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Alternating group lasso for block-term tensor decomposition with application to ECG source separation

J. H. de M. Goulart et al., 2020

I. Introduction

I. Introduction

- Biomedical Application: Atrial activity **extraction** during a persistent Atrial Fibrillation (**AF**).
- Blind Source Separation (**BSS**)
 - Matrix Approach
 - Principal component analysis (PCA)
 - Independent component analysis (ICA)
 - Tensor Approach
 - **BTD**-Gauss Newton (ALS-NLS or ELS)
 - **AGL** and its Constrained Version, **CAGL**

Matrix Approach

$$\mathbf{Y} = \mathbf{M} \times \mathbf{S}$$

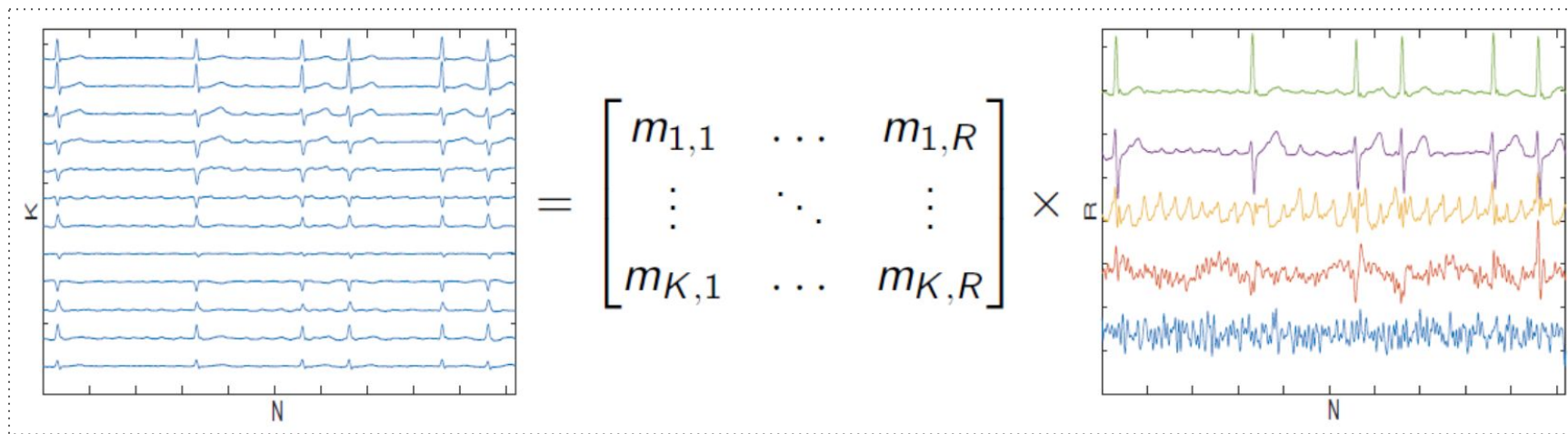


Figure : **Classic model for BSS.**

Tensor Approach

$$\mathcal{Y} \approx \sum_{r=1}^R \mathbf{A}_r \mathbf{B}_r^\top \circ \mathbf{x}_r$$

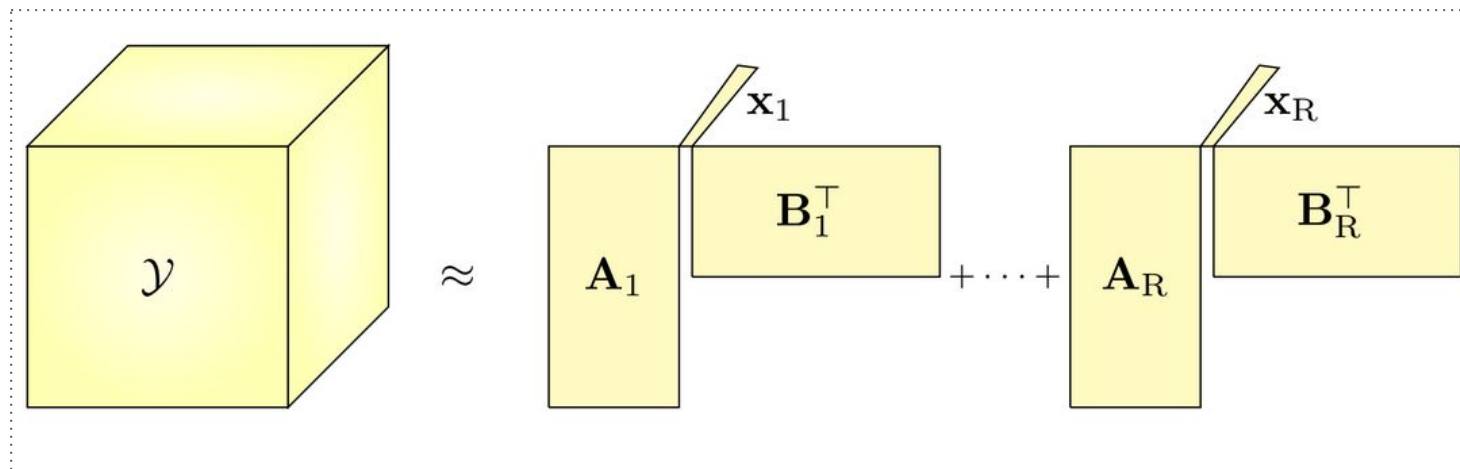


Figure : **BTD** model for **BSS**.

II. Tensor-Based Separation of Sums of Complex Exponentials

A. Low-rank Hankel source model

Discrete-time signals that can be modeled as linear combination of exponentials

- The signal $s(n)$ is represented by an all-pole model
- Mapped onto a Hankel matrix H_s
- Hankel matrix has rank at most $\min\{L, M\}$ ¹

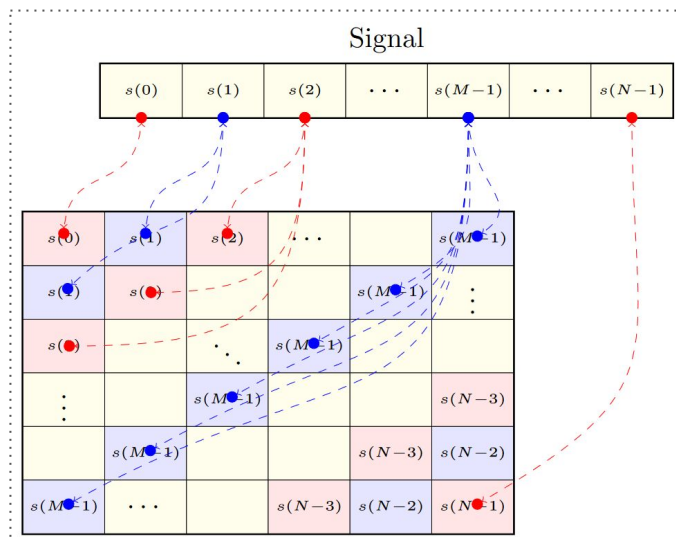
$$s(n) = \sum_{l=1}^L \alpha \exp(\zeta_l n), \quad n = 0, \dots, N - 1,$$

¹D. L. Boley, et. al (1997): “Vandermonde factorization of a Hankel matrix,” in Proc. Workshop Scientific Comput.

A. Low-rank Hankel source model

Hankel Matrix and Vandermonde Decomposition:

- Since the sources can be expressed as low-rank Hankel matrices, the signal separation can be performed via BTD.



$$\mathbf{H}_s = \mathbf{V}_s \text{Diag}(\alpha_1, \dots, \alpha_L) \mathbf{V}_s^T$$

$$\mathbf{V}_s \triangleq \begin{bmatrix} 1 & \dots & 1 \\ \exp(\zeta_1) & \dots & \exp(\zeta_L) \\ \vdots & & \vdots \\ \exp(\zeta_1(M-1)) & \dots & \exp(\zeta_L(M-1)) \end{bmatrix} \in \mathbb{C}^{M \times L}$$

Figure : Hankel mapping.

