# Forecasting the black Sigatoka development rate: A comparison of machine learning techniques

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#### Abstract

Pending.

Keywords: Machine learning, Black Sigatoka, Support vector regression, Banana disease prediction, Biological warning system

#### 1. Introduction

- The black Sigatoka disease caused by the fungus Mycosphaerella fijiensis
  - n debe ser
- 3 Morelet is the major pathological problem of banana and plantain crops in
- debe ber
- <sup>4</sup> Central America, Panama, Colombia and Ecuador, as in many parts of Africa
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- 5 and Asia [5].
- This disease attacks the plant leaves producing a rapid deterioration of the
- <sup>7</sup> leaf area, affects the growth and productivity of the plants due to the impairment
- 8 of their photosinthetic ability causes a reduction in the quality of the fruit, and
- 9 promotes premature maturation of bunches, which is the major cause of product
- losses associated with the black Sigatoka. Figure 1 shows three stages of this
- disease.
- Phytopathological studies point out that precipitation, temperature, relative
- humidity and wind are the main climatic variables that affect its development

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<sub>4</sub> [5].



Figure 1: Examples of three disease stages of the black Sigatoka. (a) Initial stage. (b) Intermediate stage, and (c) Advanced stage.

In Costa Rica for the control of black Sigatoka is necessary the application 15 of chemical fungicides. Depending of the zone of production and the weather 16 conditions 45 55 cycles/year of fungicides is needed to keep this disease under 17 control and to produce fruit with quality for exportation. This represent a cost per hectare per year ranged between \$1600 USD and \$2000 USD, about 0,64 -19 0.80 cents of the cost of production of a box of 18.14 kilograms. Overall, this 20 represents 10% to 12% of the total production cost. 21 The past and present rates of disease development can in principle be used 22 to predict its future behavior and to determine whether particular fungicide 23

to predict its future behavior and to determine whether particular fungicide spray schedules will be able to effectively and economically control the disease Chuang and Jeger [2].

There are efforts to apply machine learning methods for decision-making in agriculture, including the control of crop diseases. For example, [Camargo et al.,2012] present an intelligent system for the assessment of crop disorders, [3] introduce a plant virus identification method based on neural networks with an evolutionary preprocessing stage, [4] summarize in their survey crop pests prediction methods using regression and machine learning approaches, while [7] present an intelligent agricultural forecasting system based on wireless sensor networks.

In this work, we compare four machine learning techniques (support vector regression (SVR), echo state networks (ESN), ridge regression and ordinary least squares linear regression) to predict the development rate of the black Sigatoka disease.

- The main contribution of this work is a comparison between machine learning
- methods to forecast black Sigatoka development rate.

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#### 2. Materials and methods

- 2.1. Concepts
- 41 2.1.1. Black Sigatoka disease
- Black Sigatoka, disease caused by the fungus Mycosphaerella fijiensis Morelet,
- 43 is the main problem phytopathologic of banana and plantain crops in Central
- 44 America [5].
- This disease attacks the leaves of plants producing a rapid deterioration of
- 46 the leaf area. It affects the growth and productivity of plants by decreasing
- photosynthetic capacity. Also causes a reduction in quality of the fruit [5].
- The climate has a major effect on the behavior of the black Sigatoka. Precip-
- 49 itation, temperature, relative humidity and wind are the main climatic variables
- 50 affecting the development of this disease [5].

## 51 2.1.2. Biological warning system

- The early warning system for black Sigatoka is an adaptation of the yellow
- Sigatoka warning system developed by Ganry and Meyer and modified by Ganry
- 54 and Laville to use for controlling yellow Sigatoka in Cameroon. Ternesien and
- Four later improved Ganry and Laville's system. The latter system is based on
- weekly observations of disease symtoms on young leaves of the plant, according
- 57 to Four's symptom (stages) descriptions. Arbitrary coefficientes, based on inci-
- dence and severity of disease development, are used to calculate two variables:
- 59 gross sum and state of evolution. Gross sum is based on the stage present and
- 60 an arbitrary coefficient, which increases with the advance of the symptoms and
- the juvenility of the leaf. The state of evolution is calculated using the gross
- sum and the foliar emission period. Although threshold levels were initially
- suggested as a guide to spray timing, the fluctuation of these two variables was
- found to better define appropriate times to spray [6].

