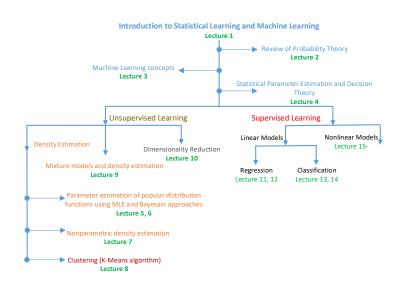
Statistical Learning and Machine Learning

Lecture 13 - Linear Models for Classification 1

October 10, 2021

Course overview and where do we stand



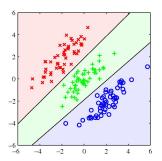
Objectives of the lecture

- Linear models for classification
 - Discriminant functions
 - Least squares for classification
 - The perceptron algorithm

Linear classification

The goal of classification is to assign an input vector \mathbf{x} to one of the K classes C_k , k = 1, ..., K:

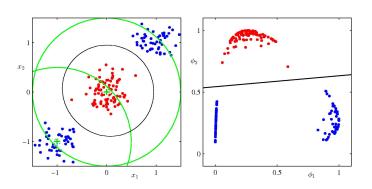
- The input space is divided into K decision regions, separated by decision boundaries or decision surfaces
- **Linear models**: are those for which decision boundaries are linear functions of x i.e., $w^T x + w_0$



Decision boundaries for a linearly separable data set

Generalized linear classification

- Generalized linear classification corresponds to using linear combination of (nonlinearly) transformed vectors $\phi(\mathbf{x})$ i.e., $y(\mathbf{x}) = f(\mathbf{w}^T \phi(\mathbf{x}))$.
- Appropriately chosen linear models of basis functions $\phi(x)$ can be equivalent to nonlinear models in x



Three approaches to classification

- Finding a function y(x) called discriminant function which maps a new input x_* onto a class label.
- **Quantizative models:** Determining class-conditional densities $p(\mathbf{x}|\mathcal{C}_k)$ or joint distributions $p(\mathbf{x}, \mathcal{C}_k)$, followed by the estimation of posterior densities:

$$p(C_k|\mathbf{x}) = \frac{p(\mathbf{x}|C_k)p(C_k)}{p(\mathbf{x})} = \frac{p(\mathbf{x}|C_k)p(C_k)}{\sum_j p(\mathbf{x}|C_j)p(C_j)}$$

Finally, decision theory is used to determine class membership for new x.

Discriminative models: Obtaining posterior class probabilities $p(C_k|x)$ directly, followed by discrimination.

Linear discriminant function:

$$y(\mathbf{x}) = \mathbf{w}^{\mathsf{T}} \mathbf{x} + w_0 \tag{1}$$

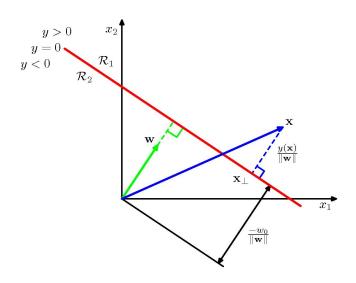
w is called *weight vector* and w_0 is called *bias* $(-w_0$ is called *threshold*).

Classification rule:

- Assign x to class C_1 if $y(x) \ge 0$
- Assign x to class C_2 if y(x) < 0

The decision boundary at y(x) = 0, which corresponds to a (D-1)-dimensional hyperplane in \mathbb{R}^D .





• w is orthogonal to any vector lying on the decision surface. How? Consider two arbitrary points x_A and x_B on the decision boundary or hyperplane, then

$$y(\mathbf{x}_A) = y(\mathbf{x}_B) = 0 \Rightarrow \mathbf{w}^T(\mathbf{x}_A - \mathbf{x}_B) = 0.$$
 (2)

Thus, **w** is orthogonal to the vector $(\mathbf{x}_A - \mathbf{x}_B)$.

The normal distance from the origin to the decision hyperplane is:

$$\frac{\mathbf{w}^T \mathbf{x}}{\|\mathbf{w}\|} = -\frac{w_0}{\|\mathbf{w}\|}.\tag{3}$$

Thus, w_0 determines the location of the decision hyperplane.

