## INF721

2024/2



# Deep Learning

L17: Transformers

### Logistics

#### **Last Lecture**

- Machine Translation
- Decoding
  - Greedy Search
  - Beam Search
- Attention in RNNs



#### Lecture Outline

- Machine Translation
- ▶ Problems with RNNs
- ▶ Transformers
  - Self-Attention
  - Multi-head Attention
  - ▶ Encoder & Decoder
  - Positional Encoding
  - Masked Multi-head Attention



#### **Machine Translation**

Given a dataset of sentence pairs:

$$(x = \{x^{<1>}, x^{<2>}, \dots, x^{}\}, y = \{y^{<1>}, y^{<2>}, \dots, y^{}\}),$$

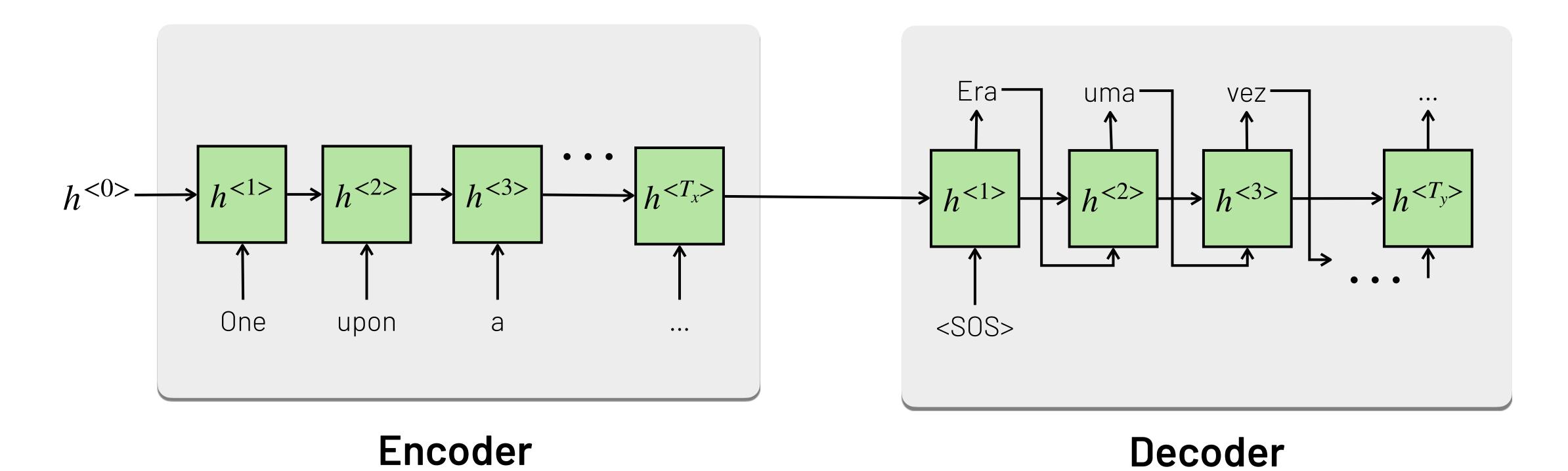
we want to learn a model that maps x into y.

Portuguese	English
Olá, como vai você?	Hello, how are you?
O livro está em cima da mesa.	The book is on the table.
Lucas irá viajar ao Rio em Dezembro.	Lucas is travelling to Rio in December.
Em Dezembro, Lucas irá viajar ao Rio.	Lucas is travelling to Rio in December.
• • •	• • •



