

```
• abstract type Distribution end
```

$$\mathcal{P} \triangleq \{p(\cdot; \theta) : \theta \in \Theta\}$$

Distribution space

Define set \mathcal{P} as the collection of all probability distributions. Emphasizing generality, this set definition describes all of the possible models to describe the behavior of phenomena (in our case, random variables). To quantify our understanding of the nature of events, we turn to the probability distribution.

$$\begin{aligned}\mathcal{P} &= \mathcal{P}_M \cup \mathcal{P}_J \cup \mathcal{P}_C, \text{ where} \\ \mathcal{P}_M &\triangleq \{p(\cdot; \theta(X)); \theta(X) \in \Theta(X)\}, \\ \mathcal{P}_J &\triangleq \{p(\cdot; \theta(X_1^n); \theta(X_1^n) \in \Theta(X_1^n)\}, \\ \mathcal{P}_C &\triangleq \{p(\cdot; \theta(X|Y)); \theta(X|Y) \in \Theta(X|Y)\}\end{aligned}$$

Distribution subspaces

Specifically, the distribution space is composed of three categories of probability distributions:

1. **Marginal distribution** — describes a single random variable X
2. **Joint distribution** — describes a collection of random variables X_1, \dots, X_n
3. **Partial or Conditional distribution** — describes a single random variable X given the random variable Y

To begin, we emphasize that the collection of random variables X_1, \dots, X_n can be conceptualized instead as a single random variable $X_1^n \triangleq (X_1, \dots, X_n)$. Our development of probability distributions begins with a univariate focus, and readily extends into a multivariate analysis.

```
• mutable struct Marginal <: Distribution
•
•     p::AbstractDict
•
•     Marginal(p::AbstractDict) = new(p)
•
•     Marginal() = new(Dict())
•
```

```
• end
```

$$p_X(x; \theta(X)) = \begin{cases} \theta_1(X), & x = \mathbf{a}_1, \\ \theta_2(X), & x = \mathbf{a}_2, \\ \vdots & \\ \theta_m(X), & x = \mathbf{a}_m \end{cases}$$

Marginal distributions

```
p = Marginal distribution:
  θ1, x = a1
  θ2, x = a2
  ...
  θm, x = am
```

```
• p = Marginal(Dict(
•   :a1 => :θ1,
•   :a2 => :θ2,
•   :a3 => :θ3,
•   :am => :θm)
• )
```

```
• mutable struct Joint <: Distribution
•
•   p::AbstractDict
•
•   Joint(p::AbstractDict) = new(p)
•
•   Joint() = new(Dict())
•
• end
```

$$p(x_1^n; \theta(X_1^n)) = \begin{cases} \theta_1(X_1^n), & (x_1, \dots, x_n) = (\mathbf{a}_1^{(1)}, \dots, \mathbf{a}_1^{(n)}) \\ \theta_2(X_1^n), & (x_1, \dots, x_n) = (\mathbf{a}_2^{(1)}, \dots, \mathbf{a}_1^{(n)}) \\ \vdots & \\ \theta_{m_1 \dots m_n}(X_1^n), & (x_1, \dots, x_n) = (\mathbf{a}_{m_1}^{(1)}, \dots, \mathbf{a}_{m_n}^{(n)}) \end{cases}$$

Joint distributions

```
q = Joint distribution:
  θ1, (x1, ..., xn) = (a1(1), ..., a1(n))
  θ2, (x1, ..., xn) = (a2(1), ..., a1(n))
  ...
  θm, (x1, ..., xn) = (am(1), ..., am(n))
```

```
• q = Joint(
•   Dict((:a1(1), :a1(2), :a1(3), :a1(n)) => :θ1,
•         (:a2(1), :a1(2), :a1(3), :a1(n)) => :θ2,
•         (:a3(1), :a1(2), :a1(3), :a1(n)) => :θ3,
• )
```

```

• # ... (:a_m^(1), :a_m^(2), :a_m^(3), :a_m^(n)) => :θ_m)
• )

```

```

• mutable struct Partial <: Distribution
•
•     p::AbstractDict
•
•     Partial(p::AbstractDict) = new(p)
•
•     Partial() = new(Dict())
•
• end

```

```

• mutable struct Conditional <: Distribution
•
•     p::AbstractDict
•
•     Conditional(p::AbstractDict) = new(p)
•
•     Conditional() = new(Dict())
•
• end

```

$$p(x|y; \theta(X|Y)) = \begin{cases} \theta_1(X|Y), & x = a_1 | y = b_1 \\ \theta_2(X|Y), & x = a_2 | y = b_1 \\ \vdots & \\ \theta_{nm}(X|Y), & x = a_n | y = b_m \end{cases}$$

Partial, Conditional distributions

r = Partial distribution:
 $\theta_1, x = a_1 \mid y = b_1$
 $\theta_2, x = a_2 \mid y = b_1$
 \dots
 $\theta_{nm}, x = a_n \mid y = b_m$

```

• r = Partial(
•     Dict(((:a_1,), (:b_1,)) => :θ_1,
•         ((:a_2,), (:b_1,)) => :θ_2,
•         ((:a_3,), (:b_1,)) => :θ_3,
•         # ...
•         ((:a_n,), (:b_m,)) => :θ_nm)
• )

```