

Lecture 9. EN.553.744 Data Science for Large-Scale Graphs

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- Today:
- GATs
 - Expressivity in graph-level tasks
 - Graph isomorphism
 - Weisfeiler-Leman test

► A final, non-convolutional GNN: graph attention (GAT)

$$[x_\ell]_i = \sigma \left(\sum_{j \in \mathcal{N}(i)} \alpha_{ij} [x_{\ell-1}]_j H_\ell \right)$$

where α_{ij} are the graph attention coefficients, computed as:

$$\left\{ \begin{array}{l} \alpha_{ij} = \text{softmax}_{\mathcal{N}(i)}(e_{ij}) \\ e_{ij} = \frac{\rho(\vec{a}(x_i H' \parallel x_j H'))}{\sum_{j' \in \mathcal{N}(i)} \rho(\vec{a}(x_i H' \parallel x_{j'} H'))} \end{array} \right.$$

Annotations:
 - "concatenation" points to \parallel in the numerator.
 - "nonlinearity" points to ρ in the numerator.
 - $\vec{a} \in \mathbb{R}^d$ is indicated.

•) $a \in \mathbb{R}^{1 \times 2d}$

•) ρ is typically the Leaky ReLU $\rho(x) = \begin{cases} x, & \text{if } x \geq 0 \\ \alpha x, & \text{if } x < 0 \end{cases}$

The learnable parameters are: \vec{a}, H_ℓ for $1 \leq \ell \leq L$, H'

GAT layer $(X_\ell)_i = \sigma(\sum_{j \in \mathcal{N}_i} \alpha_{ij} (X_{\ell-1})_j H_\ell)$ thought of as a conv. layer where S , the attn, is learned (i.e. $S_{ij} = \alpha_{ij}$)

↳ This added flexibility increases the capacity of the architecture — observed empirically — but comes at cost of more expensive forward pass → especially for large & dense graphs since

→ all available / implemented in PyTorch geometric need to compute $|\mathcal{E}|$ coeffs. α_{ij}

► The "readout" in graph-level tasks

In node-level tasks (e.g. source localization, community detection, citation networks, etc.), both the input & output are graph signals $X \in \mathbb{R}^{n \times d_0}$, $Y \in \mathbb{R}^{n \times d_1}$. so the map $\Phi_{\mathcal{G}}$ is composed strictly of GNN layers

↳ ensures a parametrization that is independent of graph size n

In graph-level tasks, the output does not need to be a graph signal, it could be $y \in \mathbb{R}$, $y \in \{0, 1, \dots, C\}$ or $y \in \mathbb{R}^d$

How to map GNN layers to such outputs?
 \hookrightarrow readout layers

•) Option 1: a fully connected layer

$\rightarrow L$ GNN layers of the form:

$$X_\ell = \sigma \left(\sum_{k=0}^{L-1} S^k X_{\ell-1} H_{\ell,k} \right)$$

\rightarrow followed by: $y = p \left(C \cdot \text{vec}(X_L) \right)$

1-layer perceptron

$\in \mathbb{R}^{nd_L}$

$\in \mathbb{R}^{d \times nd_L}$

$\hookrightarrow \text{vec}(\cdot)$ vectorizes $\mathbb{R}^{u \times v}$ matrices $\rightarrow \mathbb{R}^{uv}$ vectors

$\hookrightarrow p$ can be identity or ReLU, softmax etc...

Downsides of a fully connected readout layer:

-) adds nd_Ld learning params \rightarrow grows with graph size
-) not permutation invariant Ex.: verify
-) not transferable across graphs

•) Option 2: aggregation

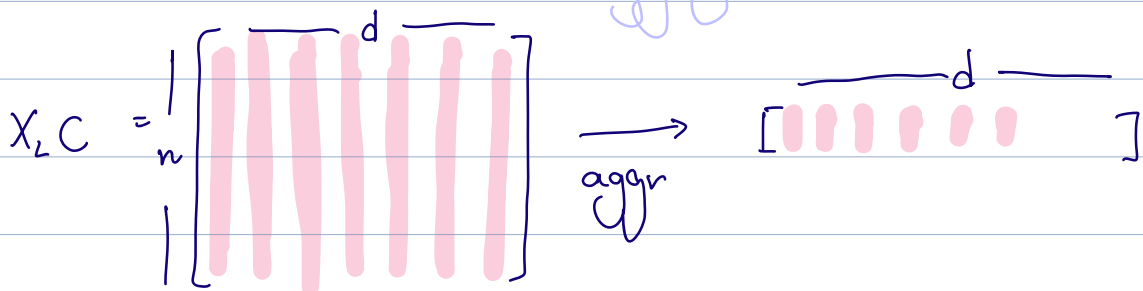
$\rightarrow L$ GNN layers of the form:

$$X_L = \sigma \left(\sum_{k=0}^{K-1} S^k X_{L-1} H_{L,k} \right)$$

\rightarrow followed by: $y = \text{aggr}(X_L C)$ $C \in \mathbb{R}^{d_L \times d}$

$$\text{aggr}: \mathbb{R}^{n \times d} \rightarrow \mathbb{R}^{1 \times d} \quad (\mathbb{R}^d)$$

(node-level aggregation)



Typical aggregation functions: mean, sum, max
(min, median, etc...)

↳ parametrization independent of n

↳ permutation invariant

↳ transferable across graphs

► Graph isomorphism problem

Let G and G' be two graphs. A graph isomorphism between G and G' is a bijection

$$f: V(G) \rightarrow V(G')$$

s.t. $\forall i, j \in V(G),$

$$(i, j) \in E(G) \Leftrightarrow (f(i), f(j)) \in E(G')$$

↳ Can we train a GNN to detect if graphs are isomorphic? I.e., ^{to} produce identical outputs for graphs in the same equivalence class (i.e., which are isomorphic) and \neq outputs for non-isomorphic graphs?

→ Consider two graphs G & G' with

$$L = V \Delta V^T \quad \text{and} \quad L' = V' \Delta V'^T$$

→ Assume they do not have node features (but we can impute them)

→ Consider the 1-layer GNN (linear):

$$y = \sum_{k=0}^{K-1} h_k L^k x \quad (*)$$

→ Suppose $\exists \lambda_j$ s.t. $\lambda_j \neq \lambda_i \quad \forall i \quad (**)$

How can we use GNN $(*)$ to solve the graph isomorphism problem for this pair?

•) Pick x white, i.e., s.t. $\mathbb{E}(\hat{C}_i) = 1 \quad \forall i$

•) Set $h_k = \begin{cases} 1 & \text{if } k=1 \\ 0 & \text{o.w.} \end{cases}$

$$\begin{aligned} \text{Then: } \mathbb{E}(\hat{y}) &= \mathbb{E}(V^T y) \\ &= \mathbb{E}(V^T \cancel{h_1} L x) \\ &= \mathbb{E}(\cancel{V^T V} \Delta V^T x) \\ &= \mathbb{E}(\Delta \hat{x}) = \Delta \mathbb{1} \end{aligned}$$

$$\Rightarrow \mathbb{E}[\hat{y}] = \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_3 \\ \vdots \\ \lambda_n \end{bmatrix}$$

"GNNs are more powerful than we think" (Karatzoulis et al.)
 ↪ for implementation in node domain

If (**) is satisfied, it suffices to compare:

sum, or aggregation, in the spectral domain

$$\mathbb{E}(\mathbb{1}^T \hat{y}) = \sum_i \lambda_i \quad \text{with}$$

$$\mathbb{E}(\mathbb{1}^T \hat{y}') = \sum_i \lambda_i'$$

)

≠

to verify $G \not\cong G'$

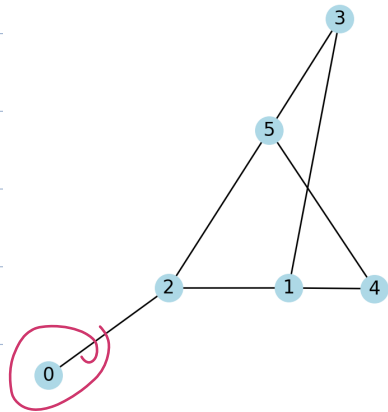
Hence: As long as graphs' eigenvalues are \neq , convolutional GNNs can distinguish them.

But what if the eigenvalues coincide?

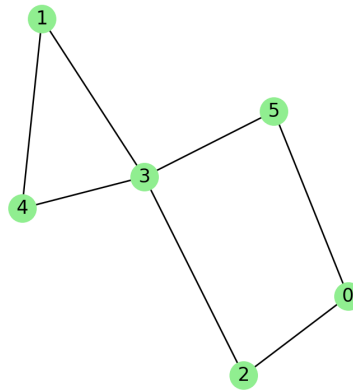
There are many non-isomorphic graphs sharing the same eigenvalues

Example :

Graph 1



Graph 2



clearly non isomorphic

but their Laplacian eigenvalues are the same :

$$\lambda_1 = 0; \lambda_2 = 0.764; \lambda_3 = 2; \lambda_4 = \lambda_5 = 3; \lambda_6 = 5.236$$

Exercise: verify!

Though our eigenvalue-based heuristic didn't work for this and other examples, a simple heuristic that works is counting degrees

For G_1 , $\{\underline{1}, 3, 3, 2, 2, 3\}$

For G_2 , $\{2, 2, 2, \underline{4}, 2, 2\}$

This is the idea behind the (1-) Weisfeiler-Leman test

The Weisfeiler-Leman graph isomorphism test

The WL test consists of running the "color refinement algorithm" for two graphs G & G' . If the "colors"/representations produced by WL are \neq , then G & G' are non-isomorphic. O.w., we don't know.

→ Given a graph $G = (V, E)$ with node features X , do:

$$c_i(0) = f(\cdot, \{x_i\}) \quad \forall i \in V$$

repeat:

\nearrow hash function

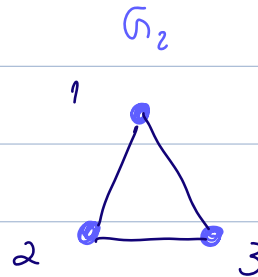
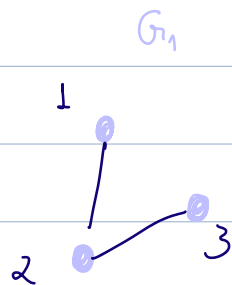
$$c_i(t) = f(c_i(t-1), \{\{c_j(t-1), j \in N(i)\}\}) \quad \forall i \in V$$

\nwarrow multisets

until colors cease to change (say at $t = T$)

return $\{\{c_i(T) \mid i \in V\}\}$

Example :



Color refinement for G_1 :

$$\begin{aligned}
 0) \quad & c_1(0) = c_2(0) = c_3(0) = f(0, 1) = \text{green} \\
 1) \quad & c_1(1) = f(\text{green}, \{\text{green}\}) = \text{green} \\
 & c_3(1) = f(\text{green}, \{\text{green}\}) = \text{green} \\
 & c_2(1) = f(\text{green}, \{\text{green}, \text{green}\}) = \text{red} \\
 2) \quad & c_1(2) = f(\text{green}, \{\text{red}\}) = \text{green} \\
 & c_3(2) = f(\text{green}, \{\text{red}\}) = \text{green} \\
 & c_2(2) = f(\text{red}, \{\text{green}, \text{green}\}) = \text{red} \\
 & \text{return } \{\{\text{green}, \text{red}, \text{green}\}\}
 \end{aligned}$$

Color refinement -or G_2 :

$$\begin{aligned}
 0) \quad & c_1(0) = c_2(0) = c_3(0) = f(0, 1) = \text{green} \\
 1) \quad & c_1(1) = c_2(1) = c_3(1) = f(\text{green}, \{\{\text{green}, \text{green}\}\}) = \text{green}
 \end{aligned}$$

return $\{\{\bullet, \bullet, \bullet\}\}$

Hence non-isomorphic!