B. Separation of linear mixture via BTD

Spatial diversity plays an essential role on source estimation

- Each observed signal (\mathbf{Y}) is mapped onto a structured Hankel Matrix
- Where we stack each these matrices in the 3rd-mode of the tensor data ($M \times M \times K$)

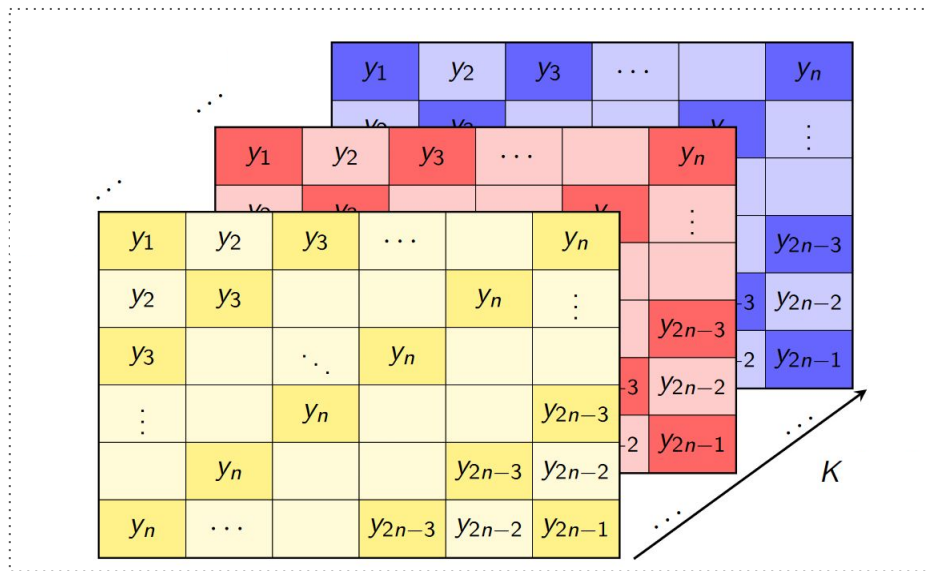


Figure : Tensor built of data Hankel matrices.

B. Separation of linear mixture via BTD

Source estimation and its associated Hankel matrix

- Each Hankel Matrix has rank L_r
- The data tensor \mathbf{y} consists of a sum of R blocks
- Each block is given by the tensor (outer) product of a low-rank Hankel matrix and a vector

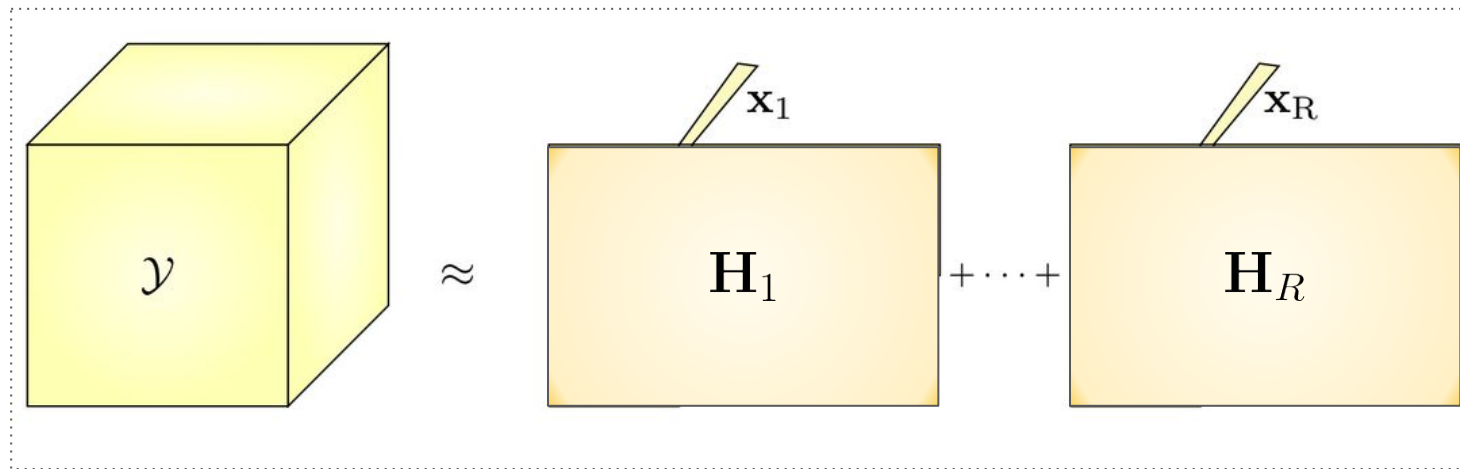


Figure : Structured-**BTD** model for **BSS**.

C. Approximate BTB

Existence and Uniqueness

- Fixed structure
- Prior Knowledge of (R, L_r)
- Complex values and require additional constraints (as a structured matrix)

$$f(\mathbf{A}, \mathbf{B}, \mathbf{X}) \triangleq \left\| \mathbf{y} - \sum_{r=1}^R (\mathbf{A}_r \mathbf{B}_r^T) \otimes \mathbf{x}_r \right\|_F^2$$

$$\min_{(\mathbf{A}, \mathbf{B}, \mathbf{X}) \in \mathcal{S}} f(\mathbf{A}, \mathbf{B}, \mathbf{X})$$

D. Shortcomings of the standard least-squares approach

Blocks and rank remarks

- Flexibility regarding the ranks L_r of the blocks (which can be very different from one another)
- Rank Inversion and overestimation
- Set of possible ranks is restricted (it becomes more severe as the number of blocks grows)

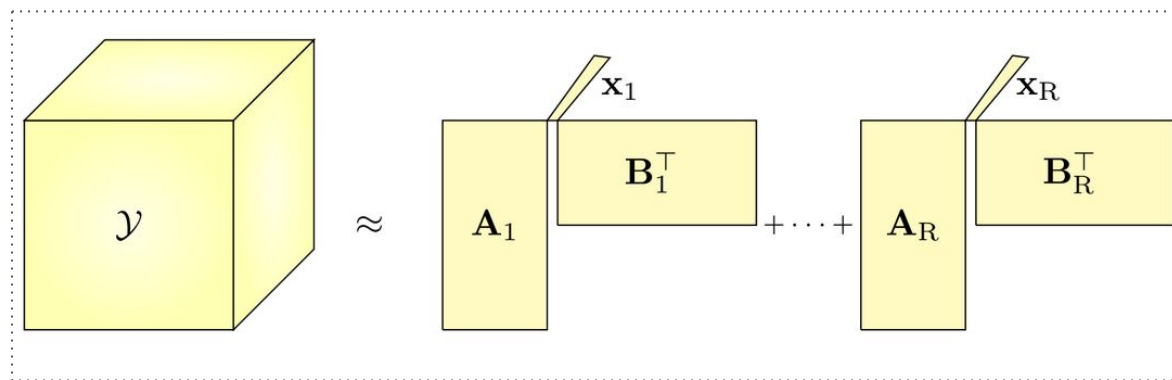


Figure : **BT-D** model for **BSS**.

