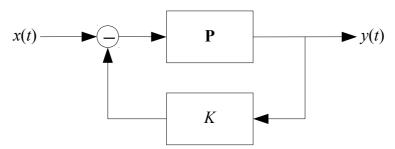


Compute the transfer function of the feedback control system.

Exercise 13. The negative feedback control system shown in figure bellow has a plant \mathbf{P} and a feedback coefficient of K, in which the plant \mathbf{P} is described by the equation

$$\frac{dy(t)}{dt} - 2y(t) = x(t)$$

and *K* is a real value.



Determine *K* so that the system is causal and stable.

<u>Exercise 14</u>. Determine the frequency response of an LTI system having the following impulse response:

$$h(t) = \sin(t)[u(t) - u(t-1)]$$

<u>Exercise 15</u>. Determine the response of an LTI system having the following impulse response:

$$h(t) = \sin(t)[u(t) - u(t-1)]$$

to the input signal:

$$x(t) = \cos(2t + \pi/4) + 1$$

<u>Exercise 16</u>. Determine the step response of the system having the following impulse response:

$$h(n) = (-1/2)^n u(n)$$

<u>Exercise 17</u>. Determine the step response of the system having the following impulse response:

$$h(n) = \delta(n) - \delta(n-2)$$

Exercise 18. Determine the step response of the system having the following impulse response:

$$h(n)=(-1)^n[u(n+2)-u(n-3)]$$

Exercise 19. Determine the step response of the system having the following impulse response:

$$h(n)=nu(n)$$

<u>Exercise 20</u>. Determine the step response of the system having the following impulse response:

$$h(t) = (1/4)[u(t) - u(t-4)]$$

Exercise 21. Determine the step response of the system having the following impulse response:

$$h(t)=u(t)$$

Exercise 22. Determine the homogeneous solution for the system described by the following differential equation:

$$5\frac{dy(t)}{dt} + 10 y(t) = 2 x(t)$$

<u>Exercise 23</u>. Determine the homogeneous solution for the system described by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 6 \frac{dy(t)}{dt} + 8 y(t) = \frac{dx(t)}{dt}$$

<u>Exercise 24</u>. Determine the homogeneous solution for the system described by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 4 y(t) = 3 \frac{dx(t)}{dt}$$

<u>Exercise 25</u>. Determine the homogeneous solution for the system described by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + 2 y(t) = x(t)$$

<u>Exercise 26</u>. Determine the homogeneous solution for the system described by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + y(t) = \frac{dx(t)}{dt}$$

Exercise 27. Determine the homogeneous solution for the system described by the following difference equation:

$$y(n)-ay(n-1)=2x(n)$$

<u>Exercise 28</u>. Determine the homogeneous solution for the system described by the following difference equation:

$$y(n)-(1/4)y(n-1)-(1/8)y(n-2)=x(n)+x(n-1)$$

<u>Exercise 29</u>. Determine the homogeneous solution for the system described by the following difference equation:

$$y(n)+(9/16)y(n-2)=x(n-1)$$

<u>Exercise 30</u>. Determine the homogeneous solution for the system described by the following difference equation:

$$y(n)+y(n-1)+(1/4)y(n-2)=x(n)+2x(n-1)$$

<u>Exercise 31</u>. Determine the particular solution for the system described by the following differential equation:

$$5\frac{dy(t)}{dt} + 10 y(t) = 2 x(t)$$

given the input:

$$x(t)=2$$

<u>Exercise 32</u>. Determine the particular solution for the system described by the following differential equation:

$$5\frac{dy(t)}{dt} + 10 y(t) = 2 x(t)$$

given the input:

$$x(t)=e^{-t}$$

Exercise 33. Determine the particular solution for the system described by the following differential equation:

$$5\frac{dy(t)}{dt} + 10y(t) = 2x(t)$$

given the input:

$$x(t) = \cos(3t)$$

Exercise 34. Determine the particular solution for the system described by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 4 y(t) = 3 \frac{dx(t)}{dt}$$

given the input:

$$x(t)=t$$

<u>Exercise 35</u>. Determine the particular solution for the system described by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 4 y(t) = 3 \frac{dx(t)}{dt}$$

given the input:

$$x(t)=e^{-t}$$

<u>Exercise 36</u>. Determine the particular solution for the system described by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 4 y(t) = 3 \frac{dx(t)}{dt}$$

given the input:

$$x(t) = \cos(t) + \sin(t)$$

Exercise 37. Determine the particular solution for the system described by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + y(t) = \frac{dx(t)}{dt}$$

given the input:

$$x(t) = e^{-3t}$$

Exercise 38. Determine the particular solution for the system described by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + y(t) = \frac{dx(t)}{dt}$$

given the input $x(t)=2e^{-t}$

<u>Exercise 39</u>. Determine the particular solution for the system described by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + y(t) = \frac{dx(t)}{dt}$$

