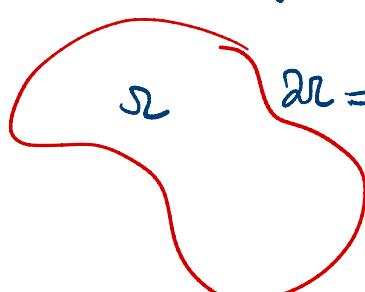


Hilbert Core: Lax Milgram Lemma

Context: V Hilbert Space (Sobolev Space on Ω)
 think of Lip. subset of \mathbb{R}^d)

$\begin{cases} -\Delta u = f & \text{in } \Omega \\ u = g & \text{on } \partial\Omega = \Gamma \end{cases}$	
---	--

Idea: Hilbert Space (separable) V .

$$① A_u = F \quad \text{in } V' \quad A: V \rightarrow V'$$

\equiv

$$\langle A_u, v \rangle = \langle F, v \rangle \quad \forall v \in V$$

$$a(u, v) := \langle A_u, v \rangle \quad \exists \ c > 0, \alpha > 0 \text{ s.t.}$$

$$\begin{array}{ll} a(u, v) \text{ is bounded} & i) |a(u, v)| \leq c \|u\|_V \|v\|_V \text{ for all } \\ " & ii) |a(v, v)| \geq \alpha \|v\|_V^2 \end{array}$$

Then

$$② a(u, v) = \langle F, v \rangle \quad \forall v \in V$$

Has a unique solution $u \in V$ and $\|u\|_V \leq \frac{1}{\alpha} \|F\|_V$.

Riesz operator: $\mathcal{Z}: V' \rightarrow V$

$$(\pi F, v)_V = \langle F, v \rangle \quad \forall v \in V$$

$$-g z(Av - F) + v =: T_g(v)$$

\Rightarrow if u is fixed point of T_g , then u solves \exists

$$T_g(u) = u \quad \Rightarrow \quad g z(Au - F) = 0$$

Find g for which T_g is contraction

$$\|T_g(v_1) - T_g(v_2)\|_V^2 = \|v_1 - v_2 - g z A(v_1 - v_2)\|_V^2$$

$$\frac{\|v_1 - v_2\|^2 + g^2 \|z A(v_1 - v_2)\|_V^2 - 2\langle (v_1 - v_2), g z A(v_1 - v_2) \rangle}{\|v_1 - v_2\|^2 + g^2 \|z A(v_1 - v_2)\|_V^2}$$

$$-2g \langle A(v_1 - v_2), v_1 - v_2 \rangle$$

$$\leq \underbrace{\|v_1 - v_2\|^2}_{\text{if } |1 + Cg^2 - 2\alpha g| < 1} \left(1 + Cg^2 - 2\alpha g\right)$$

$$\text{if } |1 + Cg^2 - 2\alpha g| < 1$$

Then $\exists!$ fixed point to $T_g \Leftrightarrow g < \frac{2\alpha}{C}$

$$\|Au\|_V \leq \|A\|_* \|u\| \leq C \|u\|$$

$$\|Au\|_V \geq \|A^{-1}\|_* \|u\| \geq \alpha \|u\|$$

Take $V_h \subset V$, restrict A to V_h

Find $u_h \in V_h$ s.t.

$$\langle A u_h, v_h \rangle = \langle F, v_h \rangle \quad \forall v_h \in V_h$$

$$\underline{\langle A(u - u_h), v_h \rangle = 0} \quad \forall v_h \in V_h}$$

Orthogonality

Cea's lemma :

$$d \parallel u - u_h \parallel_V^2 \leq \langle A(u - u_h), (u - u_h) \rangle \leq \langle A(u - u_h), u - v_h \rangle$$

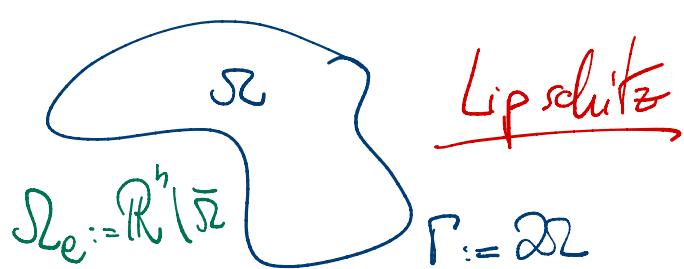
Hypothesis

$$\leq C \parallel u - u_h \parallel_V \parallel u - v_h \parallel_V \quad \forall v_h \in V_h$$

$$\boxed{\parallel u - u_h \parallel_V^2 \leq \inf_{v_h \in V_h} C \parallel u - v_h \parallel}$$