III. Alternating Group Lasso Algorithm for BTD

A. Problem formulation

Constrained Alternating Group Lasso (CAGL) Approach

- Non-fixed structure minimizing $F(\mathbf{A}, \mathbf{B}, \mathbf{X})$ ensuring the Hankel structure
- Penalization term (γ) and $g(\mathbf{A}, \mathbf{B}, \mathbf{X})$ limiting the multilinear ranks and number of blocks
- Allows simultaneous estimation of (R, Lr) and model factors

$$F(\mathbf{A}, \mathbf{B}, \mathbf{X}) \triangleq f(\mathbf{A}, \mathbf{B}, \mathbf{X}) + \gamma g(\mathbf{A}, \mathbf{B}, \mathbf{X})$$

$$g(\mathbf{A}, \mathbf{B}, \mathbf{X}) \triangleq \|\mathbf{A}\|_{2,1} + \|\mathbf{B}\|_{2,1} + \|\mathbf{X}\|_{2,1}$$

$$\min_{(\mathbf{A}, \mathbf{B}, \mathbf{X}) \in \mathcal{S}} F(\mathbf{A}, \mathbf{B}, \mathbf{X})$$

B. Algorithm for unconstrained blocks

AGL Algorithm

- Solve Group Lasso Subproblems, where the factor \mathbf{A} is estimated depending on $\mathbf{B}^{(t-1)}$ and $\mathbf{X}^{(t-1)}$

Inputs: Data tensor \mathcal{Y} , penalty parameter γ , proximal term weight τ ,
initial point $(\mathbf{A}^{(0)}, \mathbf{B}^{(0)}, \mathbf{X}^{(0)})$
Outputs: Approximate BTD factors $(\mathbf{A}, \mathbf{B}, \mathbf{X})$

```

1:  $t \leftarrow 1$ 
2: while stopping criteria not met do
3:   Solve group lasso subproblem (12) to obtain  $\mathbf{A}^{(t)}$  from  $\mathbf{A}^{(t-1)}$ ,  

    $\mathbf{B}^{(t-1)}$  and  $\mathbf{X}^{(t-1)}$ 
4:   Solve group lasso subproblem in  $\mathbf{B}$  analogous to (12) to obtain  $\mathbf{B}^{(t)}$   

   from  $\mathbf{A}^{(t)}$ ,  $\mathbf{B}^{(t-1)}$  and  $\mathbf{X}^{(t-1)}$ 
5:   for  $r = 1, \dots, R$  do
6:      $L_r^{(t)} \leftarrow \text{rank}(\mathbf{A}_r^{(t)}(\mathbf{B}^{(t)})^T)$ 
7:      $(\mathbf{A}_r^{(t)}, \mathbf{B}_r^{(t)}) \leftarrow \text{slra}(\mathbf{A}_r^{(t)}(\mathbf{B}^{(t)})^T, L_r^{(t)})$ 
8:      $(\mathbf{A}_r^{(t)}, \mathbf{B}_r^{(t)}) \leftarrow (\mathbf{A}_r^{(t)} \mathbf{0}, [\mathbf{B}_r^{(t)} \mathbf{0}]_{(r, r=L_r^{(t)})})$ 
9:   Solve group lasso subproblem in  $\mathbf{X}$  analogous to (12) to obtain  $\mathbf{X}^{(t)}$   

   from  $\mathbf{A}^{(t)}$ ,  $\mathbf{B}^{(t)}$  and  $\mathbf{X}^{(t-1)}$ 
10:   $t \leftarrow t + 1$ 

```

Table I: Pseudocode for the unconstrained AGL algorithm (lines 5–8 must be omitted).

C. Handling linear constraints in \mathbf{H}_r

CAGL Algorithm

- Structured low-rank approximation (SRLA)

Inputs: Data tensor \mathcal{Y} , penalty parameter γ , proximal term weight τ ,
initial point $(\mathbf{A}^{(0)}, \mathbf{B}^{(0)}, \mathbf{X}^{(0)})$

Outputs: Approximate BTD factors $(\mathbf{A}, \mathbf{B}, \mathbf{X})$

```

1:  $t \leftarrow 1$ 
2: while stopping criteria not met do
3:   Solve group lasso subproblem (12) to obtain  $\mathbf{A}^{(t)}$  from  $\mathbf{A}^{(t-1)}$ ,
      $\mathbf{B}^{(t-1)}$  and  $\mathbf{X}^{(t-1)}$ 
4:   Solve group lasso subproblem in  $\mathbf{B}$  analogous to (12) to obtain  $\mathbf{B}^{(t)}$ 
     from  $\mathbf{A}^{(t)}$ ,  $\mathbf{B}^{(t-1)}$  and  $\mathbf{X}^{(t-1)}$ 
5:   for  $r = 1, \dots, R$  do
6:      $L_r^{(t)} \leftarrow \text{rank}(\mathbf{A}_r^{(t)}(\mathbf{B}^{(t)})_r^\top)$ 
7:      $(\mathbf{A}_r^{(t)}, \mathbf{B}_r^{(t)}) \leftarrow \text{srla}(\mathbf{A}_r^{(t)}(\mathbf{B}_r^{(t)})^\top, L_r^{(t)})$ 
8:      $(\mathbf{A}_r^{(t)}, \mathbf{B}_r^{(t)}) \leftarrow ([\mathbf{A}_r^{(t)} \mathbf{0}_{I \times L - L_r^{(t)}}], [\mathbf{B}_r^{(t)} \mathbf{0}_{I \times L - L_r^{(t)}}])$ 
9:   Solve group lasso subproblem in  $\mathbf{X}$  analogous to (12) to obtain  $\mathbf{X}^{(t)}$ 
     from  $\mathbf{A}^{(t)}$ ,  $\mathbf{B}^{(t)}$  and  $\mathbf{X}^{(t-1)}$ 
10:   $t \leftarrow t + 1$ 

```

$$\hat{\mathbf{H}}_r \approx \hat{\mathbf{A}}_r \hat{\mathbf{B}}_r^\top \in \mathcal{U}$$

Table I: Pseudocode for constrained AGL algorithm.

IV. Numerical Evaluation on Random Block Term Decomposition Models

A. Unconstrained BTD

Experiment Setup

- \mathbf{A} , \mathbf{B} , \mathbf{X} and \mathbf{N} in an i.i.d. fashion from the standard normal distribution.
- Algebraic method with rank estimates $L_1 = L_2 = L_3 = L$
- AGL is run from this initial solution and using $\gamma = \gamma_0$
- Apply a γ -sweeping procedure inspired by solution-path techniques
- Overestimation and true parameters
- SNR of 20 dB

$$\mathbf{y}_0 = \sum_{r=1}^R (\mathbf{A}_r \mathbf{B}_r^T) \otimes \mathbf{x}_r$$

$$\mathbf{y} = \mathbf{y}_0 + \sigma_{\mathbf{N}} \mathbf{N}$$

$$\text{NMSE}(\hat{\mathbf{A}}, \hat{\mathbf{B}}, \hat{\mathbf{X}}) \triangleq \frac{1}{R} \sum_{r=1}^R \frac{\|(\mathbf{A}_r \mathbf{B}_r^T) \otimes \mathbf{x}_r - (\hat{\mathbf{A}}_r \hat{\mathbf{B}}_r^T) \otimes \hat{\mathbf{x}}_r\|_F^2}{\|(\mathbf{A}_r \mathbf{B}_r^T) \otimes \mathbf{x}_r\|_F^2}$$

