Formal Inductive Synthesis -- Theory and Applications

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Acknowledgments to several Ph.D. students, postdoctoral researchers, and collaborators, and to the students of EECS 219C, Spring 2015, UC Berkeley

RiSE & LogiCS Spring School April 15, 2016

Helmut Veith – Colleague, Friend, Inspiration...



Inspiration for this Lecture Topic

Edmund M. Clarke, Orna Grumberg, Somesh Jha, Yuan Lu, Helmut Veith: Counterexample-Guided Abstraction Refinement. Proceedings of CAV 2000: 154-169

Formal Synthesis

- Given:
 - Class of Artifacts C
 - Formal (mathematical) Specification
- Find $f \in C$ that satisfies ϕ
- Example:
 - C: all affine functions f of $x \in R$
 - ϕ : $\forall x$. f(x) ≥ x + 42

Reactive Synthesis: An Example of Formal Synthesis

- Given:
 - Class C: all finite-state transducers with input alphabet I and output alphabet O
 - Linear temporal logic (LTL) Specification \(\phi \)
- Find transducer in C that satisfies \(\phi \)

Induction vs. Deduction

- Induction: Inferring general rules (functions) from specific examples (observations)
 - Generalization
- Deduction: Applying general rules to derive conclusions about specific instances
 - (generally) Specialization
- Learning/Synthesis can be Inductive or Deductive or a combination of the two

Inductive Synthesis

- Given
 - Class of Artifacts C
 - Set of (labeled) Examples E (or source of E)
 - A stopping criterion Ψ
 - May or may not be formally described
- Find, using only E, an $f \in C$ that meets Ψ
- Example:
 - C: all affine functions f of $x \in R$
 - $E = \{(0,42), (1,43), (2,44)\}$
 - Ψ -- find consistent f

Inductive Synthesis

- Given
 - Class of Artifacts C
 - Set of Examples E (or source of E)
 - A stopping criterion Ψ
- Find using only E an $f \in C$ that meets Ψ
- Example:
 - C: all affine functions f of $x \in R$
 - $E = \{(0,42), (1,43), (2,45)\}$
 - Ψ -- find consistent f

Inductive Synthesis

- Example:
 - C: all predicates of the form ax + by ≥ c
 - $E = \{(0,42), (1,43), (2,45)\}$
 - $-\Psi$ -- find consistent f
- One such: -x + y ≥ 42
- Another: $-x + y \ge 0$
- Which one to pick: need to augment Ψ?

Machine Learning

"A computer program is said to learn from experience E with respect to some class of tasks T and performance measure P, if its performance at tasks in T, as measured by P, improves with experience E."



- Tom Mitchell [1998]

Machine Learning: Typical Setup

Given:

- Domain of Examples D
- Concept class C
 - Concept is a subset of D
 - C is set of all concepts
- Criterion Ψ ("performance measure")

Find using only examples from D, $f \in C$ meeting Ψ

Inductive Bias in Machine Learning

"Inductive bias is the set of assumptions required to deductively infer a concept from the inputs to the learning algorithm."



Example:

C: all predicates of the form $ax + by \ge c$

 $E = \{(0,42), (1,43), (2,45)\}$

Ψ -- find consistent f

Which one to pick: $-x + y \ge 42$ or $-x + y \ge 0$ Inductive Bias resolves this choice

E.g., pick the "simplest one" (Occam's razor)

Formal Inductive Synthesis (Initial Defn)

Given:

- Class of Artifacts C
- Formal specification \(\phi \)
- Domain of examples D
- Find f ∈ C that satisfies φ using only elements of D
 - i.e. no direct access to ϕ , only to elements of D representing ϕ

Example:

- C: all affine functions f of $x \in R$
- $-D=R^2$
- ϕ : $\forall x$. f(x) ≥ x + 42

Importance

Formal Inductive Synthesis is Everywhere!

Many problems can be solved effectively when viewed as synthesis

Particularly effective in various tasks in Formal Methods

For the rest of this lecture series, for brevity we will often use "Inductive Synthesis" to mean "Formal Inductive Synthesis"

Formal Methods ≈ Computational Proof Methods

- Formal Methods is about Provable Guarantees
 - Specification/Modeling ≈ Statement of Conjecture/Theorem
 - Verification ≈ Proving/Disproving the Conjecture
 - Synthesis ≈ Generating (parts of) Conjecture/Proof
- Formal Methods ≈ Computational Proof methods
 - Temporal logic / Assertions
 - Boolean reasoning: SAT solving & Binary Decision Diagrams
 - Equivalence checking
 - Model checking
 - Automated theorem proving, SMT solving

_ ...

Inductive Synthesis for Formal Methods

Modeling / Specification

- Generating environment/component models
- Inferring (likely) specifications/requirements

Verification

- Synthesizing verification/proof artifacts such as inductive invariants, abstractions, interpolants, environment assumptions, etc.
- Synthesis (of course)

Questions of Interest for this Tutorial

- How can inductive synthesis be used to solve other (non-synthesis) problems?
- What is a core computational problem for formal synthesis (aka SAT or SMT)?
- Is there a theory of formal inductive synthesis distinct from (traditional) machine learning?
- Is there a complexity/computability theory for formal inductive synthesis?

Questions of Interest for this Tutorial

- How can inductive synthesis be used to solve other (non-synthesis) problems?
- Reducing a Problem to Synthesis
- What is a core computational problem for formal synthesis (aka SAT or SMT)?
- Syntax-Guided Synthesis (SyGuS)
- Is there a theory of formal inductive synthesis distinct from (traditional) machine learning?
- Oracle-Guided Inductive Synthesis (OGIS)
- Is there a complexity/computability theory for formal inductive synthesis?
- Yes! Can compare different OGIS techniques

Outline for this Lecture Sequence

- Examples of Reduction to Synthesis
 - Specification
 - Verification
- Demo: Requirement Mining for Cyber-Physical Systems
- Differences between Inductive Synthesis and Machine Learning
- Oracle-Guided Inductive Synthesis
 - Examples, CEGIS
- Theoretical Analysis of CEGIS
 - Properties of Learner
 - Properties of Verifier

Further Reading

 S. A. Seshia, "Combining Induction, Deduction, and Structure for Verification and Synthesis.", Proc. IEEE 2015, DAC 2012

http://www.eecs.berkeley.edu/~sseshia/pubs/b2hd-seshia-dac12.html

http://www.eecs.berkeley.edu/~sseshia/pubs/b2hd-seshia-pieee15.html

S. Jha and S. A. Seshia, "A Theory of Formal Synthesis via Inductive Learning"

http://www.eecs.berkeley.edu/~sseshia/pubs/b2hd-jha-arxiv15.html

Lecture notes of EECS 219C: "Computer-Aided Verification" class at UC Berkeley, available at:

Reductions to Synthesis

Artifacts Synthesized in Verification

- Inductive invariants
- Abstraction functions / abstract models
- Auxiliary specifications (e.g., pre/post-conditions, function summaries)
- Environment assumptions / Env model / interface specifications
- Interpolants
- Ranking functions
- Intermediate lemmas for compositional proofs
- Theory lemma instances in SMT solving
- Patterns for Quantifier Instantiation

• ...

