

A priori Estimates

$$\text{dist}(V, V_h) := \sup_{u \in V} \inf_{v_h \in V_h} \|u - v_h\|$$

- 1 Construct splitting of $\Omega = \overline{\bigcup K}$ into d-simplices or tensor product structures
- 2 Construct local basis on K
- 3 Make sure they glue together correctly
- 4 Estimate what happens on one reference element \hat{K}
- 5 Write all elements as $K = T_K(\hat{K})$
- 6 Estimate $| \cdot |_{m, \hat{K}}$ w.r.t. $| \cdot |_{m, K}$ and T_K
- 7 Exploit equivalence of $| \cdot |_{m, K}$ with $|[-]|_{m, \hat{K}}$ for polynomials (Bramble-Hilbert)
- 8 Sum up, "glue" together get estimate on Ω

1: Triangulation

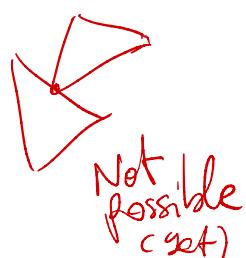
Ω is split into elements $K \subset \mathcal{T}_h$

- $\overline{\Omega} = \bigcup_{K \in \mathcal{T}_h} \overline{K}$ K open, $K \neq \emptyset$

- $K_1 \cap K_2 = \emptyset$

- ∂K Lip. Continuous

- $\overline{K}_1 \cap \overline{K}_2$ vertex, edge, or face



2: local (finite dimensional) spaces of dimension N_k

$$\cdot P_k := \{ v_h|_K \mid v_h \in V_h \}$$

• P_k should contain polynomials (or be close to polynomials)

• A "finite element" is the triple $\{K, P_k, \Sigma_k\}$

where $\Sigma_k := \{\phi^i\}_{i=1}^{N_k}$ are linear functionals

on P_k , such that Σ_k is P_k -unisolvent

iff given N_k real numbers $\{p^i\}_{i=1}^{N_k}$, $\exists! p \in P_k$

such that $p^i = \langle \phi^i, p \rangle$

$\forall \kappa$, $\exists!$ set $\{\phi_i\}_{i=1}^{N_k}$ s.t. $\langle \phi^j, \phi_i \rangle = \delta_{ij}^j$

• Σ_k is a basis for P_k^*

• $p^i = \langle \phi^i, p \rangle$ are the local degrees of freedom of p

• ϕ_i are the local basis functions on K

• $\tilde{\phi}^i$ are extensions of ϕ^i to V^* s.t.
 $\tilde{\phi}^i(p) = \phi^i(p) \quad \forall p \in P_k$

$$\cdot \Pi_K : V \longrightarrow P_K$$

$$u \longrightarrow \langle \tilde{\phi}^i, u \rangle \phi_i$$

local P_K -interpolation operator

$$3) \text{ If } V_h \subset C^m(\bar{\Omega}) \Rightarrow V_h \subset H^{m+1}(\Omega)$$

Proof: Start with $C^0(\bar{\Omega})$, $H^1(\Omega)$, proceed by induction.

We need to show that ∇u_h is well defined ^① and in $L^2(\Omega)$

$$\textcircled{1} \quad \forall \varphi \in (C_c(\Omega))^d \quad \int_{\Omega} \nabla u_h \varphi = \sum_K \left[- \int_K u_h \nabla \varphi + \int_{\partial K} u_h \varphi \right]$$

$\epsilon := \bigcup_{K \in \mathcal{T}_h} \partial K$

$$= - \int_{\Omega \setminus \epsilon} u_h \nabla \varphi + \int_{\epsilon} [u_h] \varphi \quad \xrightarrow{\text{②}} \quad u_h \in C^0(\Omega)$$

$\Rightarrow \nabla u$ is well defined in the weak sense

How do we enforce global continuity?