A. Unconstrained BTD

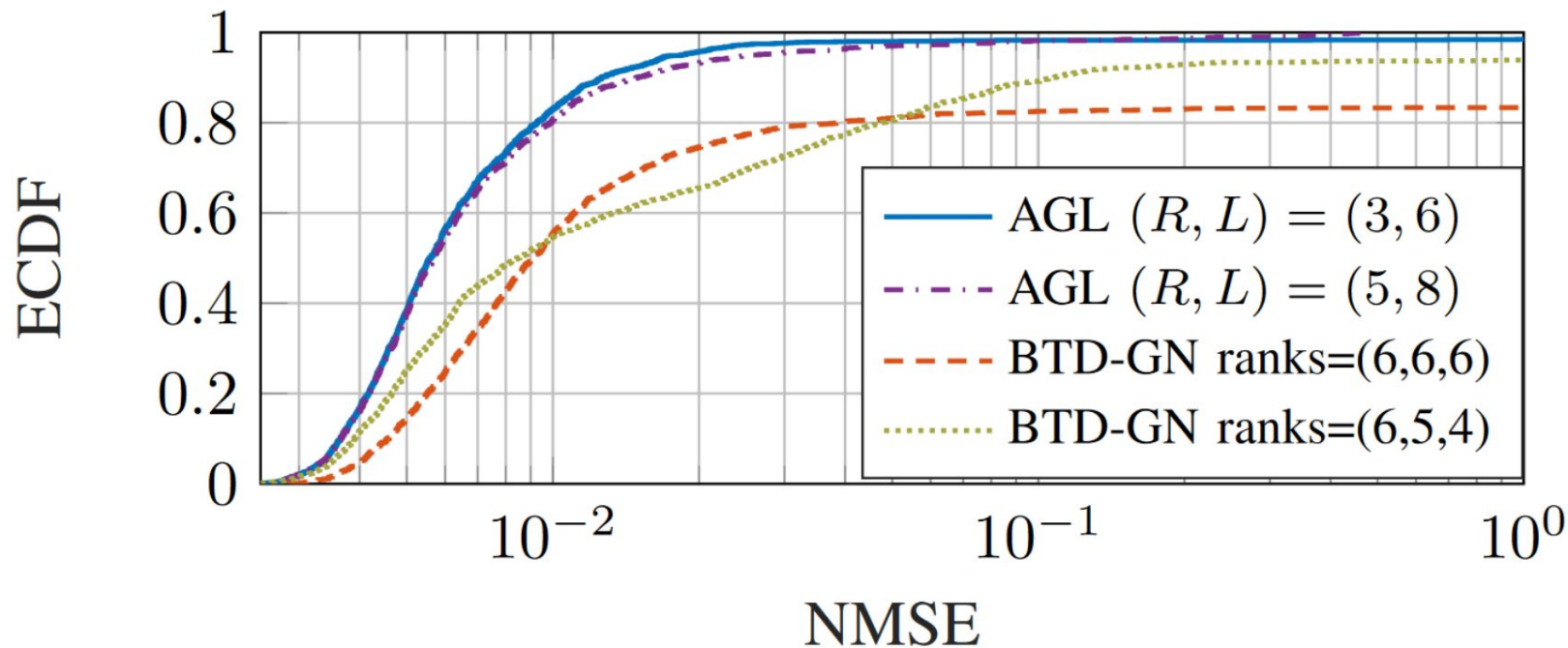


Figure 1: Empirical CDFs of NMSE over estimated blocks by AGL and BTD-GN for 500 realizations.

A. Unconstrained BTD

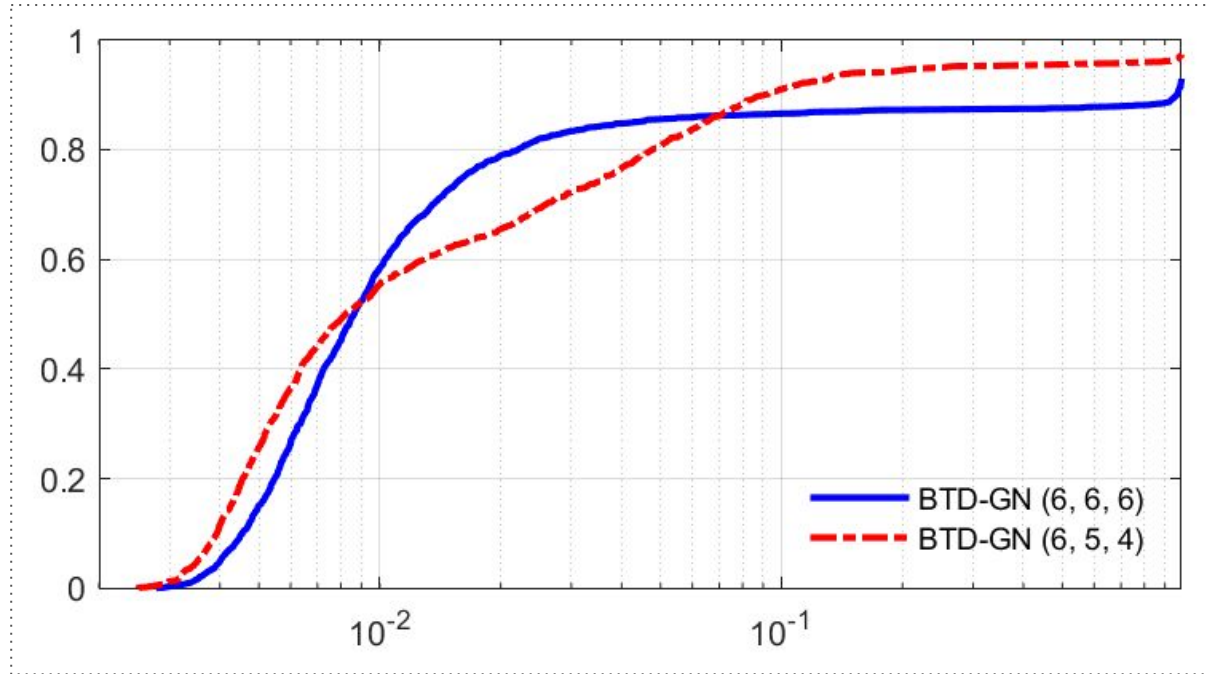


Figure: Empirical CDFs of NMSE over estimated blocks by BTD-GN for 500 realizations.

A. Unconstrained BTD

	AGL (3, 6)	AGL (5, 8)	BTD-GN (6, 5, 4)	BTD-GN (6, 6, 6)
ECDF < 0.01	83%	80%	58.8%	58.8%
True model detection	97.6%	87.6%	-	-
Rank Inversion	-	-	51%	-

A. Unconstrained BTD

Experiment Setup

- \mathbf{A} , \mathbf{B} , \mathbf{X} and \mathbf{N} in an i.i.d. fashion from the standard normal distribution.
- Constrained to employ an arbitrarily initial solution (random)
- AGL is run from this initial solution and using $\gamma = \gamma_0$
- Same γ -sweeping procedure
- For BTD-GN and AGL, 30 and 12 initializations taken, respectively
- SNR of 10 dB

Constrained Scenario

- All algorithms are followed by Cadzow's algorithm to enforce the low-rank Hankel constrain