#### Problems with RNNs

- Struggle to capture long dependencies in sequences
- Hard to parallelize



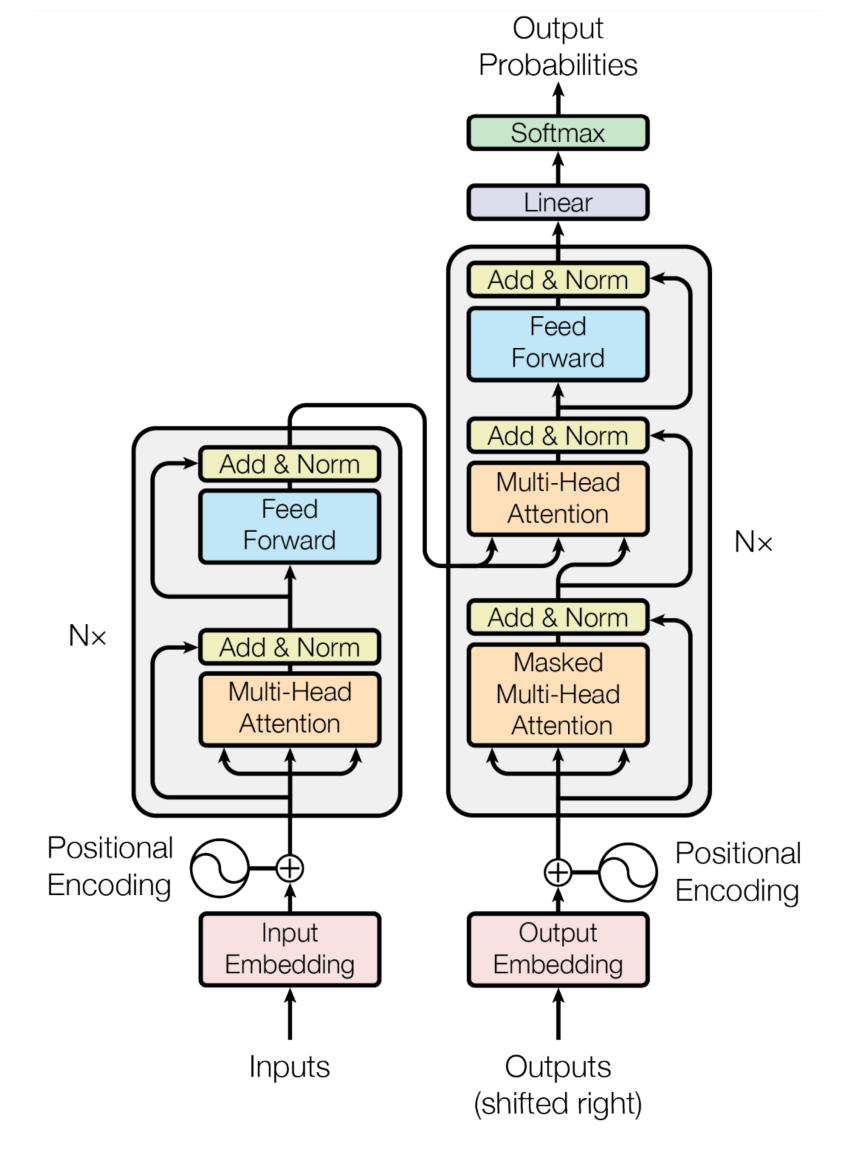


#### Transformers

**Transformers** are an encoder-decoder architecture to process sequences using only attention (eliminating recurrence).

Initially proposed for machine translation, but proved to be very effective in many other problems in:

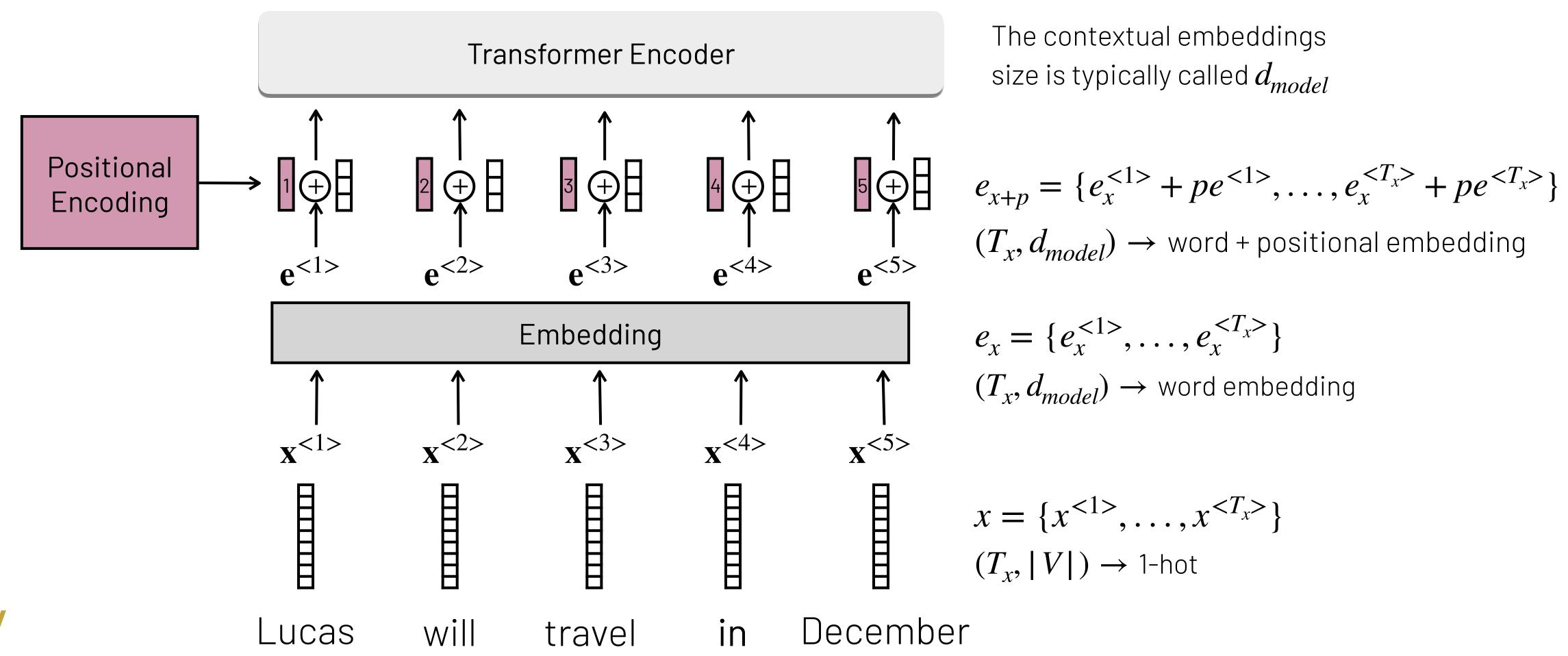
- Natural Language Processing
- Computer Vision
- Reinforcement Learning
- ...