given the input:

$$x(t)=2\sin(t)$$

<u>Exercise 40</u>. Determine the particular solution for the system described by the following difference equation:

$$y(n)-(2/5)y(n-1)=2x(n)$$

given the input:

$$x(n)=2u(n)$$

Exercise 41. Determine the particular solution for the system described by the following difference equation:

$$y(n)-(2/5)y(n-1)=2x(n)$$

given the input:

$$x(n) = -(1/2)^n u(n)$$

Exercise 42. Determine the particular solution for the system described by the following difference equation:

$$y(n)-(2/5)y(n-1)=2x(n)$$

given the input:

$$x(n) = \cos(\pi n/5)$$

<u>Exercise 43</u>. Determine the particular solution for the system described by the following difference equation:

$$y(n)-(1/4)y(n-1)-(1/8)y(n-2)=x(n)+x(n-1)$$

given the input:

$$x(n)=nu(n)$$

Exercise 44. Determine the particular solution for the system described by the following difference equation:

$$y(n)-(1/4)y(n-1)-(1/8)y(n-2)=x(n)+x(n-1)$$

given the input:

$$x(n) = (1/8)^n u(n)$$

Exercise 45. Determine the particular solution for the system described by the following difference equation:

$$y(n)-(1/4)y(n-1)-(1/8)y(n-2)=x(n)+x(n-1)$$

given the input:

$$x(n)=e^{j\pi n/4}u(n)$$

Exercise 46. Determine the particular solution for the system described by the following difference equation:

$$y(n)-(1/4)y(n-1)-(1/8)y(n-2)=x(n)+x(n-1)$$

given the input:

$$x(n)=(1/2)^n u(n)$$

<u>Exercise 47</u>. Determine the particular solution for the system described by the following difference equation:

$$y(n)+y(n-1)+(1/2)y(n-2)=x(n)+2x(n-1)$$

given the input:

$$x(n)=u(n)$$

<u>Exercise 48</u>. Determine the particular solution for the system described by the following difference equation:

$$y(n)+y(n-1)+(1/2)y(n-2)=x(n)+2x(n-1)$$

given the input:

$$x(n)=(-1/2)^n u(n)$$

Exercise 49. Determine the output of the system described by the following differential equation:

$$\frac{dy(t)}{dt} + 10 y(t) = 2 x(t)$$

given the input:

$$x(t)=u(t)$$

and the initial condition:

$$y(0-)=1$$

Exercise 50. Determine the output of the system described by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + y(t) = \frac{dx(t)}{dt}$$

given the input:

$$x(t) = \sin(t)u(t)$$

and the initial conditions:

$$y(0-)=0$$
 and $\frac{dy(t)}{dt}\Big|_{t=0-}=1$

Exercise 51. Determine the output of the system described by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 6 \frac{dy(t)}{dt} + 8 y(t) = 2 x(t)$$

given the input:

$$x(t)=e^{-t}u(t)$$

and the initial conditions:

$$y(0-)=-1$$
 and $\frac{dy(t)}{dt}\Big|_{t=0-}=1$

<u>Exercise 52</u>. Determine the output of the system described by the following differential equation:

$$\frac{d^2y(t)}{dt^2} + y(t) = 3\frac{dx(t)}{dt}$$

given the input:

$$x(t)=2te^{-t}u(t)$$

and the initial conditions:

$$y(0-)=-1$$
 and $\frac{dy(t)}{dt}\Big|_{t=0-}=1$

<u>Exercise 53</u>. Determine the natural and forced responses of the system described by the following differential equation:

$$\frac{dy(t)}{dt} + 10 y(t) = 2 x(t)$$

given the input:

$$x(t)=u(t)$$

and the initial condition:

$$y(0-)=1$$

<u>Exercise 54</u>. Determine the natural and forced responses of the system described by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} + y(t) = \frac{dx(t)}{dt}$$

given the input:

$$x(t) = \sin(t)u(t)$$

and the initial conditions:

$$y(0-)=0$$
 and $\frac{dy(t)}{dt}\Big|_{t=0-}=1$

<u>Exercise 55</u>. Determine the natural and forced responses of the system described by the following differential equation:

$$\frac{d^{2}y(t)}{dt^{2}} + 6\frac{dy(t)}{dt} + 8y(t) = 2x(t)$$

given the input:

$$x(t) = e^{-t}u(t)$$

and the initial conditions:

$$y(0-)=-1$$
 and $\frac{dy(t)}{dt}\Big|_{t=0-}=1$

<u>Exercise 56</u>. Determine the natural and forced responses of the system described by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + y(t) = 3 \frac{dx(t)}{dt}$$

given the input:

$$x(t) = 2 t e^{-t} u(t)$$

and the initial conditions:

$$y(0-)=-1$$
 and $\frac{dy(t)}{dt}\Big|_{t=0-}=1$

Exercise 57. Determine the output of the system described by the following difference equation:

$$v(n)-(1/2)v(n-1)=2x(n)$$

given the input:

$$x(n)=(-1/2)^n u(n)$$

and the initial condition:

$$y(-1)=3$$

<u>Exercise 58</u>. Determine the output of the system described by the following difference equation:

$$y(n)-(1/9)y(n-2)=x(n-1)$$

given the input:

$$x(n)=u(n)$$

the initial conditions:

$$y(-1)=1$$
 and $y(-2)=0$

Exercise 59. Determine the output of the system described by the following difference equation:

$$y(n)+(1/4)y(n-1)-(1/8)y(n-2)=x(n)+x(n-1)$$

given the input

$$x(n)=(-1)^n u(n)$$

and the initial conditions:

$$y(-1)=4$$
 and $y(-2)=-2$

Exercise 60. Determine the output of the system described by the following difference equation:

$$y(n)-(3/4)y(n-1)+(1/8)y(n-2)=2x(n)$$

given the input:

$$x(n)=2u(n)$$

and the initial conditions:

$$y(-1)=1$$
 and $y(-2)=-1$

<u>Exercise 61</u>. Determine the natural and forced responses of the system described by the following difference equation:

$$v(n)-(1/2)v(n-1)=2x(n)$$

given the input:

$$x(n)=(-1/2)^nu(n)$$

and the initial condition:

$$y(-1)=3$$

Exercise 62. Determine the natural and forced responses of the system described by the following difference equation:

$$y(n)-(1/9)y(n-2)=x(n-1)$$

given the input:

$$x(n)=u(n)$$

and the initial conditions:

$$y(-1)=1$$
 and $y(-2)=0$

<u>Exercise 63</u>. Determine the natural and forced responses of the system described by the following difference equation:

$$y(n)+(1/4)y(n-1)-(1/8)y(n-2)=x(n)+x(n-1)$$

given the input:

$$x(n)=(-1)^n u(n)$$

and the initial conditions:

$$y(-1)=4$$
 and $y(-2)=-2$

<u>Exercise 64</u>. Determine the natural and forced responses of the system described by the following difference equation:

$$y(n)-(3/4)y(n-1)+(1/8)y(n-2)=2x(n)$$

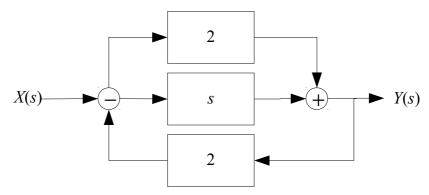
given the input:

$$x(n)=2u(n)$$

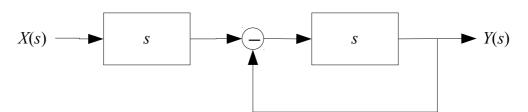
and the initial conditions:

$$y(-1)=1$$
 and $y(-2)=-1$

<u>Exercise 65</u>. Find the difference equation describing the discrete-time system represented by the following block diagram:



<u>Exercise 66</u>. Find the difference equation describing the discrete-time system represented by the following block diagram:



<u>Exercise 67</u>. Draw the block-diagram representation of a discrete-time LTI system described by the following state-variable representation matrices:

$$A = \begin{bmatrix} 1 & -1/2 \\ 1/3 & 0 \end{bmatrix}$$
, $B = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$, $C = \begin{bmatrix} 1 & 1 \end{bmatrix}$, and $D = \begin{bmatrix} 0 \end{bmatrix}$

<u>Exercise 68</u>. Draw the block-diagram representation of a discrete-time LTI system described by the following state-variable representation matrices:

$$A = \begin{bmatrix} 1 & -1/2 \\ 1/3 & 0 \end{bmatrix}$$
, $B = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$, $C = \begin{bmatrix} 1 & -1 \end{bmatrix}$, and $D = \begin{bmatrix} 0 \end{bmatrix}$

<u>Exercise 69</u>. Draw the block-diagram representation of a discrete-time LTI system described by the following state-variable representation matrices:

$$A = \begin{bmatrix} 0 & -1/2 \\ 1/3 & -1 \end{bmatrix}$$
, $B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$, $C = \begin{bmatrix} 1 & 0 \end{bmatrix}$, and $D = \begin{bmatrix} 1 \end{bmatrix}$

Exercise 70. Draw the block-diagram representation of a discrete-time LTI system described by the following state-variable representation matrices:

$$A = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$
, $B = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$, $C = \begin{bmatrix} 1 & -1 \end{bmatrix}$, and $D = \begin{bmatrix} 0 \end{bmatrix}$

<u>Exercise 71</u>. Draw the block-diagram representation of a continuous-time LTI system described by the following state-variable representation matrices:

$$A = \begin{bmatrix} 1/3 & 0 \\ 0 & -1/2 \end{bmatrix}$$
, $B = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$, $C = \begin{bmatrix} 1 & 1 \end{bmatrix}$, and $D = \begin{bmatrix} 0 \end{bmatrix}$