A. Unconstrained BTD

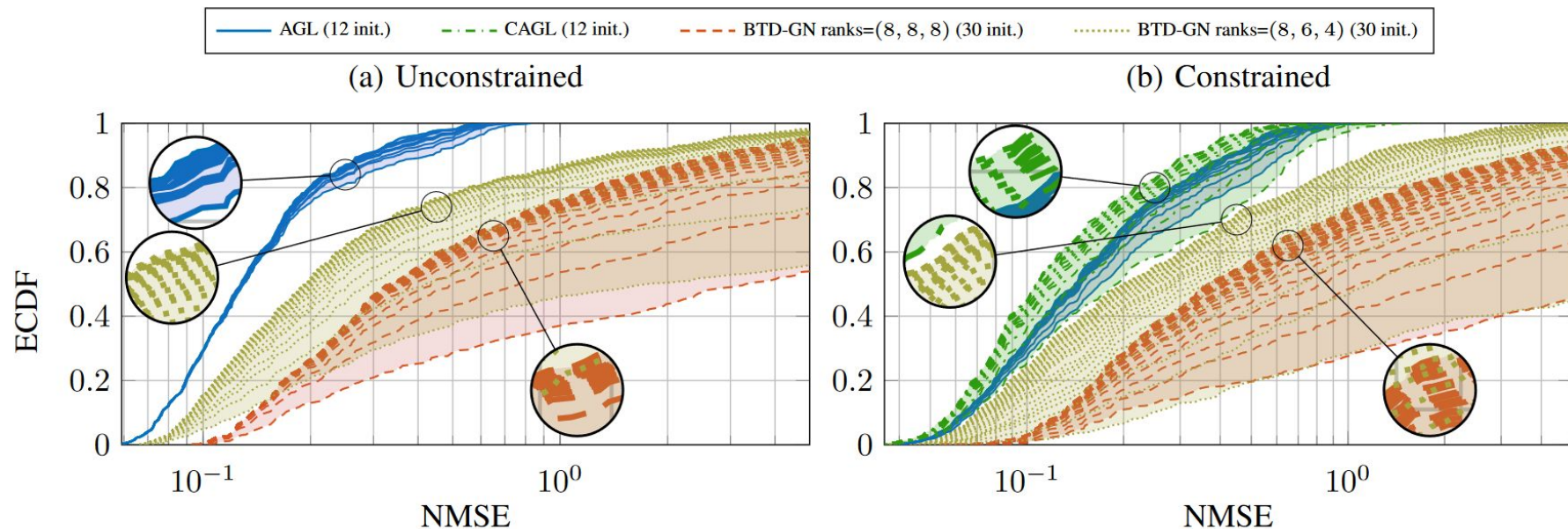


Figure 2: Empirical CDFs of NMSE over estimated blocks by AGL and BTD-GN for 500 realizations, with 12 and 30 initializations, respectively. The best solution among is chosen.

A. Unconstrained BTD

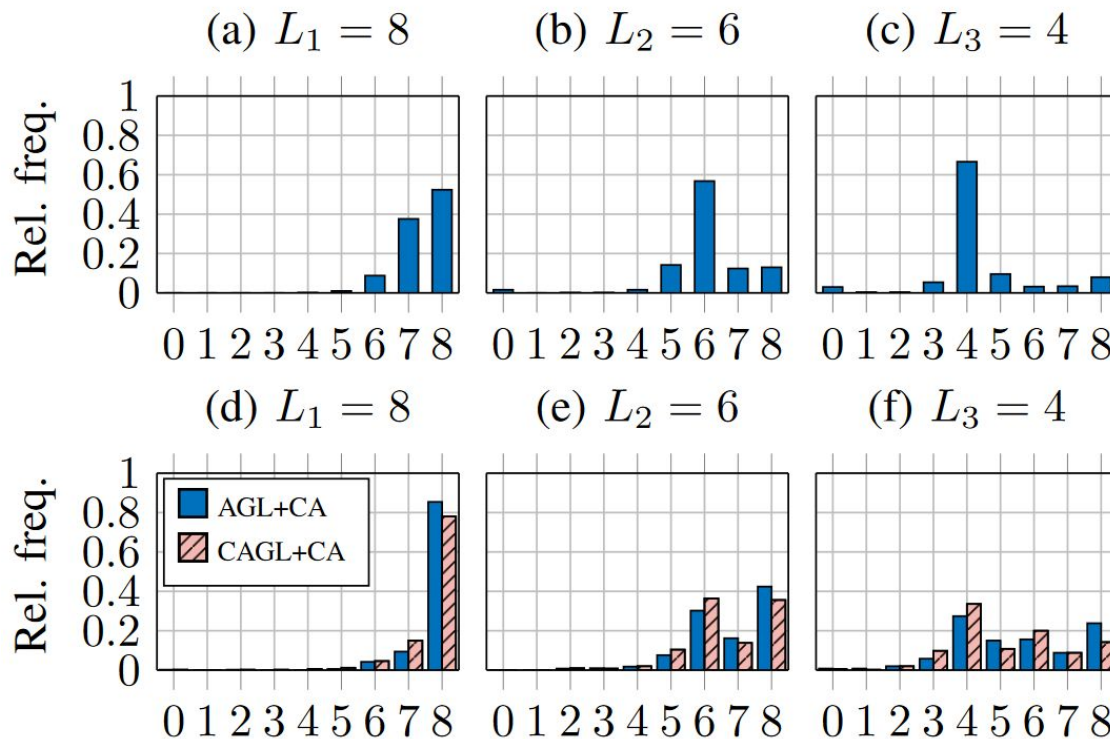


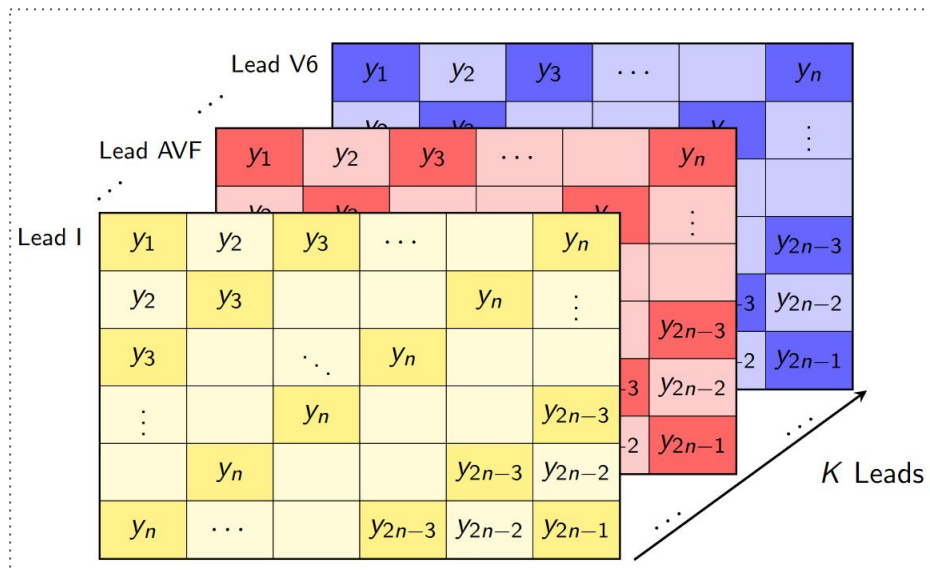
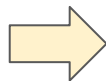
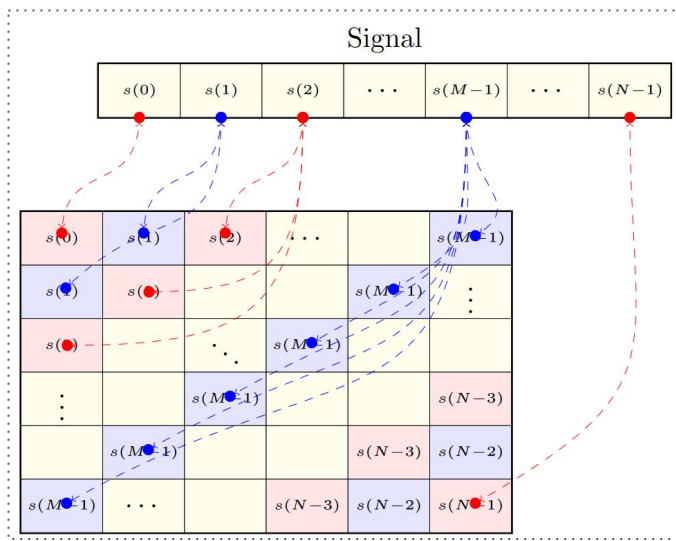
Figure 3: Proportion of block ranks estimated by AGL and CAGL with SNR = 10dB.

V. Experimental Results with ECG Data

A. Tensor representation of ECG signals

Experimental Setup

- Each ECG lead mapped onto a Hankel matrix. Stack in the data tensor 3rd-mode.



B. Semi-synthetic AF data

Stridh Model

- Sum real ventricular activity and a signal that mimics the sawtooth pattern (**AF**)
- Random spatial signature and Additive white Gaussian noise (AWGN)

$$\mathbf{Y} = \mathbf{V} + \alpha \mathbf{x} \mathbf{s}^T + \mathbf{N} \in \mathbb{R}^{12 \times N}$$

$$s(n) = - \sum_{p=1}^P a_p(n) \sin(p \theta(n))$$

Model	P	a	Δa	f_a	F_s	f_0	Δf	F_f
1	5	150	50	0.08	1000	6	0.2	0.10
2	3	60	18	0.50	1000	8	0.3	0.23

Table III: Parameters of the synthetic AA signal model.

