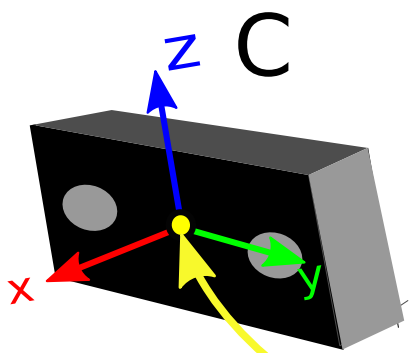
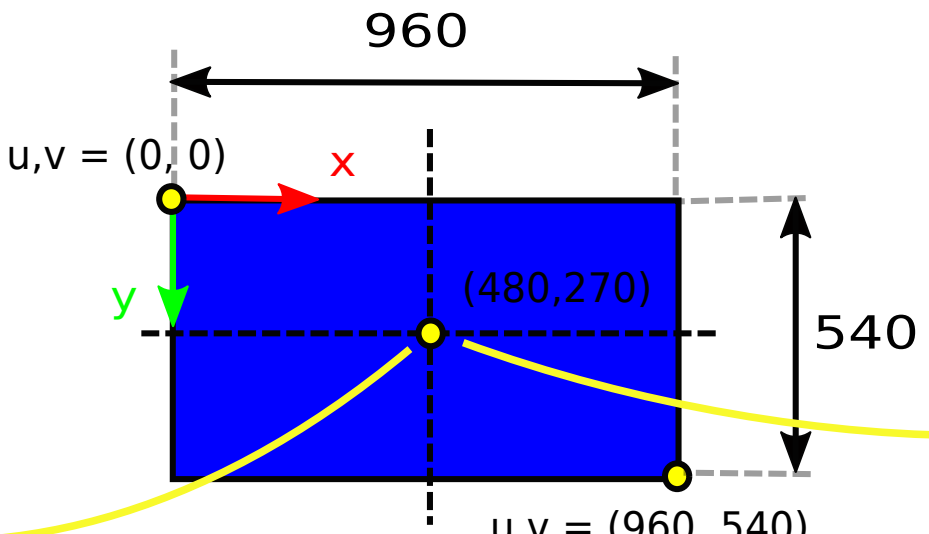
ZED2 CAMERA

Real Robot

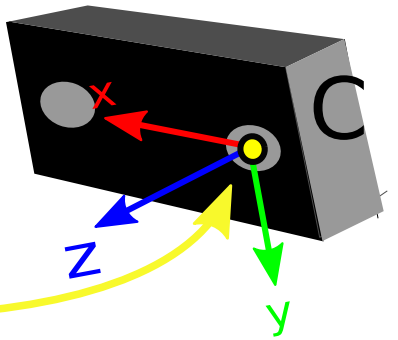


zed2_camera_frame

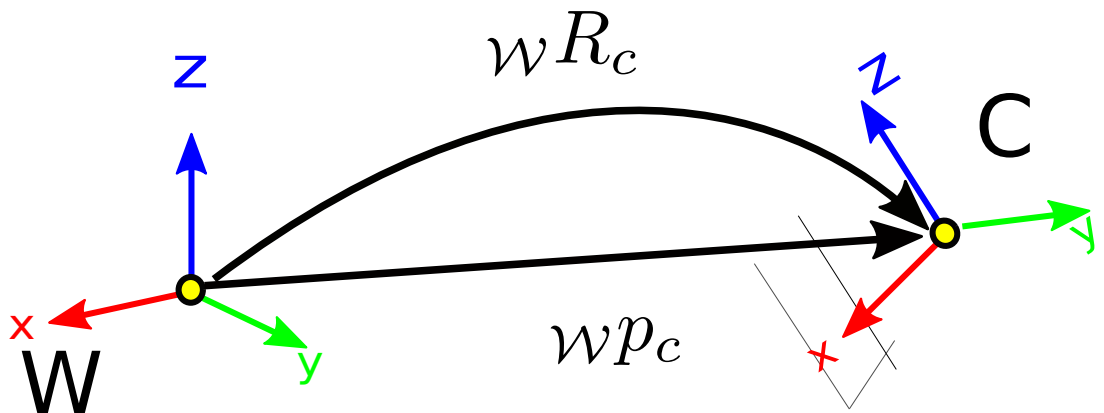
Image plane
(seen from backwards)



Simulation



zed2_left_camera_optical_frame



$$_Wp_i = {}_Wp_c + {}_WR_{cc}p_i$$