### Encoder Input

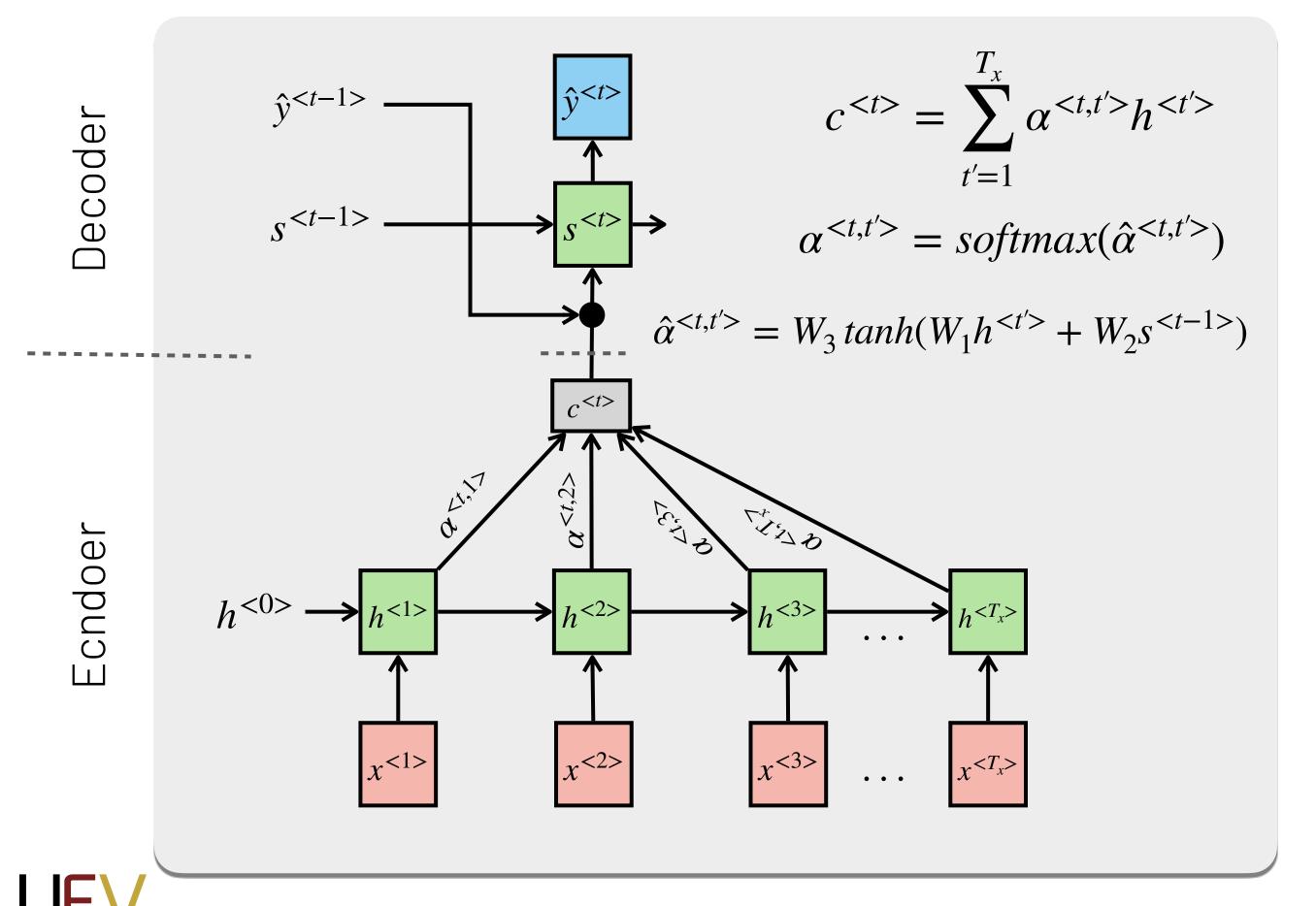
The transformer encoder takes as input a sequence of word embeddings summed with positional encodings. This sequence has the constant size  $(T_x, d_{model})$  throughout the entire model