B. Semi-synthetic AF data

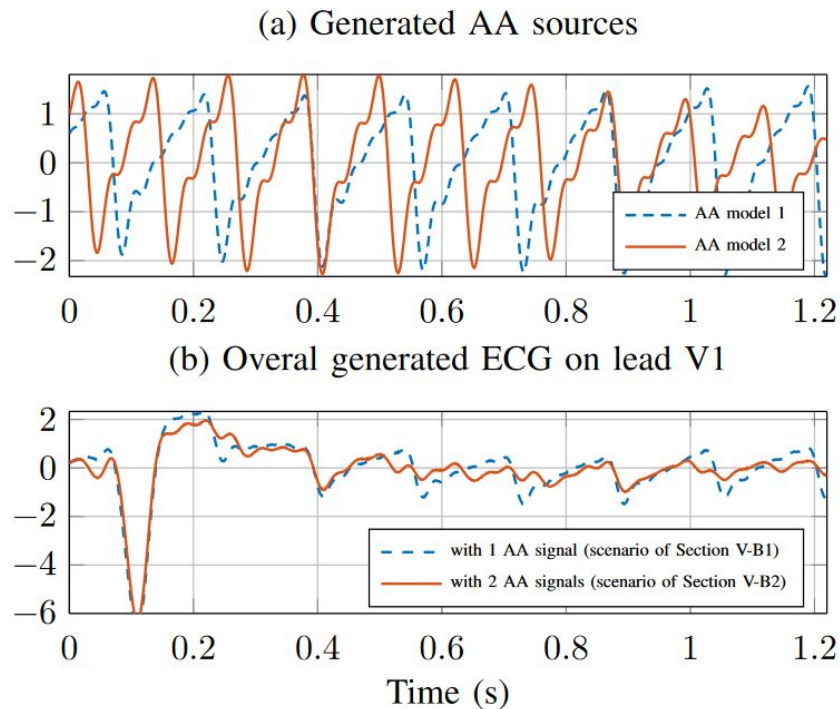


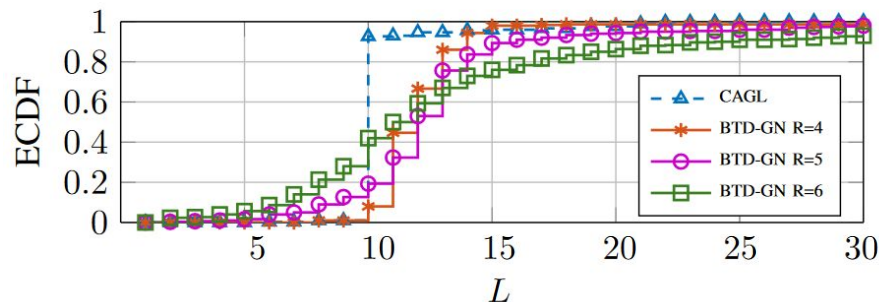
Figure 5: Examples of generated semi-synthetic models

B. Semi-synthetic AF data

BTD-GN vs CAGL

- **BTD-GN**: Produces good results with a proper combination of R , L and initial point.
- **CAGL**: Only requires choosing a reasonable range for γ , and behaves much more robustly with regard to initialization.

(a) 1 AA source



(b) 2 AA sources

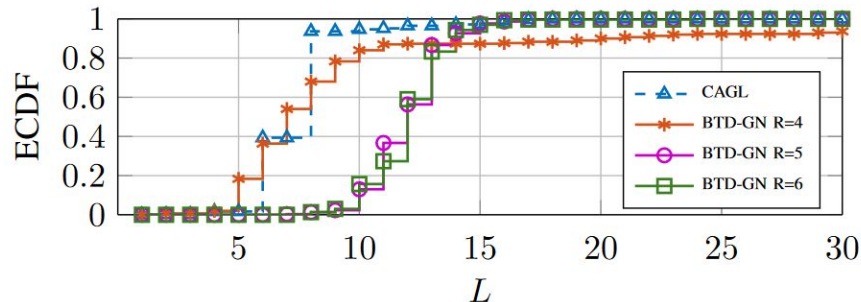


Figure 6: Empirical distribution of rank chosen by **CAGL** for the **AA** source and of rank L yielding the best **AA** extraction for **BTD-GN** with different numbers of blocks R .

B. Semi-synthetic AF data

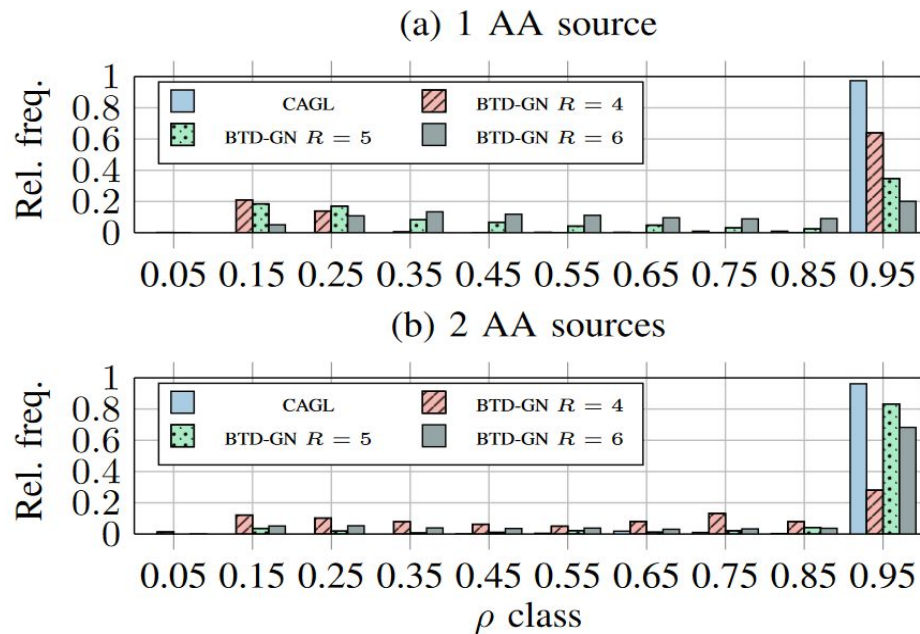


Figure 7: Histogram of computed correlation coefficient ρ (in absolute value) between true and estimated AA sources.

C. Real **AF** data

12-lead ECG recordings

- Cardiology Department of Princess Grace Hospital
- **Very short ECG** segments: 1.08 to 1.40 seconds (Largest TQ interval)
- Zero-phase forward-backward Type-II Chebyshev bandpass filter (cutoff: 0.5 and 40 Hz)

TABLE IV: Block ranks of the ECG sources extracted by CAGL and characteristics of the potential AA sources.

Patient	Non-AA source ranks	AA source	SC (%)	DF (Hz)	$\hat{\kappa}$	AA source rank
1	3, 9, 10, 16, 18	1	80.23	6.44	163.69	8
2	28, 32	1	59.36	6.20	116.77	29
		2	82.05	6.20	163.77	12
3	21, 27, 29	1	66.13	6.20	132.29	20
4	8, 16, 20	1	74.51	5.96	196.16	10
5	32, 38, 39	1	91.70	5.72	348.42	10
		2	78.63	5.01	166.95	21

Table IV: Block ranks of the **ECG** sources extracted by **CAGL** and characteristics of the potential **AA** sources.