<u>Exercise 72</u>. Draw the block-diagram representation of a continuous-time LTI system described by the following state-variable representation matrices:

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$$
, $B = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$, $C = \begin{bmatrix} 0 & -1 \end{bmatrix}$, and $D = \begin{bmatrix} 0 \end{bmatrix}$

<u>Exercise 73</u>. Draw the block-diagram representation of a continuous-time LTI system described by the following state-variable representation matrices:

$$A = \begin{bmatrix} 1 & -2 \\ 1 & 1 \end{bmatrix}$$
, $B = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$, $C = \begin{bmatrix} 1 & 1 \end{bmatrix}$, and $D = \begin{bmatrix} 0 \end{bmatrix}$

<u>Exercise 74</u>. Determine the discrete-time Fourier series representation for the following signal:

$$x(n) = \cos(6\pi n/17 + \pi/3)$$
.

<u>Exercise 75</u>. Determine the discrete-time Fourier series representation for the following signal:

$$x(n)=2\sin(4\pi n/19)+\cos(10\pi n/19)+1$$
.

<u>Exercise 76</u>. Determine the discrete-time Fourier series representation for the following signal:

$$x(n) = \sum_{k=-\infty}^{+\infty} \{ (-1)^k [\delta(n-2k) + \delta(n+3k)] \} .$$

<u>Exercise 77</u>. Determine the time-domain signal represented by the following discrete-time Fourier series coefficients:

$$X_k = \cos(8\pi k/21)$$

Exercise 78. Determine the time-domain signal represented by the following discrete-time Fourier series coefficients:

$$X_k = \cos(10\pi k/19) + 2 j \sin(4\pi k/19)$$

Exercise 79. Determine the time-domain signal represented by the following discrete-time Fourier series coefficients:

$$X_{k} = \sum_{m=-\infty}^{+\infty} \{ (-1)^{m} [\delta(k-2m) - 2\delta(k+3m)] \}$$

Exercise 80. Determine the Fourier series representation for the following signal:

$$x(t) = \sin(3\pi t) + \cos(4\pi t) .$$

Exercise 81. Determine the Fourier series representation for the following signal:

$$x(t) = \sum_{k=-\infty}^{+\infty} \{ (-1)^k [\delta(t-k/3) + \delta(t+2k/3)] \}$$

Exercise 82. Determine the Fourier series representation for the following signal:

$$x(t) = \sum_{k=-\infty}^{+\infty} \left[e^{2\pi k/7} \delta(t-2k) \right] .$$

<u>Exercise 83</u>. Determine the time-domain signal represented by the following Fourier series coefficients:

$$X_k = j \delta(k-1) - j \delta(k+1) + \delta(k-3) + \delta(k+3)$$
 $(\omega_0 = 2\pi)$

<u>Exercise 84</u>. Determine the time-domain signal represented by the following Fourier series coefficients:

$$X_k = j \delta(k-1) - j \delta(k+1) + \delta(k-3) + \delta(k+3)$$
 $(\omega_0 = 4\pi)$

<u>Exercise 85</u>. Determine the time-domain signal represented by the following Fourier series coefficients:

$$X_k = (-1/3)^{|k|}$$
 $(\omega_0 = 1)$

Exercise 86. Determine the magnitude and phase spectra of the following signal:

$$x(n)=(3/4)^n u(n-4)$$
.

Exercise 87. Determine the magnitude and phase spectra of the following signal:

$$x(n)=a^{|n|} \qquad (|a|<1) \quad .$$

Exercise 88. Determine the magnitude and phase spectra of the following signal:

$$x(n) = \begin{cases} 1/2 + 1/2\cos(\pi n/N) & (|n| \le N) \\ 0 & (|n| > N) \end{cases}$$

Exercise 89. Determine the magnitude and phase spectra of the following signal:

$$x(n)=2\delta(4-2n) .$$

<u>Exercise 90</u>. Determine the time-domain signal corresponding to the following discrete-time Fourier transform:

$$X(\Omega) = \cos(2\Omega) + j\sin(2\Omega)$$

<u>Exercise 91</u>. Determine the time-domain signal corresponding to the following discrete-time Fourier transform:

$$X(\Omega) = \sin(\Omega) + \cos(\Omega/2)$$

<u>Exercise 92</u>. Determine the time-domain signal corresponding to the following discrete-time Fourier transform:

$$|X(\Omega)| = \begin{cases} 1 & (\pi/4 < |\Omega| < 3\pi/4) \\ 0 & (|\Omega| \le \pi/4 \lor |\Omega| \ge 3\pi/4) \end{cases}$$

$$arg\{X(\Omega)\} = -4\Omega$$

Exercise 93. Determine the Fourier transform of the following signal:

$$x(t) = e^{-2t}u(t-3)$$

Exercise 94. Determine the Fourier transform of the following signal:

$$x(t) = e^{-4|t|}$$

Exercise 95. Determine the Fourier transform of the following signal:

$$x(t)=te^{-t}u(t)$$

Exercise 96. Determine the Fourier transform of the following signal:

$$x(t) = \sum_{k=0}^{\infty} a^k \delta(t-k) \qquad (|a|<1)$$

<u>Exercise 97</u>. Determine the time-domain signal corresponding to the following Fourier transform:

$$X(\omega) = \begin{bmatrix} \cos(2\omega) & (|\omega| < \pi/4) \\ 0 & (|\omega| \ge \pi/4) \end{bmatrix}$$

Exercise 98. Determine the time-domain signal corresponding to the following Fourier transform:

$$X(\omega) = e^{-2\omega}u(\omega)$$

<u>Exercise 99</u>. Determine the time-domain signal corresponding to the following Fourier transform:

$$X(\omega) = e^{-2|\omega|}$$

Exercise 100. Determine the appropriate Fourier representation of the following signal:

$$x(t) = e^{-t}\cos(2\pi t)u(t)$$

Exercise 101. Determine the appropriate Fourier representation of the following signal:

$$x(n) = \begin{cases} \cos(\pi n/10) + j\sin(\pi n/10) & (|n| < 10) \\ 0 & (|n| \ge 10) \end{cases}$$

Exercise 102. Determine the appropriate Fourier representation of the following signal:

$$x(t)=e^{1+t}u(2-t)$$

Exercise 103. Determine the appropriate Fourier representation of the following signal:

$$x(t) = |\sin(2\pi t)|$$

<u>Exercise 104</u>. Determine the time-domain signal corresponding to the following frequency-domain representation:

$$X_{k} = \begin{cases} e^{-jk\pi/2} & (|k| < 10) \\ 0 & (|k| \ge 10) \end{cases}$$

and the fundamental period of the signal T=1

<u>Exercise 105</u>. Determine the time-domain signal corresponding to the following frequency-domain representation:

$$X(\omega) = \begin{bmatrix} \cos(\omega/4) + j\sin(\omega/4) & (|\omega| < \pi) \\ 0 & (|\omega| \ge \pi) \end{bmatrix}$$

<u>Exercise 106</u>. Determine the time-domain signal corresponding to the following frequency-domain representation:

$$X(\Omega) = |\sin(\Omega)|$$

Exercise 107. Determine the Fourier transform of the following signal:

$$x(t) = \sin(2\pi t)e^{-t}u(t)$$

Exercise 108. Determine the Fourier transform of the following signal:

$$x(t) = te^{-3|t-1|}$$

Exercise 109. Determine the Fourier transform of the following signal:

$$x(t) = \frac{2\sin(3\pi t)}{\pi t} \frac{\sin(2\pi t)}{\pi t}$$

Exercise 110. Determine the Fourier transform of the following signal:

$$x(t) = \frac{d}{dt} t e^{-2t} \sin(t) u(t)$$

Exercise 111. Determine the Fourier transform of the following signal:

$$x(t) = \int_{-\infty}^{t} \frac{\sin(2\pi\tau)}{\pi\tau} d\tau$$

Exercise 112. Determine the Fourier transform of the following signal:

$$x(t) = e^{-t+2}u(t-2)$$

Exercise 113. Determine the Fourier transform of the following signal:

$$x(t) = \frac{\sin(t)}{\pi t} * \frac{d}{dt} \frac{\sin(2t)}{\pi t}$$

Exercise 114. Determine the time-domain signal corresponding to the following Fourier transform:

$$X(\omega) = \frac{j \omega}{(1 + j \omega)^2}$$

<u>Exercise 115</u>. Determine the time-domain signal corresponding to the following Fourier transform:

$$X(\omega) = \frac{4\sin(2\omega - 4)}{2\omega - 4} - \frac{4\sin(2\omega + 4)}{2\omega + 4}$$

<u>Exercise 116</u>. Determine the time-domain signal corresponding to the following Fourier transform:

$$X(\omega) = \frac{1}{j\omega(j\omega+2)} - \pi \delta(\omega)$$

<u>Exercise 117</u>. Determine the time-domain signal corresponding to the following Fourier transform:

$$X(\omega) = \frac{d}{d\omega} \left[4\sin(4\omega) \frac{\sin(2\omega)}{\omega} \right]$$

<u>Exercise 120</u>. Determine the time-domain signal corresponding to the following Fourier transform:

$$X(\omega) = \frac{2\sin(\omega)}{\omega(j\omega+2)}$$

Exercise 121. Determine the time-domain signal corresponding to the following Fourier transform:

$$X(\omega) = \frac{4\sin^2(\omega)}{\omega^2}$$

Exercise 122. Given the following Fourier transform pair:

$$x(t) = \begin{cases} 1 & (|t| < 1) \\ 0 & (|t| \ge 1) \end{cases} \iff X(\omega) = \frac{2\sin(\omega)}{\omega}$$

