# Forecasting the black Sigatoka development rate: A comparison of machine learning techniques

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## Abstract

Pending.

Keywords: Machine learning, Black Sigatoka, Support vector regression, Banana disease prediction, Biological warning system

#### 1 1. Introduction

- The black Sigatoka disease caused by the fungus Mycosphaerella fijiensis
  - n debe ser

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- 3 Morelet is the major pathological problem of banana and plantain crops in
  - Central America, Panama, Colombia and Ecuador, as in many parts of Africa autor, anno
- 5 and Asia [5].
- This disease attacks the plant leaves producing a rapid deterioration of the
- <sup>7</sup> leaf area, affects the growth and productivity of the plants due to the impairment
- of their photosinthetic ability causes a reduction in the quality of the fruit, and
- 9 promotes premature maturation of bunches, which is the major cause of product
- losses associated with the black Sigatoka. Figure 1 shows three stages of this
- disease.
- Phytopathological studies point out that precipitation, temperature, relative
- 13 humidity and wind are the main climatic variables that affect its development

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Figure 1: Examples of three disease stages of the black Sigatoka. (a) Initial stage. (b) Intermediate stage, and (c) Advanced stage.

In Costa Rica for the control of black Sigatoka is necessary the application 15 of chemical fungicides. Depending of the zone of production and the weather 16 conditions 45 - 55 cycles/year of fungicides is needed to keep this disease under 17 control and to produce fruit with quality for exportation. This represent a cost per hectare per year ranged between \$1600 USD and \$2000 USD, about 0,64 -19 0.80 cents of the cost of production of a box of 18.14 kilograms. Overall, this represents 10% to 12% of the total production cost. 21 The past and present rates of disease development can in principle be used 22 to predict its future behavior and to determine whether particular fungicide 23 spray schedules will be able to effectively and economically control the disease 24 Chuang and Jeger [2].

There are efforts to apply machine learning methods for decision-making in 26 agriculture, including the control of crop diseases. For example, [Camargo et al., 2012] present an intelligent system for the assessment of crop disorders, [3] introduce a plant virus identification method based on neural networks with an evolu-29 tionary preprocessing stage, [4] summarize in their survey crop pests prediction 30 methods using regression and machine learning approaches, while [7] present an 31 intelligent agricultural forecasting system based on wireless sensor networks.

In this work, we compare five machine learning techniques (support vector regression (SVR), echo state networks (ESN), ridge regression, elastic-net 34 regression and ordinary least squares linear regression) to predict the development rate of the black Sigatoka disease.

- The main contribution of this work is a comparison between machine learning
- methods to forecast black Sigatoka development rate.

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## 2. Materials and methods

- 2.1. Concepts
- 2.1.1. Black Sigatoka disease
- Black Sigatoka, disease caused by the fungus Mycosphaerella fijiensis Morelet,
- 43 is the main problem phytopathologic of banana and plantain crops in Central
- 44 America [5].
- This disease attacks the leaves of plants producing a rapid deterioration of
- 46 the leaf area. It affects the growth and productivity of plants by decreasing
- photosynthetic capacity. Also causes a reduction in quality of the fruit [5].
- The climate has a major effect on the behavior of the black Sigatoka. Precip-
- 49 itation, temperature, relative humidity and wind are the main climatic variables
- 50 affecting the development of this disease [5].

## 51 2.1.2. Biological warning system

- The early warning system for black Sigatoka is an adaptation of the yellow
- Sigatoka warning system developed by Ganry and Meyer and modified by Ganry
- 54 and Laville to use for controlling yellow Sigatoka in Cameroon. Ternesien and
- 55 Fouré later improved Ganry and Laville's system. The latter system is based on
- weekly observations of disease symtoms on young leaves of the plant, according
- to Fouré's symptom (stages) descriptions. Arbitrary coefficientes, based on in-
- cidence and severity of disease development, are used to calculate two variables:
- 59 gross sum and state of evolution. Gross sum is based on the stage present and
- 60 an arbitrary coefficient, which increases with the advance of the symptoms and
- the juvenility of the leaf. The state of evolution is calculated using the gross
- sum and the foliar emission period. Although threshold levels were initially
- suggested as a guide to spray timing, the fluctuation of these two variables was
- found to better define appropriate times to spray [6].