C. Real AF data

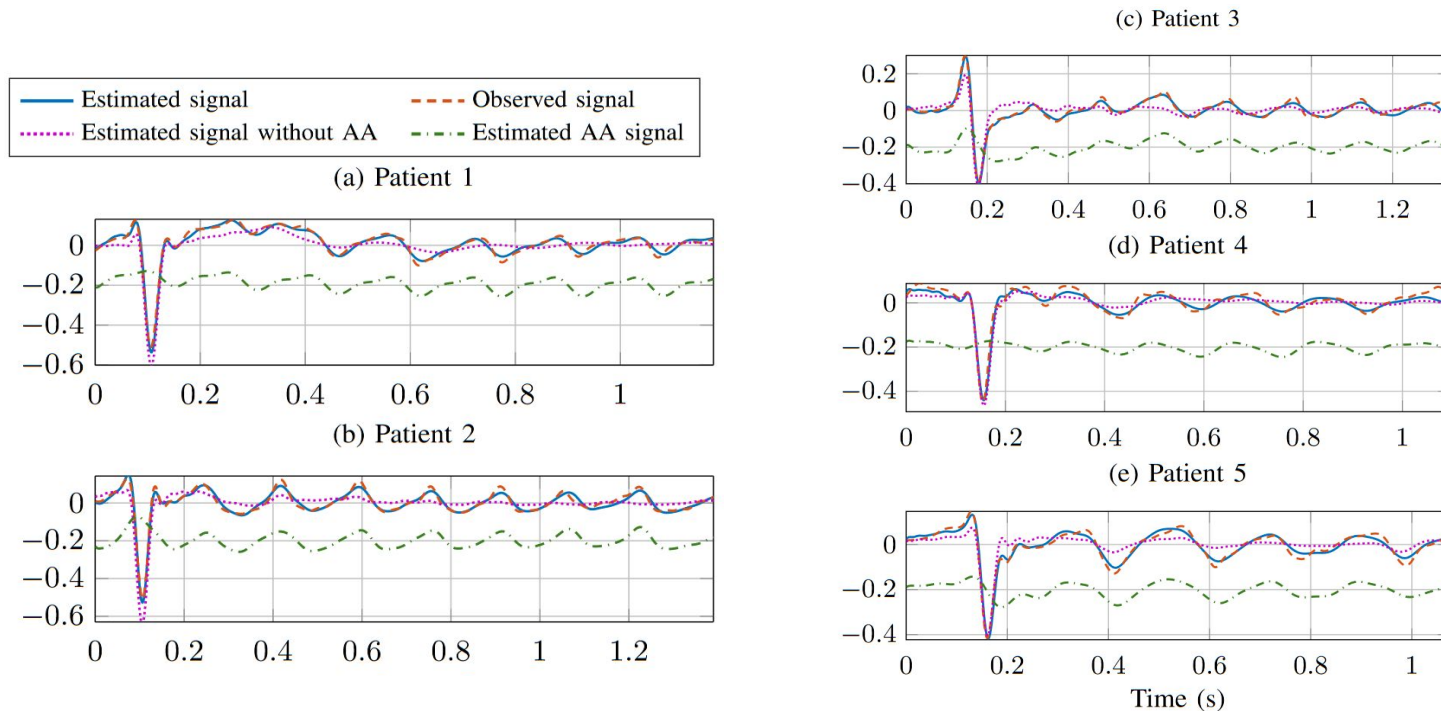


Figure 8: Results produced by CAGL with real-world ECG data: observed and estimated signals at lead V1. Estimated **AA** signals are vertically shifted for ease of visualization.

C. Real AF data

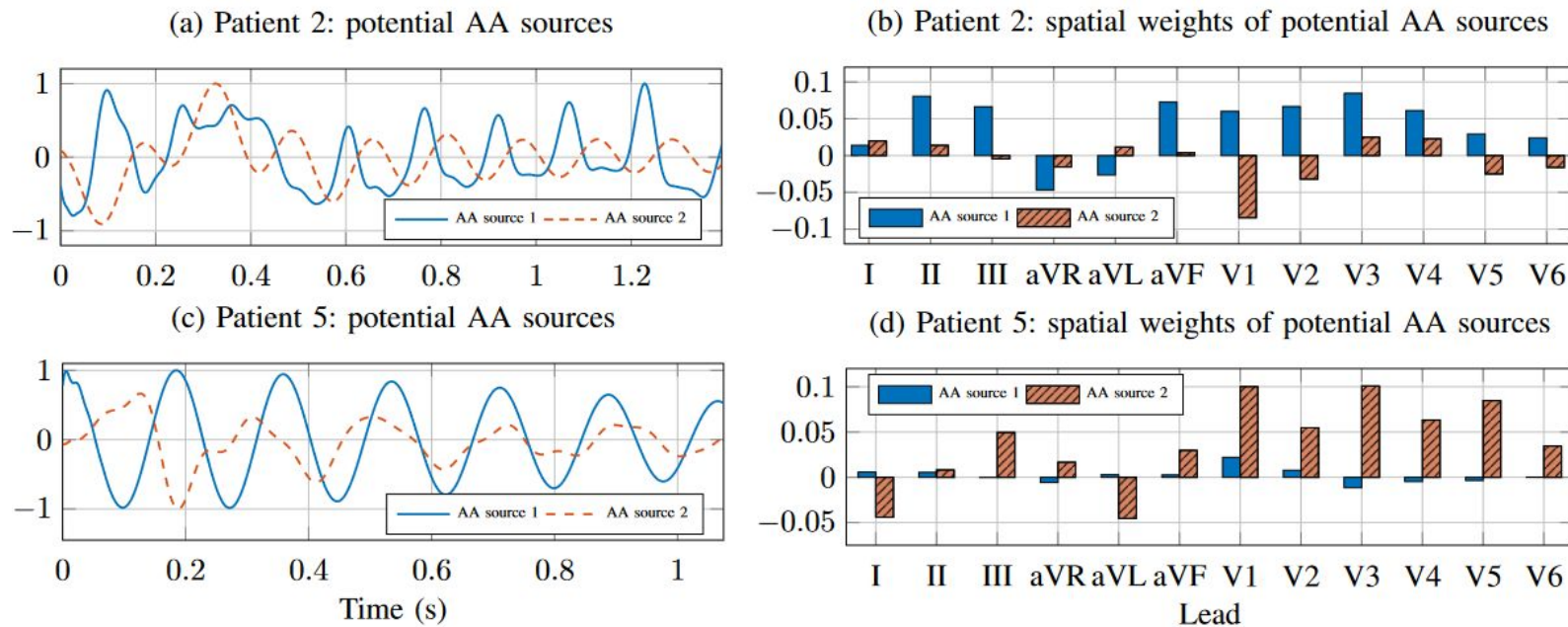


Figure 9: Results produced by CAGL with ECG data from Patients 2 and 5.

VI. Conclusion

VI. Conclusion

Contributions

- Allows simultaneous estimation of model parameters and factors
- The resulting subproblems can be solved by existing group lasso method
- Experimental results show that AGL approach and its constrained version is much more robust with respect to initialization than the conventional least-squares approach

Clinical Impact

- Extract AA by using a structured low-rank approximation method
- Without the need of choosing structural parameters *a priori*

Further Work

- How to automatically tune γ in practice (CAGL)
- Physiological interpretation of characteristics and spatial signatures diversity
- Multiple atrial sources analysis and enlarge database of AF patients

Supplementary Material

Algorithm for unconstrained blocks

AGL e CAGL

- Solve Group Lasso Subproblems, where $w_A^{(t)}(\mathbf{A})$ is a linear map depending on $\mathbf{B}^{(t-1)}$ and $\mathbf{X}^{(t-1)}$

$$\min_{\mathbf{A} \in \mathbb{C}^{I \times LR}} \frac{1}{2} \|\mathbf{y} - \mathcal{W}_{\mathbf{A}}^{(t)}(\mathbf{A})\|_F^2 + \gamma \|\mathbf{A}\|_{2,1} + \frac{\tau}{2} \|\mathbf{A} - \hat{\mathbf{A}}^{(t-1)}\|_F^2$$

