

## Lab 2

# Systemy CAD/CAE

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### 1. Zmodyfikowany fragment kodu

```
1. function spline2D_comp()
2.
3. knot_vectorx % data;
4. knot_vectorx % data;
5.
6. coefficient_vector %data;
7.
8. precision = 0.01
9.
10. %macros
11. compute_nr_basis_functions = @(knot_vector,p) size(knot_vector, 2) -
    p - 1
12. mesh = @(a,c) [a:precision*(c-a):c]
13.
14. %splines in x
15. px = compute_p(knot_vectorx)
16. tx = check_sanity(knot_vectorx,px)
17. nrx = compute_nr_basis_functions(knot_vectorx,px)
18.
19. x_begin = knot_vectorx(1)
20. x_end = knot_vectorx(size(knot_vectorx,2))
21.
22. x=mesh(x_begin,x_end);
23.
24. %splines in y
25. py = compute_p(knot_vectorx)
26. ty = check_sanity(knot_vectorx,py)
27. nry = compute_nr_basis_functions(knot_vectorx,py)
28.
29. y_begin = knot_vectorx(1)
30. y_end = knot_vectorx(size(knot_vectorx,2))
31.
32. y=mesh(y_begin,y_end);
33.
34. %X and Y coordinates of points over the 2D mesh
35. [X,Y]=meshgrid(x,y);
36.
37. M = zeros(length(x), length(y));
38.
39. for i=1:nrx
40.     %compute values of
41.     vx=compute_spline(knot_vectorx,px,i,X);
42.     for j=1:nry
43.         vy=compute_spline(knot_vectorx,py,j,Y);
44.         spline = vx .* vy;
```

```

45.
46.     M = M + spline .* coefficient_vector(i, j)
47. end
48. end
49. surf(X,Y,M);
50.
51. return

```

## 2. Wektory węzłów oraz współczynników użytych do rysowania labiryntu

```
knot_vectorx = [0 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 16];
```

```
knot_vectory = [0 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 16];
```

```
coefficient_vector = [
```

```
    1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1;
```

```
    1 0 0 0 0 0 1 0 0 0 0 0 1 0 0 0 1;
```

```
    1 0 1 1 1 0 1 0 1 1 1 0 1 1 1 0 1;
```

```
    1 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 1;
```

```
    1 0 1 0 1 1 1 1 1 0 1 1 1 0 1 0 1;
```

```
    1 0 1 0 0 0 0 0 0 0 0 0 0 0 1 0 1;
```

```
    1 0 1 1 1 1 1 1 1 1 1 1 1 1 1 0 1;
```

```
    1 0 0 0 0 0 1 0 0 0 1 0 0 0 0 0 1;
```

```
    1 1 1 1 1 0 1 0 1 1 1 0 1 1 1 1 1;
```

```
    1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1;
```

```
    1 1 1 0 1 1 1 1 1 0 1 1 1 0 1 1 1;
```

```
    1 0 1 0 0 0 0 0 0 0 0 0 0 0 1 0 1;
```

```
    1 0 1 1 1 1 1 1 1 1 1 1 1 1 1 0 1;
```

```
    1 0 0 0 0 0 1 0 0 0 1 0 0 0 0 0 1;
```

```
    1 1 1 1 1 0 1 1 1 0 1 1 1 0 1 1 1;
```

```
    1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1;
```

```
    1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1;
```

];

### 3. Wygenerowany labirynt