- 1) construct V_h such that $\text{dist}(V, V_h)$ is small a-priori
- 2) Given $F \in V'$, try to construct best V_h for F a-posteriori
- 3) Relate the constraint that $V_h \subset V$
→ "Variational Crimes" ($V_h \not\subset V$)
- 4) Mixed formulations / Stabilized formulations

Sobolev Notations:



$$u : \Omega \rightarrow \mathbb{R}$$

$D^\alpha u$: multi index
weak derivative of u of order $m = |\alpha|$

$C^m(\Omega)$: linear space with continuous derivatives

$$L^p(\Omega) := \left\{ v : \Omega \rightarrow \mathbb{R} \text{ st. } \left(\int_{\Omega} |v|^p \right)^{\frac{1}{p}} := \|v\|_{L^p(\Omega)} < \infty \right\}$$

$$L^\infty(\Omega) := \sup_{x \in \Omega} |v(x)|$$

$$W^{m,p}(\Omega) := \left\{ v : \Omega \rightarrow \mathbb{R} \mid D^\alpha v \in L^p(\Omega) \text{ for } |\alpha| \leq m \right\}$$

$$\|v\|_{m,p,\Omega} := \left(\sum_{|\alpha| \leq m} \|D^\alpha v\|_{L^p(\Omega)}^p \right)^{\frac{1}{p}}$$

three subscripts: Sobolev norm

When $p=2$

$$\|v\|_{m,\Omega} := \|v\|_{m,2,\Omega}$$

Hilbert Space,
with inner product

two subscripts: $p=2$

$$(v, v)_{m,\Omega} := \sum_{|\alpha| \leq m} \int_{\Omega} D^\alpha v \cdot D^\alpha v \, d\Omega$$

$$\text{Seminorm} \quad \|u\|_{m,p,\Omega} := \|D^m u\|_{L^p(\Omega)}$$

$$C^{m,p}_1 := \{ u \in C^m(\Omega) \mid \|u\|_{m,p,\Omega} < +\infty \}$$

$$H^{m,p}(\Omega) := \overline{C^{m,p}_1} \cdot \| \cdot \|_{m,p,\Omega}$$

Meyers / Serrin : Ω Lip. $\Rightarrow \underline{H^{m,p}(\Omega)} = \underline{W^{m,p}(\Omega)}$

Formal Definition of Finite Element (Chiarlet)

Triple K, P, Σ

i) K is a compact, connected, Lip. subset of \mathbb{R}^d
s.t. $K \neq \{\text{id}\}$

ii) P is a vector space of dimension N from K to \mathbb{R}
 $m=1$ or d

iii) $\Sigma := \{v_i\}_{i=1}^N$ a basis for $L_0(P, R)$

iii) $\Leftrightarrow P \ni p \rightarrow \{v_i(p)\}_{i=1}^N \in \mathbb{R}^N$
is bijective

Σ is the set of "degrees of freedom"

1) Canonical basis $\{v_i\}_{i=1}^N$ for P s.t.

$$v^j(v_i) = \delta_{ij}^j = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$$

Local basis functions

Ex 1 Lagrange Finite Element Spaces.

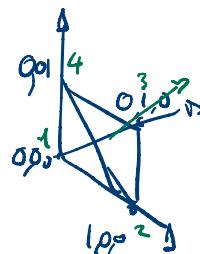
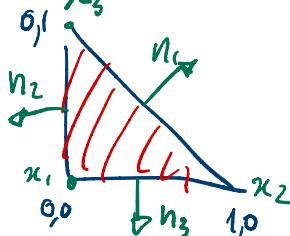
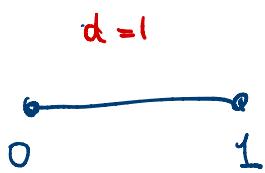
A $\{K, P, \Sigma\}$ is a Lagrange FE space if $\exists \{a_i\}_{i=1}^N$
(support points) $a_i \in \mathbb{R}^d$ s.t.

$$v^i(p) = p(a_i) \quad \forall p \in P, \quad i=1, \dots, N$$

or Nodal Finite Element (and a_i are the "nodes")

Simplicial Lagrangian FÉ (in \mathbb{R}^d)

$$K := \left\{ x \text{ s.t. } x_i \geq 0, \sum_{i=1}^d x_i \leq 1 \right\}$$

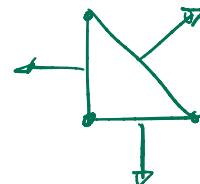


P = Polynomial space of order k : $N = \binom{d+k}{k}$

$$d=1 \quad N = k+1$$

$$d=2 \quad N = \frac{1}{2} (k+1)(k+2)$$

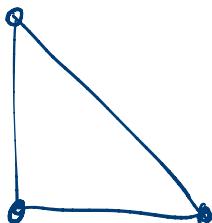
$$N = \frac{1}{6} (k+1)(k+2)(k+3)$$



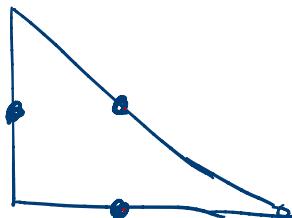
Example $k=1$ set a_i = vertices of K

$$v_i(x) = 1 - \frac{(x-a_i) \cdot n_i}{(a_j-a_i) \cdot n_i} \quad \text{for any } j \neq i$$

$$d=2 \rightarrow 1-x-y, \quad x, \quad y$$



VS
?

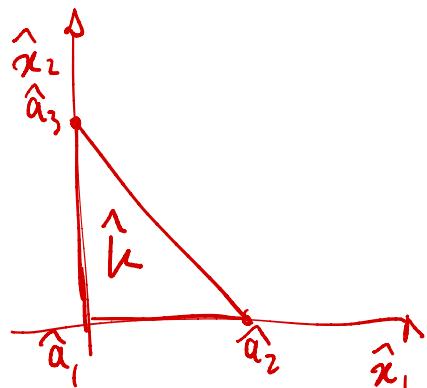


- ① Any simplex can be constructed as an affine transformation from the reference simplex

Start by defining a ref. FE $\hat{k}, \hat{P}, \hat{\Sigma}$
assume it is Lagrangian of order k .

Then write

$$T_k \hat{x} : \sum_{i=1}^N a_i \hat{v}_i$$



where $a_i \in \mathbb{R}^d$
 and \hat{v}_i is the canonical basis
 for \hat{P}

$\hat{a}_i :=$ support points of $\hat{v}_i (\alpha \hat{v}_i)$

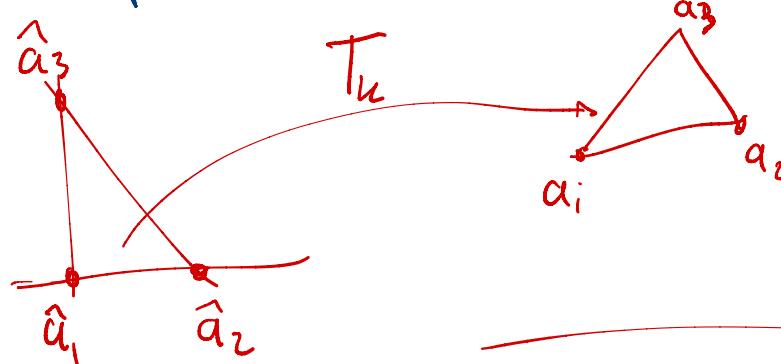
$$\hat{v}_i := \delta(\hat{x} - \hat{a}_i)$$

Define k as image under T_k of \hat{k}

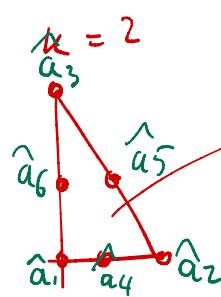
$$k = T_k(\hat{k})$$

know when you know $\{a_i\}_{i=1}^N$

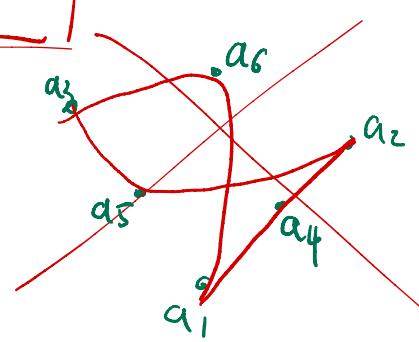
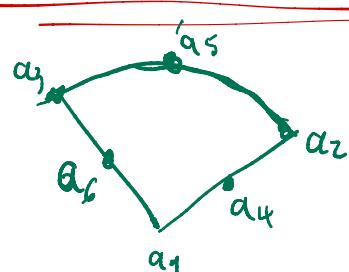
order of $P^{(k=1)}$ $= 1 \rightarrow d=2, N=3$



We ask that $\boxed{\det J T_k > 0}$ $\forall \hat{x}$



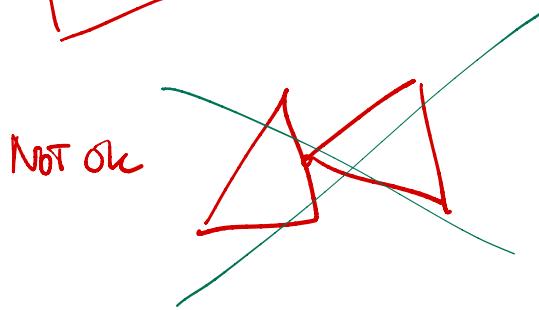
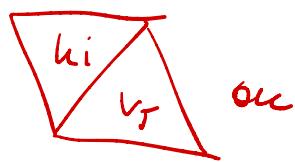
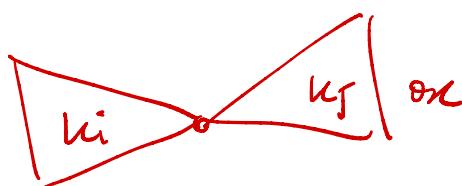
$$\boxed{\det J T_k > 0}$$