## 2.1.3. Support Vector Regression (SVR)

From the perspective of Support Vector Regression (SVR) the regression function y=f(s) for a given dataset  $D=\{(s_i,y_i)\}_{i=1}^n$  , is represented as a linear function of the form [8]:

$$f(s) = w^T s + b$$

- where w and b are respectively the weight vector and the intercept of the model,
- and they are selected to find an optimal fit to the data available in D.
- For nonlinear cases, one proceeds by mapping the input p-dimensional vec-
- tors via a nonlinear function  $\phi: \mathbb{R}^p \to F$ , onto the feature space F. After 69
- nonlinear mapping, the regression function evolves to a pervasive form:

$$f(s) = w^T \phi(s) + b$$

SVR uses the  $\epsilon$  – insensitive loss function:

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$$l = |y - f(s)|_{\epsilon} = \begin{cases} 0 & |y - f(s)| \le \epsilon \\ |y - f(s)| - \epsilon & else \end{cases}$$

which ignores the error if the difference between the prediction value and 72 the actual value is smaller than  $\epsilon$ . The  $\epsilon$  – insensitive loss function allows to

find the coefficients w and b by solving a convex optimization problem, which

balances the empirical error and the generalization ability. In SVR, the empirical

error is measured by the loss function -insensitive and the generalization ability 76

is measured by the Euclidean norm of w [9]. Then, the optimization problem

to identify the regression model can be formulated by [8]:

 $\xi_i, \xi_i^* \geq 0$ 

completar la  $J(w,\xi_i,\xi_i^*) = \frac{1}{2} \left| \left| w \right| \right|^2 + C \sum_{i=1}^n (\xi_i,\xi_i^*)$ cita XXXXX con el libro de  $y_i - w^T \phi(s) - b \le \epsilon + \xi_i$ (1)SVR  $w^T \phi(s) + b - y_i \le \epsilon + \xi_i^* \quad i = 1, 2, ..., n$ subject to

Falta

- where C denotes the penalty parameter between empirical and generalization
- $_{80}$   $\,$  errors, and  $\xi_i,\xi_i^*$  are slack variables. Figure.2 shows this situation.

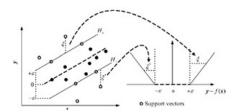


Figure 2:  $\epsilon - insensitive loss function[8]$ .

The solution of this optimization problem by the Lagrange method is given by:

$$f(s) = w^T \phi(s) + b = \sum_{i=1}^{n} (\alpha_i - \alpha_i^*) K(s, s_i) + b$$

where  $\alpha_i - \alpha_i^*$  are the Lagrange multipliers of the optimization problems dual form and  $K(s_i, s_j)$  is the kernel function satisfying the Mercer condition, and holds:

$$K(s_i, s_j) = \langle \phi(s_i), \phi(s_j) \rangle$$

- Operations in the kernel function  $K(s,s_i)$  are performed in the input space
- rather than in the potentially high dimensional feature space of  $\phi$  [10].
- 2.1.4. Ordinary least squares regression
- This method fits a linear model with coefficients w = (w1, ..., wp) to minimize
- the residual sum of squares between the observed responses in the dataset, and
- the responses predicted by the linear approximation. Mathematically it solves
- a problem of the form [?]:

$$\min_{w} \left| \left| Xw - y \right| \right|_{2}^{2}$$

- where X denotes the features matriz.
- 89 According Pedregosa et al. [11] the coefficient estimates for Ordinary Least
- 90 Squares rely on the independence of the model terms. When terms are correlated

- and the columns of the design matrix X have an approximate linear dependence,
- <sub>92</sub> the design matrix becomes close to singular and as a result, the least-squares
- estimate becomes highly sensitive to random errors in the observed response,
- 94 producing a large variance. This situation of multicollinearity can arise, for
- example, when data are collected without an experimental design

