SEMESTER 8

ELECTRICAL AND COMPUTER ENGINEERING

SEMESTER S8

SMART GRID TECHNOLOGIES

Course Code	PEEET861	CIE Marks	40
Teaching Hours/Week (L: T:P: R)	3:0:0:0	ESE Marks	60
Credits	3	Exam Hours	2 Hrs. 30 Min.
Prerequisites (if any)	None/ (Course code)	Course Type	PE - Theory

Course Objectives:

1. To introduce various advancements in the area of smart grid.
2. To introduce distributed energy resources and micro-grid.
3. To introduce cloud computing, cyber security and power quality issues in smart grids.

SYLLABUS

Module No.	Syllabus Description	Contact Hours
1	**Introduction to Smart Grid:** Evolution of electric grid, Definitions, Need for smart grid, Smart grid drivers, Functions of smart grid, Opportunities and barriers of smart grid, Difference between conventional grid and smart grid, Concept of resilient and self- healing grid. Components and architecture, Inter-operability, Impacts of smart grid on system reliability, Present development and international policies in smart grid, Smart grid standards. **Information and Communication Technology in Smart Grid:** Wired and wireless communication -radio mesh, ZIGBEE, 3G, 4G and 5G. Digital PLC, DSL, Wi-Max, LAN, NAN, HAN, Wi-Fi, Bluetooth, Bluetooth Low Energy (BLE), Li-Fi. Communication Protocols in Smart grid, Introduction to IEC 61850 standard and benefits, IEC Generic Object-Oriented Substation Event - GOOSE, Substation model.	9
2	**Smart grid Technologies Part I:** Introduction to smart meters, Electricity tariff, Real Time Pricing- Automatic Meter Reading (AMR) - System, Services and Functions, Components of AMR Systems, Advanced Metering Infrastructure (AMI). Plug in Hybrid Electric Vehicles (PHEV), Vehicle to Grid (V2G), Grid to Vehicle (G2V), Smart Sensors, Smart energy efficient end use devices, Home & Building Automation. Intelligent Electronic	9

	Devices (IED) and their application for monitoring & protection: Digital Fault Recorder (DFR), Digital Protective Relay (DPR), Circuit Breaker Monitor (CBM), Phasor Measurement Unit (PMU), Standards for PMU. Time synchronization techniques, Wide Area Monitoring System (WAMS), control and protection systems (Architecture, components of WAMS, and applications: Voltage stability assessment, frequency stability assessment, power oscillation assessment, communication needs of WAMS, remedial action scheme).	
3	**Smart grid Technologies Part II:** Smart substations, Substation automation, Feeder automation, Fault detection, Isolation, and Service Restoration (FDISR), Geographic Information System (GIS), Outage Management System (OMS). Introduction to Smart distributed energy resources and their grid integration, Smart inverters, Concepts of microgrid, Need and application of microgrid – Energy Management- Role of technology in demand response- Demand side management, Demand side Ancillary Services, Dynamic line rating.	**9**
4	**Cloud computing in smart grid:** Private, Public and hybrid cloud. Types of cloud computing services- Software as a Service (SaaS), Platform as a service (PaaS), Infrastructure as a service (IaaS), Data as a service (DaaS), Cloud architecture for smart grid. **Cyber Security** - Cyber security challenges and solutions in smart grid, Cyber security risk assessment, Security index computation. **Power Quality Management in Smart Grid**- Fundamentals, Power Quality (PQ) & Electromagnetic Compatibility (EMC) in smart grid, Power quality conditioners for smart grid. Case study of smart grid.	**9**

Course Assessment Method
(CIE: 40 marks, ESE: 60 marks)

Continuous Internal Evaluation Marks (CIE):

Attendance	Assignment/ Microproject	Internal Examination-1 (Written)	Internal Examination- 2 (Written)	Total
5	**15**	**10**	**10**	**40**

End Semester Examination Marks (ESE)

In Part A, all questions need to be answered and in Part B, each student can choose any one full question out of two questions

Part A	Part B	Total
• 2 Questions from each module. • Total of 8 Questions, each carrying 3 marks **(8x3 =24marks)**	• Each question carries 9 marks. • Two questions will be given from each module, out of which 1 question should be answered. • Each question can have a maximum of 3 sub divisions. **(4x9 = 36 marks)**	**60**

Course Outcomes (COs)

At the end of the course students should be able to:

Course Outcome		Bloom's Knowledge Level (KL)
CO1	Explain the basic concept of distributed energy resources, micro-grid and smart grid	**K2**
CO2	Choose appropriate Information and Communication Technology (ICT) in smart grid	**K2**
CO3	Select infrastructure and technologies for consumer domain of smart grid	**K2**
CO4	Select infrastructure and technologies for smart substation and distribution automation	**K2**
CO5	Formulate cloud computing infrastructure for smart grid considering cyber security	**K3**
CO6	Categorize power quality issues and appraise it in smart grid context	**K2**

