# Biosorption model

Yaroslav Smolin

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#### 1 Conventions

Unknown function  $\bar{L}_f(\bar{x},\bar{t})$ ,  $\bar{q}(\bar{x},\bar{r},\bar{t})$ ,  $\bar{S}_s(\bar{x},\bar{t})$ ,  $\bar{S}_f(\bar{x},\bar{r},\bar{t})$ ,  $\bar{S}_{fs}(\bar{x},\bar{t})$ ,  $\bar{S}(\bar{x},\bar{t})$ ,  $\bar{S}_{av}(\bar{x},\bar{t})$ , the bar under the functions and functions variables means that they are not normalized and have their dimensions. Transformation to the dimensionless form is made by next equations:

$$x = \frac{\bar{x}}{L} \quad r = \frac{\bar{r}}{R} \quad t = \frac{\bar{t}}{T \cdot D_g} \tag{1}$$

$$\bar{x} = xL \quad \bar{r} = rR \quad \bar{t} = t \cdot TD_q$$
 (2)

$$E_d = \frac{TD_sD_g}{R^2} \quad D_g = \frac{\rho_a q_0(1-\epsilon)}{\epsilon S_0} \quad D = D_gD_x \frac{T}{L^2} \quad St = 3k_f T \frac{1-\epsilon}{R\epsilon} \quad B_0 = \frac{L_{fmax}}{R}$$
 (3)

Table 1: Naming convention

x, r, u, t	axial, radial substrate $(0, R)$ , radial biofilm $(R, R + L_f)$ , and time coordinate
M, M, M, N	grid size for $x, r, u, t$
i,j,j,k	grid index for $x, r, u, t$
m, p	upper-inner loop variables
$ar{v}$	bar under variable mark that dimensionless procedure was not done yet
Ed	ration of the surface diffusion transport to bulk transport
au	timestep $t_{k+1}$ - $t_k$

#### 2 Kinetic equation

Standard equation

$$\frac{\partial \bar{q}(\bar{x}, \bar{r}, \bar{t})}{\partial \bar{t}} = \frac{D_s}{\bar{r}^s} \cdot \frac{\partial}{\partial \bar{r}} \left( \bar{r}^s \frac{\partial \bar{q}(\bar{x}, \bar{r}, \bar{t})}{\partial \bar{r}} \right) \tag{4}$$

Using (3) and (2) we get dimensionless equation

$$\frac{\partial q(x,r,t)}{\partial t} = \frac{E_d}{r^s} \cdot \frac{\partial}{\partial r} \left( r^s \frac{\partial q(x,r,t)}{\partial r} \right)$$
 (5)

$$\frac{\partial q(x,r,t)}{\partial t} = E_d \frac{s}{r} \frac{\partial q(x,r,t)}{\partial r} + E_d \frac{\partial^2 q(x,r,t)}{\partial r^2}$$
(6)

Table 2: Experimental data

R	radius of the particle, $r_M$ or $r_{max}$	0.039	cm
L	length of the adsorber, $x_M$ or $x_{max}$	40	cm
T	time of supervising, $t_N$ or $t_{max}$ ; $T = \tau_{res} \cdot n_t$	$3.6 \cdot 10^4$	s
$ au_{res}$	adsorber resident time, or empty bed contact time, $\tau_{res} = L/V_x$		s
$n_{res}$	number of treatment cycles supervised $n_t = T/\tau_{res}$		_
Ds	surface diffusion coefficient of the substrate within the adsorbent particle	$9.12 \cdot 10^{-9}$	$cm^2/s$
s	symmetry of a particle, 0 - slab, 1 - cylinder, 2 - sphere	2	-
$\rho_a$	density of adsorbent particle	$7 \cdot 10^{2}$	$mg/cm^3$
q0	substrate concentration in adsorbent in equilibrium with the initial adsor-	$(S_0)^n$	mg/mg
	ber influent concentration $S_0$		
$\epsilon$	adsorber bed porosity	0.7	_
$S_0$	Initial substrate concentration	0.11	$mg/cm^3$

Initial and boundary conditions

$$q(x_i, r_j, t_1) = 0 \qquad \frac{\partial q(x, r, t)}{\partial r} \Big|_{s=0}^{(i, 1, k)} = 0 \qquad q(x_i, r_M, t_k) = S_s(x_i, t_k)^n$$

$$(7)$$

Simplify and make expansion in (i, j, k) point

$$\frac{\partial q(x,r,t)}{\partial t} \Big|_{s=0}^{(i,j,k)} = E_d \frac{s}{r} \cdot \frac{\partial q(x,r,t)}{\partial r} \Big|_{s=0}^{(i,j,k)} + E_d \left. \frac{\partial^2 q(x,r,t)}{\partial r^2} \right|_{s=0}^{(i,j,k)}$$
(8)

Lagrange polynomial approximation

$$q(x,r,t) = \sum_{m=1}^{M} \prod_{p=1}^{M} \frac{r - r_p}{r_m - r_p} \cdot q(x,r_m,t) = \sum_{m=1}^{M} l_m(r) \cdot q(x,r_m,t)$$
(9)

$$\frac{\partial q(x,r,t)}{\partial r} \Big|_{i,j,k}^{(i,j,k)} = \sum_{m=1}^{M} l'_{m}(r) \cdot q(x,r_{m},t) \Big|_{i,j,k}^{(i,j,k)} = \sum_{m=1}^{M} A_{jm} \cdot q(x_{i},r_{m},t_{k}) \tag{10}$$

$$\frac{\partial^2 q(x,r,t)}{\partial r^2} \Big|_{(i,j,k)}^{(i,j,k)} = \sum_{m=1}^M l_m''(r) \cdot q(x,r_m,t) \Big|_{(i,j,k)}^{(i,j,k)} = \sum_{m=1}^M B_{jm} \cdot q(x_i,r_m,t_k) \tag{11}$$

$$\left. \frac{\partial q(x,r,t)}{\partial t} \right|^{(i,j,k)} = \frac{q(x_i,r_j,t_k) - q(x_i,r_j,t_{k-1})}{\tau} \tag{12}$$

Insert (10), (11), (12) into (8)

$$\frac{q(x_i, r_j, t_k) - q(x_i, r_j, t_{k-1})}{\tau} = E_d \frac{s}{r_j} \cdot \sum_{m=1}^M A_{jm} \cdot q(x_i, r_m, t_k) + E_d \sum_{m=1}^M B_{jm} \cdot q(x_i, r_m, t_k)$$
(13)

$$\tau E_d \sum_{m=1}^{M} \left( \frac{s}{r_j} A_{jm} + B_{jm} \right) q(x_i, r_m, t_k) - q(x_i, r_j, t_k) + q(x_i, r_j, t_{k-1}) = 0$$
(14)

Upper boundary equation

$$q(x_i, r_M, t_k) = S_s(x_i, t_k)^n, r_M = 1$$
 (15)

Inserting equation (15) into (14) we will get

$$\tau E_d \sum_{m=1}^{M-1} \left( \frac{s}{r_j} \cdot A_{jm} + B_{jm} \right) q(x_i, r_m, t_k) + \tau E_d \left( s A_{jM} + B_{jM} \right) S_s(x_i, t_k)^n - q(x_i, r_j, t_k) + q(x_i, r_j, t_{k-1}) = 0$$
(16)

for each slice of column  $x_i \in [x_1, x_2..., x_i, ..., x_{H-1}]$  (roots of Legendre polynomial of H-1 degree) for each time layer  $t_i \in [t_2, t_3, ..., t_k, ..., t_N]$ , where  $t_k = \tau * (k-1)$ 

for each radial layer  $r_j \in [r_2..., r_j, ..., r_{M-1}]$  (roots of Legendre polynomial of M-2 degree) we use (16) for  $t_1$  we have already known q from initial conditions  $q(x_i, r_j, t_1) = 0$ 

The last equation are added from lower boundary condition

$$\frac{\partial q(x,r,t)}{\partial r}\Big|^{(i,1,k)} = \frac{q(x_i, r_2, t_k) - q(x_i, r_1, t_k)}{r_2 - r_1} = 0 \quad \Rightarrow \quad q(x_i, r_2, t_k) - q(x_i, r_1, t_k) = 0 \quad (17)$$

Depends on  $S_s(x,t)$ .