## 2.1.5. Ridge regression

The ridge regression addresses some of the problems of ordinary least squares regression by imposing a penalty on the size of the coefficients. The ridge coefficients minimize a penalized residual sum of squares [11]:

$$\min_{w} \left| \left| Xw - y \right| \right|_{2}^{2} + \alpha \left| \left| w \right| \right|_{2}^{2}$$

- Here,  $\alpha > 0$  is a complexity parameter that controls the amount of shrinkage:
- the larger the value of  $\alpha$ , the greater the amount of shrinkage and thus the
- 99 coefficients become more robust to collinearity.

## 2.1.6. Echo State Networks (ESN)

Recurrent Neural Networks (RNN) are useful for temporal patterns, but 101 when they are trained with backpropagation methods, they are very slow. Echo 102 State Network (ESN) is an alternative training method to solve that problem. 103 ESN is based on the observation that if a random RNN possesses certain al-104 gebraic properties, training only a linear readout from it is often sufficient to achieve excellent performance in practical applications [12]. For a given train-106 ing input signal  $u(n) \in \mathbb{R}^{N_u}$  a desired target output signal  $y^{target}(n) \in \mathbb{R}^{N_y}$  is 107 known. Here n = 1, ..., T is the discrete time and T is the number of data points 108 in the training dataset. The task is to learn a model with output  $y(n) \in \mathbb{R}^{N_y}$ , 109 where y(n) matches  $y^t arget(n)$  as well as possible, minimizing an error measure  $E(y, y^t arget)$ , and, more importantly, generalizes well to unseen data. The un-111 trained RNN part of an ESN is called a dynamical reservoir, and the resulting 112 states x(n) are termed echoes of its input history [13]. Finally, these signals are 113 sent to an output layer as shown in the Figure.3. 114

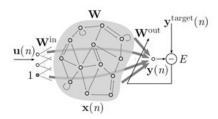


Figure 3: An echo state network [13].

The connections between the different elements of an Echo State Network have weights randomly generated. The weights of the internal connections of the reservoir (W) as well as the weights of the input layer  $(W_i n)$ , after being generated are set statically during all stages of implementation of the algorithm. The weights between the reservoir and the output layer  $(W_o ut)$  are subject to changes of a supervised learning algorithm to correct the degree of error generated by the entire system [13].

## 2.1.7. Related works

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Huang et al. [3] surveyed the development of soft computing techniques in agricultural and biological engineering, including fuzzy logic, artificial neural networks, genetic algorithms, bayesian inference and decision trees.

A related work, proposed by Romero [14] relies on regression models using 126 a stepwise procedure to predict incubation and latency times of black Sigatoka. 127 The author performed experiments on two farms located in Costa Rica (La Rita and Waldeck, the same as those used in this study but with different names). 129 The study used data from: December 1993 to August 1995. Romero concluded 130 that the model to predict the incubation period accounted a  $R^2$  of 69% in his 131 observed data but it was not a good predictor when it was validated against an 132 independent dataset (cross validation). For latency, he developed two models that accounted a  $R^2$  of 78% PONER EL VALOR OBTENIDO in the observed 134 data, however, when validated against an independent dataset (cross validation), 135 the model was incorrect PONER EL VALOR OBTENIDO for Weldeck, and for 136

> Revisar si se puede implementar la propuesta de este autor para comparar

Rita obtained an adjusted  $R^2$  of 82%.

Glezakos et al. [15] proposed to use Genetic Algorithms (GA) and Neural Networks (NN) to identify plant virus (Tobacco Rattle Virus (TRV) and the Cucumber Green Mottle Mosaic Virus (CGMMV)). This is achieved by the development of ana-lytical tools of evolutionary adaptive width, propelled by Genetic Algorithms (GAs) and Neural Networks (NNs). The method was tested against some of the most commonly used classifiers in machine learning (Bayes, Trees and k-NN) via cross-validation and proved its potential towards the identification.

