

f-26-jupyter-tri-qr

May 6, 2021

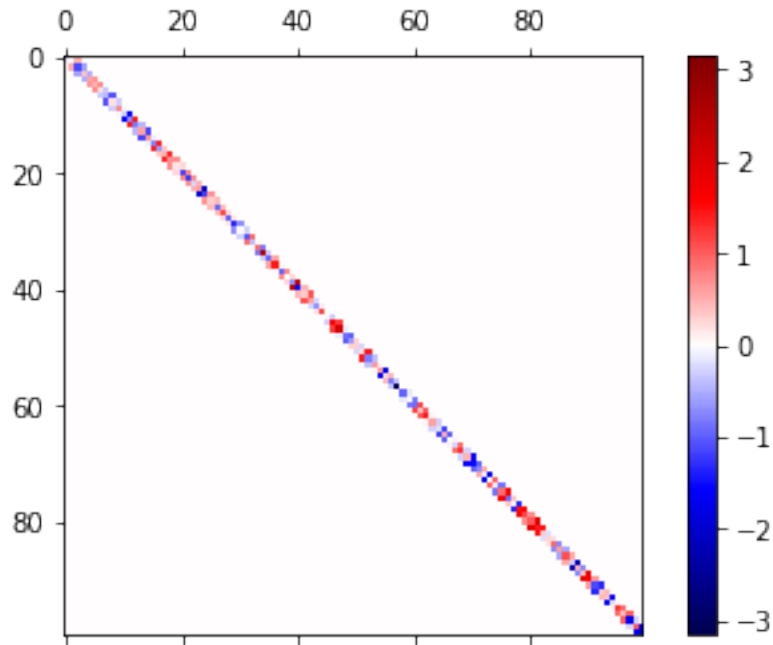
```
[1]: import matplotlib.pyplot as plt
import numpy as np
```

```
[20]: def heat_map(a):
    fig, ax = plt.subplots()
    ax.set_aspect('equal')
    mx = a.max()
    mi = a.min()
    r = np.max([mx, -mi])
    if r < 20 * np.finfo(float).eps:
        r = 1
    im = ax.matshow(a, cmap='seismic', clim = (-r, r))
    fig.colorbar(im)
```

```
[21]: rng = np.random.default_rng()
```

```
[22]: n = 100
d = rng.standard_normal(n)
u = rng.standard_normal(n-1)
a = np.diag(d) + np.diag(u, 1) + np.diag(u, -1)
```

```
[23]: heat_map(a)
```