Note*: K1- Remember, K2- Understand, K3- Apply, K4- Analyse, K5- Evaluate, K6- Create*

CO-PO Mapping Table (Mapping of Course Outcomes to Program Outcomes)

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12
CO1	3	2										
CO2	3	3	3	3	2							
CO3	3	3	3	3	2							
CO4	3	3	3	3								
CO5	3	3	3	3	3							
CO6	3	3	3	3	3							

Note: *1: Slight (Low), 2: Moderate (Medium), 3: Substantial (High), -: No Correlation*

Text Books				
Sl. No	**Title of the Book**	**Name of the Author/s**	**Name of the Publisher**	**Edition and Year**
1	Smart Grid Infrastructure Technology and Solutions	Stuart Borlase	CRC Press	2nd edition
2	Smart Grid: Fundamentals of Design and Analysis	James Momoh	Wiley	2012
3	Microgrids and Active Distribution Networks	S. Chowdhury	Institution of Engineering and Technology	2009
4	Smart Grids Technology and Applications	Janaka Ekanayake, Kythira Liyanage, Jianzhong Wu, Akihiko Yokohama, Nick Jenkins-	Wiley	2012
5	Smart Grids Technology and Applications	Janaka Ekanayake, Kythira Liyanage, Jianzhong Wu, Akihiko Yokohama, Nick Jenkins	Wiley	2012
6	Cybersecurity for the Electric Smart Grid: Elements and Considerations	Barker, Preston, Price, Rudy F	Nova Science Publishers Inc	2012

SEMESTER S8

HVDC AND FACTS

Course Code	PEEET862	CIE Marks	40
Teaching Hours/Week (L: T:P: R)	3:0:0:0	ESE Marks	60
Credits	3	Exam Hours	2 Hrs. 30 Min.
Prerequisites (if any)	PCEET403	Course Type	PE - Theory

Course Objectives:

1. To introduce HVDC concepts and analysis of HVDC systems.
2. To provide a detailed study of FACTS devices.

SYLLABUS

Module No.	Syllabus Description	Contact Hours
1	**Introduction to HVDC System:** Comparison of AC and DC Transmission - Types of HVDC system - Current Source Converters - Analysis without and with overlap period. Voltage Source Converters (VSC) - VSC with AC current control and VSC with AC voltage control **HVDC Controls** - Functions of HVDC Controls - Equivalent circuit for a two terminal DC Link - Control Basics for a two terminal DC Link - Current Margin Control Method - Current Control at the Rectifier - Inverter Extinction Angle Control - Hierarchy of Controls	9
2	**Introduction to FACTS:** Power flow in Power Systems – Voltage regulation and reactive power flow control in Power Systems - Power flow control -Constraints of maximum transmission line loading - Needs and emergence of FACTS - Types of FACTS controllers-Advantages and disadvantages Transmission line compensation- Uncompensated line -shunt compensation - Series compensation -Phase angle control.	9
3	**Shunt and Series Facts Devices:** Static shunt Compensator - Objectives of shunt compensations - Variable impedance type VAR Generators -TCR, TSR, TSC, FC-TCR (Principle of operation and schematic) and - STATCOM (Principle of operation and schematic). Static Series compensator - Objectives of series compensations-Variable impedance type series compen-	9

	sators - GCSC. TCSC, TSSC (Principle of operation and schematic) Switching converter type Series Compensators-(SSSC) (Principle of operation and schematic)	
4	**UPFC AND IPFC:** Unified Power Flow Controller: Circuit Arrangement, Operation of UPFC- Basic principle of P and Q control- independent real and reactive power flow control- Applications Introduction to interline power flow controller (IPFC) (Principle of operation and schematic) Thyristor controlled Voltage and Phase angle Regulators (Principle of operation and schematic)	**9**

Course Assessment Method
(CIE: 40 marks, ESE: 60 marks)

Continuous Internal Evaluation Marks (CIE):

Attendance	Assignment/ Microproject	Internal Examination-1 (Written)	Internal Examination- 2 (Written)	Total
5	**15**	**10**	**10**	**40**

End Semester Examination Marks (ESE)

In Part A, all questions need to be answered and in Part B, each student can choose any one full question out of two questions

Part A	Part B	Total
• 2 Questions from each module. • Total of 8 Questions, each carrying 3 marks **(8x3 =24marks)**	• Each question carries 9 marks. • Two questions will be given from each module, out of which 1 question should be answered. • Each question can have a maximum of 3 sub divisions. **(4x9 = 36 marks)**	**60**