In the agricultural context, Alves et al. [16] used geoinformation techniques 146 to develop predictive models to study the areas of risk to soybean rust in soy-147 bean, coffee leaf rust in coffee, and black Sigatoka in banana, considering Brazils 148 climatic characterization and the distribution of soybean, coffee and banana 149 crops. Temperature and rainfall data were obtained for the period from 1950 to 2000, and of simulations for 2020, 2050 and 2080 using the SRES A2 cli-151 mate change scenarios. Using principal components analysis, a single variable 152 was generated based on 57 variables, in order to determine an index explain-153 ing 87%, 88% and 90% of the variability of soybean, coffee and banana crops, 154 respectively, in municipal districts across Brazil. The climatic model was used 155 to generate the zoning of the three plant diseases, using temperature and leaf 156 wetness as input. Areas of favorability for the diseases were plotted against the 157 main coffee, soybean and banana growing areas in Brazil. This methodology 158 enabled the visualization of the changes in areas favorable for epidemics under possible future scenarios of climate change. 160

Other applications of machine learning methods in precision agriculture include the use of support vector regression to predict carcass weight in beef cattle in advance to the slaughter [10], machine learning assessments of soil drying for agricultural planning [17], and early detection and classification of plant diseases with support vector machines based on hyperspectral reflectance [18].

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Furthermore, there have been attempts to generate software tools. Camargo et al. [Camargo et al.,2012] presented an information system for the assessment of plant disorders (Isacrodi). They proposed that experts will attain a much

better accuracy than the Isacrodi classifier, particularly when provided with samples from the affected crop. However, those cases where such expertise is not available, they suggest that Isacrodi can provide valuable support to farmers. Isacordi includes 15 crop disorders, but the black Sigatoka no is one of them. The prediction process is based on multi-class support vector machines.

Regarding the prediction of the development of the black Sigatoka with ma-174 chine learning methods, Bendini et al. [19] presented a study about the risk 175 analysis of black Sigatoka occurrence based on polynomial models. A case study 176 was developed in a commercial banana plantation located in Jacupiranga, Brazil. 177 It was monitored weekly during the period from February to December 2005. 178 Data included the weekly monitoring of the diseases evolution stage, time series 179 of meteorological data and remote sensing data. They obtained a model to esti-180 mate the evolution of the disease from satellite imagery. This model relates gray levels (NC) of the band 2 images of the Landsat-5 satellite, with the progress 182 status or disease severity (EE). The authors claim to reach an  $\mathbb{R}^2$  of 90%. 183

Also there are works related to banana fruit. Soares et al. [20] apply two techniques: artificial neural networks (ANNs) and multiple linear regression (MLR) in banana plant to predict the yield, their results show that the neural network proved to be more accurate in forecasting the weight of the bunch in comparison to the multiple linear regressions in terms of the mean prediction-error (MPE = 1.40), mean square deviation (MSD = 2.29) and coefficient of determination ( $R^2 = 91\%$ ).

In general, the machine learning methods applied to predict the evolution of plant diseases, can be classified in two main approaches: 1) Those whose main inputs are images, and 2) Those whose main inputs are environmental and biological variables. Our study focuses in the second case.

#### 195 2.1.8. Data

In this work we use data acquired in two research farms of Corbana in Costa Rica: 1) 28 Millas (previously called Waldeck and located at Matina) and La Rita (located at Pococ), both in the province of Limn, Costa Rica. The banana type is Musa AAA, subgroup Cavendish, cv. Grande Naine. The Table.1 shows
 the variables available.

