

Deep Learning Mini-Project 1 Report

Prediction of Finger Movements from EEG Recordings

Group 78

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1 Introduction

The goal of this project is to design and train a Deep Neural Network to analyse EEG data. In particular, we perform a two-class classification of EEG time signals collected from one patient to predict the direction of her upcoming finger movements (left vs. right). The dataset, part of the “BCI Competition II” [1], is composed of 416 recordings sampled with a 1000 Hz frequency for 28 channels (i.e., electrodes placed at different locations on the skull). The dataset is split in training and test datasets of 316 and 100 samples, respectively.

This report is organised as follows: we will briefly present and visualise the datasets in Section 2, where we introduce the suggested down-sampling, a possible data augmentation strategy and consider sample shuffling before splitting into train and test sets (si o no..?). Then, in Section 3, we will present five different models we tried and the corresponding results obtained on the test set. Of these, the one that performs best is selected for further tests in Section 4. In particular, we present a smoothing pre-processing strategy to reduce noise in the signals and an optimisation setup to select the hyper-parameters. Final conclusions and discussions are provided in Section 5.

2 Data Visualisation

Before rushing at adding extra layers or more neurons to increase the complexity of our model, we take a look at the given data. Figure 1 shows the average over all samples of the training and test datasets for three randomly chosen channels, i.e. channels 3, 10 and 25. The averages are shown separately for the two-classes, i.e. left and right, and for both the signal sampled at 1000 Hz (in red and blue) and its down-sampled signals (in black and magenta). We can observe that the down-sampled signals present a less noisy average with respect to the 1000 Hz signal. Moreover, we remark that the means over the test and train dataset are very different. This behaviour is observed, although with different intensity, for all 28 channels. One possible explanation of this discrepancy lies in the fact that the averages were not performed on equally numerous datasets: 316 samples and 100 samples in the training and test datasets, respectively. Indeed, we can confirm that the average obtained from a subset of the training dataset of 100 samples is quite different from the average over 316 samples shown in Figure 1. This behaviour can be justified if samples have a high variance and Figure 2, which shows the behaviour of three randomly chosen down-sampled samples for each class (i.e., left and right) for both the training and test dataset, confirms it. Immediately, we can see that both the training and test selected samples are all very noisy and distant from their corresponding mean.

Even if we understand that the average is not a sufficient meaningful quantity to describe a complex dataset, the high variability of data makes us believe that this apparently simple two-class 1D classi-

*As agreed with Dr. F. Fleuret, L. Pegolotti has collaborated with group 78 for Project 1 and with group 79, with M. Martin, for Project 2. C. Bigoni and N. Ripamonti has worked together on both projects.

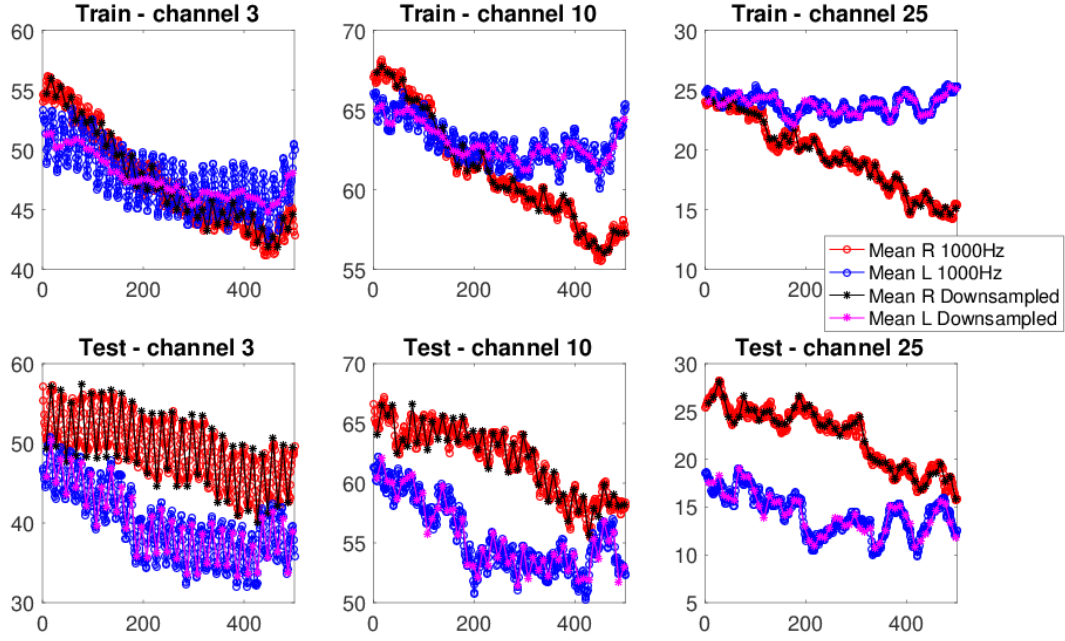


Figure 1: lala

fication problem, will instead be quite challenging. In order to ..., we normalise the training dataset using its mean and standard deviation for all channels. The same values are used for the test dataset.