### 3 Adsorbent phase material balance

$$\frac{\partial}{\partial t} \int_0^R q(x, r, t) 4\pi r^2 dr = \frac{k_f A_p R^3}{3V_c \rho} (S(x, t) - S_{fs}(x, t)) - \frac{R^2 k X_f}{\rho Y} L_f(x, t) \frac{S_{f,av}(x, t)}{k_s + S_{f,av}(x, t)}$$
(18)

where

$$S_{f,av}(x,t) = \frac{1}{M} \sum_{j=1}^{M} S_f(x,r_j,t)$$
(19)

Let's introduce new function

$$S_{av}(x,t) = \frac{S_{f,av}(x,t)}{k_s + S_{f,av}(x,t)} = \frac{\frac{1}{M} \sum_{j=1}^{M} S_f(x,u_j,t)}{k_s + \frac{1}{M} \sum_{j=1}^{M} S_f(x,u_j,t)} = \frac{S_s(x,t) + \sum_{j=2}^{M-1} S_f(x,u_j,t) + S_{fs}(x,t)}{Mk_s + S_s(x,t) + \sum_{j=2}^{M-1} S_f(x,u_j,t) + S_{fs}(x,t)}$$
(20)

Dimensionless form:

$$S_{av}(x,t) = \frac{S_{f,av}(x,t)}{k_s/S_0 + S_{f,av}(x,t)}$$
(21)

Then material balance equation will look like

$$\frac{\partial}{\partial t} \int_0^R q(x, r, t) 4\pi r^2 dr = \frac{k_f A_p R^3}{3V_c \rho} (S(x, t) - S_{fs}(x, t)) - \frac{R^2 k X_f}{\rho Y} L_f(x, t) S_{av}(x, t)$$
(22)

Dimensionless form:

$$\frac{\partial}{\partial t} \int_{0}^{1} q(x, r, t) r^{2} dr = \frac{T D_{g} A_{p} k_{f} S_{0}}{12\pi V_{c} \rho} (S(x, t) - S_{f}(x, t)) - \frac{T D_{g} k X_{f} L_{max}}{4R\pi \rho Y} L_{f}(x, t) S_{av}(x, t)$$
(23)

I got another result than in the paper. You can use any result that you like.

$$K_{1} = \frac{TD_{g}A_{p}k_{f}S_{0}}{12\pi V_{c}\rho} \quad K_{2} = \frac{TD_{g}kX_{f}L_{max}}{4R\pi\rho Y}$$
 (24)

We get the equation

$$\frac{\partial}{\partial t} \int_{0}^{1} q(x, r, t) r^{2} dr = K_{1}(S(x, t) - S_{f}(x, t)) - K_{2} L_{f}(x, t) S_{av}(x, t)$$
(25)

Depends on  $L_f$ ,  $S_f$ , S

As we use Legandre polynomials with weight function  $W(x) = r^{\alpha}(1-r)^{\beta}$ , with  $\alpha = 0$  and  $\beta = 2$  we get  $W(x) = r^2$ , that is why in (i, j, k) we get

$$\frac{\partial}{\partial t} \int_0^1 q(x_i, r, t) r^2 dr = \frac{\partial}{\partial t} \sum_{m=1}^M W_m q(x_i, r_m, t) = \sum_{m=1}^M W_m \frac{\partial q(x_i, r_m, t)}{\partial t} = \sum_{m=1}^M W_m \frac{q(x_i, r_m, t_k) - q(x_i, r_m, t_{k-1})}{\tau}$$
(26)

All together in (i, j, k) we get

$$\sum_{m=1}^{M} W_m \cdot \frac{q(x_i, r_m, t_k) - q(x_i, r_m, t_{k-1})}{\tau} = K_1 S(x_i, t_k) - K_1 S_f(x_i, t_k) - K_2 L_f(x_i, t_k) S_{av}(x_i, t_k)$$
(27)

$$\frac{1}{\tau} \sum_{m=1}^{M} W_m[q(x_i, r_m, t_k) - q(x_i, r_m, t_{k-1})] - K_1 S(x_i, t_k) + K_1 S_f(x_i, t_k) + K_2 L_f(x_i, t_k) S_{av}(x_i, t_k) = 0 \quad (28)$$