# 2.1.3. Support Vector Regression (SVR)

From the perspective of Support Vector Regression (SVR) the regression function y = f(s) for a given dataset  $D = \{(s_i, y_i)\}_{i=1}^n$ , is represented as a linear function of the form [8]:

$$f(s) = w^T s + b$$

- where w and b are respectively the weight vector and the intercept of the model,
- and they are selected to find an optimal fit to the data available in D.
- For nonlinear cases, one proceeds by mapping the input p-dimensional vec-
- 69 tors via a nonlinear function  $\phi: \mathbb{R}^p \to F$ , onto the feature space F. After
- 70 nonlinear mapping, the regression function evolves to a pervasive form:

$$f(s) = w^T \phi(s) + b$$

SVR uses the  $\epsilon$  – insensitive loss function:

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$$l = |y - f(s)|_{\epsilon} = \begin{cases} 0 & |y - f(s)| \le \epsilon \\ |y - f(s)| - \epsilon & else \end{cases}$$

 $^{72}$  which ignores the error if the difference between the prediction value and

- the actual value is smaller than  $\epsilon$ . The  $\epsilon$  insensitive loss function allows to
- find the coefficients w and b by solving a convex optimization problem, which
- balances the empirical error and the generalization ability. In SVR, the empirical
- <sub>76</sub> error is measured by the loss function -insensitive and the generalization ability
- <sub>77</sub> is measured by the Euclidean norm of w [9]. Then, the optimization problem
- to identify the regression model can be formulated by [8]:

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minimize  $J(w, \xi_i, \xi_i^*) = \frac{1}{2} \left| \left| w \right| \right|^2 + C \sum_{i=1}^n (\xi_i, \xi_i^*)$  completar la cita XXXXX con el libro de  $y_i - w^T \phi(s) - b \le \epsilon + \xi_i$  (1) SVR

$$y_i - w^T \phi(s) - b \le \epsilon + \xi_i$$
 subject to 
$$w^T \phi(s) + b - y_i \le \epsilon + \xi_i^* \quad i = 1, 2, ..., n$$
 
$$\xi_i, \xi_i^* \ge 0$$

- where C denotes the penalty parameter between empirical and generalization
- $_{80}$   $\,$  errors, and  $\xi_i,\xi_i^*$  are slack variables. Figure.2 shows this situation.

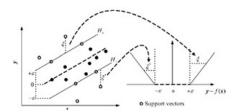


Figure 2:  $\epsilon - insensitive loss function[8]$ .

The solution of this optimization problem by the Lagrange method is given by:

$$f(s) = w^T \phi(s) + b = \sum_{i=1}^{n} (\alpha_i - \alpha_i^*) K(s, s_i) + b$$

where  $\alpha_i - \alpha_i^*$  are the Lagrange multipliers of the optimization problems dual form and  $K(s_i, s_j)$  is the kernel function satisfying the Mercer condition, and holds:

$$K(s_i, s_j) = \langle \phi(s_i), \phi(s_j) \rangle$$

- Operations in the kernel function  $K(s,s_i)$  are performed in the input space
- rather than in the potentially high dimensional feature space of  $\phi$  [10].
- 2.1.4. Ordinary least squares regression
- This method fits a linear model with coefficients w = (w1, ..., wp) to minimize
- the residual sum of squares between the observed responses in the dataset, and
- the responses predicted by the linear approximation. Mathematically it solves
- a problem of the form [?]:

$$\min_{w} \left| \left| Xw - y \right| \right|_{2}^{2}$$

- where X denotes the features matriz.
- 89 According Pedregosa et al. [11] the coefficient estimates for Ordinary Least
- 90 Squares rely on the independence of the model terms. When terms are correlated

and the columns of the design matrix X have an approximate linear dependence,

the design matrix becomes close to singular and as a result, the least-squares

93 estimate becomes highly sensitive to random errors in the observed response,

producing a large variance. This situation of multicollinearity can arise, for

95 example, when data are collected without an experimental design

96 2.1.5. Ridge regression

The ridge regression addresses some of the problems of ordinary least squares regression by imposing a penalty on the size of the coefficients. The ridge coefficients minimize a penalized residual sum of squares [11]:

$$\min_{w} \left| \left| Xw - y \right| \right|_{2}^{2} + \alpha \left| \left| w \right| \right|_{2}^{2}$$

Here,  $\alpha > 0$  is a complexity parameter that controls the amount of shrinkage: the larger the value of  $\alpha$ , the greater the amount of shrinkage and thus the coefficients become more robust to collinearity.