Table 1: Variables used in the study

Variable	Meaning0'0'
$T_{a_m ax}$	Max air temperature
$T_{a_min}$	Min air temperature
$\overline{T}_a$	Mean air temperature
H	Humidity
$H_min$	Min humidity
$H_m ax$	Max humidity
R	Solar radiation
$\overline{P}$	Mean precipitation
$W_m ax$	Max speed wind
$\overline{W}$	Mean speed wind
$L_2$	Biological warning system Leaf 2
$L_3$	Biological warning system Leaf 3
$L_4$	Biological warning system Leaf 4
$E_s$	Biological warning system Evolution Stage

The value to be predicted in all cases was  $E_s$ , that is the total measure of 201 Mas detalle the biological warning system. 202 The data on the biological warning system are collected once a week. Alaqui? o 203 though Corbana has meteorological stations that take data every five minutes, ampliar en los 204 for these experiments, weekly averages generated by nearby stations to each of conceptos? 205 the farms were used. 206 The time intervals used for this study were: La Rita, week 48 of 2002 to week 17 of the 2015 (647 weeks) and for 28 Miles, week 37 of 2003 to week 18 of 2015 (605 weeks).

2.1.9. Data preprocessing

In 28 Miles farm, 1% of the data were missing, while in La Rita was 2.25%.
To fill-in the missing values we use spline interpolation. The data collected did
not exhibit outliers.

Due the fact that the variables measure meteorological or biological process, they are discretized in order to reflect trends in the data, i.e. the continuous values are not directly used. The coefficient of variation  $C_v(x)$  of each variable x was used to determine the number n of discretization levels.

$$n = \lfloor 100 \ C_v(x) \rfloor$$

214 where | | is the round operator.

Each discretization range was uniformly partitioned. Besides enabling the capture of tendencies, the discretization removes the effect of small variations in the data collection, either by inaccuracies of the instruments (meteorological variables) or by subjective bias introduced by the human who collects the data (biological warning system). ESTO DEBE ESTAR DESCRITO EN ALGUNA PARTE

Each feature was scaled to fit in a range between 0 and 1. The variable to be predicted was not scaled.

## 223 2.2. Evaluation criteria

Although there are many types of indicators to assess the quality of the prediction, we selected the root mean square error (RMSE) and the determination coefficient  $(R^2)$ .

Given n records, let be y the actual value of the series,  $\hat{y}$  the predicted value and  $\hat{y}$  the mean of the observed data.

$$RMSE = \sqrt{\sum_{i=1}^{n} \frac{(y - \hat{y})^2}{n}}$$

$$\bar{y} = \frac{1}{n} \sum_{i=1}^{n} y_i$$

$$S_e^2 = \frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{n}$$

$$S_R^2 = \frac{\sum_{i=1}^n (\hat{y}_i - \bar{y}_i)^2}{n}$$

$$S_y^2 = S_R^2 + S_e^2$$

$$R^2 = \frac{S_R^2}{S_y^2}$$

This decision is supported by the widespread use in machine learning and agriculture areas [20], [21], [22] and [23].

229 2.3. Methodology

The selection of methods and their parametrisation was performed in two stages.

#### Phase one

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- In the phase one, we did ten-fold-cross-validation on a set of machine learning methods and different configurations:
- Patterns: n by m, where n from 1 to 8 and m from 1 to 3.
- Methods: support vector regression with the kernels functions: linear,
  RBF (Gaussian) and sigmoid; echo state networks; ordinary least squares
  linear regression and ridge regression.
  - Variables included in the model:
- All variables.
- from the set  $\{\overline{T}_a, H, \overline{P}, \overline{W}\}$  use the subsets with one, two or four elements. These variables are according to experts the ones having most impact on the disease development [5].

## Phase two

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In the second phase, the best configurations obtained in phase one are used to validate with the last 52 and 102 weeks.

This second phase intents to expose how these methods behave on a considerable climate in the years 2014 and 2015.

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## 2.4. Programming environment

We use the python programming language with the Integrated Development Environment (IDE) Spyder [24], particularly with the libraries pandas [25] and numpy [26]. For SVR, ridge and ordinary least squares regressions, we used sklearn [11] and for ESN the python-based code of Dr. *Lukoševičius* [13] on which the necessary were done for adjustments for the experiments of this work. The computer used a processor Intel(R) Core i7-4800MQ CPU @ 2.70GHz, 16.0

### 3. Results

## 4. Discussion and conclusions

GB RAM, running Windows 8 Pro.

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