Evaluate the Fourier transform of the following signal:

$$y(t) = x \left(\frac{t-2}{2} \right)$$

Exercise 123. Given the following Fourier transform pair:

$$x(t) = \begin{cases} 1 & (|t| < 1) \\ 0 & (|t| \ge 1) \end{cases} \iff X(\omega) = \frac{2\sin(\omega)}{\omega}$$

Evaluate the Fourier transform of the following signal:

$$y(t) = \sin(\pi t) x(t)$$

Exercise 124. Given the following Fourier transform pair:

$$x(t) = \begin{cases} 1 & (|t| < 1) \\ 0 & (|t| \ge 1) \end{cases} \iff X(\omega) = \frac{2\sin(\omega)}{\omega}$$

Evaluate the Fourier transform of the following signal:

$$y(t) = x(t+1) - x(2t-1)$$

Exercise 125. Given the following Fourier transform pair:

$$x(t) = \begin{cases} 1 & (|t| < 1) \\ 0 & (|t| \ge 1) \end{cases} \iff X(\omega) = \frac{2\sin(\omega)}{\omega}$$

Evaluate the Fourier transform of the following signal:

$$y(t)=2tx(t)$$

Exercise 126. Given the following Fourier transform pair:

$$x(t) = \begin{cases} 1 & (|t| < 1) \\ 0 & (|t| \ge 1) \end{cases} \iff X(\omega) = \frac{2\sin(\omega)}{\omega}$$

Evaluate the Fourier transform of the following signal:

$$y(t) = x(t) * x(t)$$

Exercise 127. Given the discrete-time Fourier transform $X(\Omega)$ of the following signal:

$$x(n)=n(3/4)^{|n|}$$

Without evaluating $X(\Omega)$, find the signal y(n) if its discrete-time Fourier transform $Y(\Omega)$ is given by:

$$Y(\Omega) = e^{-j4\Omega} X(\Omega)$$

Exercise 128. Given the discrete-time Fourier transform $X(\Omega)$ of the following signal:

$$x(n)=n(3/4)^{|n|}$$

Without evaluating $X(\Omega)$, find the signal y(n) if its discrete-time Fourier transform $Y(\Omega)$ is given by:

$$Y(\Omega) = \text{Re}[X(\Omega)]$$

Exercise 129. Given the discrete-time Fourier transform $X(\Omega)$ of the following signal:

$$x(n)=n(3/4)^{|n|}$$

Without evaluating $X(\Omega)$, find the signal y(n) if its discrete-time Fourier transform $Y(\Omega)$ is given by:

$$Y(\Omega) = \frac{dX(\Omega)}{d\Omega}$$

Exercise 130. Given the discrete-time Fourier transform $X(\Omega)$ of the following signal:

$$x(n)=n(3/4)^{|n|}$$

Without evaluating $X(\Omega)$, find the signal y(n) if its discrete-time Fourier transform $Y(\Omega)$ is given by:

$$Y(\Omega) = X(\Omega) + X(-\Omega)$$

Exercise 131. Given the discrete-time Fourier transform $X(\Omega)$ of the following signal:

$$x(n)=n(3/4)^{|n|}$$

Without evaluating $X(\Omega)$, find the signal y(n) if its discrete-time Fourier transform $Y(\Omega)$ is given by:

$$Y(\Omega) = \frac{dX(2\Omega)}{d\Omega}$$

Exercise 132. A periodic signal x(t) has the following Fourier series representation:

$$X_k = -k 2^{-|k|}$$

Without determining x(t) , find the Fourier series representation of the following signal:

$$y(t)=x(3t)$$

Exercise 133. A periodic signal x(t) has the following Fourier series representation:

$$X_k = -k 2^{-|k|}$$

Without determining x(t) , find the Fourier series representation of the following signal:

$$y(t) = x(t-1)$$

Exercise 134. A periodic signal x(t) has the following Fourier series representation:

$$X_k = -k 2^{-|k|}$$

Without determining x(t) , find the Fourier series representation of the following signal:

$$y(t) = \frac{dx(t)}{dt}$$

Exercise 135. A periodic signal x(t) has the following Fourier series representation:

$$X_k = -k 2^{-|k|}$$

Without determining x(t) , find the Fourier series representation of the following signal:

$$y(t) = \cos(4\pi t)x(t)$$

<u>Exercise 136</u>. Sketch the magnitude response and the phase response of the system described by the following impulse response:

$$h(t) = \delta(t) - 2e^{-2t}u(t)$$

<u>Exercise 137</u>. Sketch the magnitude response and the phase response of the system described by the following impulse response:

$$h(t) = 4e^{-2t}\cos(50t)$$

<u>Exercise 138</u>. Sketch the magnitude response and the phase response of the system described by the following impulse response:

$$h(n) = \frac{1}{8} \left(\frac{7}{8}\right)^n u(n)$$

<u>Exercise 139</u>. Sketch the magnitude response and the phase response of the system described by the following impulse response:

$$h(n) = \begin{cases} (-1)^n & (|n| \le 10) \\ 0 & (|n| > 10) \end{cases}$$

<u>Exercise 140</u>. Determine the frequency response and the impulse response of a system, given the following pair of input and output signals for the system:

$$x(t)=e^{-t}u(t)$$
 and $y(t)=e^{-2t}u(t)+e^{-3t}u(t)$

<u>Exercise 141</u>. Determine the frequency response and the impulse response of a system, given the following pair of input and output signals for the system:

$$x(t)=e^{-3t}u(t)$$
 and $y(t)=e^{-3(t-2)}u(t-2)$

Exercise 142. Determine the frequency response and the impulse response of a system, given the following pair of input and output signals for the system:

$$x(t) = e^{-2t}u(t)$$
 and $y(t) = 2te^{-2t}u(t)$

<u>Exercise 143</u>. Determine the frequency response and the impulse response of a system, given the following pair of input and output signals for the system:

$$x(n)=(1/2)^n u(n)$$
 and $y(n)=(1/4)(1/2)^n u(n)+(1/4)^n u(n)$

<u>Exercise 144</u>. Determine the frequency response and the impulse response of a system, given the following pair of input and output signals for the system:

$$x(n)=(1/4)^n u(n)$$
 and $y(n)=(1/4)^n u(n)-(1/4)^{n-1} u(n-1)$

<u>Exercise 145</u>. Determine the frequency response and the impulse response of the system described by the following differential equation:

$$\frac{dy(t)}{dt} + 3 y(t) = x(t)$$

<u>Exercise 146</u>. Determine the frequency response and the impulse response of the system described by the following differential equation:

$$\frac{d^2 y(t)}{dt^2} + 5 \frac{dy(t)}{dt} + 6 y(t) = \frac{-dx(t)}{dt}$$

<u>Exercise 147</u>. Determine the frequency response and the impulse response of the system described by the following difference equation:

$$y(n)-(1/4)y(n-1)-(1/8)y(n-2)=3x(n)-(3/4)x(n-1)$$

<u>Exercise 148</u>. Determine the frequency response and the impulse response of the system described by the following difference equation:

$$y(n)+(1/2)y(n-1)=x(n)-2x(n-1)$$

<u>Exercise 149</u>. Determine the time-domain signal corresponding to the following unilateral Laplace transform:

$$X^{1}(s) = \frac{1}{(s+2)(s+3)}$$

<u>Exercise 150</u>. Determine the time-domain signal corresponding to the following unilateral Laplace transform:

$$X^{1}(s) = e^{-2s} \frac{d}{ds} \left[\frac{1}{(s+1)^{2}} \right]$$

<u>Exercise 151</u>. Determine the time-domain signal corresponding to the following unilateral Laplace transform:

$$X^{1}(s) = \frac{1}{(2s+1)^{2}+4}$$

Exercise 152. Given the Laplace transform X(s) of the following signal:

$$x(t) = \cos(2t)u(t)$$

Determine the signal y(t) if its Laplace transform is given by:

$$Y(s)=(s+1)X(s)$$

Exercise 153. Given the Laplace transform X(s) of the following signal:

$$x(t) = \cos(2t)u(t)$$

Determine the signal y(t) if its Laplace transform is given by:

$$Y(s) = X(3s)$$

Exercise 154. Given the Laplace transform X(s) of the following signal:

$$x(t) = \cos(2t)u(t)$$

Determine the signal y(t) if its Laplace transform is given by:

$$Y(s) = s^{-2}X(s)$$

Exercise 155. Given the Laplace transform of the signal x(t) as follows:

$$X(s) = \frac{2s}{s^2 + 2}$$

Determine Laplace transform of the following signal:

$$y(t) = x(3t)$$

Exercise 156. Given the Laplace transform of the signal x(t) as follows:

$$X(s) = \frac{2s}{s^2 + 2}$$

Determine Laplace transform of the following signal:

$$y(t)=x(t-2)$$

Exercise 157. Given the Laplace transform of the signal x(t) as follows:

$$X(s) = \frac{2s}{s^2 + 2}$$

Determine Laplace transform of the following signal:

$$y(t) = x(t) * \frac{dx(t)}{dt}$$

Exercise 158. Given the Laplace transform of the signal x(t) as follows:

$$X(s) = \frac{2s}{s^2 + 2}$$

Determine Laplace transform of the following signal:

$$v(t) = e^{-t} x(t)$$

Exercise 159. Given the Laplace transform of the signal x(t) as follows:

$$X(s) = \frac{2s}{s^2 + 2}$$

Determine Laplace transform of the following signal:

$$y(t) = 2tx(t)$$

Exercise 160. Given the following Laplace transform pair:

$$x(t) = e^{-at}u(t) \iff X(s) = \frac{1}{s+a}$$

Evaluate the unilateral Laplace transform of the following signal:

$$y(t) = e^{-at} \cos(\omega_0 t) u(t)$$

<u>Exercise 160</u>. Determine the forced and natural responses for the LTI system described by the following differential equation with the specified initial and input conditions:

$$\frac{dy(t)}{dt}$$
 + 10 $y(t)$ = 10 $x(t)$, $y(0-)$ = 1, and $x(t)$ = $u(t)$

Exercise 161. Determine the forced and natural responses for the LTI system described by the following differential equation with the specified initial and input conditions:

$$\frac{d^{2}y(t)}{dt^{2}} + 5\frac{dy(t)}{dt} + 6y(t) = -4x(t) - 3\frac{dx(t)}{dt}, \quad y(0-) = -1, \quad \frac{dy(t)}{dt}\Big|_{t=0-} = 5 \quad \text{and} \quad x(t) = e^{-t}u(t)$$

Exercise 162. Determine the forced and natural responses for the LTI system described by the following differential equation with the specified initial and input conditions:

$$\frac{d^2 y(t)}{dt^2} + y(t) = 8x(t) , y(0-) = 0 , \frac{dy(t)}{dt} \Big|_{t=0-} = 2 \text{ and } x(t) = e^{-t}u(t)$$

Exercise 163. Determine the forced and natural responses for the LTI system described by the following differential equation with the specified initial and input conditions:

$$\frac{d^2y(t)}{dt^2} + 2\frac{dy(t)}{dt} + 5y(t) = \frac{dx(t)}{dt}, \quad y(0-) = 2, \quad \frac{dy(t)}{dt}\Big|_{t=0-} = 0 \quad \text{and} \quad x(t) = u(t)$$

<u>Exercise 164</u>. Determine the time-domain signal corresponding to the following bilateral Laplace transform:

$$X(s) = \frac{e^{5s}}{s+2} \qquad (\operatorname{Re}(s) < -2)$$

<u>Exercise 165</u>. Determine the time-domain signal corresponding to the following bilateral Laplace transform:

$$X(s) = \frac{d^2}{ds^2} \left(\frac{1}{s-3} \right) \quad (\text{Re}(s) > 3)$$

<u>Exercise 166</u>. Determine the time-domain signal corresponding to the following bilateral Laplace transform:

$$X(s) = \frac{-s-4}{s^2+3s+2}$$
 $(-2 < \text{Re}(s) < -1)$

<u>Exercise 167</u>. Determine the impulse response of a causal system having the following transfer function:

$$H(s) = \frac{2s^2 + 2s - 2}{s^2 - 1}$$

<u>Exercise 168</u>. Determine the impulse response of a stable system having the following transfer function:

$$H(s) = \frac{2s^2 + 2s - 2}{s^2 - 1}$$

Exercise 169. Determine the impulse response of a causal system having the following transfer function:

$$H(s) = \frac{2s-1}{s^2+2s+1}$$

<u>Exercise 170</u>. Determine the impulse response of a stable system having the following transfer function:

$$H(s) = \frac{2s-1}{s^2+2s+1}$$

Exercise 171. Determine the impulse response of a causal system having the following transfer function:

$$H(s) = e^{-5s} + \frac{2}{s-2}$$

Exercise 172. Determine the impulse response of a stable system having the following transfer function:

$$H(s) = e^{-5s} + \frac{2}{s-2}$$

Exercise 173. Determine the transfer function and the impulse response of a stable system, given a pair of its input and output signals as follows:

$$x(t) = e^{-t}u(t)$$
 and $y(t) = e^{-2t}\cos(t)u(t)$

<u>Exercise 174</u>. Determine the transfer function and the impulse response of a stable system, given a pair of its input and output signals as follows:

$$x(t) = e^{-2t}u(t)$$
 and $y(t) = -2e^{-t}u(t) + 2e^{-3t}u(t)$

<u>Exercise 175</u>. Determine the transfer function and the impulse response of a causal system described by the following differential equation:

$$\frac{dy(t)}{dt} + 10 y(t) = 10 x(t)$$

Exercise 176. Determine the transfer function and the impulse response of a causal system described by the following differential equation:

$$\frac{d^2y(t)}{dt^2} + 5\frac{dy(t)}{dt} + 6y(t) = x(t) + \frac{dx(t)}{dt}$$

Exercise 177. Determine the transfer function and the impulse response of a causal system described by the following differential equation:

$$\frac{d^{2}y(t)}{dt^{2}} - \frac{dy(t)}{dt} - 2y(t) = -4x(t) + 5\frac{dx(t)}{dt}$$