Course Outcomes (COs)

At the end of the course students should be able to:

Course Outcome		Bloom's Knowledge Level (KL)
CO1	Analyse current source and voltage source converters for HVDC systems	**K4**
CO2	Describe the control schemes for HVDC systems	**K2**
CO3	Explain the need for FACTS devices	**K2**
CO4	Classify reactive power compensators in power system	**K2**
CO5	Interpret series and shunt connected FACTS devices for power system applications	**K2**
CO6	Explain the dynamic interconnection mechanisms of FACTS devices	**K2**

Note*: K1- Remember, K2- Understand, K3- Apply, K4- Analyse, K5- Evaluate, K6- Create*

CO-PO Mapping Table (Mapping of Course Outcomes to Program Outcomes)

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12
CO1	3	3			2							
CO2	3	3			2							
CO3	3	3			2							
CO4	3	3			2							
CO5	3	3			2							
CO6	3	3			2							

Note: *1: Slight (Low), 2: Moderate (Medium), 3: Substantial (High), -: No Correlation*

Text Books				
Sl. No	**Title of the Book**	**Name of the Author/s**	**Name of the Publisher**	**Edition and Year**
1	HVDC and FACTS Controllers	Vijay K Sood	Springer	2004
2	Understanding FACTS	N.G. Hingorani and L.Gyugyi	IEEE Press	2000
3	High Voltage DC Transmission	K.R.Padiyar	Wiley	1993
4	FACTS Controllers in Power Transmission and distribution	K.R.Padiyar	New age international Publishers	2007
5	Flexible AC Transmission systems (FACTS)	Y.H. Song and A.T.Jones	IEEE Press	1999
6	Reactive Power control in Power systems	T.J.E. Miller	John Wiley	1982

SEMESTER S8

MECHATRONIC SYSTEMS

Course Code	PEEET863	CIE Marks	40
Teaching Hours/Week (L: T:P: R)	3:0:0:0	ESE Marks	60
Credits	3	Exam Hours	2 Hrs. 30 Min.
Prerequisites (if any)	None/ (Course code)	Course Type	PE - Theory

Course Objectives:

1. To familiarise mechatronic systems with fundamental knowledge in sensors and actuators achieve conceptual understanding of mechatronic systems
2. To enhance the fundamental knowledge in microprocessors and microcontrollers
3. To learn the fundamentals of system models and controllers
4. To understand control actions such as Proportional, derivative and integral and study its significance in industrial applications

SYLLABUS

Module No.	Syllabus Description	Contact Hours
1	Introduction to Mechatronics: Introduction, Examples of Mechatronic systems, Electric circuits and components, Semiconductor Electronics, Transistor Applications Sensors and transducers: Performance terminology of sensors, Displacement, Position & Proximity Sensors-I, Displacement, Position & Proximity Sensors-II, Force, Fluid pressure, Liquid flow sensors, temperature, light sensor, Acceleration and Vibration measurement, Semiconductor sensor and MEMS, SAW	9
2	Actuators and mechanisms: Mechanical Actuation System, Hydraulic & Pneumatic Actuation System, Electrical Actuation System-I, Electrical Actuation System-II, Data Presentation system Signal conditioning: Introduction to signal processing & Op-Amp, Op-Amp as signal conditioner, Analogue to Digital Converter, Digital to Analogue Converter, Artificial intelligence	10
3	Microprocessors and microcontrollers: Digital circuits-I, Digital circuits-II,	

	Microprocessor Micro Controller, Programming of Microcontrollers Modeling and system response: Mechanical system model, Electrical system model, Fluid system model, Dynamic response of systems, Transfer function and frequency response.	**10**
4	Closed loop controllers: P, I, PID Controllers, Digital Controllers, Program Logic Controllers, Input/output & Communication systems, Fault findings Mechatronics designs, examples and case studies	**7**

Course Assessment Method
(CIE: 40 marks, ESE: 60 marks)

Continuous Internal Evaluation Marks (CIE):

Attendance	Assignment/ Microproject	Internal Examination-1 (Written)	Internal Examination- 2 (Written)	Total
5	**15**	**10**	**10**	**40**

End Semester Examination Marks (ESE)

In Part A, all questions need to be answered and in Part B, each student can choose any one full question out of two questions

Part A	Part B	Total
• 2 Questions from each module. • Total of 8 Questions, each carrying 3 marks **(8x3 =24marks)**	• Each question carries 9 marks. • Two questions will be given from each module, out of which 1 question should be answered. • Each question can have a maximum of 3 sub divisions. **(4x9 = 36 marks)**	**60**