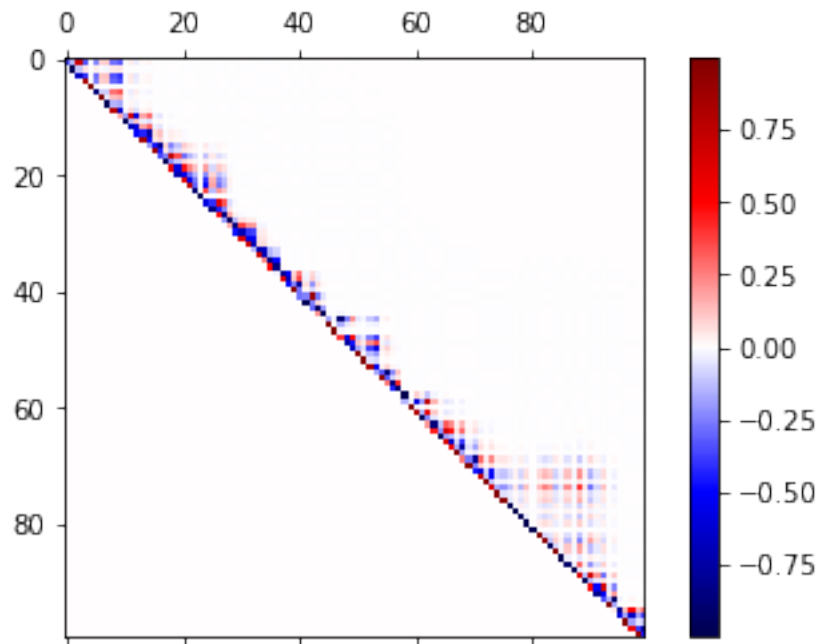
```
[24]: def house(x):
    norm_x = np.linalg.norm(x)
    if norm_x == 0:
        v = np.zeros_like(x)
        v[0] = 1
        s = 0
    else:
        u = x / norm_x
        eps = -1 if u[0] >= 0 else +1
        s = 1 + np.abs(u[0])
        v = -eps * u
        v[0] += 1
        v /= s
    return v, s

def householder_qr_data(a):
    data = np.copy(a)
    k = a.shape[1]
    s = np.empty(k)
    for j in range(k):
        v, s[j] = house(data[j:, [j]])
        data[j:, j:] -= s[j] * v @ (v.T @ data[j:, j:])
        data[j+1:, [j]] = v[1:]
    return data, s
```

```
def householder_qr(a):
    data, s = householder_qr_data(a)
    n, k = a.shape
    r = np.triu(data[:k, :k])
    q = np.eye(n, k)
    for j in reversed(range(k)):
        x = data[j+1:, [j]]
        v = np.vstack([[1], x])
        q[j:, j:] -= s[j] * v @ (v.T @ q[j:, j:])
    return q, r
```

```
[25]: q, r = householder_qr(a)
```

```
[26]: heat_map(q)
```



```
[27]: np.diag(q, -1)
```

```
[27]: array([-0.36022396, -0.98886188, -0.663464   ,  0.83475541,  0.99975293,
          -0.88818622,  0.97866166, -0.97524032,  0.76590158,  0.16505643,
          -0.98260121, -0.71628775, -0.5018436   ,  0.86678428, -0.19839219,
           0.88141037, -0.35495346, -0.96393336,  0.56875911, -0.71428554,
           0.61482539,  0.73797247, -0.89045042, -0.99999149, -0.58780744,
          -0.86206892,  0.4870187   , -0.2064181   ,  0.16137599, -0.47431932,
           0.6186366   ,  0.68912392, -0.13119791,  0.68727316,  0.24007252,
           0.49954097, -0.01665477,  0.60330319, -0.49039053,  0.96034573,
```

```
[28]: np.diag(q,-2)
```

