view_frames Result Recorded at time: 199.467 odom Broadcaster: /gazebo Average rate: 100.289 Hz Most recent transform: 199.460 (0.007 sec old) Buffer length: 3.460 sec base_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (199.467 sec old) Buffer length: 0.000 sec base_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz

Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (199.467 sec old) Most recent transform: 0.000 (199.467 sec old) Most recent transform: 0.000 (199.467 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec caster_back_link caster_front_link velodyne_base_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (199.467 sec old) Buffer length: 0.000 sec

velodyne