Course Outcomes (COs)

At the end of the course students should be able to:

Course Outcome		Bloom's Knowledge Level (KL)
CO1	Comprehend the importance of sensors and actuators with application to mechatronic systems	**K2**
CO2	Identify actuator mechanisms and signal conditioning processes	**K2**
CO3	Select microprocessors and microcontrollers for the implementation in mechatronic system	**K2**
CO4	Analyse the models and responses of different systems	**K3**

Note*: K1- Remember, K2- Understand, K3- Apply, K4- Analyse, K5- Evaluate, K6- Create*

CO-PO Mapping Table (Mapping of Course Outcomes to Program Outcomes)

	PO1	**PO2**	**PO3**	**PO4**	**PO5**	**PO6**	**PO7**	**PO8**	**PO9**	**PO10**	**PO11**	**PO12**
CO1	3					1						1
CO2	3					1						1
CO3	3					1						1
CO4	3	3	3	2	3	2					2	2

Note: *1: Slight (Low), 2: Moderate (Medium), 3: Substantial (High), -: No Correlation*

Text Books				
Sl. No	**Title of the Book**	**Name of the Author/s**	**Name of the Publisher**	**Edition and Year**
1	Mechatronics: Electronic Control Systems in Mechanical and Electrical Engineering	W. Bolton	Pearson Education	4th Edition 2010
2	Introduction to Mechatronics and Measurement Systems	Michael B. Histand, David G. Alciatore	McGraw-Hill Series in Mechanical Engineering	2003
3	Mechatronics system design. CL-Engineering	Shetty, Devdas, and Richard A. Kolk.		2010.
4	Mechatronics: an introduction.,	Bishop, Robert H.	CRC Press	2017.
5	Intelligent Mechatronic Systems: Modeling, Control and Diagnosis	R. Merzouki, A. K. Samantaray, P. M. Pathak, B. Ould Bouamama	Springer, London	2003

Video Links (NPTEL, SWAYAM…)	
Module No.	**Link ID**
1	https://archive.nptel.ac.in/courses/112/107/112107298/
2	https://archive.nptel.ac.in/courses/112/107/112107298/
3	https://archive.nptel.ac.in/courses/112/107/112107298/
4	https://archive.nptel.ac.in/courses/112/107/112107298/

SEMESTER S8

ELECTRONIC COMMUNICATION

Course Code	PEEET864	CIE Marks	40
Teaching Hours/Week (L: T:P: R)	3:0:0:0	ESE Marks	60
Credits	3	Exam Hours	2 Hrs. 30 Min.
Prerequisites (if any)	GYEST104, PBEET304	Course Type	PE - Theory

Course Objectives:

1. To acquire knowledge about analog and digital communication systems

SYLLABUS

Module No.	Syllabus Description	Contact Hours
1	**Analog Communication:** Introduction to communication systems, Classification of channels, Need for modulation. Amplitude modulation: Equation and frequency spectrum of AM signal, Double-side band suppressed carrier (DSB-SC) modulation, Single sideband modulation (SSB), comparison of spectrum, power and efficiency of all the three variants, Amplitude modulator circuits -balanced modulator, AM demodulators – Envelope detector.	9
2	**Angle Modulation:** Frequency and phase modulation, Narrow and wide band FM and their spectra, Modulation and demodulation techniques for FM, pre-emphasis and de-emphasis, FM transmitter and receiver, Noise in receivers, Noise figures, Performance of analog modulation schemes in AWGN: SNR and figure of merit for different schemes.	9
3	**Digital baseband communication:** Elements of digital communication system. Sources, channels and receivers, Sampling and Reconstruction of Analog Signals: Nyquist Sampling Theorem, Ideal Reconstruction Filter, Pulse Amplitude Modulation (PAM), Time division multiplexing with PAM, Pulse Code Modulation (PCM), A-law and mu-law quantization.	9
4	**Digital bandpass communication**: Digital bandpass communication system, Bandpass modulation techniques:	9

	Amplitude shift keying, Phase shift keying, Frequency shift keying, Methods of generation and detection, Signal constellations, M-ary digital modulation schemes, Quadrature phase shift keying, Minimum shift keying, Quadrature amplitude modulation.	