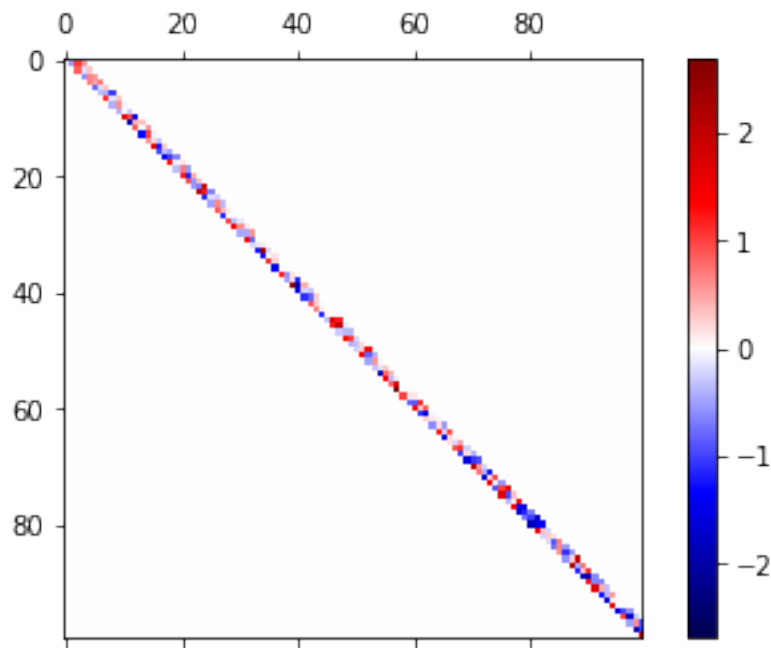
```
[29]: np.diag(q,10)
```

4

```
[30]: np.diag(q, 30)
```

```
[30]: array([-1.94679032e-07,  2.87661413e-07, -4.37560110e-08, -3.18718290e-08,  
          -2.58072489e-08, -2.23249431e-10,  2.99575333e-09, -1.81846772e-11,  
           1.32305427e-11, -7.87932951e-12, -2.42157832e-10, -3.45328334e-12,  
          -6.54819928e-11, -4.91582539e-11, -7.07001527e-12,  2.41657097e-13,  
           1.73235593e-14, -3.79072151e-12,  3.11379204e-13, -1.46300095e-12,  
          -4.13519373e-13, -2.76682970e-13, -1.86472578e-12,  2.13410720e-12,  
           1.11708187e-15, -9.95948188e-13,  1.87871597e-13, -3.22415083e-13,  
           7.18542273e-15, -2.03481463e-16,  7.34136656e-15,  3.45422179e-15,  
          -1.81748679e-14,  3.61802273e-14,  4.65508586e-15, -8.01555274e-14,  
          -1.02867443e-13,  8.94377396e-13,  5.85186376e-12, -9.55183385e-13,  
          -1.00901909e-12, -4.53517693e-12,  1.90461276e-13, -1.24813065e-11,  
          -1.00957745e-11, -7.20875082e-10, -7.12190235e-11,  3.87225130e-12,  
          -1.11367330e-09, -8.46740425e-10, -1.43249632e-10,  5.77579660e-10,  
           3.98950606e-10,  1.96465301e-09,  1.83807374e-08,  1.86079349e-09,  
          -9.97325886e-08, -3.22342161e-08,  1.02950682e-04, -8.60543240e-05,  
           1.53144996e-05,  1.16235358e-04,  6.54265081e-05, -7.85298248e-05,  
          -9.38097099e-04,  7.70290192e-06, -6.22696686e-06, -4.65596709e-05,  
          -3.15527911e-06, -1.17952320e-04])
```

```
[31]: heat_map(r)
```



```
[32]: np.diag(r,-1)
```

```
[33]: np.diag(r,2)
```

```
[34]: np.diag(r, 3)
```

```
[35]: b = r @ q
```

```
[36]: heat_map(b)
```



```

1.73472348e-18, -2.71050543e-20, -2.34187669e-17, 0.00000000e+00,
-1.38777878e-16, 7.63278329e-17, 0.00000000e+00, 2.63677968e-16,
-1.11022302e-16, 0.00000000e+00, -1.38777878e-17, 0.00000000e+00,
5.55111512e-17, 2.22044605e-16, -2.08166817e-17, -1.11022302e-16,
5.55111512e-17, -1.38777878e-17, -2.77555756e-17, 1.56125113e-17,
7.63278329e-17, 6.93889390e-18, -4.33680869e-19, 1.12757026e-16,
-2.77555756e-17, 6.24500451e-17, 1.90819582e-17, 8.67361738e-18,
3.46944695e-17, 1.04083409e-17, 1.80411242e-16, -1.38777878e-17,
-2.77555756e-17, 1.11022302e-16, 5.55111512e-17, 6.93889390e-18,
8.32667268e-17, 0.00000000e+00, -8.67361738e-19, -8.32667268e-17,
5.55111512e-17, -2.77555756e-16])

```

```
[39]: np.max(np.abs(np.diag(b, 2)))
```

```
[39]: 2.7755575615628914e-16
```

```
[40]: def qr_metode_ide(a):
      b = np.copy(a)
      for i in range(20):
          q, r = householder_qr(b)
          b = r @ q
      return b

```

```
[41]: a = np.diag(np.full(10, 2.0)) + np.diag(np.full(9, -1.0), 1) + np.diag(np.
      ↪full(9, -1.0), -1)

