## Maier-Saupe free energy in weak form

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## 1 Introduction

Here we will find the time evolution equation according to the Maier-Saupe free energy, and then put it into weak form so that it can be solved by a finite element method.

## 2 Maier-Saupe free energy and equations of motion

We begin by defining the tensor order parameter of the nematic system in terms of the probability distribution of the molecular orientation:

$$Q_{ij}(\mathbf{x}) = \int_{S^2} \left( \xi_i \xi_j - \frac{1}{3} \delta_{ij} \right) p(\xi; \mathbf{x}) d\xi \tag{1}$$

where  $p(\xi; \mathbf{x})$  is the probability distribution of molecular orientation in local equilibrium at some temperature T and position  $\mathbf{x}$ . Note that this quantity is traceless and symmetric. Then the mean field free energy is given by:

$$F\left[Q_{ij}\right] = H\left[Q_{ij}\right] - T\Delta S \tag{2}$$

where H is the energy of the configuration, and  $\Delta S$  is the entropy relative to the uniform distribution. We choose H to be:

$$H[Q_{ij}] = \int_{\Omega} \left\{ -\alpha Q_{ij} Q_{ji} + f_e(Q_{ij}, \partial_k Q_{ij}) \right\} d\mathbf{x}$$
(3)

with  $\alpha$  some interaction parameter and  $f_e$  the elastic free energy density. The entropy is given by:

$$\Delta S = -nk_B \int_{\Omega} \left( \int_{S^2} p(\xi; \mathbf{x}) \log \left[ 4\pi p(\xi; \mathbf{x}) \right] d\xi \right) d\mathbf{x}$$
 (4)

where n is the number density of molecules. Now, in general for a given  $Q_{ij}$  there is no unique  $p(\xi; \mathbf{x})$  given by (1). Hence, there is no unique  $\Delta S$ . To find the appropriate  $\Delta S$  corresponding to some fixed  $Q_{ij}$ , we seek to maximize the entropy density for a fixed  $Q_{ij}$  via the method of Lagrange multipliers. This goes as follows:

$$\mathcal{L}[p] = \Delta s[p] - \Lambda_{ij} Q_{ij}[p]$$

$$= \int_{S^2} p(\xi) \left( \log \left[ 4\pi p(\xi) \right] - \Lambda_{ij} \left( \xi_i \xi_j - \frac{1}{3} \delta_{ij} \right) \right) d\xi$$
(5)

Here we've taken the spatial dependence to be implicit, since each of these are local quantities, and we're minimizing them *locally*. So, define a variation in p given by:

$$p'(\xi) = p(\xi) + \varepsilon \eta(\xi) \tag{6}$$

Then we have that:

$$\frac{\delta \mathcal{L}}{\delta p} = \frac{d\mathcal{L}[p']}{d\varepsilon} \bigg|_{\varepsilon=0}$$

$$= \frac{d\mathcal{L}[p']}{dp'} \frac{dp'}{d\varepsilon} \bigg|_{\varepsilon=0}$$

$$= \int_{S^2} \left( \log \left[ 4\pi p(\xi) \right] - \Lambda_{ij} \left( \xi_i \xi_j - \frac{1}{3} \delta_{ij} \right) + 1 \right) \eta(\xi) d\xi$$
(7)

Since this is for an arbitrary variation  $\eta$ , we must have that

$$\log [4\pi p(\xi)] - \Lambda_{ij} \left( \xi_i \xi_j - \frac{1}{2} \delta_{ij} \right) + 1 = 0 \tag{8}$$

Solving for  $p(\xi)$  yields:

$$p(\xi) = \frac{1}{4\pi} \exp\left[-\left(\frac{1}{3}\Lambda_{ij}\delta_{ij} + 1\right)\right] \exp\left[\Lambda_{ij}\xi_{i}\xi_{j}\right]$$
(9)

However,  $p(\xi)$  is a probability distribution, so we need to normalize it over the domain. When we do this, the constant factors out front cancel and we're just left with:

$$p(\xi) = \frac{\exp\left[\Lambda_{ij}\xi_i\xi_j\right]}{Z\left[\Lambda\right]} \tag{10}$$

$$Z\left[\Lambda\right] = \int_{S^2} \exp\left[\Lambda_{ij}\xi_i\xi_j\right] d\xi \tag{11}$$

Now p is uniquely defined in terms of the Lagrange multipliers  $\Lambda_{ij}$ . Plugging this back into the constraint equation (1) we get:

$$Q_{ij} = \frac{1}{Z[\Lambda]} \left( \int_{S^2} \left( \xi_i \xi_j \exp[\Lambda_{kl} \xi_k \xi_l] - \frac{1}{3} \delta_{ij} \exp[\Lambda_{kl} \xi_k \xi_l] \right) d\xi \right)$$

$$= \frac{1}{Z[\Lambda]} \left( \frac{\partial Z[\Lambda]}{\partial \Lambda_{ij}} - \frac{1}{3} \delta_{ij} Z[\Lambda] \right)$$

$$= \frac{\partial \log Z}{\partial \Lambda_{ij}} - \frac{1}{3} \delta_{ij}$$
(12)