Course Assessment Method
(CIE: 40 marks, ESE: 60 marks)

Continuous Internal Evaluation Marks (CIE):

Attendance	Assignment/ Microproject	Internal Examination-1 (Written)	Internal Examination- 2 (Written)	Total
5	15	10	10	40

End Semester Examination Marks (ESE)

In Part A, all questions need to be answered and in Part B, each student can choose any one full question out of two questions

Part A	Part B	Total
• 2 Questions from each module. • Total of 8 Questions, each carrying 3 marks **(8x3 =24marks)**	• Each question carries 9 marks. • Two questions will be given from each module, out of which 1 question should be answered. • Each question can have a maximum of 3 sub divisions. **(4x9 = 36 marks)**	60

Course Outcomes (COs)

At the end of the course students should be able to:

Course Outcome		Bloom's Knowledge Level (KL)
CO1	Explain the working of Amplitude modulator and demodulator circuits using mathematical relations.	K2
CO2	Explain the characteristics of various analog modulation schemes in terms of spectra, power and efficiency.	K3
CO3	Understand the various processing blocks of a digital communication system.	K2
CO4	Apply the knowledge of digital modulation in digital transmission.	K3

Note*: K1- Remember, K2- Understand, K3- Apply, K4- Analyse, K5- Evaluate, K6- Create*

CO-PO Mapping Table (Mapping of Course Outcomes to Program Outcomes)

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12
CO1	3											
CO2	3	2										
CO3	3											1
CO4	3	2										1

Note: *1: Slight (Low), 2: Moderate (Medium), 3: Substantial (High), -: No Correlation*

Text Books				
Sl. No	**Title of the Book**	**Name of the Author/s**	**Name of the Publisher**	**Edition and Year**
1	Kennedy's Electronic Communication Systems	Kennedy, Davis and Prasanna	Tata McGraw Hill	6th Edition, 2018
2	Electronic Communication Systems – Fundamentals through Advanced	Wayne Tomasi	Pearson	5th edition, 2008
3	Communication Systems	Simon Haykin and Michael Mohre	Wiley	5th Edition,2021
4	Principles of Communication Systems	Taub& Schilling	McGraw-Hill	4th edition, 2017

Reference Books				
Sl. No	**Title of the Book**	**Name of the Author/s**	**Name of the Publisher**	**Edition and Year**
1	Principles of Communications	Rodger E. Ziemer& William H. Tranter	Wiley	7the edition, 2014
2	Communication System Engineering	J. G. Proakis and M. Salehi	Pearson Education	2nd Edition, 2018.
3	Digital and Analog Communication Systems	Leon W. Couch	Prentice Hall	8th edition, 2012
4	Modern Digital and Analog Communication Systems	B. P. Lathi, Zhi Ding	Oxford University Press	4th edition, 2011

SEMESTER S8

INTRODUCTION TO ROBOTICS

Course Code	OEEET831	CIE Marks	40
Teaching Hours/Week (L: T:P: R)	3:0:0:0	ESE Marks	60
Credits	3	Exam Hours	2 Hrs. 30 Min.
Prerequisites (if any)	None/ (Course code)	Course Type	OE - Theory

Course Objectives:

1. To familiarise mechatronic systems with fundamental knowledge in sensors and actuators achieve conceptual understanding of mechatronic systems
2. To enhance the fundamental knowledge in microprocessors and microcontrollers
3. To learn the fundamentals of system models and controllers
4. To understand control actions such as Proportional, derivative and integral and study its significance in industrial applications

SYLLABUS

Module No.	Syllabus Description	Contact Hours
1	**Definitions-** Robots, Robotics; Types of Robots- Manipulators, Mobile Robots-wheeled & Legged Robots, Aerial Robots; Anatomy of a robotic manipulator-links, joints, actuators, sensors, controller; open kinematic vs closed kinematic chain; degrees of freedom; Robot considerations for an application- number of axes, work volume, capacity & speed, stroke &reach, Repeatability, Precision and Accuracy, Operating environment, point to point control or continuous path control	7
2	**Sensors and Actuators** Sensor classification- touch, force, proximity, vision sensors. Internal sensors-Position sensors, velocity sensors, acceleration sensors, Force sensors; External sensors-contact type, noncontact type Actuators for robots- classification-Electric, Hydraulic, Pneumatic actuators; their advantages and disadvantages; Electric actuators- Stepper motors, DC motors, DC servo motors and their drivers, AC motors, Linear actuators, selection of motors **Robotic configurations and end effectors** Robot configurations-PPP, RPP,	10

