

# EE-559: Mini-project II

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## 1 Objective

The objective of this project is to design a mini “deep learning framework” using only tensor operations in pytorch and the standard math library, in particular without using autograd or the neural-network modules.

## 2 Code structure

The framework is composed by two modules: `modules`, `criteriaions` and `networks`. The classes implemented in each module interact as shown in Figure 1.

### 2.1 Modules

Modules implement some of the typical building blocks of a neural network. Each of these building blocks derives from the class `Module` (see Figure 1), the basic structure of which (except for the methods `resetGradient` and `updateParameters`) was suggested in the description of the project. The methods `forward` and `backward` implement a forward and backward pass respectively. The method `resetGradient` resets all the gradient tensors (if any) to zero, whereas the method `updateWeights` updates the weights (if any) of the module according to the learning rate `eta`.

All the modules deriving from `Module` possess a variable `input` taking the value of the input which was provided during the latest call to the `forward` method: this is necessary to compute the `backward` call. The classes which derive from `Module` are:

- **Linear**: given an input tensor  $x \in \mathbb{R}^{n_s \times n_{in}}$ , the output  $y \in \mathbb{R}^{n_s \times n_{out}}$  of this module is given by  $y_{ij} = \sum_k x_{ik} A_{kj} + b_j$ , where  $A \in \mathbb{R}^{n_{out} \times n_{in}}$  is the weight matrix,  $b \in \mathbb{R}^{n_{out}}$  is the bias, and  $n_{in}$ ,  $n_{out}$  and  $n_s$  are the number of input/output features and samples respectively. This module has the attributes `weight` and `bias`, which store the values of  $A$  and  $b$  respectively, and `weight_grad` and `bias_grad` which store the respective gradients.
- **ReLU**: this module applies the ReLU function to any given input tensor, namely, given  $x \in \mathbb{R}^{n \times m}$ , the output tensor  $y \in \mathbb{R}^{n \times m}$  is defined by  $y_{ij} = \text{ReLU}(x_{ij}) = \max\{0, x_{ij}\}$ .
- **Tanh**: this module applies the tanh function to each component of the input tensor  $x \in \mathbb{R}^{n \times m}$ , i.e. the output tensor  $y \in \mathbb{R}^{n \times m}$  is defined by  $y_{ij} = \tanh(x_{ij})$ .

### 2.2 Criteriaions

The `criteriaions` module contains the implementation of the loss functions. These share the interface given by the following base class `Loss` (see Figure 1). The method `function` computes the loss function of the `output` of a forward pass of a network with respect to the `expected`, and the `grad` method computes the gradient of the loss corresponding to the same parameters.

The available criteriaions are:

- **LossMSE**: Mean Square Error loss function. If  $x \in \mathbb{R}^{N \times m}$  is the output of the forward pass and  $y \in \mathbb{R}^{N \times m}$  is the expected output, the loss function is computed as  $\text{MSE}(x, y) = \sum_{i,j} (x_{ij} - y_{ij})^2$  **we need to check this, in the solution of ex 3 they don't do the mean.**
- **LossCrossEntropy**: to be implemented?

