CS222 Algorithm Design and Analysis Homework 3

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Exercise 1 Given an integer array, please use the divide and conquer algorithm to find the reverse pair in the sequence.

Solution. See Algorithm 1.

```
Algorithm 1: Find Reverse Pair
   Input: Integer Array S
   Output: Reverse Pair Count R
1 Function ReversePair(S, lptr, rptr):
      mid = (lptr + rptr)/2;
2
      Initialize R = 0;
3
      call ReversePair(S, lptr, mid) and add result to R;
 4
      call ReversePair(S, mid + 1, rptr) and add result to R;
 5
      i = lptr, j = mid + 1;
 6
      while i \leq mid and j \leq rptr do
 7
         if S[i] \leq S[j] then
 8
             append S[i] to newS;
 9
             i = i + 1;
10
          else
11
             append S[j] to newS;
12
             j = j + 1;
13
             R = R + mid - i + 1 ;
14
          end
15
      end
16
      append rest of the elements in S to newS;
17
      replace S by newS;
18
19 return R
20 Function Main(S):
      lptr = 0, rptr = length of <math>S - 1;
      R = ReversePair(S, lptr, rptr);
23 return R
```

Exercise 2 Given any positive integers K and M, find the K-th largest element and the M-th smallest element in the unsorted array. Please note that you need to find the K-th largest element, and the M-th smallest element after the array is sorted, not different elements.

Solution. For K and M sufficiently smaller than number of elements N, the problem can be solved within

Algorithm 2: Find K-th largest element

```
Input: Unsorted array S of N elements
Output: The K-th largest element

1 Initialize a priority queue (min-heap) Q;
2 foreach n \in S do

3 | push n into Q;
4 | if size \ of \ Q > K then

5 | pop the top-element in Q;
6 | end

7 end
8 return the top-element in Q
```

Algorithm 3: Find M-th smallest element

```
Input: Unsorted array S of N elements Output: The M-th smallest element

1 Initialize a priority queue (max-heap) Q;

2 foreach n \in S do

3 | push n into Q;

4 | if size of Q > M then

5 | pop the top-element in Q;

6 | end

7 end

8 return the top-element in Q
```

Exercise 3 Given an array of linked lists, and the lists have been sorted in descending order. Please merge all linked lists into an ascending list and return the merged list.

Solution. The solution is to use a max-heap to efficiently maintain the frontier of the merge, see Algorithm 4.

Algorithm 4: Merge k sorted linked lists

```
Input: An K-element array of descending sorted linked lists L
Output: The merged list R in ascending order
1 Initialize a max-heap Q, an empty linked list R;
2 Remove the head of all linked lists (if exist) and push them, together with their index in the array ⟨n, i⟩ into Q (according to n);
3 while the top-element of Q is not empty do
4 | pop the top-element ⟨n, i⟩ from Q;
5 | append n to the head of R;
6 | if L[i] is not empty then
7 | remove the head of L[i] and push the head value, together with the array index into Q;
8 | end
9 end
10 return R
```

Exercise 4 Given an array a, if $i \le j$ and $a[i] \le a[j] + 1$ and j == i + 1, we call (i, j) an important flip pair. Please return the number of significant flip pairs in a given array.

Algorithm 5: Find important flip pair

```
Input: Array A
Output: Number of important flip pair n

1 Initialize n=0;
2 for i=0: A.size-2 do
3 | if A[i] \leq A[i+1]+1 then
4 | n=n+1;
5 | end
6 end
7 return n
```

Exercise 5 Please write an efficient algorithm to search for a target value target in the $m \times n$ matrix. The matrix has the following characteristics:

- 1. The elements of each row are arranged in descending order from left to right.
- 2. The elements of each column are arranged in ascending order from top to bottom.

Solution. See algorithm 6.

Algorithm 6: Find target value

Input: An $m \times n$ sorted matrix A **Output:** one position of the target value $\langle i, j \rangle$

1 Function FindRec(A, i_1, i_2, j_1, j_2): $\langle i_1, j_1 \rangle$ indicates the top-left corner of the search range, $\langle i_2, j_2 \rangle$ indicates the bottom-right corner

```
if i_1 > i_2 or j_1 > j_2 then
          return None
 3
 4
       i_{mid} = (i_1 + i_2)/2, j_{mid} = (j_1 + j_2)/2;
 5
       if A[i_{mid}][j_{mid}] = target then
 6
 7
           return \langle i_{mid}, j_{mid} \rangle
 8
       end
       if A[i_{mid}][j_{mid}] < target then
 9
           call FindRec(A, i_1, i_2, j_1, j_{mid}) and return if result is not None;
10
           call FindRec(A, i_{mid}, i_2, j_{mid} + 1, j_2) and return if result is not None;
11
       else
12
           call FindRec(A, i_1, i_{mid}, j_1, j_2) and return if result is not None;
13
           call FindRec(A, i_{mid} + 1, i_2, j_{mid}, j_2) and return if result is not None;
       end
16 return None
   Function Main(S):
      R = \text{FindRec}(S, 0, 0, m-1, n-1);
19 return R
```

Exercise 6 Quicksort is based on the Divide-and-Conquer method. Here is the two-step divide-and-conquer process for sorting a typical subarray $A[p \dots r]$:

1. **Divide:** Partition the array $A[p \dots r]$ into two subarrays $A[p \dots q-1]$ and $A[q+1 \dots r]$ such that each element of $A[p \dots q-1]$ is less than or equal to A[q], which is, in turn, less than or equal to each element of $A[q+1 \dots r]$. Compute the index q as part of this partitioning procedure.

2. Conquer: Sort $A[p \dots q-1]$ and $A[q+1\dots r]$ respectively by recursive calls to Quicksort.

Write down the recurrence function T(n) of QuickSort and compute its time complexity.

Hint: At this time T(n) is split into two subarrays with different sizes (usually), and you need to describe its recurrence relation by the sum of two subfunctions plus additional operations.

Solution. For array A of the size N, we first need to traverse the array and do the partition, which will cost cNtime. The recursion will take T(i-1) and T(N-i-1) time for elements smaller than the pivot and greater than the pivot, where T(n) is the time taken for n inputs.

For average case, we can take the average of every possible dividing case. The partition of N elements can be $\{0, N-1\}, \{1, N-2\}, \ldots, \{N-1, 0\}$. Hence we have

$$T(N) = 2\left(\frac{T(0) + T(1) + \dots + T(N-1)}{N}\right) + cN\tag{1}$$

$$NT(N) = 2(T(0) + T(1) + \dots + T(N-1)) + cN^{2}$$
(2)

$$(N-1)T(N-1) = 2(T(0) + T(1) + \dots + T(N-2)) + c(N-1)^{2}$$
(3)

By subtracting Equation 3 from Equation 2 we have

$$NT(N) - (N-1)T(N-1) = 2T(N-1) + 2cN - c^{2}$$
(4)

Since constant c^2 can be ignored

$$NT(N) = (N+1)T(N-1) + 2cN$$

$$\frac{T(N)}{N+1} = \frac{T(N-1)}{N} + \frac{2c}{N+1}$$

$$\frac{T(N-1)}{N} = \frac{T(N-2)}{N-1} + \frac{2c}{N}$$
.....
$$\frac{T(2)}{3} = \frac{T(1)}{2} + \frac{2c}{3}$$
(5)

By taking the sum of Equation 5 together, we have

$$T(N) = (N+1) \left(\frac{T(1)}{2} + 2c \sum_{i=3}^{N+1} \frac{1}{i} \right)$$

$$\leq (N+1)2c \ln N \in O(N \log N)$$
(6)

For best case, all partitions are perfect $\{N/2, N/2\}$,

$$T(N) = 2T(\frac{N}{2}) + cN$$

$$= 4T(\frac{N}{4}) + 2cN$$

$$= \dots = NT(1) + \log_2 N \cdot cN \in O(N \log N)$$
(7)

For worst case, assume all partitions are $\{0, N-1\}$,

$$T(N) = T(N-1) + cN$$

$$= T(N-2) + c(N-1) + cN$$

$$= \dots = c(1+2+\dots+N) \in O(N^2)$$
(8)