2.1.6. Elastic-Net regression

Elastic-Net is a linear regression model trained with L1 and L2 prior as regularizer. This combination allows for learning a sparse model where few of the weights are non-zero like Lasso, while still maintaining the regularization properties of Ridge [11]. The convex combination of L1 and L2 is controlled by using the  $l1_ratio$  parameter.

Elastic-Net is useful when there are multiple features which are correlated with one another. Lasso is likely to pick one of these at random, while elastic-net is likely to pick both. A practical advantage of trading-off between Lasso and Ridge is it allows Elastic-Net to inherit some of Ridges stability under rotation.

The objective function to minimize is [11]:

$$\min_{w} \frac{1}{2n_{samples}} \left| \left| Xw - y \right| \right|_{2}^{2} + \alpha \rho \left| \left| w \right| \right|_{1} + \frac{\alpha(1-\rho)}{2} \left| \left| w \right| \right|_{2}^{2}$$

## 2.1.7. Echo State Networks (ESN)

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Recurrent Neural Networks (RNN) are useful for temporal patterns, but 115 when they are trained with backpropagation methods, they are very slow. Echo 116 State Network (ESN) is an alternative training method to solve that problem. 117 ESN is based on the observation that if a random RNN possesses certain algebraic properties, training only a linear readout from it is often sufficient to 119 achieve excellent performance in practical applications [12]. For a given train-120 ing input signal  $u(n) \in \mathbb{R}^{N_u}$  a desired target output signal  $y^{target}(n) \in \mathbb{R}^{N_y}$  is 121 known. Here n = 1, ..., T is the discrete time and T is the number of data points 122 in the training dataset. The task is to learn a model with output  $y(n) \in \mathbb{R}^{N_y}$ , 123 where y(n) matches  $y^t arget(n)$  as well as possible, minimizing an error measure 124  $E(y, y^t arget)$ , and, more importantly, generalizes well to unseen data. The un-125 trained RNN part of an ESN is called a dynamical reservoir, and the resulting 126 states x(n) are termed echoes of its input history [13]. Finally, these signals are sent to an output layer as shown in the Figure.3.

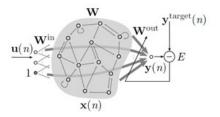


Figure 3: An echo state network [13].

The connections between the different elements of an Echo State Network have weights randomly generated. The weights of the internal connections of the reservoir (W) as well as the weights of the input layer  $(W_i n)$ , after being generated are set statically during all stages of implementation of the algorithm. The weights between the reservoir and the output layer  $(W_o ut)$  are subject to changes of a supervised learning algorithm to correct the degree of error generated by the entire system [13].

## 2.1.8. Related works

Huang et al. [3] surveyed the development of soft computing techniques in agricultural and biological engineering, including fuzzy logic, artificial neural networks, genetic algorithms, bayesian inference and decision trees.

A related work, proposed by Romero [14] relies on regression models using a stepwise procedure to predict incubation and latency times of black Sigatoka. 141 The author performed experiments on two farms located in Costa Rica (La Rita 142 and Waldeck, the same as those used in this study but with different names). 143 The study used data from: December 1993 to August 1995. Romero concluded 144 that the model to predict the incubation period accounted a  $R^2$  of 69% in his observed data but it was not a good predictor when it was validated against an 146 independent dataset (cross validation). For latency, he developed two models 147 that accounted a  $R^2$  of 78% PONER EL VALOR OBTENIDO in the observed 148 data, however, when validated against an independent dataset (cross validation), the model was incorrect PONER EL VALOR OBTENIDO for Weldeck, and for Rita obtained an adjusted  $R^2$  of 82%. 151

Glezakos et al. [15] proposed to use Genetic Algorithms (GA) and Neural Networks (NN) to identify plant virus (Tobacco Rattle Virus (TRV) and the Cucumber Green Mottle Mosaic Virus (CGMMV)). This is achieved by the development of analytical tools of evolutionary adaptive width, propelled by Genetic Algorithms (GAs) and Neural Networks (NNs). The method was tested against some of the most commonly used classifiers in machine learning (Bayes, Trees and k-NN) via cross-validation and proved its potential towards the identification.