Supported by poor accuracy results obtained with the methods proposed in the next section, we decide to introduce here our *data-augmentation* strategy. In particular, we exploit the 1000 Hz dataset to extract not one but 10 other signals with frequency 100 Hz. In this way, our training dataset has the following dimensions: 3160 samples, 28 channels, 50 time-steps. We considered the possibility of extending the data-augmentation strategy to the test dataset to further increase the dimension of our training dataset by including some samples from the test dataset after shuffling. However, we soon realised that this would imply solving an oversimplified problem being the 10 down-sampled signals all very alike. We therefore apply the data-augmentation strategy only to the training dataset.

Finally, supported by the results already published for this dataset, known as dataset VI in the BCI competition [1], and by other studies (see e.g. [3]), we propose a preprocessing strategy. In particular we introduce a filtering for the signals that will be used on our final model, as explained in Section 4. TODO!!!!

- Linear Perceptron – Error train vs. test when overfitting
- Cross Validation (how many?)
- Each model is averaged over N times

3 Models we tried and why they don't work

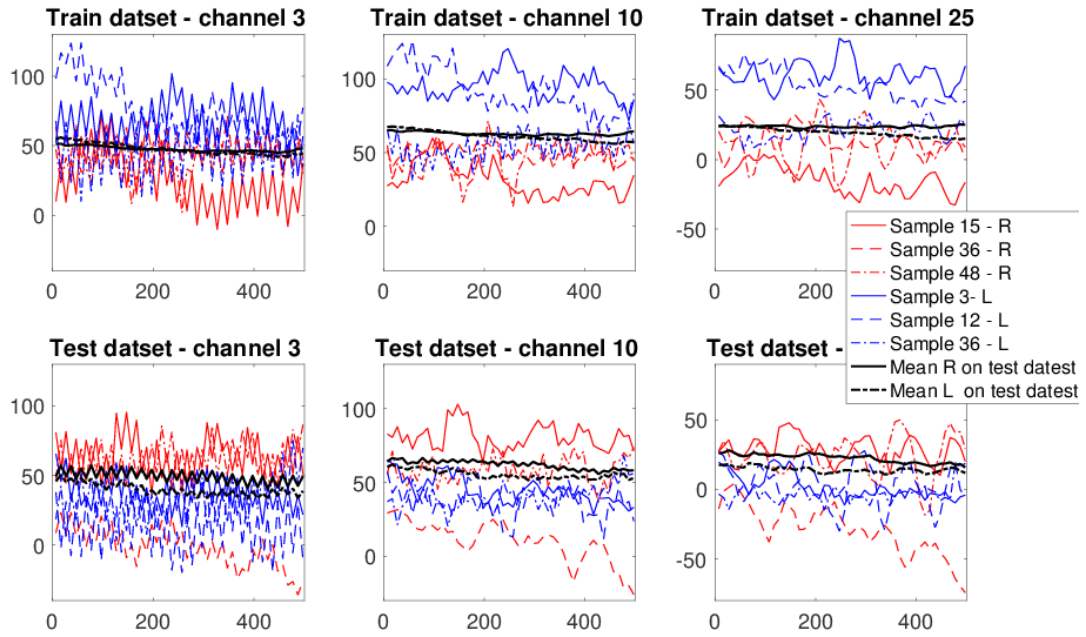


Figure 2: lala

| Number of tirals | Linear Perceptron | MC-DCNNNet bis 3 | ShallowConvNetPredictor eta = 1e-3 hidden = 20 |
|------------------|-------------------|------------------|--|
| 1 | | | |
| 2 | | | |
| 3 | | | |
| 4 | | | |
| 5 | | | |
| 6 | | | |
| Average | | | |

- 2 Conv 1D + 3 linear
- Conv only in the direction of the channels [5]
- Conv with "images", i.e. Conv 2D asymmetric (only in one direction) [3]
- All of them with Data Augmentation + white random noise [4]
- adaptive eta in gradient descent
- L1 and L2 Regularization [2]
- dropout

4 Model that works best

it doesnt overfit + graph

- Optimization with Hyperparameters

5 Conclusion

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