#### 4 Liquid phase material balance

$$\frac{\partial S(x,t)}{\partial t} = D \frac{\partial^2 S(x,t)}{\partial x^2} - V_x \frac{\partial S(x,t)}{\partial x} - \frac{3k_f (R + L_f(x,t))^2 (1 - \epsilon)}{R^3 \epsilon} (S(x,t) - S_{fs}(x,t))$$
(29)

$$\frac{\partial S(x,t)}{\partial t} = D \cdot \frac{\partial^2 S(x,t)}{\partial x^2} - n_t D_g \frac{\partial S(x,t)}{\partial x} - D_g St (1 + B_0 L_{max})^2 (S(x,t) - S_{fs}(x,t))$$
(30)

Initial and boundary conditions

$$S(x,t_1) = 0 S(x_1,t) = 1 \frac{\partial S(x_H,t)}{\partial x} = 0 (31)$$

Depends on  $S_{fs}(x,t)$ 

Let  $D_1 = D_g St(1 + B_0 L_{max})^2$  and use extension in (i, k)

$$\frac{\partial S(x,t)}{\partial t} \Big|^{(i,k)} = D \cdot \frac{\partial^2 S(x,t)}{\partial x^2} \Big|^{(i,k)} - n_t D_g \frac{\partial S(x,t)}{\partial x} \Big|^{(i,k)} - D_1(S(x_i,t_k) - S_{fs}(x_i,t_k)) \tag{32}$$

Using for (32) the same Lagrange polynomial expansion (11) and finite difference scheme (12) as for kinetic equation (8) we get:

$$\frac{S(x_i, t_k) - S(x_i, t_{k-1})}{\tau} = D \sum_{m=1}^{M} B_{im} \cdot S(x_m, t_k) - n_t D_g \sum_{m=1}^{M} A_{im} \cdot S(x_m, t_k) - D_1(S(x_i, t_k) - S_{fs}(x_i, t_k))$$
(33)

$$\tau D \sum_{m=2}^{M} B_{im} \cdot S(x_m, t_k) + \tau D B_{i1} S(x_1, t_k) - \tau n_t D_g \sum_{m=2}^{M} A_{im} \cdot S(x_m, t_k) - \tau n_t D_g A_{i1} S(x_1, t_k) - \tau D_1 (S(x_i, t_k) - S_{fs}(x_i, t_k)) = S(x_i, t_k) - S(x_i, t_{k-1}) \quad (34)$$

With lower boundary conditions (31) and remember  $D = D_k D_g$  we get

$$(1+\tau D_1)S(x_i,t_k) - \tau D_g \sum_{m=2}^{M} (D_k B_{im} - n_t A_{im})S(x_m,t_k) - \tau D_1 S_{fs}(x_i,t_k) = \tau D B_{i1} - \tau D_g n_t A_{i1} + S(x_i,t_{k-1})$$

for each time layer  $t_i \in [t_2, t_3, ..., t_k, ..., t_N]$ , where  $t_k = \tau * (k-1)$  for each slice of column  $x_i \in [x_2, x_3..., x_i, ..., x_{H-1}]$  (roots of Legendre polynomial of H-2 degree) we use (35), for  $t_1$  we have already known  $S(t_1, x)$  from initial conditions  $S(t_1, x) = 0$  The last equation are added from upper boundary condition (31)

$$\frac{\partial S(x,t)}{\partial x} \Big|^{(i,k)} = \frac{S(x_i, t_k) - S(x_{i+1}, t_k)}{x_2 - x_1} = 0 \quad \Rightarrow \quad S(x_i, t_k) - S(x_{i+1}, t_k) = 0$$
 (36)