In the agricultural context, Alves et al. [16] used geoinformation techniques to develop predictive models to study the areas of risk to soybean rust in soybean, coffee leaf rust in coffee, and black Sigatoka in banana, considering Brazils climatic characterization and the distribution of soybean, coffee and banana crops. Temperature and rainfall data were obtained for the period from 1950 to 2000, and of simulations for 2020, 2050 and 2080 using the SRES A2 cli-

mate change scenarios. Using principal components analysis, a single variable 166 was generated based on 57 variables, in order to determine an index explain-167 ing 87%, 88% and 90% of the variability of soybean, coffee and banana crops, 168 respectively, in municipal districts across Brazil. The climatic model was used 169 to generate the zoning of the three plant diseases, using temperature and leaf 170 wetness as input. Areas of favorability for the diseases were plotted against the 171 main coffee, soybean and banana growing areas in Brazil. This methodology 172 enabled the visualization of the changes in areas favorable for epidemics under 173 possible future scenarios of climate change. 174

Other applications of machine learning methods in precision agriculture include the use of support vector regression to predict carcass weight in beef cattle in advance to the slaughter [10], machine learning assessments of soil drying for agricultural planning [17], and early detection and classification of plant diseases with support vector machines based on hyperspectral reflectance [18].

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Furthermore, there have been attempts to generate software tools. Camargo et al. [Camargo et al.,2012] presented an information system for the assessment of plant disorders (Isacrodi). They proposed that experts will attain a much better accuracy than the Isacrodi classifier, particularly when provided with samples from the affected crop. However, those cases where such expertise is not available, they suggest that Isacrodi can provide valuable support to farmers. Isacordi includes 15 crop disorders, but the black Sigatoka no is one of them. The prediction process is based on multi-class support vector machines.

Regarding the prediction of the development of the black Sigatoka with ma-188 chine learning methods, Bendini et al. [19] presented a study about the risk 189 analysis of black Sigatoka occurrence based on polynomial models. A case study 190 was developed in a commercial banana plantation located in Jacupiranga, Brazil. 191 It was monitored weekly during the period from February to December 2005. 192 Data included the weekly monitoring of the diseases evolution stage, time series 193 of meteorological data and remote sensing data. They obtained a model to esti-194 mate the evolution of the disease from satellite imagery. This model relates gray 195 levels (NC) of the band 2 images of the Landsat-5 satellite, with the progress status or disease severity (EE). The authors claim to reach an  $\mathbb{R}^2$  of 90%.

Also there are works related to banana fruit. Soares et al. [20] apply two techniques: artificial neural networks (ANNs) and multiple linear regression (MLR) in banana plant to predict the yield, their results show that the neural network proved to be more accurate in forecasting the weight of the bunch in comparison to the multiple linear regressions in terms of the mean prediction-error (MPE = 1.40), mean square deviation (MSD = 2.29) and coefficient of determination ( $R^2 = 91\%$ ).

In general, the machine learning methods applied to predict the evolution of plant diseases, can be classified in two main approaches: 1) Those whose main inputs are images, and 2) Those whose main inputs are environmental and biological variables. Our study focuses in the second case.

## 209 2.1.9. Data

In this work we use data acquired in two research farms of Corbana in Costa Rica: 1) 28 Millas (previously called Waldeck and located at Matina) and La Rita (located at Pococ), both in the province of Limn, Costa Rica. The banana type is Musa AAA, subgroup Cavendish, cv. Grande Naine. The Table.1 shows the variables available.

The value to be predicted in all cases was  $E_s$ , that is the total measure of the biological warning system.

The data on the biological warning system are collected once a week. Although Corbana has meteorological stations that take data every five minutes, for these experiments, weekly averages generated by nearby stations to each of the farms were used.