Example Verification Problem

- Transition System
 - Init: I

$$x = 1 \land y = 1$$

– Transition Relation: δ

$$x' = x+y \wedge y' = y+x$$

- Property: $\Psi = G (y \ge 1)$
- Attempted Proof by Induction:

$$y \ge 1 \land x' = x + y \land y' = y + x \implies y' \ge 1$$

$$x = 1 \land y = 1 \Rightarrow \phi$$

 $\phi \land y \ge 1 \land x' = x + y \land y' = y + x \Rightarrow \phi' \land y' \ge 1$

Example Verification Problem

- Transition System
 - Init: I

$$x = 1 \land y = 1$$

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- Property: $\Psi = G (y \ge 1)$
- Attempted Proof by Induction:

$$y \ge 1 \land x' = x + y \land y' = y + x \implies y' \ge 1$$

$$x \ge 1 \land y \ge 1 \land x' = x + y \land y' = y + x \implies x' \ge 1 \land y' \ge 1$$

■ Safety Verification → Invariant Synthesis

One Reduction from Verification to Synthesis

NOTATION

Transition system $M = (I, \delta)$ Safety property $\Psi = G(\psi)$

VERIFICATION PROBLEM

Does M satisfy Ψ?



SYNTHESIS PROBLEM

Synthesize of s.t.

$$I \Rightarrow \phi \wedge \psi$$

$$\phi \wedge \psi \wedge \delta \Rightarrow \phi' \wedge \psi'$$

Two Reductions from Verification to Synthesis

NOTATION

Transition system M = (I, δ), S = set of states Safety property Ψ = $G(\psi)$

VERIFICATION PROBLEM

Does M satisfy Ψ?



SYNTHESIS PROBLEM #1

Synthesize • s.t.

$$I \Rightarrow \phi \wedge \psi$$

$$\phi \wedge \psi \wedge \delta \Rightarrow \phi' \wedge \psi'$$

SYNTHESIS PROBLEM #2

Synthesize
$$\alpha: S \to \hat{S}$$
 where $\alpha(M) = (\hat{I}, \hat{\delta})$ s.t. $\alpha(M)$ satisfies Ψ iff M satisfies Ψ

Common Approach for both: Inductive Synthesis

Synthesis of:-

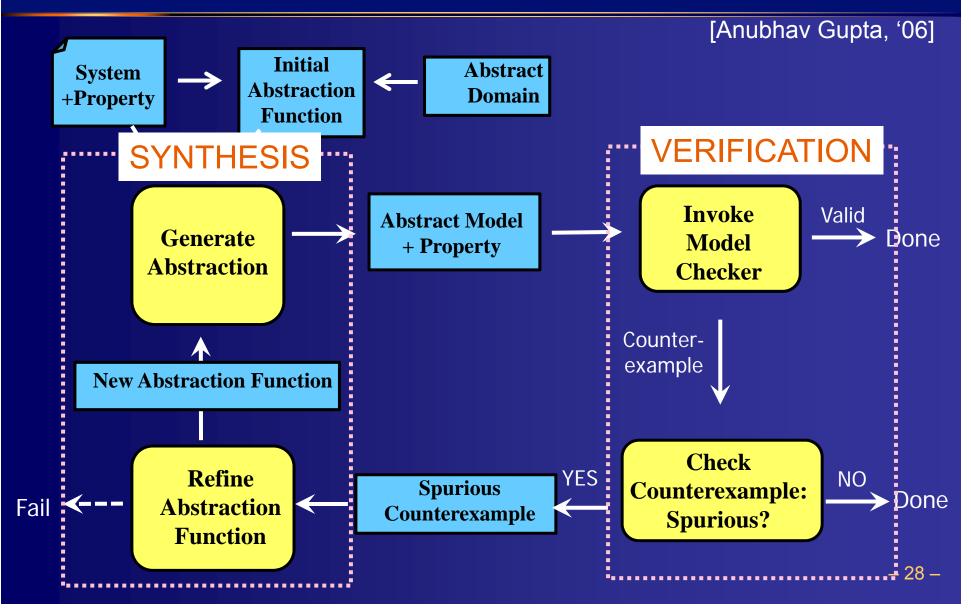
Inductive Invariants

- Choose templates for invariants
- Infer likely invariants from tests (examples)
- Check if any are true inductive invariants, possibly iterate

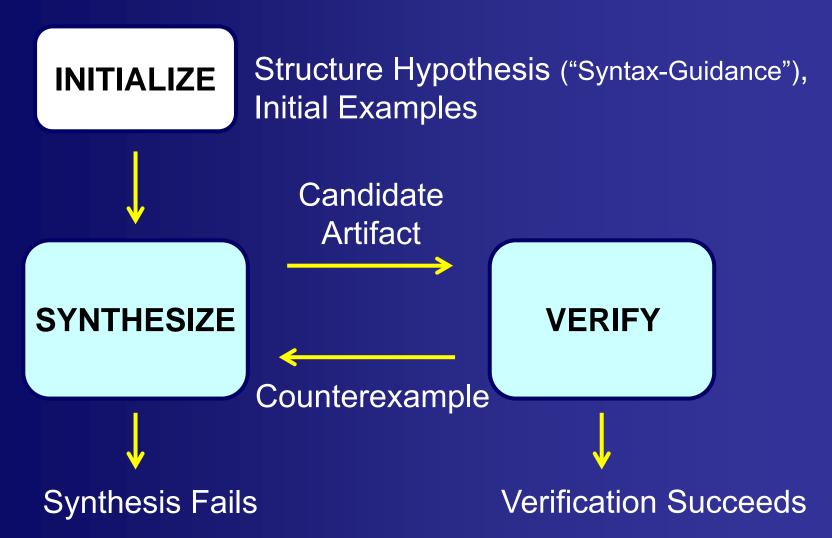
Abstraction Functions

- Choose an abstract domain
- Use Counter-Example Guided Abstraction Refinement (CEGAR)

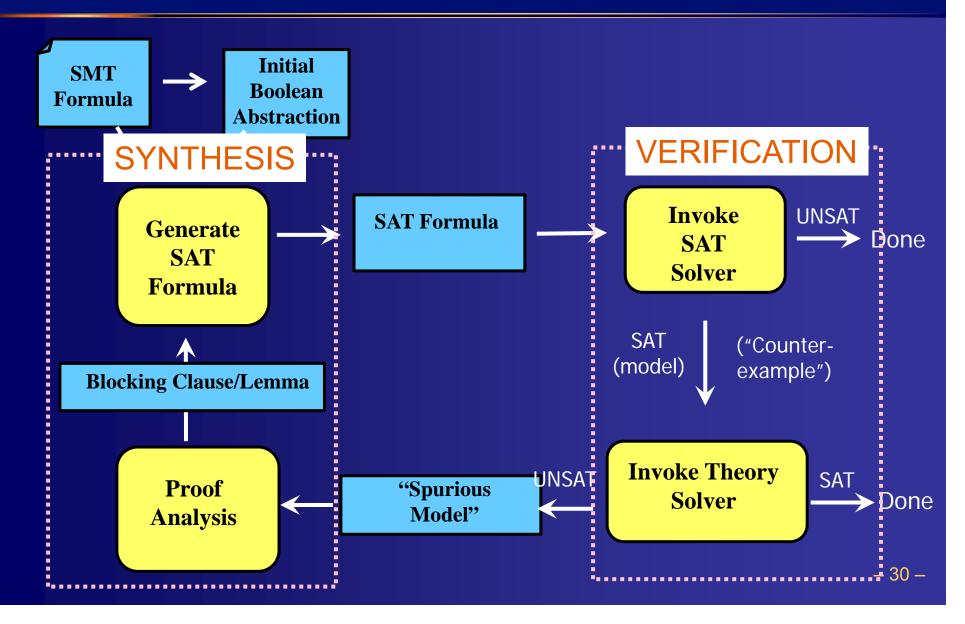
Counterexample-Guided Abstraction Refinement is Inductive Synthesis



CEGAR = Counterexample-Guided Inductive Synthesis (of Abstractions)



Lazy SMT Solving performs Inductive Synthesis (of Lemmas)



Other Examples

- Invariant Generation via ICE Learning [P. Garg & M. Parthasarathy]
- Invariant Generation, Interpolation via Machine Learning + SMT Solving [R. Sharma, A. Aiken, et al.] and many more...

Reducing Specification to Synthesis

- Formal Specifications difficult for non-experts
- Tricky for even experts to get right!
- Yet we need them!

"A design without specification cannot be right or wrong, it can only be surprising!"

- paraphrased from [Young et al., 1985]
- Specifications are crucial for effective testing, verification, synthesis, ...

Two Award-Winning Dissertations, circa 2000

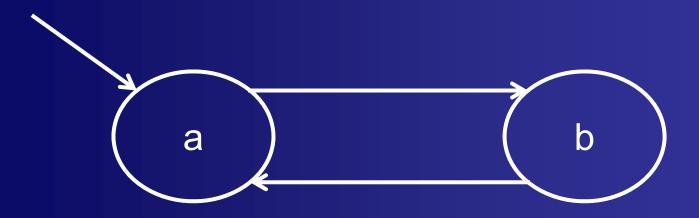
- Michael Ernst: "Dynamically Discovering Likely Program Invariants"
 - Learning (likely) Invariants from Tests

- William Chan: "Symbolic Model Checking for Large Software Specifications"
 - "Temporal logic queries"

Reduction of Specification to Synthesis

- VERIFICATION: Given (closed) system M, and specification φ, does M satisfy φ?
- Suppose we don't have (a good enough) φ.
- SYNTHESIS PROBLEM: Given (closed) system
 M, find specification φ such that M satisfies φ.
 - Is this enough?

Example



Let a and b be atomic propositions.

What linear temporal logic formulas does the above system satisfy?

Reduction of Specification to Synthesis

- VERIFICATION: Given (closed) system M, and specification φ, does M satisfy φ?
- SYNTHESIS PROBLEM: Given (closed) system M and class of specifications C, find specification φ in C such that M satisfies φ.
 - C can be defined syntactically (e.g. with a template)
 - E.g. G($_\Rightarrow X_$)

Reduction of Specification to Synthesis

- VERIFICATION: Given (closed) system M, and specification φ, does M satisfy φ?
- SYNTHESIS PROBLEM: Given (closed) system M and class of specifications C, find "tightest" specification φ in C such that M satisfies φ.
 - Industrial Tech. Transfer Story: Requirement Synthesis for Automotive Control Systems [Jin, Donze, Deshmukh, Seshia, HSCC 2013, TCAD 2015]
 - http://www.eecs.berkeley.edu/~sseshia/pubs/b2hd-jin-tcad15.html
 - Implemented in Breach toolbox by A. Donze

Specification Mining

- Inductive Synthesis of Specifications
- See recent Ph.D. dissertation by Wenchao Li: "Specification Mining: New Formalisms, Algorithms and Applications"

http://www.eecs.berkeley.edu/Pubs/TechRpts/2014/ EECS-2014-20.html

Two Applications of Inductive Synthesis of Specifications

- Requirements Mining for Closed-Loop Control Systems
- 2. Environment Assumptions for Reactive Synthesis [see Wenchao Li thesis]
- Relevance to Robotics/Cyber-Physical Systems

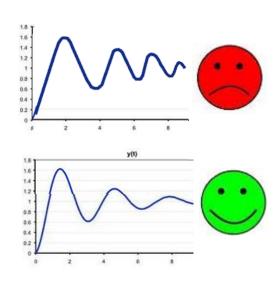
Challenges for Verification of Automotive Control Systems

- Closed-loop setting very complex
 - software + physical artifacts
 - nonlinear dynamics
 - large look-up tables
 - large amounts of switching

Requirements Incomplete/Informal

- Specifications often created concurrently with the design!
- Designers often only have informal intuition about what is "good behavior"
 - "shape recognition"





Solution: Requirements Mining

Requirements Expressed in Signal Temporal Logic

(STL) [Maler & Nickovic, '04]

Value added by mining:

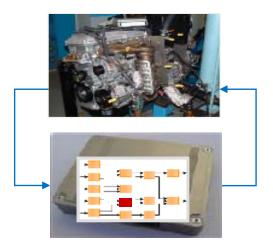
- Mined Requirements become useful documentation
- Use for code maintenance and revision
- Use during tuning and testing

It's working, but I don't understand why!



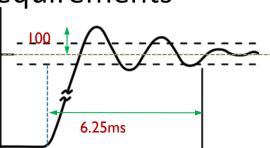
Control Designer's Viewpoint of the Method

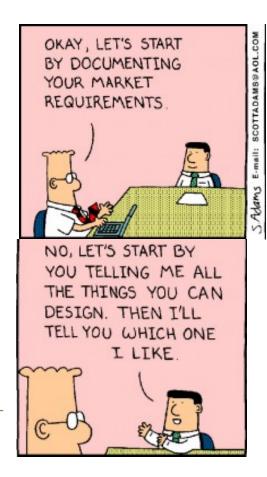
Tool extracts properties of closed-loop design



- Designer reviews mined requirements
 - "Settling time is 6.25 ms"
 - "Overshoot is 100 units"
 - Expressed in Signal

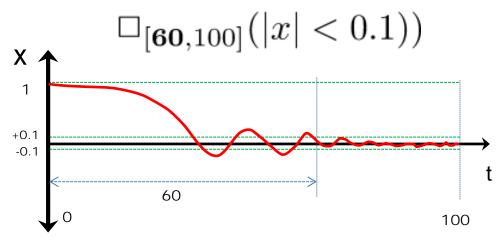
Temporal Logic [Maler & Nickovic, '04]





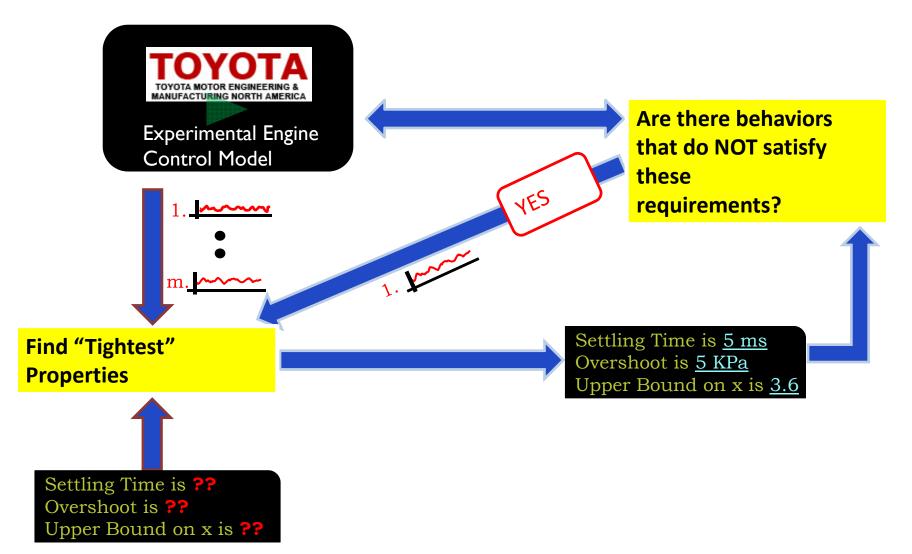
Signal Temporal Logic (STL)

- Extension of Linear Temporal Logic (LTL) and Variant of Metric Temporal Logic (MTL)
 - Quantitative semantics: satisfaction of a property over a trace given real-valued interpretation
 - Greater value → more easily satisfied
 - Non-negative satisfaction value ≡ Boolean satisfaction
- Example: "For all time points between 60 and 100, the absolute value of x is below 0.1"

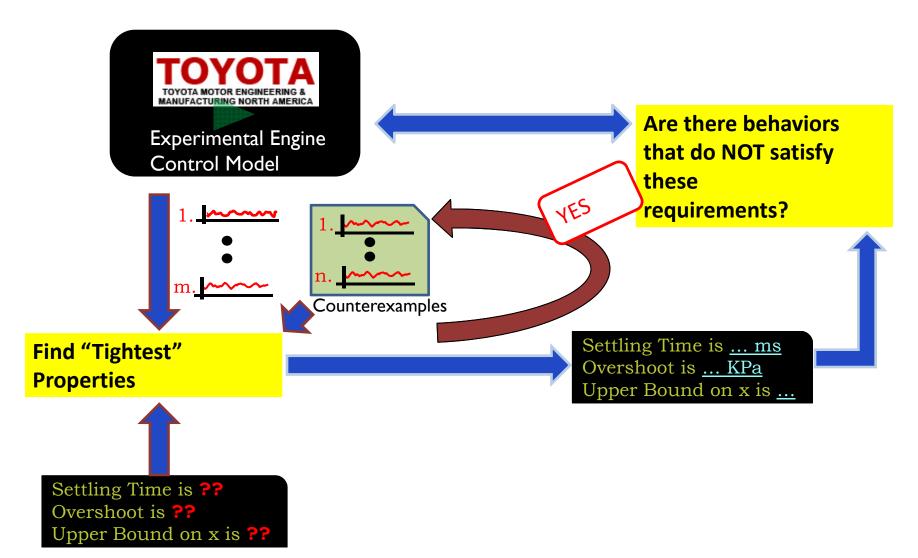


CounterExample Guided Inductive Synthesis

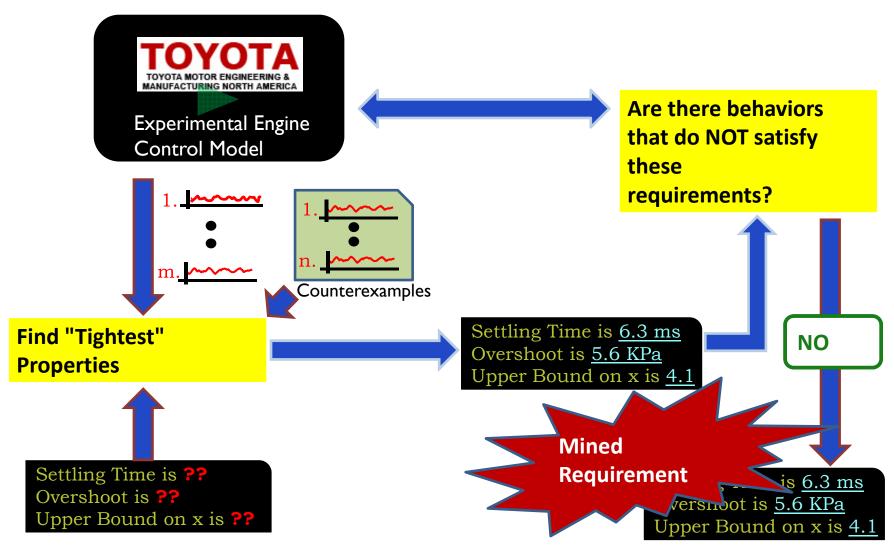
[Jin, Donze, Deshmukh, Seshia, HSCC 2013]



CounterExample Guided Inductive Synthesis



CounterExample Guided Inductive Synthesis

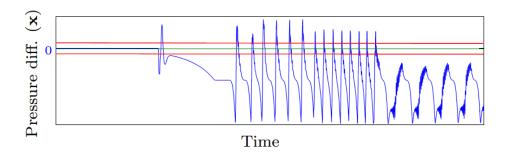


Experimental Results on Industrial Airpath

Controller [Jin, Donze, Deshmukh, Seshia, HSCC 2013]



- Found max overshoot with 7000+ simulations in 13 hours
- Attempt to mine maximum observed settling time:
 - stops after 4 iterations
 - gives answer t_{settle} = simulation time horizon (shown in trace below)



Mining can expose deep bugs

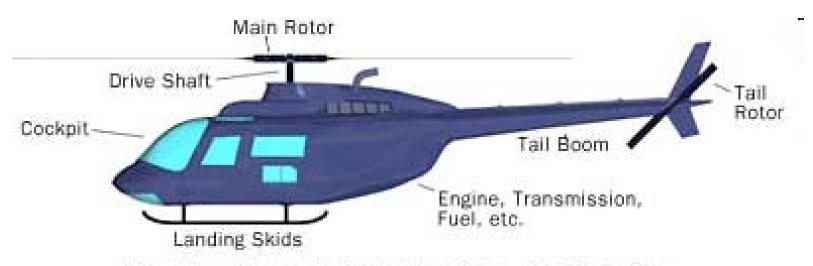




- Uncovered a tricky bug
 - Discussion with control designer revealed it to be a real bug
 - Root cause identified as wrong value in a look-up table, bug was fixed
- Duality between spec mining and bug-finding:
 - Synthesizing "tightest" spec could uncover corner-case bugs
 - Looking for bugs ≈ Mine for negation of bug

Demo: Requirement Mining for a Helicopter Control Model

An Example: Modeling Helicopter Dynamics (taken from textbook available at http://LeeSeshia.org, Chapter 2)



The Fundamental Parts of any Helicopter

@2000 HawStuffWorks

Go to **Breach** webpage for this example:

http://www.eecs.berkeley.edu/~donze/mining_example.html

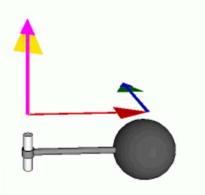
Modeling Physical Motion

Six degrees of freedom:

O Position: x, y, z

O Orientation: pitch, yaw, roll Yaw y axis x axis Roll Pitch z axis

Feedback Control Problem



A helicopter without a tail rotor, like the one below, will spin uncontrollably due to the torque induced by friction in the rotor shaft.

Control system problem: Apply torque using the tail rotor to counterbalance the torque of the top rotor.



Model of the helicopter

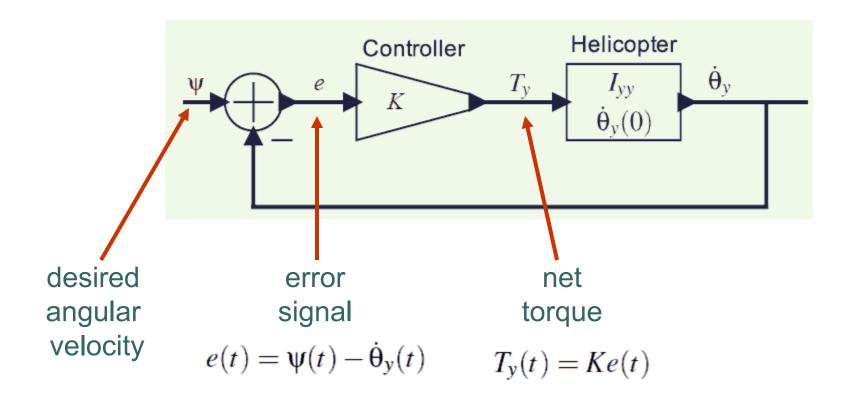
Input is the net torque of the tail rotor and the top rotor. Output is the angular velocity around the *y* axis.

Helicopter I_{yy} $\dot{\theta}_y$ $\dot{\theta}_y$

Parameters of the model are shown in the box. The input and output relation is given by the equation to the right.

$$\dot{\theta}_y(t) = \dot{\theta}_y(0) + \frac{1}{I_{yy}} \int_0^t T_y(\tau) d\tau$$

Proportional controller



How long does it take for theta_dot to reach desired psi?

Summary of Part 1

- Basic Terminology
 - Formal Synthesis
 - Inductive Synthesis
 - Formal Inductive Synthesis
 - Notions from Machine Learning
- Reductions to Synthesis
 - Verification artifacts
 - Specifications
 - Case Study: requirement mining for closed-loop control systems
 - Demo on simple helicopter example: see http://www.eecs.berkeley.edu/~donze/mining_exam ple.html

Syntax-Guided Synthesis

Formal Synthesis (recap)

- Given:
 - Formal Specification
 - Class of Artifacts C
- Find $f \in C$ that satisfies ϕ

Syntax-Guided Synthesis (SyGuS)

Given:

- An SMT formula
 on UF + T (where T is some combination of theories)
- Typed uninterpreted function symbols f₁,..,f_k in φ
- Grammars G, one for each function symbol f_i
- Generate expressions e₁,...,e_k from G s.t.
 - ϕ [f₁,...,f_k \leftarrow e₁,...,e_k] is valid in T

SyGuS ≠ ∃∀ SMT

Exists-Forall SMT

$$\exists f \forall x \phi(f,x)$$

SyGuS (abusing notation slightly)

$$\exists \ f \in G \ \forall \ x \ \phi(f,x)$$

Sometimes SyGuS is solved by reduction to EF-SMT

SyGuS Example 1

- Theory QF-LIA
 - Types: Integers and Booleans
 - Logical connectives, Conditionals, and Linear arithmetic
 - Quantifier-free formulas
- Function to be synthesized f(int x, int y): int
- Specification: $x \le f(x, y) \land y \le f(x, y) \land (f(x, y) = x \lor f(x, y) = y)$
- Grammar

LinExp := x | y | Const | LinExp + LinExp | LinExp - LinExp

Is there a solution?

SyGuS Example 2

- Theory QF-LIA
 - Types: Integers and Booleans
 - Logical connectives, Conditionals, and Linear arithmetic
 - Quantifier-free formulas
- Function to be synthesized f(int x, int y): int
- Specification: $x \le f(x, y) \land y \le f(x, y) \land (f(x, y) = x \lor f(x, y) = y)$
- Grammar

Term := x | y | Const | If-Then-Else (Cond, Term, Term) Cond := Term <= Term | Cond & Cond | ~Cond | (Cond)

Is there a solution?

From SMT-LIB to SYNTH-LIB

```
(set-logic LIA)
(synth-fun max2 ((x Int) (y Int)) Int
   ((Start Int (x y 0 1 (+ Start Start)(- Start Start)
                (ite StartBool Start Start)))
    (StartBool Bool ((and StartBool StartBool)
                     (or StartBool StartBool)
                     (not StartBool)
                     (<= Start Start)))))
(declare-var x Int)
(declare-var y Int)
(constraint (>= (max2 x y) x))
(constraint (>= (max2 x y) y))
(constraint (or (= x (max2 x y)) (= y (max2 x y))))
(check-synth)
```

Invariant Synthesis via SyGuS

Find \$\phi\$ s.t.

$$x = 1 \land y = 1 \implies \phi \land y \ge 1$$

$$\phi \land y \ge 1 \land x' = x + y \land y' = y + x \implies \phi' \land y' \ge 1$$

Syntax-Guidance: Grammar expressing simple linear predicates of the form $S \ge 0$ where S is an expression defined as:

$$S := 0 | 1 | x | y | S + S | S - S$$

Homework: Try encoding this in SyGuS and solve it using one of the reference solvers

More Demos (time permitting)

- Impact of Grammar definition
 - Expression size
 - Symmetries
- Visit http://www.sygus.org for publications, benchmarks and sample solvers

Other Considerations

- Let-Expressions (for common sub-expressions)
 - Example:

```
S ::= let [t := T] in t * t
T ::= x | y | 0 | 1 | T + T | T - T
```

Cost constraints/functions (for "optimality" of synthesized function)

SyGuS vs. CEGIS

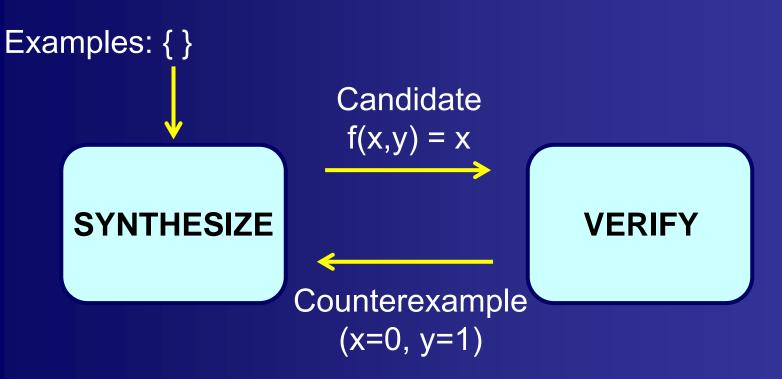
SyGuS --- problem classes

CEGIS --- solution classes

- Specification: $x \le f(x,y) \land y \le f(x,y) \land (f(x,y) = x \lor f(x,y) = y)$
- Grammar

Term := $x \mid y \mid 0 \mid 1 \mid \text{If-Then-Else (Cond, Term, Term)}$

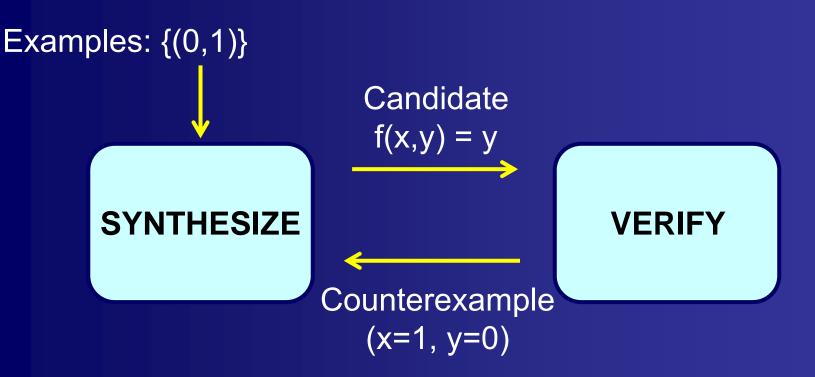
Cond := Term <= Term | Cond & Cond | ~Cond | (Cond)