- The value of y(x) gives a signed measure of the perpendicular distance r of x to the decision hyperplane:
 - Let x be an arbitrary vector and x⊥ be its orthogonal projection to the decision hyperplane:

$$\mathbf{x} = \mathbf{x}_{\perp} + r \frac{\mathbf{w}}{\|\mathbf{w}\|}.\tag{4}$$

- We multiply with \mathbf{w}^T and add w_0 both sides
- We use:
 - $y(x) = w^T x + w_0$
 - $y(x_{\perp}) = w^T x_{\perp} + w_0 = 0$
- Then:

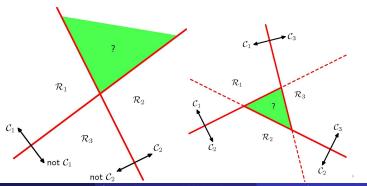
$$r = \frac{y(x)}{\|\mathbf{w}\|}. (5)$$



Discriminant Functions: K > 2 classes

We can extend binary discriminant functions to K-class discriminant functions using two schemes:

- One-versus-rest: Use K-1 binary discriminant functions, each of which separating points in C_k and not in that class
- One-versus-one: Use K(K-1)/2 binary discriminant functions, one for every possible pair of classes C_k , $C_{i\neq k}$.



Discriminant Functions: K > 2 classes

Single K class Discriminant: comprises K linear functions of the form:

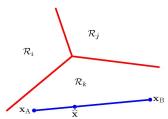
$$y_k(\mathbf{x}) = \mathbf{w}_k^T \mathbf{x} + w_{k0}. \tag{6}$$

The classification rule:

assigning x to class C_k if $y_k(x) > y_j(x)$ for all $j \neq k$.

The decision boundary between C_k and C_j is given by $y_k(\mathbf{x}) = y_j(\mathbf{x})$, corresponding to

$$(\mathbf{w}_k - \mathbf{w}_j)^T \mathbf{x} + (w_{k0} - w_{j0}) = 0.$$
 (7)



Each class C_k , k = 1, ..., K is described by:

$$y_k(\mathbf{x}) = \mathbf{w}_k^T \mathbf{x} + w_{k0} = \tilde{\mathbf{w}}_k^T \tilde{\mathbf{x}}$$
 (8)

where $\tilde{\boldsymbol{w}}_k = [w_{0k}, \boldsymbol{w}_k^T]^T$, and $\tilde{\boldsymbol{x}} = [1, \boldsymbol{x}^T]^T$.

We can group all K outputs together:

$$\mathbf{y}(\mathbf{x}) = \tilde{\mathbf{W}}^{\mathsf{T}} \tilde{\mathbf{x}} \tag{9}$$

where $\tilde{\boldsymbol{W}} = [\tilde{\boldsymbol{w}}_1, \dots, \tilde{\boldsymbol{w}}_K]$.

The classification rule is:

assign x to class C_k if $y_k(x) > y_j(x)$ for all $j \neq k$.



Problem: Given a training set $\{x_n, t_n\}$ for n = 1, ..., N, we want to estimate the parameters \tilde{W} of the regression model.

We use the 1-of-K binary coding scheme for t. Denoting

$$\tilde{\mathbf{X}} = \begin{bmatrix} \tilde{\mathbf{x}}_{1}^{T} \\ \tilde{\mathbf{x}}_{2}^{T} \\ \vdots \\ \tilde{\mathbf{x}}_{N}^{T} \end{bmatrix} \text{ and } \tilde{\mathbf{T}} = \begin{bmatrix} \tilde{\mathbf{t}}_{1}^{T} \\ \tilde{\mathbf{t}}_{2}^{T} \\ \vdots \\ \tilde{\mathbf{t}}_{N}^{T} \end{bmatrix}$$
(10)

Cost function: The sum-of-squares error for all training data points is

$$E_D(\tilde{\boldsymbol{W}}) = \frac{1}{2} Tr\{(\tilde{\boldsymbol{X}} \tilde{\boldsymbol{W}} - \boldsymbol{T})^T (\tilde{\boldsymbol{X}} \tilde{\boldsymbol{W}} - \boldsymbol{T})\}$$