Inputs: Data tensor \mathbf{y} , penalty parameter γ , proximal term weight τ , initial point $(\mathbf{A}^{(0)}, \mathbf{B}^{(0)}, \mathbf{X}^{(0)})$

Outputs: Approximate BTD factors $(\mathbf{A}, \mathbf{B}, \mathbf{X})$

```

1:  $t \leftarrow 1$ 
2: while stopping criteria not met do
3:   Solve group lasso subproblem (12) to obtain  $\mathbf{A}^{(t)}$  from  $\mathbf{A}^{(t-1)}$ ,  $\mathbf{B}^{(t-1)}$  and  $\mathbf{X}^{(t-1)}$ 
4:   Solve group lasso subproblem in  $\mathbf{B}$  analogous to (12) to obtain  $\mathbf{B}^{(t)}$  from  $\mathbf{A}^{(t)}$ ,  $\mathbf{B}^{(t-1)}$  and  $\mathbf{X}^{(t-1)}$ 
5:   for  $r = 1, \dots, R$  do
6:      $L_r^{(t)} \leftarrow \text{rank}(\mathbf{A}_r^{(t)}(\mathbf{B}^{(t)})^\top)$ 
7:      $(\mathbf{A}_r^{(t)}, \mathbf{B}_r^{(t)}) \leftarrow \text{srra}(\mathbf{A}_r^{(t)}(\mathbf{B}_r^{(t)})^\top, L_r^{(t)})$ 
8:      $(\mathbf{A}_r^{(t)}, \mathbf{B}_r^{(t)}) \leftarrow ([\mathbf{A}_r^{(t)} \mathbf{0}_{I \times L - L_r^{(t)}}], [\mathbf{B}_r^{(t)} \mathbf{0}_{I \times L - L_r^{(t)}}])$ 
9:   Solve group lasso subproblem in  $\mathbf{X}$  analogous to (12) to obtain  $\mathbf{X}^{(t)}$  from  $\mathbf{A}^{(t)}$ ,  $\mathbf{B}^{(t)}$  and  $\mathbf{X}^{(t-1)}$ 
10:   $t \leftarrow t + 1$ 

```

Table I: Pseudocode for the unconstrained AGL algorithm (lines 5–8 must be omitted).

Constrained BTD: Further Results

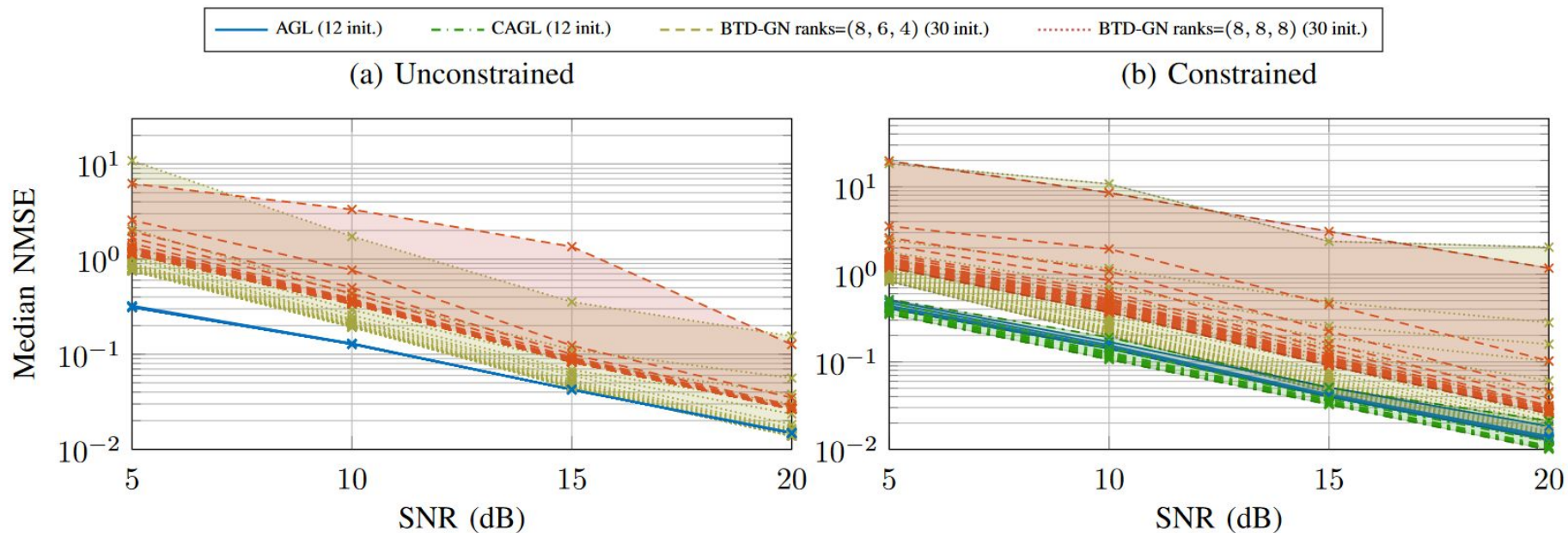


Figure 4: Median NMSE over estimated blocks attained by AGL and BTD-GN for 500 realizations of a noisy random BTD model in the unconstrained and (Hankel-)constrained scenarios.

Unconstrained BTD

Cadzow's Algorithm (CA)

- Performs alternating projections onto the Hankel subspace with rank bounded by a prescribed value.
- Approximations provided by CA are not (locally) optimal, but they are often satisfying in practice.

Inputs: Data matrix \mathbf{Y} , target rank L , tolerance ϵ_{CA} and maximum number of iterations T_{CA}

Outputs: Low-rank Hankel approximation \mathbf{H} of \mathbf{Y}

```
1: Initialization:  $t \leftarrow 1$ ,  $\mathbf{H}^{(0)} \leftarrow \mathbf{Y}$ 
2: for  $t = 1, 2, \dots$  do
3:    $\mathbf{H}^{(t)} \leftarrow \mathcal{P}_{\mathcal{H}}(\mathbf{H}^{(t-1)})$ 
4:   Compute the SVD:  $\mathbf{H}^{(t)} = \mathbf{U}\Sigma\mathbf{V}^T$ 
5:   Truncate the computed SVD at rank  $L$ :  $\mathbf{H}^{(t)} \leftarrow \mathbf{U}_L \Sigma_L \mathbf{V}_L^T$ 
6:   if  $\|\mathbf{H}^{(t)} - \mathbf{H}^{(t-1)}\|_F < \epsilon_{\text{CA}} \|\mathbf{H}^{(t-1)}\|_F$  or  $t = T_{\text{CA}}$  then
7:     break for loop and output  $\mathbf{H} = \mathbf{H}^{(t)}$ 
```

Table II: Pseudocode for the Cadzow's algorithm.

Stridh Model

Details

- Sum real ventricular activity and a signal that mimics the sawtooth pattern (**AF**)
- Random spatial signature and Additive white Gaussian noise (AWGN)

$$\mathbf{Y} = \mathbf{V} + \alpha \mathbf{x} \mathbf{s}^T + \mathbf{N} \in \mathbb{R}^{12 \times N}$$

$$a_p(n) = \frac{2}{p\pi} \left[a + \Delta a \sin \left(2\pi \frac{f_a}{F_s} n \right) \right]$$

$$s(n) = - \sum_{p=1}^P a_p(n) \sin(p\theta(n))$$

$$\theta(n) = 2\pi \frac{f_0}{F_s} n + \left(\frac{\Delta f}{F_f} \right) \sin \left(2\pi \frac{F_f}{F_s} n \right)$$

Model	P	a	Δa	f_a	F_s	f_0	Δf	F_f
1	5	150	50	0.08	1000	6	0.2	0.10
2	3	60	18	0.50	1000	8	0.3	0.23

Table III: Parameters of the synthetic AA signal model.