- Specification: $x \le f(x, y) \land y \le f(x, y) \land (f(x, y) = x \lor f(x, y) = y)$
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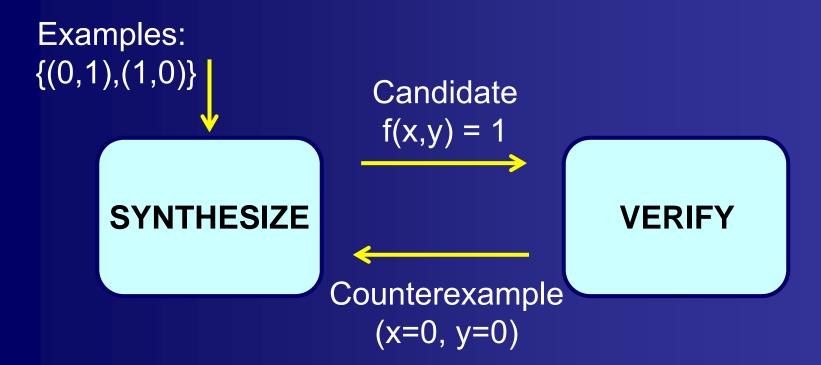


• Specification: $x \le f(x, y) \land y \le f(x, y) \land (f(x, y) = x \lor f(x, y) = y)$

Grammar

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• Specification: $x \le f(x, y) \land y \le f(x, y) \land (f(x, y) = x \lor f(x, y) = y)$

Grammar

Term := $x \mid y \mid 0 \mid 1 \mid \text{If-Then-Else (Cond, Term, Term)}$

Cond := Term <= Term | Cond & Cond | ~Cond | (Cond)

Examples:

Candidate
$$f(x,y) = ITE(x \le y, y, x)$$

SYNTHESIZE

VERIFY

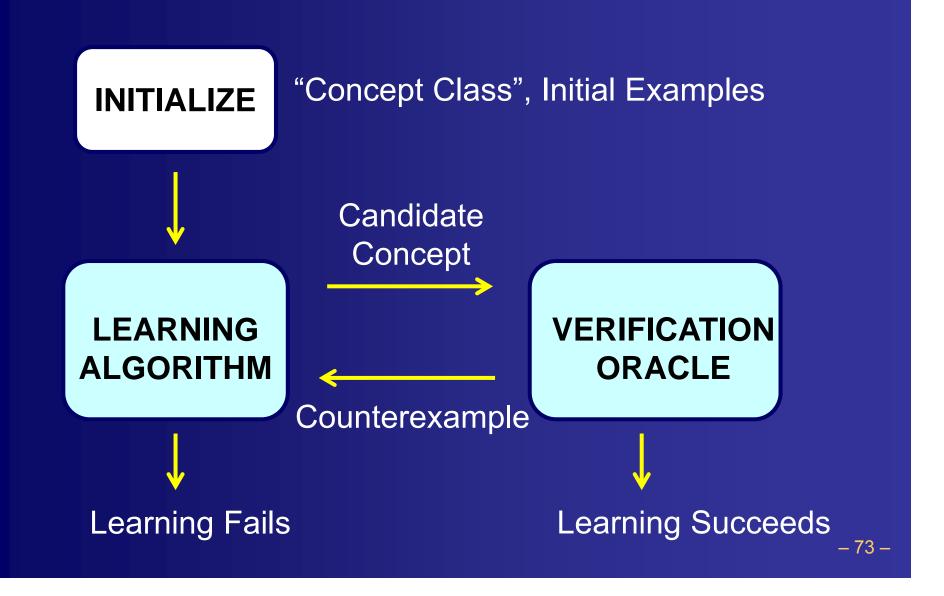
Verification Succeeds!

Three Flavors of SyGuS Solvers

- All use CEGIS, differ in implementation of "Synthesis" step
- Enumerative [Udupa et al., PLDI 2013]
 - Enumerate expressions in increasing order of "syntactic simplicity" with heuristic optimizations
- Symbolic [Jha et al., ICSE 2010, PLDI 2011]
 - Encode search for expressions as SMT problem
 - Similar approach used in SKETCH [Solar-Lezama'08]
- Stochastic [Schkufza et al., ASPLOS 2013]
 - Markov Chain Monte Carlo search method over space of expressions
- See [Alur et al., FMCAD 2013] paper for more details

Theoretical Aspects of Formal Inductive Synthesis

CEGIS = Learning from Examples & Counterexamples



How is Formal Inductive Synthesis different from (traditional) Machine Learning?

Comparison*

[see also, Jha & Seshia, 2015]

Feature	Formal Inductive Synthesis	Machine Learning
Concept/Program Classes	Programmable, Complex	Fixed, Simple
Learning Algorithms	General-Purpose Solvers	Specialized
Learning Criteria	Exact, w/ Formal Spec	Approximate, w/ Cost Function
Oracle-Guidance	Common (can select Oracle)	Rare (black-box oracles)

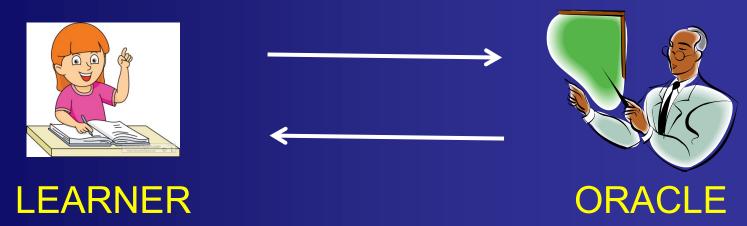
^{*} Between typical inductive synthesizer and machine learning algo

Formal Inductive Synthesis

- Given:
 - Class of Artifacts C
 Formal specification \(\phi \)
 - Domain of examples D
 - Oracle Interface O
 - Set of (query, response) types
- Find using only O an f ∈ C that satisfies φ
 - i.e. no direct access to D or ∅
- Example:
 - C: all affine functions f of $x \in R = D$
 - O = $\{(pos-witness, x satisfying \phi)\}$
 - $-\phi$: $\forall x. f(x) \ge x + 42$

Oracle Interface

Generalizes the simple model of sampling positive/negative examples from a corpus of data



- Specifies WHAT the learner and oracle do
- Does not specify HOW the oracle/learner is implemented

Common Oracle Query Types (for trace property ϕ)

Positive Witness

 $x \in \phi$, if one exists, else \bot

Negative Witness

 $x \notin \phi$, if one exists, else \bot

Membership: Is $x \in \emptyset$?

Yes / No

Equivalence: Is $f = \phi$?

Yes / No + $x \in \phi \oplus f$

Subsumption/Subset: Is $f \subseteq \phi$?

Yes / No + $x \in f \setminus \phi$

Distinguishing Input: $f, X \subseteq f$

f' s.t. f' \neq f \wedge X \subseteq f', if it exists; o.w. \perp



LEARNER

ORACLE

Formal Inductive Synthesis

- Given:
 - Class of Artifacts C
 Formal specification \(\phi \)
 - Domain of examples D
 - Oracle Interface O
 - Set of (query, response) types
- Find using only O an $f \in C$ that satisfies ϕ
 - i.e. no direct access to D or ∅
- How do we solve this?

Design/Select:





Oracle-Guided Inductive Synthesis (OGIS)

- A dialogue is a sequence of (query, response) confirming to an oracle interface O
- An OGIS engine is a pair <L, T> where
 - L is a learner, a non-deterministic algorithm mapping a dialogue to a concept c and query q
 - T is an oracle/teacher, a non-deterministic algorithm mapping a dialogue and query to a response r
- An OGIS engine <L,T> solves an FIS problem if there exists a dialogue between L and T that converges in a concept f ∈ C that satisfies φ

Language Learning in the Limit

EXPORMATION AND CONTROL 10, 447-474 (1967)

Language Identification in the Limit

E Mark Gold*

The RAND Corporation

Language learnability has been investigated. This refers to the following situation: A class of possible languages is specified, together with a method of presenting information to the learner about an unknown language, which is to be chosen from the class. The question is now asked, "Is the information sufficient to determine which of the possible languages is the unknown language?" Many definitions of learnability are possible, but only the following is considered here: Time is quantized and has a finite starting time. At each time the learner receives a unit of information and is to make a guess as to the identity of the unknown language on the basis of the information received so far. This process continues forever. The class of languages will be considered learnable with respect to the specified method of information presentation if there is an algorithm that the learner can use to make his guesses, the algorithm having the following property: Given any language of the class, there is some finite time after which the guesses will all be the same and they will be correct.

In this preliminary investigation, a language is taken to be a set of strings on some finite alphabet. The alphabet is the same for all languages of the class. Several variations of each of the following two basic methods of information presentation are investigated: A text for a language generates the strings of the language in any order such that every string of the language occurs at least once. An informant for a language tells whether a string is in the language, and chooses the strings in some order such that every string occurs at least once.

It was found that the class of context-sensitive languages is learnable from an informant, but that not even the class of regular languages is learnable from a text.

1. MOTIVATION: TO SPEAK A LANGUAGE

The study of language identification described here derives its motivation from artificial intelligence. The results and the methods used also

[E.M. Gold, 1967]

- Concept = Formal Language
- Class of languages identifiable in the limit if there is a learning procedure that, for each language in that class, given an infinite stream of strings, will eventually generate a representation of the language.

Results:

- Cannot learn regular languages, CFLs, CSLs using just positive witness queries
- Can learn using both positive & negative witness queries (assuming all examples eventually enumerated)₈₁

Query-Based Learning



Dana Angluin

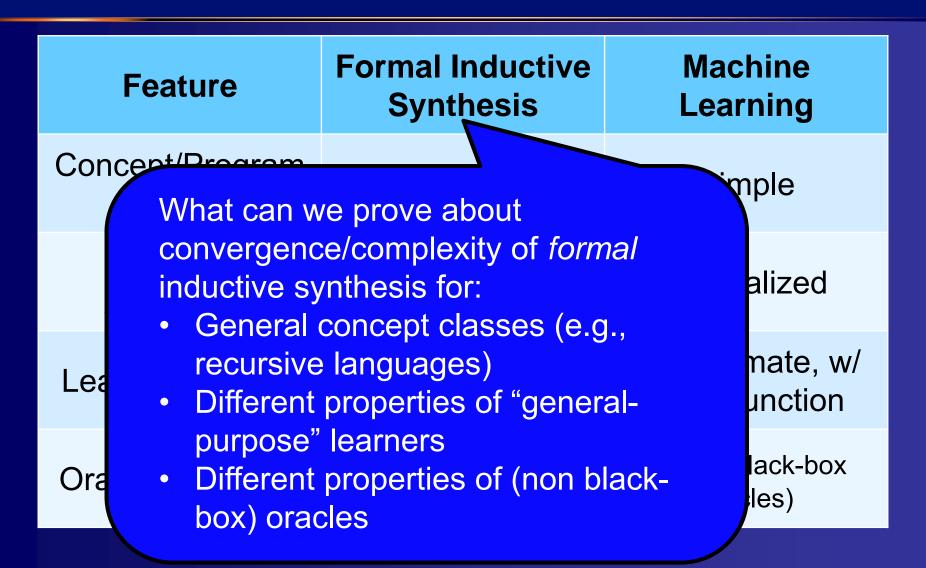
[Queries and Concept Learning, 1988] [Queries Revisited, 2004]

- First work on learning based on querying an oracle
 - Supports witness, equivalence, membership, subsumption/subset queries
 - Oracle is BLACK BOX
 - Oracle determines correctness: No separate correctness condition or formal specification
 - Focus on proving complexity results for specific concept classes
- Sample results
 - Can learn DFAs in poly time from membership and equivalence queries
 - Cannot learn DFAs or DNF formulas in poly time with just equivalence queries

Examples of OGIS

- L* algorithm to learn DFAs: counterexample-guided
 - Membership + Equivalence queries
- CEGIS used in SyGuS solvers
 - (positive) Witness + Counterexample/Verification queries
- CEGIS for Hybrid Systems
 - Requirement Mining [HSCC 2013]
 - Reactive Model Predictive Control [HSCC 2015]
- Two different examples:
 - Learning Programs from Distinguishing Inputs [Jha et al., ICSE 2010]
 - Learning LTL Properties for Synthesis from Counterstrategies [Li et al., MEMOCODE 2011]

Revisiting the Comparison



Query Types for CEGIS

LEARNER

Positive Witness

 $x \in \phi$, if one exists, else \bot

ORACLE



Equivalence: Is
$$f = \phi$$
?

Yes / No + $x \in \phi \oplus f$

Subset: Is f ⊆ φ?

Yes / No + $x \in f \setminus \phi$



 Finite memory vs Infinite memory

 Type of counterexample given

Concept class: Any set of recursive languages

Questions

 Convergence: How do properties of the learner and oracle impact convergence of CEGIS? (learning in the limit for infinite-sized concept classes)

Sample Complexity: For finite-sized concept classes, what upper/lower bounds can we derive on the number of oracle queries, for various CEGIS variants?

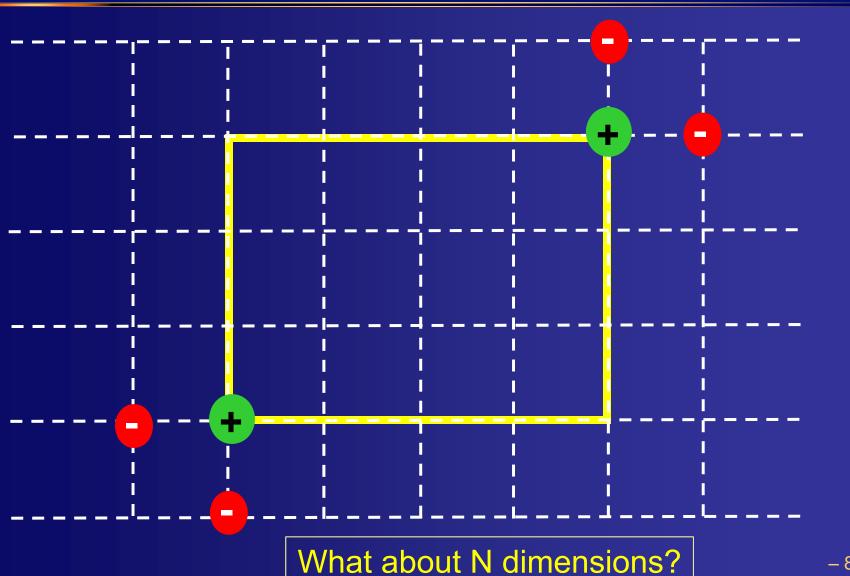
Problem 1: Bounds on Sample Complexity

Teaching Dimension

[Goldman & Kearns, '90, '95]

The minimum number of (labeled) examples a teacher must reveal to uniquely identify any concept from a concept class

Teaching a 2-dimensional Box



Teaching Dimension

The minimum number of (labeled) examples a teacher must reveal to uniquely identify any concept from a concept class

$$TD(C) = \max_{c \in C} \min_{\sigma \in \Sigma(c)} |\sigma|$$

where

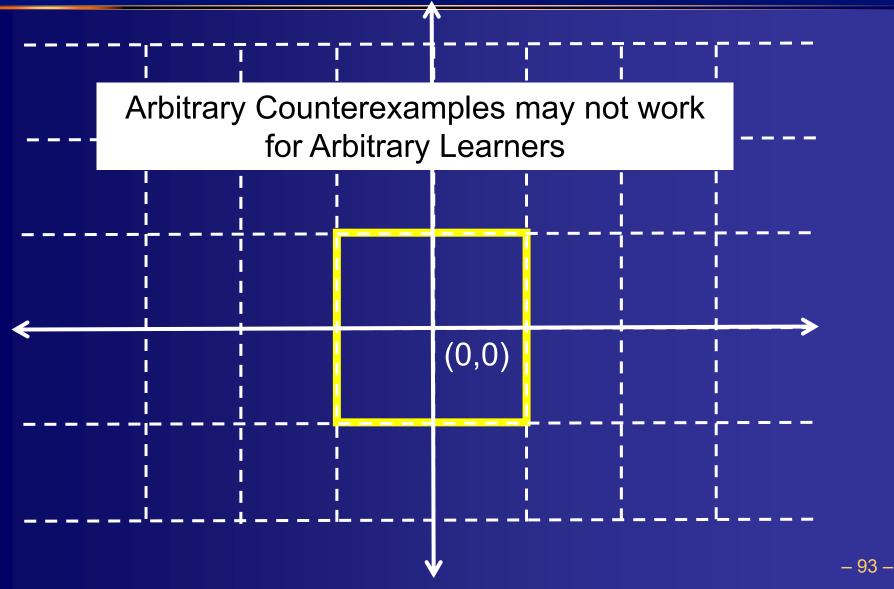
- C is a concept class
- c is a concept
- σ is a teaching sequence (uniquely identifies concept c)
- Σ is the set of all teaching sequences

Theorem: *TD(C)* is lower bound on Sample Complexity

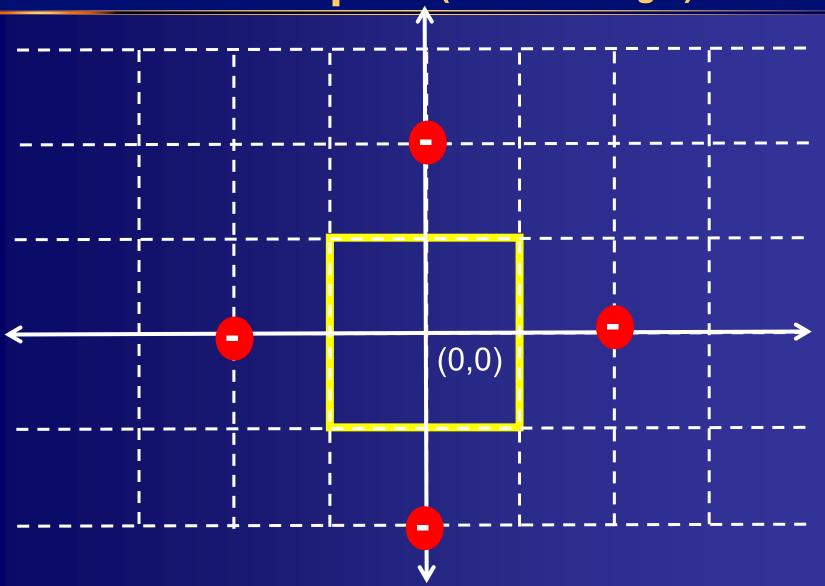
- OGIS: TD gives a lower bound on number of counterexample queries to solve FIS problem
- Finite TD is necessary for termination
 - If C is finite, TD(C) ≤ |C|-1
- Finding Optimal Teaching Sequence is NP-hard (in size of concept class)
 - Hence also finding optimal query sequence for OGIS
 - But heuristic approach works well ("learning from distinguishing inputs")
- Open Problems: Compute TD for common classes of SyGuS problems

Problem 2: Convergence of Counterexampleguided loop with positive witness and counterexample/verification queries

Learning $-1 \le x \le 1 \land -1 \le y \le 1$ (C = Boxes around origin)



Learning $-1 \le x, y \le 1$ from Minimum Counterexamples (dist from origin)



Types of Counterexamples

Assume there is a function size: $D \rightarrow N$

- Maps each example x to a natural number
- Imposes total order amongst examples
- CEGIS: Arbitrary counterexamples
 - Any element of f ⊕ φ
- MinCEGIS: Minimal counterexamples

 - Motivated by debugging methods that seek to find small counterexamples to explain errors & repair

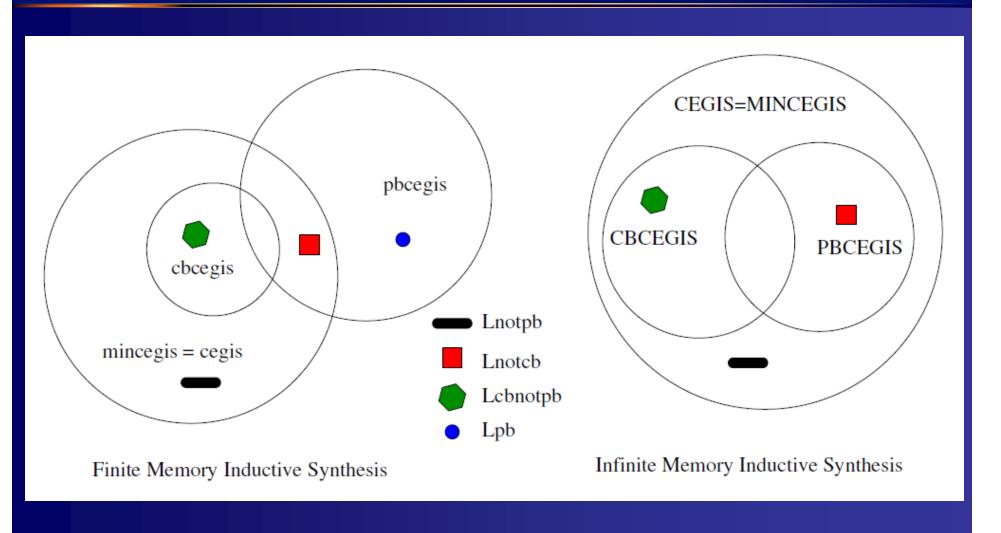
Types of Counterexamples

Assume there is a function size: $D \rightarrow N$

- CBCEGIS: Constant-bounded counterexamples (bound B)
 - An element x of $f \oplus \phi$ s.t. size(x) < B
 - Motivation: Bounded Model Checking, Input Bounding, Context bounded testing, etc.
- PBCEGIS: Positive-bounded counterexamples
 - An element x of $f \oplus \phi$ s.t. size(x) is no larger than that of any positive example seen so far
 - Motivation: bug-finding methods that mutate a correct execution in order to find buggy behaviors

Summary of Results

[Jha & Seshia, SYNT'14; TR'15]



Open Problems

For Finite Domains: What is the impact of type of counterexample and buffer size to store counterexamples on the speed of termination of CEGIS?

For Specific Infinite Domains (e.g., Boolean combinations of linear real arithmetic): Can we prove termination of CEGIS loop?

Summary

- Formal Synthesis and its Applications
 - Demo on Requirement Mining
- Syntax-Guided Synthesis
- Formal Inductive Synthesis
 - Counterexample-guided inductive synthesis (CEGIS)
 - General framework for solution methods: Oracle-Guided Inductive Synthesis (OGIS)
 - Theoretical analysis
- Lots of potential for future work!