```

```
[42]: a
```

```
[42]: array([[ 2., -1.,  0.,  0.,  0.,  0.,  0.,  0.,  0.,  0.],
       [-1.,  2., -1.,  0.,  0.,  0.,  0.,  0.,  0.,  0.],
       [ 0., -1.,  2., -1.,  0.,  0.,  0.,  0.,  0.,  0.],
       [ 0.,  0., -1.,  2., -1.,  0.,  0.,  0.,  0.,  0.],
       [ 0.,  0.,  0., -1.,  2., -1.,  0.,  0.,  0.,  0.],
       [ 0.,  0.,  0.,  0., -1.,  2., -1.,  0.,  0.,  0.],
       [ 0.,  0.,  0.,  0.,  0., -1.,  2., -1.,  0.,  0.],
       [ 0.,  0.,  0.,  0.,  0.,  0., -1.,  2., -1.,  0.],
       [ 0.,  0.,  0.,  0.,  0.,  0.,  0., -1.,  2., -1.],
       [ 0.,  0.,  0.,  0.,  0.,  0.,  0.,  0., -1.,  2.]])

```

```
[43]: b = qr_metode_ide(a)
```

```
[44]: b
```

```
[44]: array([[ 3.86011489e+00, -1.09161607e-01,  8.44807597e-17,
        2.86033281e-16,  2.73067337e-16,  2.69092696e-17,
       -1.03245780e-16, -1.60032334e-17, -3.32471999e-17,
       -1.16754420e-17],
       [-1.09161607e-01,  3.67326756e+00, -1.54863157e-01,

```

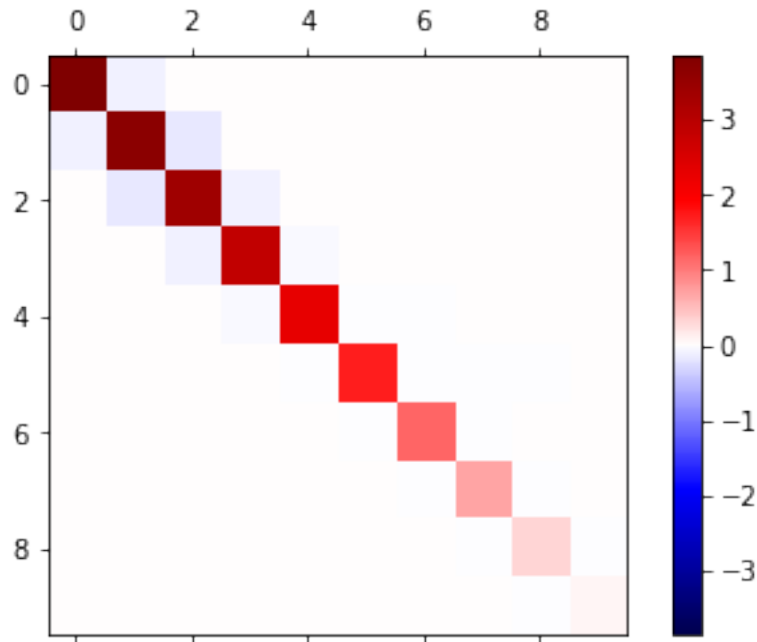


```

2.87445786e-16, 7.81101374e-17, -4.78791728e-17,
1.76526103e-16, -1.49801159e-16, -6.22751373e-17,
-5.24423619e-17],
[ 0.00000000e+00, -1.54863157e-01, 3.35419157e+00,
-1.08303279e-01, -6.46986586e-17, 6.12156592e-16,
9.54403057e-17, 3.77003045e-17, 6.82191767e-17,
8.26028603e-17],
[ 0.00000000e+00, 0.00000000e+00, -1.08303279e-01,
2.85100306e+00, -4.38814554e-02, -1.08840848e-16,
5.50469935e-16, 7.15021816e-16, 2.54401666e-16,
1.21897649e-16],
[ 0.00000000e+00, 0.00000000e+00, 0.00000000e+00,
-4.38814554e-02, 2.28787915e+00, -1.11540140e-02,
-3.84638736e-16, 8.69746479e-17, 4.91478204e-16,
1.87690091e-16],
[ 0.00000000e+00, 0.00000000e+00, 0.00000000e+00,
0.00000000e+00, -1.11540140e-02, 1.71558433e+00,
-1.46856659e-03, -8.13334317e-16, -6.36725476e-16,
-1.68162485e-16],
[ 0.00000000e+00, 0.00000000e+00, 0.00000000e+00,
0.00000000e+00, 0.00000000e+00, -1.46856659e-03,
1.16917391e+00, -6.22818934e-05, -5.61325307e-17,
-4.73942813e-17],
[ 0.00000000e+00, 0.00000000e+00, 0.00000000e+00,
0.00000000e+00, 0.00000000e+00, 0.00000000e+00,
-6.22818934e-05, 6.90278540e-01, -2.41065834e-07,
-2.55605470e-17],
[ 0.00000000e+00, 0.00000000e+00, 0.00000000e+00,
0.00000000e+00, 0.00000000e+00, 0.00000000e+00,
0.00000000e+00, -2.41065834e-07, 3.17492934e-01,
-6.21302329e-13],
[ 0.00000000e+00, 0.00000000e+00, 0.00000000e+00,
0.00000000e+00, 0.00000000e+00, 0.00000000e+00,
0.00000000e+00, 0.00000000e+00, -6.21426878e-13,
8.10140528e-02]]