By minimizing the above cost function w.r.t $\tilde{\boldsymbol{W}}$, we get

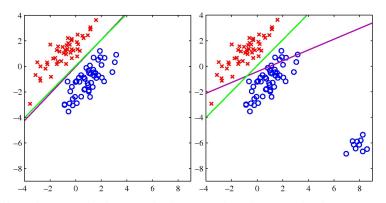
$$\tilde{\mathbf{W}} = \tilde{\mathbf{X}}^{\dagger} \mathbf{T} \tag{11}$$

where $ilde{m{X}}^\dagger$ is the pseudo-inverse of the matrix and is given by

$$\tilde{\boldsymbol{X}}^{\dagger} = (\tilde{\boldsymbol{X}}^{T} \tilde{\boldsymbol{X}})^{-1} \tilde{\boldsymbol{X}}^{T} \tag{12}$$

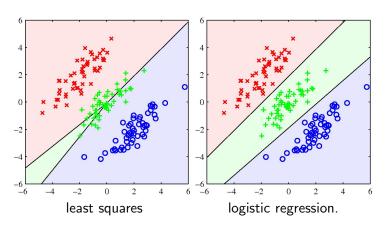
How is this different from the least squares solution for the regression problem?

Least squares-based classification is not robust to outliers.



Magenta line corresponds to least squares-based regression and green line corresponds to logistic regression.

Not optimal even for linearly separable data sets



Given an input vector x, the Perceptron algorithm:

- ullet uses a fixed nonlinear transformation $\phi({m x})$ (also including $\phi_0({m x})=1)$
- uses a generalized linear model:

$$y(\mathbf{x}) = f(\mathbf{w}^T \phi(\mathbf{x})) \tag{13}$$

where:

$$f(a) = \begin{cases} +1, & a \ge 0 \\ -1, & a < 0. \end{cases}$$
 (14)

is the nonlinear activation function.

• Target values: t = +1 for C_1 and t = -1 for C_2

Goal: Finding \boldsymbol{w} that is optimal for classification (in some sense).

We want a w such that:

- ullet for all $oldsymbol{x}_n \in \mathcal{C}_1$ we have $oldsymbol{w}^T \phi(oldsymbol{x}_n) > 0$
- for all $\mathbf{x}_n \in \mathcal{C}_2$ we have $\mathbf{w}^T \phi(\mathbf{x}_n) < 0$

Using $t_n \in \{-1, +1\}$ we can unify the two cases to: $\mathbf{w}^T \phi(\mathbf{x}_n) t_n > 0$.

The Perceptron criterion:

- assigns zero error for any correclty classified data point
- assigns an error equal to $-\mathbf{w}^T \phi(\mathbf{x}_n) t_n$ to \mathbf{x}_n if it is misclassified.

$$E_P(\mathbf{w}) = -\sum_{n \in \mathcal{M}} \mathbf{w}^T \phi(\mathbf{x}_n) t_n, \tag{15}$$

where \mathcal{M} is the set of misclassified data points.



- Randomly initialize w⁰
- Iterate (until convergence)
 - shuffle the training vectors \mathbf{x}_n , n = 1, ..., N
 - **2** set $E_P(w) = 0$
 - **3** iterate through the training vectors \mathbf{x}_{τ}
 - **4** if \mathbf{x}_{τ} is misclassified:
 - Compute the gradient $\nabla E_P(\mathbf{w}) = -\phi(\mathbf{x}_{\tau})t_n$
 - Update the weight vector

$$\boldsymbol{w}^{(\tau)} = \boldsymbol{w}^{(\tau-1)} - \eta \nabla E_{P}(\boldsymbol{w}) = \boldsymbol{w}^{(\tau-1)} + \eta \phi(\boldsymbol{x}_{\tau}) t_{n}$$
 (16)

where $\eta > 0$ is a *learning rate* parameter.

Limitations: Applicable only for linearly separable data and for $\mathcal{K}=2$ classes