The time intervals used for this study were: La Rita, week 48 of 2002 to week 17 of the 2015 (647 weeks) and for 28 Miles, week 37 of 2003 to week 18 of 2015 (605 weeks).

Mas detalle aqui? o ampliar en los conceptos?

Table 1: Variables used in the study

Variable	Meaning0'0'
$T_{a_m ax}$	Max air temperature
$T_{a_min}$	Min air temperature
$\overline{T}_a$	Mean air temperature
H	Humidity
$H_min$	Min humidity
$H_m ax$	Max humidity
R	Solar radiation
$\overline{P}$	Mean precipitation
$W_m ax$	Max speed wind
$\overline{W}$	Mean speed wind
$L_2$	Biological warning system Leaf 2
$L_3$	Biological warning system Leaf 3
$L_4$	Biological warning system Leaf 4
$E_s$	Biological warning system Evolution Stage

2.1.10. Data preprocessing

In 28 Miles farm, 1% of the data were missing, while in La Rita was 2.25%.
To fill-in the missing values we use spline interpolation. The data collected did
not exhibit outliers.

Due the fact that the variables measure meteorological or biological process, they are discretized in order to reflect trends in the data, i.e. the continuous values are not directly used. The coefficient of variation  $C_v(x)$  of each variable x was used to determine the number n of discretization levels.

$$n = \lfloor 100 \ C_v(x) \rfloor$$

where | | is the round operator.

Each discretization range was uniformly partitioned. Besides enabling the capture of tendencies, the discretization removes the effect of small variations

 $_{231}$  in the data collection, either by inaccuracies of the instruments (meteorological

variables) or by subjective bias introduced by the human who collects the data

233 (biological warning system). ESTO DEBE ESTAR DESCRITO EN ALGUNA

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Each feature was scaled to fit in a range between 0 and 1. The variable to be predicted was not scaled.

2.2. Evaluation criteria

Although there are many types of indicators to assess the quality of the prediction, we selected the determination coefficient  $(R^2)$ .

Given n records, let be y the actual value of the series,  $\hat{y}$  the predicted value and  $\hat{y}$  the mean of the observed data.

$$\bar{y} = \frac{1}{n} \sum_{i=1}^{n} y_i$$

$$S_e^2 = \frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{n}$$

$$S_R^2 = \frac{\sum_{i=1}^n (\hat{y}_i - \bar{y}_i)^2}{n}$$

$$S_y^2 = S_R^2 + S_e^2$$

$$R^2 = \frac{S_R^2}{S_u^2}$$

This decision is supported by the widespread use in machine learning and agriculture areas [20], [21], [22] and [23].

244 2.3. Methodology

The selection of methods and their parametrisation was performed in two stages.

Phase one

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In the phase one, we did ten-fold-cross-validation on a set of machine learning methods and different configurations:

- Patterns: n by m, where n from 1 to 8 and m from 1 to 2.
- Methods: support vector regression with the kernels functions: linear,
  RBF (Gaussian) and sigmoid; echo state networks; ordinary least squares
  linear regression, ridge regression and elastic-net regression.
- Variables included in the model:
  - All variables.
    - from the set  $\{\overline{T}_a, H, \overline{P}, \overline{W}\}$  use the subsets with one, two or four elements. These variables are according to experts the ones having most impact on the disease development [5].

#### Phase two

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In the second phase, the best configurations obtained in phase one are used to validate with the last 52 and 102 weeks.

This second phase intents to expose how these methods behave on a considerable climate in the years 2014 and 2015.

# 2.4. Programming environment

We use the python programming language with the Integrated Development Environment (IDE) Spyder [24], particularly with the libraries pandas [25] and numpy [26]. For SVR, ridge and ordinary least squares regressions, we used sklearn [11] and for ESN the python-based code of Dr. *Lukoševičius* [13] on which the necessary were done for adjustments for the experiments of this work. The computer used a processor Intel(R) Core i7-4800MQ CPU @ 2.70GHz, 16.0 GB RAM, running Windows 8 Pro.

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## 3. Results

## 4. Discussion and conclusions

## <sub>274</sub> 5. References

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