```

[45]: `heat_map(b)`



```
[46]: np.diag(b)
```

```
[46]: array([3.86011489, 3.67326756, 3.35419157, 2.85100306, 2.28787915,
          1.71558433, 1.16917391, 0.69027854, 0.31749293, 0.08101405])
```

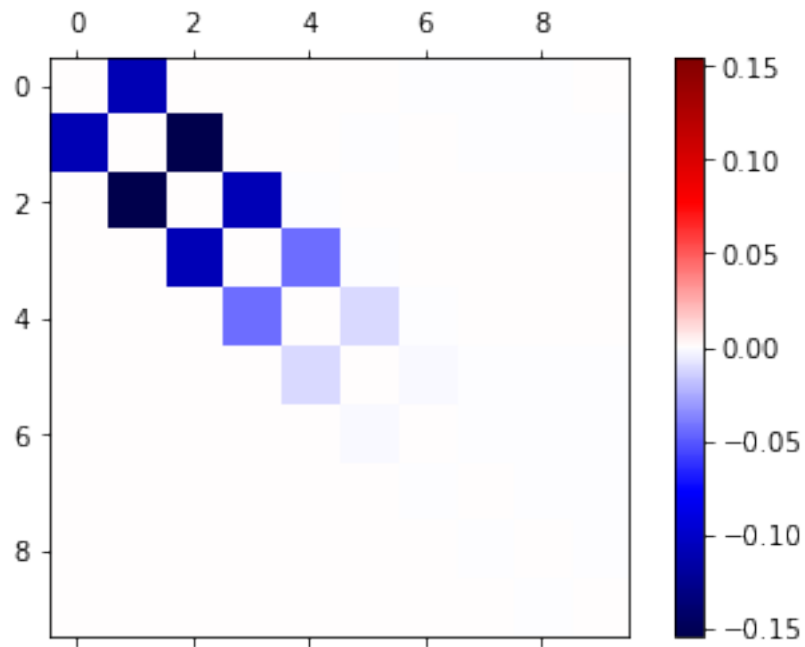
```
[47]: np.diag(b, 1)
```

```
[47]: array([-1.09161607e-01, -1.54863157e-01, -1.08303279e-01, -4.38814554e-02,
          -1.11540140e-02, -1.46856659e-03, -6.22818934e-05, -2.41065834e-07,
          -6.21302329e-13])
```

```
[48]: np.diag(b, 2)
```

```
[48]: array([ 8.44807597e-17,  2.87445786e-16, -6.46986586e-17, -1.08840848e-16,
          -3.84638736e-16, -8.13334317e-16, -5.61325307e-17, -2.55605470e-17])
```

```
[49]: heat_map(b - np.diag(np.diag(b)))
```



[]: