

LUCA MANOLACHE

lucar23o@gmail.com ◊ luca.manolache@berkeley.edu ◊ (408) · 204 · 0841 ◊ github.com/lucamanolache ◊ lucamanolache.github.io

EDUCATION

University of California, Berkeley

2026

Classes CS 61A, CS 61C, CS 194 - Responsible GenAI and Decentralized Intelligence

EXPERIENCE

Machine Learning at Berkeley

August 2023 - Present

Member

Berkeley

- Worked on RL project using Q-learning for playing multiplayer statistics games.

Palo Alto High School Robotics Team

October 2019 - June 2023

Software Lead

Palo Alto High School

- Coordinating the software team (12 developers) to use OpenCV and Java using github, CI/CD. Taught members how to implement PID controllers, fine-tune algorithms, and test the robot.

Auditoria.ai / Intern

June 2022 - August 2022

Intern

Santa Clara, CA

- Worked at local startup Auditoria, which automates finance processes, focusing on identifying structured elements (such as tables) in financial documents using DNNs in PyTorch and OpenCV

NASA Ames Research Center/ Intern

June 2021 - August 2021

Intern

NASA, Ames

- Worked on SafeDNN project exploring new techniques and tools to ensure that systems that use Deep Neural Networks (DNN) are safe, robust and interpretable.
- Applied the new techniques to the analysis of deep neural networks, publishing <https://arxiv.org/abs/2208.03407>.

PROJECTS

Wordle solver using entropy

2023

github.com/lucamanolache/wordle

Solved using the algorithm presented in 3b1b for maximizing information with each guess. Written in Rust using Rayon for parallelism.

Inverse kinematic robotic arm

2023

github.com/lucamanolache/inverse-kinematics

Created a robotic arm to pick up blue berries using OpenCV. Implemented inverse kinematics using Arduino C.

Attendance System

2022

github.com/lucamanolache/attendance

Created full stack attendance system for tracking robotics team member's participation with MongoDB database and async Rust backend.

SightWalk

2021

github.com/team8/outdoor-blind-navigation

Worked on SightWalk project - "Outdoor blind navigation", runner up at the International 2021 FIRST Innovation Challenge. Uses OpenCV and ML to implement a sidewalk navigation device for blind using CNNs.

PAPERS

An Overview of Structural Coverage Metrics for Testing Neural Networks

August 2022

Usman, M., Sun, Y., Gopinath, D., Dange, R., Manolache, L., Pasareanu, C.S. (2022). An Overview of Structural Coverage Metrics for Testing Neural Networks. ArXiv, [abs/2208.03407](https://arxiv.org/abs/2208.03407).

TECHNICAL STRENGTHS

Languages

Java, Python, C++, Rust, Javascript

Libraries

PyTorch, OpenCV, Flask, Numpy, React

Tools

Git, Vim, Tensorboard

Awards

USACO Gold, FRC Utah Winner