Case Stack:

* Describe context
* Show tabular results
* Discuss takeaways

Cases:

* Case 0 – defaults
* Case 1 – agreements – show impact on object types
* Case 0 – defaults
* Case 1 – ideal use case
  + High confidence observations under clear conditions
  + Sensor readings agree for SIZE and SPEED
  + Toggle to show feature impact on obj\_type
* Case 2 – degraded conditions use case
  + Hold constant conditions from A
  + This time, under inclement conditions
  + Compare results set to A
* Case 3 – sensor observation disagreement – non-adjacent – stealth case
  + For SIZE or SPEED, have sensors disagree
  + Show how impacts object determination
  + Show how impacts intent classification
* Case 4 – sensor reliability for different ranges – stealth case
  + Holding constant all from C except RANGE
  + Show how ranges impact sensor reliabilities
  + Compare to C
* Case 5 – Object/Platform type observation impact
  + Note hypothetical external ATR classifier correction via BN
  + Show how this impacts Intent