Most important case:

* K : d-simplices

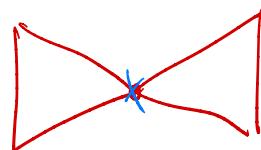


* $P_K = \mathbb{P}^n(K)$ complete polynomial spaces

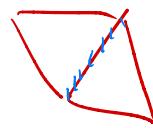
Let k_i, k_j be such that $\overline{K_i} \cap \overline{K_j} = X$

for example:

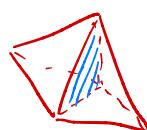
$X = V$: vertex



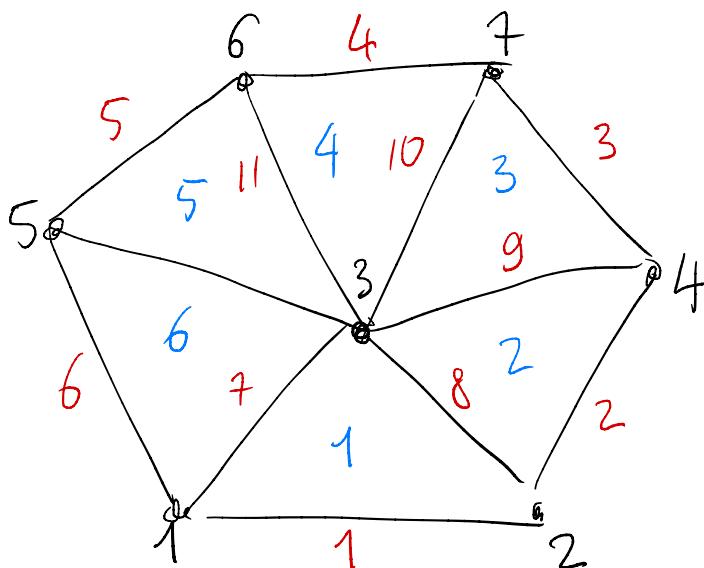
$X = E$: edge



$X = T$: triangle



- * Associate a global number to every (shared) object in T_h



- * Count the dimension of $P^n(k)|_X$, starting from vertices

Convention: $\dim(P^n(k)|_V) \equiv \begin{cases} 1 & n > 0 \\ 0 & n = 0 \end{cases}$

* Start with vertices: 1-dof associated to each vertex (if $n > 0$) $N_v = 1$ for scalar problems.

* Edges: each edge has two vertices. associate to each edge N_e dofs



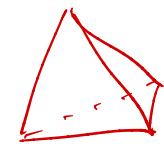
$$N_e := [\dim(P^n(\kappa))|_e] - 2N_v$$

* Triangles: three vertices, three edges



$$N_T := [\dim(P^n(\kappa))|_T] - 3N_e - 3N_v$$

* Tetrahedrons: 4 triangles, 4 vertices, 6 edges



$$N_{\text{Tet}} := [\dim(P^n(\kappa))] - 4N_T - 6N_e - 4N_v$$

Example: P^1 on triangles.

$$N_v = 1$$

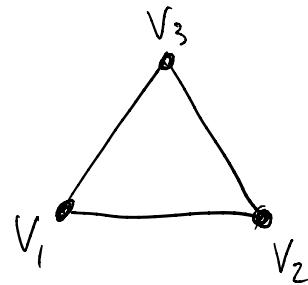
$$\dim(P^1)|_e = 2 \Rightarrow N_e = 0$$

$$\dim(P^1)|_T = 3 \Rightarrow N_T = 0$$

All dofs are associated to vertices

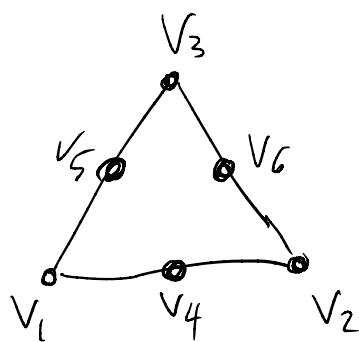
- * Notation - "•" represents a Dirac Delta
- "↗" "directional derivative of the Dirac Delta"
- "○" gradient of Dirac Delta