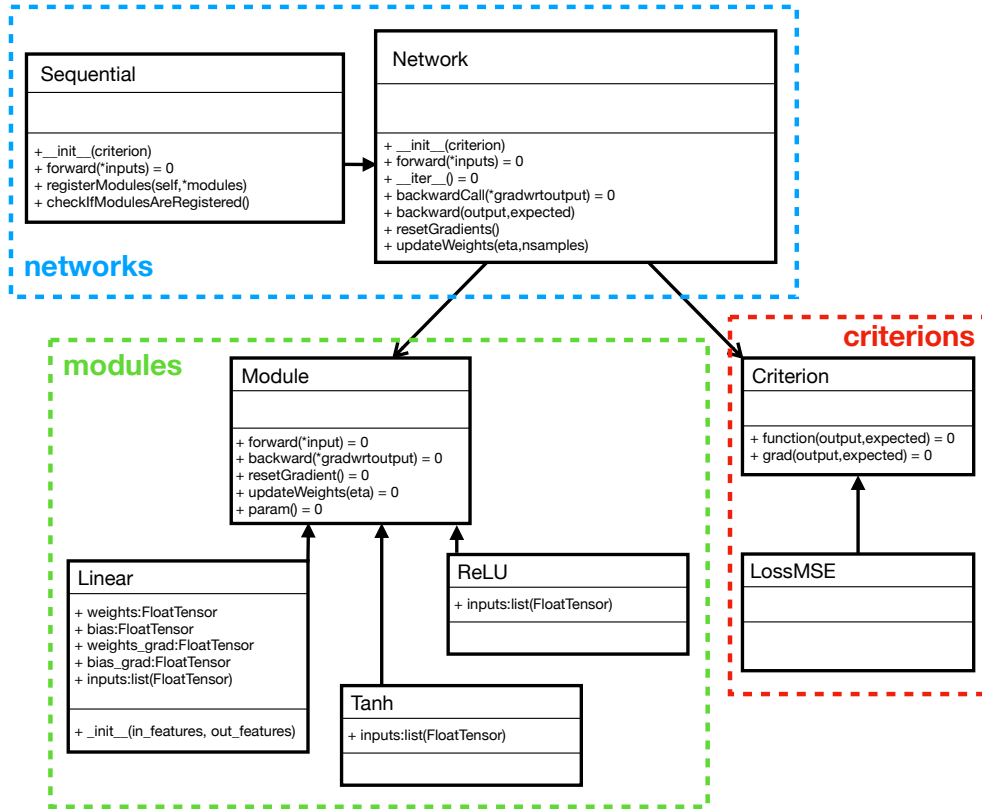


Figure 1: Class diagram of the framework. We indicate with the notation “= 0” the methods that need to be implemented by the derived classes, even though such methods are not actually abstract in a strict sense.

## 2.3 Networks

The **criteria** module provides generic structures for the implementation of neural networks. The base class is the **Network** class (see Figure 1). Each derived class must be iterable (namely, it must provide the abstract method `__iter__`) and must implement the **forward** and the **backward** methods, which depend on the topology of the underlying graph.

The available networks are:

- **Sequential**: template for neural networks: it provides a blueprint for derived classes implementing fully connected neural networks. Each graph must include a unique “source” (a node with only one input), a unique “sink” (a node with only one output) and nodes with exactly one input and one output. Each node is in fact an object derived from the **Module** class and must be defined as an attribute of a derived class in the constructor. Importantly, at the end of the constructor these objects must be registered via the method `registerModules(self, *modules)`, where the `*modules` must contain the modules in the order they appear in the network itself. Internally, the `registerModules` method builds a list of the modules, which provides a way to iterate over the elements composing the **Sequential** network. The forward and backward passes are executed in a straightforward manner by calling the **forward** and **backward** method of all the modules of the graph sequentially and propagating the result to the next or the previous node.

## 3 Test case

The structure of the test code, implementing a network with two input units, two output units, three hidden layers of 25 units is:

- Generate 1000 training sample, and 1000 testing points
- Normalize them with a zero mean and unit std

- Built a three hidden layer with linear neural network, and ReLU after each linear module "SimpleNet"
- Train the neural network using the 1000 training sample, for 1000 epochs and a constant learning rate  $= 1e - 2$ .
- Plot the training error and the testing error while training the network, and verify these results with the framework PyTorch.

The parameters of the sample length is hidden in the *mean* function, and we had to modify the eta in the final code:  $\eta = \eta / n_{sample}$ .

```
class LossMSE(object):
    def function(self,output,expected):
        return torch.mean(torch.pow(expected - output,2))

    def grad(self,output,expected):
        return -2 * (expected - output)
```

The sequential class work as follow:

```
class Sequential(Module):
    def __init__(self,criterion):

        def registerModules(self,*modules):

        def checkIfModulesAreRegistered(self):

        def resetGradient(self):

        def updateParameters(self,eta,nsamples):

        def backward(self,*gradwrtoutput):

        def backwardPass(self, output, expected):
```

where the *registerModules* needs to be called when we define a new network, in order to store the modules in a list. We will use the list ordered when we will call the methods *forward*, *backward*, and *updateparameters*

## References