Luca Scimeca, Ph.D. Candidate

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Employment History

2017 – current	🔖 **Ph.D Candidate** at Biologically Inspired Robotics Laboratory, University of Cambridge.
	🔖 **Demonstrator** Demonstrator for the University of Cambridge course "Engineering Tripos Part IIA - 3D Printing", Engineering.
	🔖 **Demonstrator** Demonstrator for the University of Cambridge course "3F8 Inference", Machine Learning.
	🔖 **Demonstrator** Demonstrator for the University of Cambridge course Part IA Lego, Robotics.
2016	🔖 **Junior Software Engineer** at Extraordinary Managed Services Ltd, Edinburgh

Education

2017 – current	🔖 **Ph.D. in Engineering (AI and Biologically Inspired Robotics), University of Cambridge, United Kingdom.**
2019	🔖 **Brains, Minds, and Machines summer course, Massachusetts Institute of Technology (MIT), United States**
2013 – 2017	🔖 **BEng (Hons) in Software Engineering and Artificial Intelligence, University of Edinburgh, United Kingdom.** First Class Honours (summa cum laude) - 4.0 GPA, Department prize and Howe Prize for highest cumulative GPA of graduating class

Research Publications

Journal Articles

1. Hughes, J., **Scimeca, L.**, Ifrim, I., Maiolino, P., & Iida, F. (2018). Achieving robotically peeled lettuce. *IEEE Robotics and Automation Letters*, *3*(4), 4337–4342.

2. Stone, T., Webb, B., Adden, A., Weddig, N. B., Honkanen, A., Templin, R., … Heinze, S. (2017). An anatomically constrained model for path integration in the bee brain. *Current Biology*, *27*(20), 3069–3085.

3. Hughes, J., Gilday, K., **Scimeca, L.**, & Iida, F. (forthcoming). Flexible, adaptive industrial assembly: driving innovation through competition. *IEEE Robotics and Automation Letters*.

4. **Scimeca, L.**, Hughes, J., Maiolino, P., & Iida, F. (forthcoming). Model-free soft-structure reconstruction for proprioception using tactile arrays. *IEEE Robotics and Automation Letters*.

Conference Proceedings

1. **Scimeca, L.**, Maiolino, P., & Iida, F. (2018). Soft morphological processing of tactile stimuli for autonomous category formation. In *2018 ieee international conference on soft robotics (robosoft)* (pp. 356–361). IEEE.

(2) **Scimeca**, **L.**, Maiolino, P., Cardin-Catalan, D., P. del Pobil, A., & Iida, F. (forthcoming). Non-destructive robotic assessment of mango ripeness via multi-point soft haptics. In *Ieee international conference on robotics and automation (icra).*

Skills

Languages	▌	English (fluent), Italian (native)
Coding	▌	Python, C++, C, Java, MATLAB, Haskell, Assembly, SQL, XML/XSL
Misc.	▌	TensorFlow, PyTorch, Keras, Darknet, ROS, V-Rep, CAD, 3D-Printing

Miscellaneous

Academic Services

2020	▌	**Workshop Organizer** 'Human-Robot Medical Interaction', Cambridge, UK (2020)
2018	▌	**Workshop Co-organizer** 'Agri-Food Robotics', Cambridge, UK (2018)
2017 – current	▌	**Reviewer** for Journal 'IEEE Robotics and Automation Letters'.
	▌	**Reviewer** for Journal 'Applied Sciences'.
	▌	**Reviewer** for 'International Conference on Robotics and Automation' (ICRA).
	▌	**Reviewer** for 'IEEE International Conference on Soft Robotics' (RoboSoft).

Awards and Achievements

2018	▌	**AJS Special Award** for Industrial Manipulation Challenge, World Robotics Summit 2018, Tokyo, Japan.
	▌	**1st Place Award** Robot Rescue Simulation League, RoboCup 2018, Montreal, Canada.
	▌	**1st Place Award** at "RoboSoft Competition - Manipulation", RoboSoft 2018 IEEE Conference on Soft Robotics, Livorno, Italy.
2017	▌	**Howe Undergraduate Prize**, The University of Edinburgh, United Kingdom. Best performance in Artificial Intelligence of the graduating class.
	▌	**BEng AI & SE class Prize**, The University of Edinburgh, United Kingdom. Highest cumulative grade of the graduating class.
2016	▌	**Winner of Robotic 2-a-side Football Tournament** (System Design Project), The University of Edinburgh, United Kingdom.
2015	▌	**Edinburgh Award** University of Edinburgh, United Kingdom..
2014	▌	**Hackathon Winner**, The Smart Data Hack, Edinburgh, United Kingdom.
2013, 2010, 2009	▌	**Scholarship "Borsa di Studio Benivegna"**, three times winner. Highest final cumulative grade achieved in current year of "Vittorio Emanuele III", Palermo, Italy.
2013	▌	**Informatics Diploma**, graduated with a score of 100 in "Esami di Stato", Palermo, Italy.
2010	▌	**Scholarship "Premio di studi prof. Erasmo Siino"** Highest final grade achieved among all students in the town of Capaci, Palermo, Italy.

Miscellaneous (continued)

Relevant Projects

2019 ◪ **Coding With Neural Networks**, MIT, United States.
Developed a novel compositional neural network achitecture shown to be able to both learn to play 'Game of Life' on arbitrarily long boards as well as perform 'parity bit checking' on arbitrarily long bite strings.

2017 ◪ **RoboAnt Research Project**, Edinburgh, United Kingdom.
Implemented path integration network on an android application based on an insect brain model (mobile-powered, bio-inspired robotics).

2016 ◪ **CIFAR Image Classification with Deep Neural Networks**, Edinburgh, United Kingdom.
Achieved state of the art performance on CIFAR-10 and CIFAR 100 dataset; Devised new Multitask Learning procedures.

◪ **Robot-Football**, Edinburgh, United Kingdom.
Built autonomous robot for two-a-side football game, including: autonomous path planner, image tracking and recognition, physical design and implementation.

2015 ◪ **Bidirectional Transformations**, Edinburgh, United Kingdom.
Researched in the area of Bidirectional Transformations; implemented Object Oriented prototype in Java.

◪ **Carneades Argumentation System**
Developed a python implementation of the Carneades System of argument evaluation (Artificial Intelligence).

References

Dr Fumiya Iida
Cambridge University,
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Prof Perla Maiolino
Oxford University,
✉ perla.maiolino@eng.ox.ac.uk