For P^1 :



$$\Sigma_K := \left\{ \delta(x - v_i) \right\}_{i=1}^3$$

P^3 :



$$\Sigma_K := \left\{ \delta(x - v_i) \right\}_{i=1}^6$$

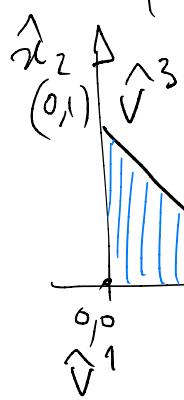
Corresponding basis functions:

$$\phi_i \in P^{1/2}(K) \quad | \quad \phi_i(v_j) = \delta_{ij}$$

If Σ contains only Dirac \Rightarrow Lagrange Basis

If Σ also derivatives of Dirac \Rightarrow Hermite Basis.

Any d-simplex K can be represented as an affine transformation of the reference d-simplex: \hat{K}

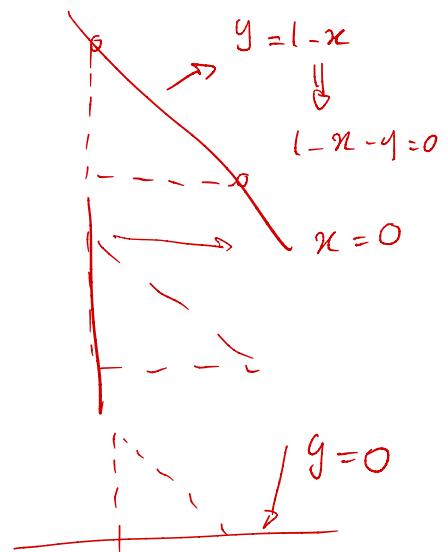


$$\Sigma_{\hat{K}} := \left\{ \delta(\hat{x} - \hat{v}^i) \right\}_{i=1}^3$$

$$\phi_1 := 1 - x - y$$

$$\phi_2 := x$$

$$\phi_3 := y$$



Affine transformation from \hat{K} to K :

$$T_K : \hat{K} \longrightarrow K$$

$$\hat{x} \longrightarrow v^i \phi_i(\hat{x})$$

By definition: $T_K(\hat{v}^i) = v^i$, $F: \mathbb{R}$

$$T_K(\hat{x}) \in \mathbb{P}^1(K)$$
z

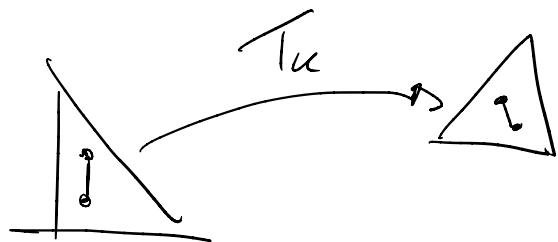
$$T_K := B_K \hat{x} + b_K$$

$$h_K := \max \{ |x-y| \mid x, y \in K \}$$

$$s_K := \sup \{ 2^j \mid B_j \subseteq K \}$$

$$\hat{\{ \}} := \hat{x} - \hat{y} \quad \text{with} \quad \hat{x}, \hat{y} \in \hat{K}$$

$$\hat{\{ \}} = \hat{B}_K \hat{\{ \}} = T_K \hat{x} - T_K \hat{y} = x - y \quad \text{with} \quad x, y \in K$$



$$\| B_K \| := \sup_{|\hat{\{ \}}| = s_K} \frac{|B_K \hat{\{ \}}|}{|\hat{\{ \}}|} \leq \frac{h_K}{s_K} \leq C h_K$$

$$\| B_K^{-1} \| := \sup_{|\{ \}| = \rho} \frac{|B_K^{-1} \{ \}|}{|\{ \}|} \leq \frac{h_K}{\rho} \leq C \rho^{-1}$$

If triangulation is shape regular

$$s_K \geq \sigma h_K \quad \checkmark_K$$

$$\| B_K \| \leq C h_K \quad \| B_K^{-1} \| \leq C h_K^{-1}$$