## 5 Biofilm equations of diffusion and biodegradation

diffusion and biodegradation

$$\frac{\partial}{\partial t}S_f(x,r,t) = D_f \frac{\partial^2}{\partial r^2}S_f(x,r,t) - \frac{kXS_f(x,r,t)}{Y(ks + S_f(x,r,t))}$$
(37)

We use in model simpler version for stationary conditions

$$D_f \frac{\partial^2}{\partial r^2} S_f(x, r, t) - \frac{kX S_f(x, r, t)}{Y(ks + S_f(x, r, t))} = 0$$

$$(38)$$

Boundary condition for  $S_f$ 

$$S_f(x, r = R, t) = S_s(x, t)$$
  $S_f(x, r = R + L_f(x, t), t) = S_{fs}(x, t)$  (39)

 $S_f$  defines only on interval  $(R, R + L_f(x, t))$  and q only on the interval (0, 1). For me it is seems more logical totally separate this variables, introducing a new variable on the interval (0, 1). That will make possible to use orthogonal collocation and normalize result. The linear transformation  $u = \frac{(r-R)}{L_f(x,t)}$  maps the interval  $(R, R + L_f(x, t))$  to the interval (0, 1), replace r with u using  $r = R + uL_f(x, t)$  we get Using dimensionless variables we get

$$\frac{\partial^2 S_f(x, u, t)}{\partial u^2} = \frac{kX L_f^2(x, t) S_f(x, u, t)}{Y D_f(ks + S_f(x, u, t))}$$
(40)

Boundary condition for  $S_f$ 

$$S_f(x, u = 0, t) = S_s(x, t)$$
  $S_f(x, u = 1, t) = S_{fs}(x, t)$  (41)

Use dimensionless transform we get

$$\frac{\partial^2 S_f(x, u, t)}{\partial u^2} = \frac{kX L_{max}^2 L_f^2(x, t) S_f(x, u, t)}{Y D_f(ks/S_0 + S_f(x, u, t))}$$
(42)

To be consistent with paper, substitute  $A_2 = \frac{kXL_{max}^2}{YD_f}$  and  $B_1 = ks/S_0$ 

$$\frac{\partial^2 S_f(x, u, t)}{\partial u^2} = A_2 \frac{L_f^2(x, t) S_f(x, u, t)}{B_1 + S_f(x, u, t)} \tag{43}$$

**Depends on**  $S_s(x,t)$  and  $S_{fs}(x,t)$ 

Let's for u the collocation discretization be the same as for r, and we will use the same notation just for convenience. Using (11) and expansion in (i, j, k) we get

$$\sum_{m=1}^{M} B_{jm} \cdot S_f(x_i, u_m, t_k) = B_{j1} S_s(x_i, t_k) + \sum_{m=2}^{M-1} B_{jm} S_f(x_i, u_m, t_k) + B_{jM} S_{fs}(x_i, t_k)$$
(44)

$$B_{j1}S_s(x_i,t) + \sum_{m=2}^{M-1} B_{jm}S_f(x_i, u_m, t_k) + B_{jM}S_{fs}(x_i, t_k) = A_2 \frac{L_f^2(x_i, t_j)S_f(x_i, u_j, t_k)}{B_1 + S_f(x_i, u_j, t_k)}$$
(45)

#### 6 Biofilm equations of grows and decay

$$\frac{\partial L_f(x,t)}{\partial t} = k \frac{S_{f,av}(x,t)}{ks + S_{f,av}(x,t)} - k_d L_f(x,t) = k S_{av}(x,t) - k_d L_f(x,t)$$

$$\tag{46}$$

Initial and boundary conditions

$$L_f(x, t_1) = L_{f0} L_f(x, t_N) = L_{max} (47)$$

Dimensionless form of that below, where  $A_3 = kT$ 

$$\frac{\partial L_f(x,t)}{\partial t} = D_g A_3 \frac{S_{f,av}(x,t)}{B_1 + S_{f,av}(x,t)} - D_g A_3 L_f(x,t) = D_g A_3 S_{av}(x,t) - D_g A_3 L_f(x,t)$$
(48)

where  $S_{av}(x,t) = \frac{S_{f,av}(x,t)}{B_1 + S_{f,av}(x,t)}$  and  $B_1 = k_s/S_0$  substitute (20) to (48) and make expansion in (i,k) we get

$$\frac{L_f(x_i, t_k) - L_f(x_i, t_{k-1})}{\tau} = D_g A_3 S_{av}(x_i, t_k) - D_g A_3 L_f(x_i, t_k)$$
(49)

Finally, we get

$$L_f(x_i, t_k) - \tau D_q A_3 S_{av}(x_i, t_k) + \tau D_q A_3 L_f(x_i, t_k) = L_f(x_i, t_{k-1})$$
(50)

Initial and boundary conditions

$$L_f(x, t_1) = \frac{L_{f0}}{L_{max}}$$
  $L_f(x, t_N) = 1$  (51)

### 7 all together

Initial conditions

$$L_f(x,t_1) = L_{f0}/L_{max} \quad L_f(x,t_N) = 1 \quad q(x,r,t_1) = 0$$
  

$$S_s(x,t_1) = 0, \quad S_f(x,r,t_1) = 0, \quad S_{fs}(x,t_1) = 0, \quad S(x,t_1) = 0$$
(52)

Boundary conditions

$$\frac{\partial q(x,r,t)}{\partial r}\Big|_{s=0}^{(i,1,k)} = 0 \qquad q(x_i, r_M, t_k) = S_s(x_i, t_k)^n$$

$$S(x_1,t) = 1 \qquad \frac{\partial S(x,t)}{\partial x}\Big|_{s=0}^{(H,j,k)} = 0$$

$$S_f(x, u_1, t) = S_s(x, t) \qquad S_f(x, u_M, t) = S_{fs}(x, t)$$
(53)

For each time step  $t = [t_2, t_3, ..., t_N]$ . Do not forget that on  $t_N$  the  $L_f(x, t) = L_{fmax}$ , so it is already known. for each slice of column  $x_i \in [x_1, x_2, ..., x_i, ..., x_H]$  and for each radial layer  $r_j \in [r_2, ..., r_j, ..., r_{M-1}]$  and for  $u_j \in [u_2, ..., u_j, ..., u_{M-1}]$  we have discretization. So it's big non linear equation and we need to solve it. Just do it, man!

For  $x_1$  due to boundary conditions we get simpler system, so  $S(x_1,t)=1$  and  $S_{fs}(x_1,t)=1$  are already known. We get:

$$\tau E_d \sum_{m=1}^{M-1} \left( \frac{s}{r_j} \cdot A_{jm} + B_{jm} \right) q(x_1, r_m, t_k) + \tau E_d \left( s A_{jM} + B_{jM} \right) S_s(x_i, t_k)^n - q(x_1, r_j, t_k) + q(x_1, r_j, t_{k-1}) = 0$$
(54)

$$\sum_{m=1}^{M} W_m \cdot q(x_1, r_m, t_k) - \tau D_1 D_g L_f(x_1, t_k) S_{av}(x_1, t_k) = \tau D_1 + \sum_{m=1}^{M} W_m \cdot q(x_1, r_m, t_{k-1})$$
(55)

$$L_f(x_1, t_k) - \tau D_g A_3 S_{av}(x_1, t_k) + \tau D_g A_3 L_f(x_1, t_k) = L_f(x_i, t_{k-1})$$
(56)

$$\left(B_{j1}S_s(x_1, t_k) + \sum_{m=2}^{M-1} B_{jm}S_f(x_1, u_m, t_k) + B_{jM}\right) - A_2 \frac{L_f^2(x_1, t_k)S_f(x_1, u_j, t_k)}{B_1 + S_f(x_1, u_j, t_k)} = 0$$
(57)

$$S_{av}(x_1, t_k) = \frac{S_s(x_1, t_k) + \sum_{j=2}^{M-1} S_f(x_1, u_j, t_k) + 1}{MB_1 + S_s(x_1, t_k) + \sum_{j=2}^{M-1} S_f(x_1, u_j, t_k) + 1}$$
(58)

We can found out extra boundary conditions

$$S_{fs}(x_1, t) = 1 (59)$$