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linear_classifier.py
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from __future__ import print_function
import numpy as np
from hmwk5_2.classifiers.linear_svm import *
from hmwk5_2.classifiers.softmax import *
class LinearClassifier(object):
 def __init__(self):
   self.W = None
 def train(self, X, y, learning_rate=1e-3, reg=1e-5, num_iters=100,
          batch_size=200, verbose=False):
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   Train this linear classifier using stochastic gradient descent.
   Inputs:
   - X: A numpy array of shape (N, D) containing training data; there are N
     training samples each of dimension D.
   - y: A numpy array of shape (N,) containing training labels; y[i] = c
     means that X[i] has label 0 <= c < C for C classes.
   - learning_rate: (float) learning rate for optimization.
   - reg: (float) regularization strength.
   - num_iters: (integer) number of steps to take when optimizing
   - batch_size: (integer) number of training examples to use at each step.
   - verbose: (boolean) If true, print progress during optimization.
   Outputs:
   A list containing the value of the loss function at each training iteration.
   num_train, dim = X.shape
   num_classes = np.max(y) + 1 # assume y takes values 0...K-1 where K is number of classes
   if self.W is None:
     # lazily initialize W
     self.W = 0.001 * np.random.randn(dim, num_classes)
   \# Run stochastic gradient descent to optimize \mathbb{W}
   loss_history = []
   for it in range(num_iters):
     X_batch = None
     y_batch = None
     # TODO:
     # Sample batch_size elements from the training data and their
     # corresponding labels to use in this round of gradient descent.
     # Store the data in X_batch and their corresponding labels in
     # y_batch; after sampling X_batch should have shape (dim, batch_size)
     # and y_batch should have shape (batch_size,)
     # Hint: Use np.random.choice to generate indices. Sampling with
                                                                     #
     # replacement is faster than sampling without replacement.
     indxs = np.random.choice(num_train,batch_size)
     X_batch = X[indxs]
     y_batch = y[indxs]
     pass
     END OF YOUR CODE
     # evaluate loss and gradient
     loss, grad = self.loss(X_batch, y_batch, reg)
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loss_history.append(loss) # perform parameter update # TODO: # Update the weights using the gradient and the learning rate. # self.W -= learning_rate*grad pass END OF YOUR CODE if verbose and it % 100 == 0: print('iteration %d / %d: loss %f' % (it, num_iters, loss)) return loss_history def predict(self, X): Use the trained weights of this linear classifier to predict labels for data points. - X: A numpy array of shape (N, D) containing training data; there are N training samples each of dimension D. - y_pred: Predicted labels for the data in X. y_pred is a 1-dimensional array of length N, and each element is an integer giving the predicted y_pred = np.zeros(X.shape[0]) # Implement this method. Store the predicted labels in y_pred. y_pred = np.argmax(np.dot(X,self.W),axis = 1) pass END OF YOUR CODE return y_pred def loss(self, X_batch, y_batch, reg): Compute the loss function and its derivative. Subclasses will override this. Inputs: - X_batch: A numpy array of shape (N, D) containing a minibatch of N data points; each point has dimension D. - y_batch: A numpy array of shape (N,) containing labels for the minibatch. - reg: (float) regularization strength. Returns: A tuple containing: - loss as a single float - gradient with respect to self.W; an array of the same shape as W pass