Construction of V_T : partitioning S_T into S_T

$$S_{Tq} = \left(\bigcup_{i=1}^H K_i \right)$$

$K_i \cap K_j$ is common vertex or common edge or common triangle in 3d



Once the position is known

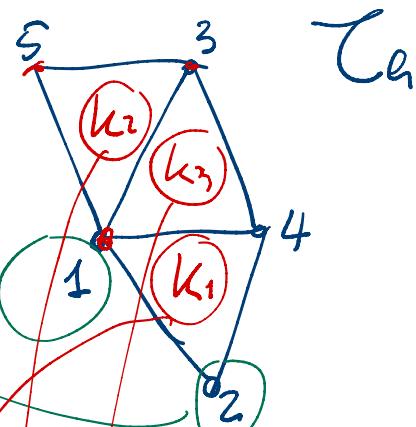
$\forall k \exists \{a_i(k_m)\}_{i=1}^N$ local support points for all $m=1,\dots,M$

m cells = a list of length m of N points in \mathbb{R}^d

Structure:

List of points with id N_p points

1	P_{11}	P_{12}	P_{13}	←
2	P_{21}	P_{22}	P_{23}	←
:				
N_p				



List of cells with id.

1	1	2	4	→ indices into the first list
2	1	3	5	←
3	1	4	3	←

How to construct V_h on \mathcal{T}_h , s.t. $V_h \subset H^1(\Omega)$

$$V_h^\circ = \{ v \in C^0(\bar{\mathcal{T}}_h) \mid v|_k \in P^1(k) \quad \forall k \in \mathbb{Z}_0 \}$$

Simpler Case:

$$V_h^{-1} \subset L^2(\Omega), \quad V_h = \{ v \in L^2(\bar{\mathcal{T}}_h) \mid v|_k \in P^1(k) \text{ and } d=2 \}$$

$$\dim(V_h^{-1}) = 3M \quad = 3 \text{ times number of cells.}$$

How about V_h° : number vertices



Idea: $N_0 = \dim(P^k)$ for $d=0$ is $\begin{cases} 1 & k \geq 1 \\ 0 & k=0 \end{cases}$

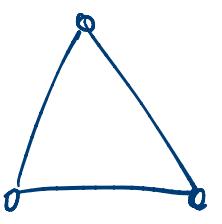
$$N_1 = \dim(P^k) \text{ for } d=1 \text{ is } (k+1)$$

$$N_2 = \dim(P^k) \text{ for } d=2 \text{ is } \frac{1}{2}(k+1)(k+2)$$

$$N_3 = \dim(P^k) \text{ for } d=3 \text{ is } \frac{1}{6}(k+1)(k+2)(k+3)$$

To ensure continuity for $\{k, P, \Sigma\}$

* support points on subelements of Σ (i.e. edges, faces, vertices)
coincides with $\dim(P^k|_X)$ where X is edge, face or vertex.

Start with $d = 0$	(Two dimensional example)
	3 vertices $d=1$
3 edges $d=1$	
1 triangle $d=2$	

1 degree of freedom (\equiv 1 support point) per vertex: N_v

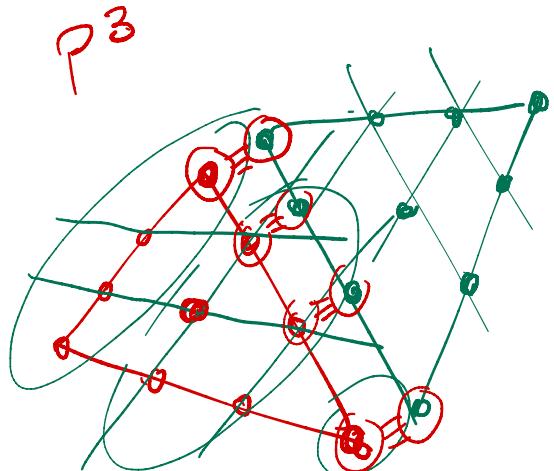
③ For each edge, Π assign $N_E = N_1 - 2N_0$ to the edge.

For each triangle Π assign $N_T = N_2 - 3N_E - 3N_v$

For each tetrahedron Π assign $N_{TET} = N_3 - 4N_E - 4N_v$

"Degrees of freedom per object" dpo

$$dpo \in \mathbb{R}^{d+1} \quad \text{s.t.} \quad \begin{aligned} dpo_0 &= N_v \\ dpo_1 &= N_E \\ dpo_2 &= N_T \\ dpo_3 &= N_{TET} \end{aligned}$$



P^3