This set of equations uniquely defines  $\Lambda_{ij}$  in terms of  $Q_{ij}$ , although the equation is not algebraically solvable. We may also plug (10) into (4) to get  $\Delta S$  as a function of  $\Lambda_{ij}$  (and therefore implicitly of  $Q_{ij}$ ):

$$\Delta S = -nk_B \int_{\Omega} \frac{1}{Z[\Lambda]} \left( \int_{S^2} \exp[\Lambda_{ij} \xi_i \xi_j] \left( \log(4\pi) + \log(1/Z[\Lambda]) + \Lambda_{ij} \xi_i \xi_j \right) d\xi \right) d\mathbf{x}$$

$$= -nk_B \int_{\Omega} \left( \log(4\pi) - \log(Z[\Lambda]) + \Lambda_{ij} \frac{\partial \log Z[\Lambda]}{\partial \lambda_{ij}} \right)$$

$$= -nk_B \int_{\Omega} \left( \log(4\pi) - \log(Z[\Lambda]) + \Lambda_{ij} \left( Q_{ij} + \frac{1}{3} \delta_{ij} \right) \right)$$
(13)

Further, we may explicitly write out the elastic free energy as:

$$f_e(Q_{ij}, \partial_k Q_{ij}) = L_1(\partial_k Q_{ij})(\partial_k Q_{ij}) + L_2(\partial_j Q_{ij})(\partial_k Q_{ik}) + L_3 Q_{kl}(\partial_k Q_{ij})(\partial_l Q_{ij})$$
(14)

Now, since  $Q_{ij}$  is traceless and symmetric, we need to use a Lagrange multiplier scheme so that there is an extra piece in our free energy:

$$f_l = -\lambda Q_{ii} - \lambda_i \epsilon_{ijk} Q_{jk} \tag{15}$$

To get a time evolution equation for Q, we just take the negative variation of the free energy density f with respect to each of them:

$$\partial_t Q_{ij} = -\frac{\partial f}{\partial Q_{ij}} + \partial_k \frac{\partial f}{\partial (\partial_k Q_{ij})} \tag{16}$$

Let's write out these terms explicitly. We start with the Maier-Saupe interaction term:

$$-\frac{\partial}{\partial Q_{ij}} \left(-\alpha Q_{kl} Q_{lk}\right) = \alpha \delta_{ik} \delta_{jl} Q_{lk} + \alpha \delta_{il} \delta_{jk} Q_{kl}$$

$$= 2\alpha Q_{ij}$$
(17)

Now elastic energy:

$$-\frac{\partial}{\partial Q_{ij}} \left( L_3 Q_{kl} (\partial_k Q_{nm}) (\partial_l Q_{nm}) \right) = -L_3 \delta_{ik} \delta_{jl} (\partial_k Q_{nm}) (\partial_l Q_{nm})$$

$$= -L_3 (\partial_i Q_{nm}) (\partial_j Q_{nm})$$
(18)

And the Lagrange multiplier terms:

$$-\frac{\partial}{\partial Q_{ij}} \left( -\lambda Q_{kk} - \lambda_k \epsilon_{klm} Q_{lm} \right) = \lambda \delta_{ik} \delta_{jk} + \lambda_k \epsilon_{klm} \delta_{il} \delta_{jm}$$

$$= \lambda \delta_{ij} + \lambda_k \epsilon_{kij}$$
(19)

Now for the other elastic energy terms:

$$\partial_k \frac{\partial f}{\partial (\partial_k Q_{ij})} L_1(\partial_l Q_{nm})(\partial_l Q_{nm}) = L_1 \partial_k \left( \delta_{kl} \delta_{in} \delta_{jm} \partial_l Q_{nm} + \partial_l Q_{nm} \delta_{kl} \delta_{ik} \delta_{jm} \right)$$

$$= 2L_1 \partial_k \partial_k Q_{ij}$$
(20)

And the  $L_2$  term:

$$\partial_{k} \frac{\partial f}{\partial(\partial_{k}Q_{ij})} L_{2}(\partial_{m}Q_{lm})(\partial_{n}Q_{ln}) = L_{2}\partial_{k} \left(\delta_{km}\delta_{il}\delta_{jm}(\partial_{n}Q_{ln}) + (\partial_{m}Q_{lm})\delta_{kn}\delta_{il}\delta_{jn}\right)$$

$$= L_{2}\partial_{k} \left(\delta_{kj}(\partial_{n}Q_{in}) + \delta_{kj}(\partial_{m}Q_{im})\right)$$

$$= 2L_{2}\partial_{i} \left(\partial_{m}Q_{im}\right)$$

$$(21)$$

And finally the  $L_3$  term:

$$\partial_{k} \frac{\partial f}{\partial(\partial_{k}Q_{ij})} L_{3}Q_{np}(\partial_{n}Q_{lm})(\partial_{p}Q_{lm}) = L_{3}\partial_{k}Q_{np}\left(\delta_{kn}\delta_{il}\delta_{jm}(\partial_{p}Q_{lm}) + (\partial_{n}Q_{lm})\delta_{kp}\delta_{il}\delta_{jm}\right)$$

$$= L_{3}\partial_{k}\left(Q_{kp}(\partial_{p}Q_{ij}) + Q_{nk}(\partial_{n}Q_{ij})\right)$$

$$= 2L_{3}\partial_{k}\left(Q_{kn}(\partial_{n}Q_{ij})\right)$$

$$(22)$$

Finally, we consider the entropy term:

$$-\frac{\partial}{\partial Q_{ij}} \left[ -nk_B T \left( \log(4\pi) - \log(Z[\Lambda]) + \Lambda_{kl}(Q_{kl} + \frac{1}{3}\delta_{kl}) \right) \right] = nk_B T \left( -\frac{\partial \log Z}{\partial \Lambda_{kl}} \frac{\partial \Lambda_{kl}}{\partial Q_{ij}} + \frac{\partial \Lambda_{kl}}{\partial Q_{ij}} \left( Q_{kl} + \frac{1}{3}\delta_{kl} \right) + \Lambda_{kl}\delta_{ik}\delta_{jl} \right)$$

$$= nk_B T \left( -\left( Q_{kl} + \frac{1}{3}\delta_{kl} \right) \frac{\partial \Lambda_{kl}}{\partial Q_{ij}} + \frac{\partial \Lambda_{kl}}{\partial Q_{ij}} \left( Q_{kl} + \frac{1}{3}\delta_{kl} \right) + \Lambda_{ij} \right)$$

$$= nk_B T \Lambda_{ij}$$

$$(23)$$

Finally, we need to write down the Lagrange multipliers in terms of Q and its spatial derivatives. To do this, note that  $Q_{ij}$  is traceless and symmetric so that  $\partial_t Q_{ij}$  is also traceless and symmetric. Hence, to find  $\lambda$  we just take negative  $\frac{1}{3}$  the trace of the source term. This gives:

$$\lambda = -\frac{1}{3} \left( -L_3(\partial_i Q_{nm})(\partial_i Q_{nm}) + 2L_2 \partial_i (\partial_m Q_{im}) \right) \tag{24}$$

where the rest of the terms are traceless. Now to find  $\lambda_k$ , we know that the anti-symmetric piece of any matrix can be given by:

$$\frac{1}{2}\left(A_{ij} - A_{ji}\right) \tag{25}$$

This anti-symmetric part will be exactly the Lagrange multiplier term:

$$\lambda_k \epsilon_{kij} = -\frac{1}{2} \left( A_{ij} - A_{ji} \right) \tag{26}$$

To solve for  $\lambda_k$  explicitly, we may calculate:

$$-\frac{1}{2}\epsilon_{lij} (A_{ij} - A_{ji}) = \lambda_k \epsilon_{kij} \epsilon_{lij}$$

$$= \lambda_k (\delta_{kl} \delta_{ii} - \delta_{ki} \delta_{il})$$

$$= 2\lambda_l$$
(27)

Hence:

$$\lambda_l = -\frac{1}{2} L_2 \epsilon_{lij} \left( \partial_i (\partial_m Q_{im}) - \partial_i (\partial_m Q_{jm}) \right) \tag{28}$$

since the  $L_2$  term is the only one that's anti-symmetric.

Hence, the total equation of motion is:

$$\partial_t Q_{ij} = 2\alpha Q_{ij} - L_3(\partial_i Q_{nm})(\partial_j Q_{nm}) + \frac{1}{3} \left( L_3(\partial_k Q_{nm})(\partial_k Q_{nm}) - 2L_2(\partial_k \partial_m Q_{im}) \right) \delta_{ij}$$

$$+ \frac{1}{2} L_2 \left( (\partial_m \partial_n Q_{kn}) - (\partial_k \partial_n Q_{kn}) \right) \epsilon_{lkm} \epsilon_{lij} + nk_B T \Lambda_{ij}$$

$$+ 2L_1 \partial_k \partial_k Q_{ij} + 2L_2 (\partial_j \partial_m Q_{im}) + 2L_3 \partial_k \left( Q_{kn}(\partial_n Q_{ij}) \right)$$

$$(29)$$

To put this into weak form, we just integrate against

Now, since  $Q_{ij}$  is traceless and symmetric, we only have five independent degrees of freedom. We label as follows:

$$Q_{ij} = \begin{bmatrix} Q_1 & Q_2 & Q_3 \\ Q_2 & Q_4 & Q_5 \\ Q_3 & Q_5 & -(Q_1 + Q_4) \end{bmatrix}$$
(30)