	RRP, RRR; features of SCARA, PUMA Robots; Classification of robots based on motion control methods and drive technologies; 3R concurrent wrist; Classification of End effectors - mechanical grippers, special tools, Magnetic grippers, Vacuum grippers, adhesive grippers, Active and passive grippers, selection and design considerations of grippers in robot.	
3	**Kinematics and Motion Planning** Robot Coordinate Systems- Fundamental and composite rotations, homogeneous co-ordinates and transformations, Kinematic parameters, D-H representation, Direct Kinematics. The Arm equation- forward Kinematic analysis of a typical robots upto 3 DOF. Motion Planning- joint space trajectory planning-cubic polynomial, linear trajectory with parabolic blends; Cartesian space planning, Point to point vs continuous path planning.	**9**
4	**Dynamics and Control of Robots** Building of a servo controlled robot – 1R two link chain, construction of link and joint and mounting of encoder, actuator, etc. Dynamics- Dynamic model of a robot using Lagrange's equation, dynamic modelling of 1DOF robot, including motor and gearbox, 2R planar manipulator. Control Techniques- Transfer function and state space representation, Performance and stability of feedback control, PID control of a single link manipulator, selection of PID controller gains; nonlinear nature of manipulators, and need for nonlinear control techniques.	**9**

Course Assessment Method
(CIE: 40 marks, ESE: 60 marks)

Continuous Internal Evaluation Marks (CIE):

Attendance	Assignment/ Microproject	Internal Examination-1 (Written)	Internal Examination- 2 (Written)	Total
5	**15**	**10**	**10**	**40**

End Semester Examination Marks (ESE)

In Part A, all questions need to be answered and in Part B, each student can choose any one full question out of two questions

Part A	Part B	Total
• 2 Questions from each module. • Total of 8 Questions, each carrying 3 marks **(8x3 =24marks)**	• Each question carries 9 marks. • Two questions will be given from each module, out of which 1 question should be answered. • Each question can have a maximum of 3 sub divisions. **(4x9 = 36 marks)**	**60**

Course Outcomes (COs)

At the end of the course students should be able to:

Course Outcome		Bloom's Knowledge Level (KL)
CO1	Familiarise with anatomy, specifications and applications of Robots	**K2**
CO2	Choose the appropriate sensors and actuators for robots	**K2**
CO3	Choose appropriate Robotic configuration and gripper for a particular application	**K2**
CO4	Obtain kinematic model of robotic manipulators	**K3**
CO5	Plan trajectories in joint space and Cartesian space	**K3**
CO6	Develop dynamic model and design the controller for robotic manipulators	**K3**

Note*: K1- Remember, K2- Understand, K3- Apply, K4- Analyse, K5- Evaluate, K6- Create*

CO-PO Mapping Table (Mapping of Course Outcomes to Program Outcomes)

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12
CO1	2	1										3
CO2	2	1										3
CO3	2	1										3
CO4	3	2	2									3

Note: *1: Slight (Low), 2: Moderate (Medium), 3: Substantial (High), -: No Correlation*

Text Books				
Sl. No	**Title of the Book**	**Name of the Author/s**	**Name of the Publisher**	**Edition and Year**
1	Introduction to Robotics	S K Saha	McGraw Hill Education (India) Private Limited	2014
2	Fundamentals of robotics – Analysis and control	Robert. J. Schilling	Prentice Hall of India	1996.
3	Robotics and Control	R K Mittal and I J Nagrath	Tata McGraw Hill, New Delhi	2003
4	Introduction to Robotics: Mechanics and control	John. J. Craig	Pearson Education Asia	4th Edition, 2018
5	Robotics-Fundamental concepts and analysis	Ashitava Ghosal	Oxford University press.	2006
6	Robotics Technology and Flexible Automation	S. R. Deb	McGraw-Hill Education LLC	Second Edition,

Video Links (NPTEL, SWAYAM…)	
Module No.	**Link ID**
1	https://archive.nptel.ac.in/courses/107/106/107106090/
2	https://archive.nptel.ac.in/courses/107/106/107106090/
3	https://archive.nptel.ac.in/courses/107/106/107106090/
4	https://archive.nptel.ac.in/courses/107/106/107106090/

SEMESTER S8

PLC AND AUTOMATION

Course Code	OEEET832	CIE Marks	40
Teaching Hours/Week (L: T:P: R)	3:0:1:0	ESE Marks	60
Credits	4	Exam Hours	2 Hrs. 30 Min.
Prerequisites (if any)	None	Course Type	Theory

Course Objectives:

1. Learn the roles, architectures, and interfacing techniques of computer-based measurement and control systems, including HMI and hardware integration.
2. Gain hands-on experience with PLC programming and simulation, and understand the functionalities and interfacing of Distributed Control Systems for process control.

SYLLABUS

Module No.	Syllabus Description	Contact Hours
1	**Introduction to computer based control system** -Role of computers in measurement and (process) control Basic components of computer based measurement and control systems Architecture – computer based process control system –Centralised, Distributed and Hierarchical. Human Machine Interface (HMI) Hardware for computer based process control system, Interfacing computer system with process. Architecture of DDC, SCADA and DCS. **Programmable logic Controller (PLC)**: Introduction, Evolution, Relay VS PLC VS Computer	9
2	PLC- Hardware and Internal Architecture-Input –output devices .Basics of Ladder Programming, on/off instructions, internal relay, jump instructions, data handling instruction, data manipulation instructions, Arithmetic and Comparison ,PID and other important instructions	9
3	Timers and Counters in PLC. Problems. Design Development and Simulation of PLC Programme Program on Temperature control Valve	9

	sequencing, Conveyor belt control and Control of a process. PLC Installation, trouble shooting and maintenance, Design of Alarms and Interlocks, Networks of PLC Distributed Control System- DCS - Evolution– Various Architectures – Comparison – Local control unit	
4	DCS -LCU Languages-Process interfacing issues-communication facilities-Operator interface-Low level and High level Operator interface- Displays - Engineering interfaces – Low level and high level engineering interfaces – Factors to be considered in selecting DCS – Other key issues in DCS – Packaging and Power system issues.	**9**

Course Assessment Method
(CIE: 40 marks, ESE: 60 marks)

Continuous Internal Evaluation Marks (CIE):

Attendance	*Internal Ex*	*Evaluate*	*Analyse*	*Total*
5	**15**	**10**	**10**	**40**

Criteria for Evaluation (Evaluate and Analyse): 20 marks

Micro projects on automation using PLC and DCS for student group comprising of 3 students.
Report – 5 marks
Working Model – 15 Marks

End Semester Examination Marks (ESE):

In Part A, all questions need to be answered and in Part B, each student can choose any one full question out of two questions

Part A	Part B	Total
• 2 Questions from each module. • Total of 8 Questions, each carrying 3 marks **(8x3 =24marks)**	• 2 questions will be given from each module, out of which 1 question should be answered. • Each question can have a maximum of 3 sub divisions. • Each question carries 9 marks. **(4x9 = 36 marks)**	**60**

Course Outcomes (COs)

At the end of the course students should be able to:

Course Outcome		Bloom's Knowledge Level (KL)
CO1	Understand the basic architecture and components of computer-based measurement and control systems.	**K2**
CO2	Understand the human-machine interfaces (HMI) and learn the hardware and interfacing techniques needed to integrate computer systems with process controls.	**K2**
CO3	Create and troubleshoot PLC programs using ladder logic for various applications.	**K5**
CO4	Understand and apply the architecture and interfaces of Distributed Control Systems in various process control settings.	**K2**

Note*: K1- Remember, K2- Understand, K3- Apply, K4- Analyse, K5- Evaluate, K6- Create*

CO-PO Mapping Table (Mapping of Course Outcomes to Program Outcomes)

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12
CO1	3											
CO2	3											
CO3	3				2							
CO4	3											

Note: *1: Slight (Low), 2: Moderate (Medium), 3: Substantial (High), -: No Correlation*

Text Books				
Sl. No	**Title of the Book**	**Name of the Author/s**	**Name of the Publisher**	**Edition and Year**
1	Instrument Engineer's Handbook – Process Control,	B G Liptak	CRC Press	4th edtion
2	Understanding Distributed Processor Systems for Control,	Samel M. Herb	ISA Publication	1st edition 1999
3	Programmable Logic Controllers – Principles and Applications.	John W.Webb & Ronald A. Reiss,	PHI	5th edition
4	Computer Control of Processes,	M. Chidambaram	Alpha Science International Ltd	1st edition 2002

Reference Books				
Sl. No	**Title of the Book**	**Name of the Author/s**	**Name of the Publisher**	**Edition and Year**
1	Process Software and Digital Networks, CRC Press.	B G Liptak	CRC	3rd edition
2	Programmable Logic Controllers – Programming Methods and Applications, Pearson Education.	John R. Hackworth & Frederick D. Hackworth Jr	Pearson	1st edition 2003

Video Links (NPTEL, SWAYAM…)	
Module No.	**Link ID**
1	https://onlinecourses.nptel.ac.in/noc21_me67/preview
2	https://onlinecourses.nptel.ac.in/noc21_me67/preview
3	https://onlinecourses.nptel.ac.in/noc21_me67/preview
4	https://onlinecourses.nptel.ac.in/noc21_me67/preview

SEMESTER S8

MECHATRONIC SYSTEMS AND CONTROL

Course Code	OEEET833	CIE Marks	40
Teaching Hours/Week (L: T:P: R)	3:0:0:0	ESE Marks	60
Credits	3	Exam Hours	2 Hrs. 30 Min.
Prerequisites (if any)	None/ (Course code)	Course Type	OE - Theory

Course Objectives:

1. To familiarise mechatronic systems with fundamental knowledge in sensors and actuators achieve conceptual understanding of mechatronic systems
2. To enhance the fundamental knowledge in microprocessors and microcontrollers
3. To learn the fundamentals of system models and controllers
4. To understand control actions such as Proportional, derivative and integral and study its significance in industrial applications

SYLLABUS

Module No.	Syllabus Description	Contact Hours
1	Introduction to Mechatronics: Introduction, Examples of Mechatronic systems, Electric circuits and components, Semiconductor Electronics, Transistor Applications Sensors and transducers: Performance terminology of sensors, Displacement, Position & Proximity Sensors-I, Displacement, Position & Proximity Sensors-II, Force, Fluid pressure, Liquid flow sensors, temperature, light sensor, Acceleration and Vibration measurement, Semiconductor sensor and MEMS, SAW	9
2	Actuators and mechanisms: Mechanical Actuation System, Hydraulic & Pneumatic Actuation System, Electrical Actuation System-I, Electrical Actuation System-II, Data Presentation system Signal conditioning: Introduction to signal processing & Op-Amp, Op-Amp as signal conditioner, Analogue to Digital Converter, Digital to Analogue Converter, Artificial intelligence	10

3	Microprocessors and microcontrollers: Digital circuits-I, Digital circuits-II, Microprocessor Micro Controller, Programming of Microcontrollers Modeling and system response: Mechanical system model, Electrical system model, Fluid system model, Dynamic response of systems, Transfer function and frequency response.	**10**
4	Closed loop controllers: P, I, PID Controllers, Digital Controllers, Program Logic Controllers, Input/output & Communication systems, Fault findings Mechatronics designs and case studies	**7**

Course Assessment Method
(CIE: 40 marks, ESE: 60 marks)

Continuous Internal Evaluation Marks (CIE):

Attendance	Assignment/ Microproject	Internal Examination-1 (Written)	Internal Examination- 2 (Written)	Total
5	**15**	**10**	**10**	**40**

End Semester Examination Marks (ESE)

In Part A, all questions need to be answered and in Part B, each student can choose any one full question out of two questions

Part A	Part B	Total
• 2 Questions from each module. • Total of 8 Questions, each carrying 3 marks **(8x3 =24marks)**	• Each question carries 9 marks. • Two questions will be given from each module, out of which 1 question should be answered. • Each question can have a maximum of 3 sub divisions. **(4x9 = 36 marks)**	**60**

Course Outcomes (COs)

At the end of the course students should be able to:

Course Outcome		Bloom's Knowledge Level (KL)
CO1	Comprehend the importance of sensors and actuators with application to mechatronic systems	**K2**
CO2	Identify actuator mechanisms and signal conditioning processes	**K2**
CO3	Select microprocessors and microcontrollers for the implementation in mechatronic system	**K2**
CO4	Analyse the models and responses of different systems	**K3**

Note*: K1- Remember, K2- Understand, K3- Apply, K4- Analyse, K5- Evaluate, K6- Create*

CO-PO Mapping Table (Mapping of Course Outcomes to Program Outcomes)

	PO1	**PO2**	**PO3**	**PO4**	**PO5**	**PO6**	**PO7**	**PO8**	**PO9**	**PO10**	**PO11**	**PO12**
CO1	3					1						1
CO2	3					1						1
CO3	3					1						1
CO4	3	3	3	2	3	2					2	2

Note: *1: Slight (Low), 2: Moderate (Medium), 3: Substantial (High), -: No Correlation*

Text Books				
Sl. No	**Title of the Book**	**Name of the Author/s**	**Name of the Publisher**	**Edition and Year**
1	Mechatronics: Electronic Control Systems in Mechanical and Electrical Engineering	W. Bolton	Pearson Education	4th Edition 2010
2	Introduction to Mechatronics and Measurement Systems	Michael B. Histand, David G. Alciatore	McGraw-Hill Series in Mechanical Engineering	2003
3	Mechatronics system design. CL-Engineering,	Shetty, Devdas, and Richard A. Kolk.		2010.
4	Mechatronics: an introduction.,	Bishop, Robert H.	CRC Press	2017.
5	Intelligent Mechatronic Systems: Modeling, Control and Diagnosis	R. Merzouki, A. K. Samantaray, P. M. Pathak, B. Ould Bouamama	Springer, London	2003

Video Links (NPTEL, SWAYAM…)	
Module No.	**Link ID**
1	https://archive.nptel.ac.in/courses/112/107/112107298/
2	https://archive.nptel.ac.in/courses/112/107/112107298/
3	https://archive.nptel.ac.in/courses/112/107/112107298/
4	https://archive.nptel.ac.in/courses/112/107/112107298/