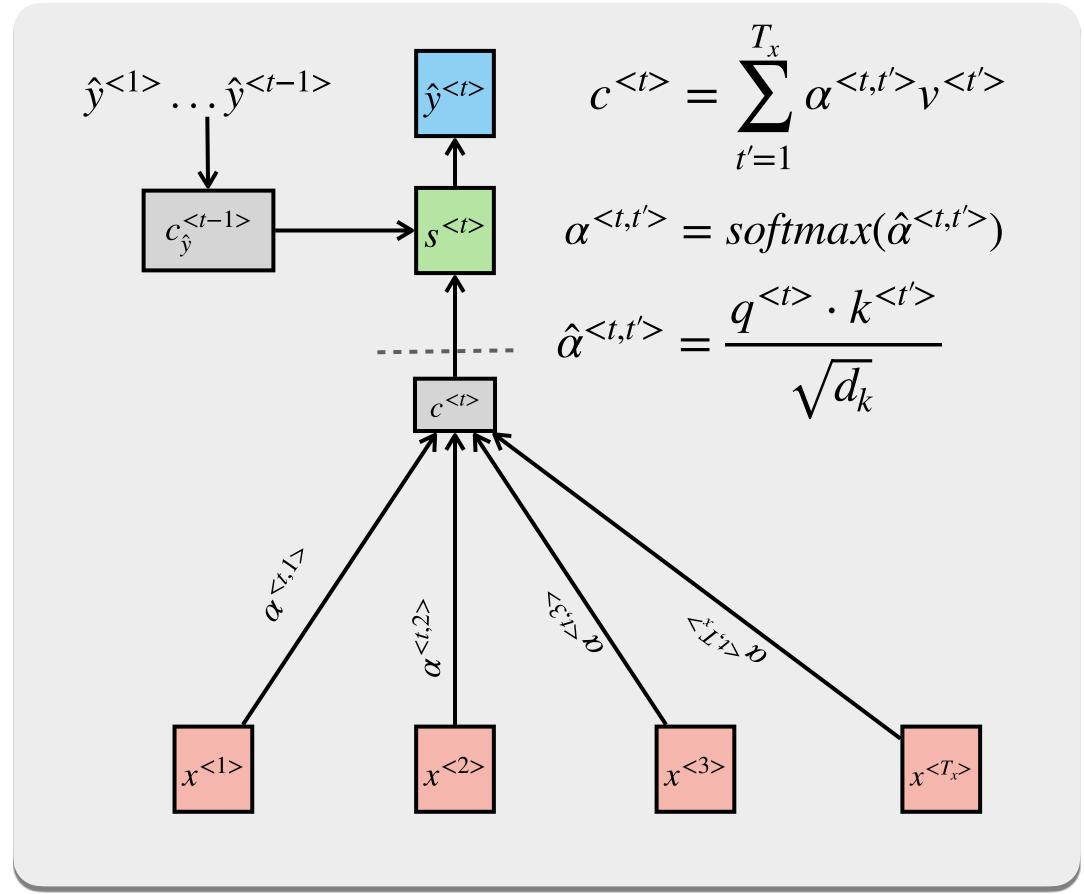


#### Attention in RNNs vs. Transformers

RNNs Badahnau (Additive) Attention

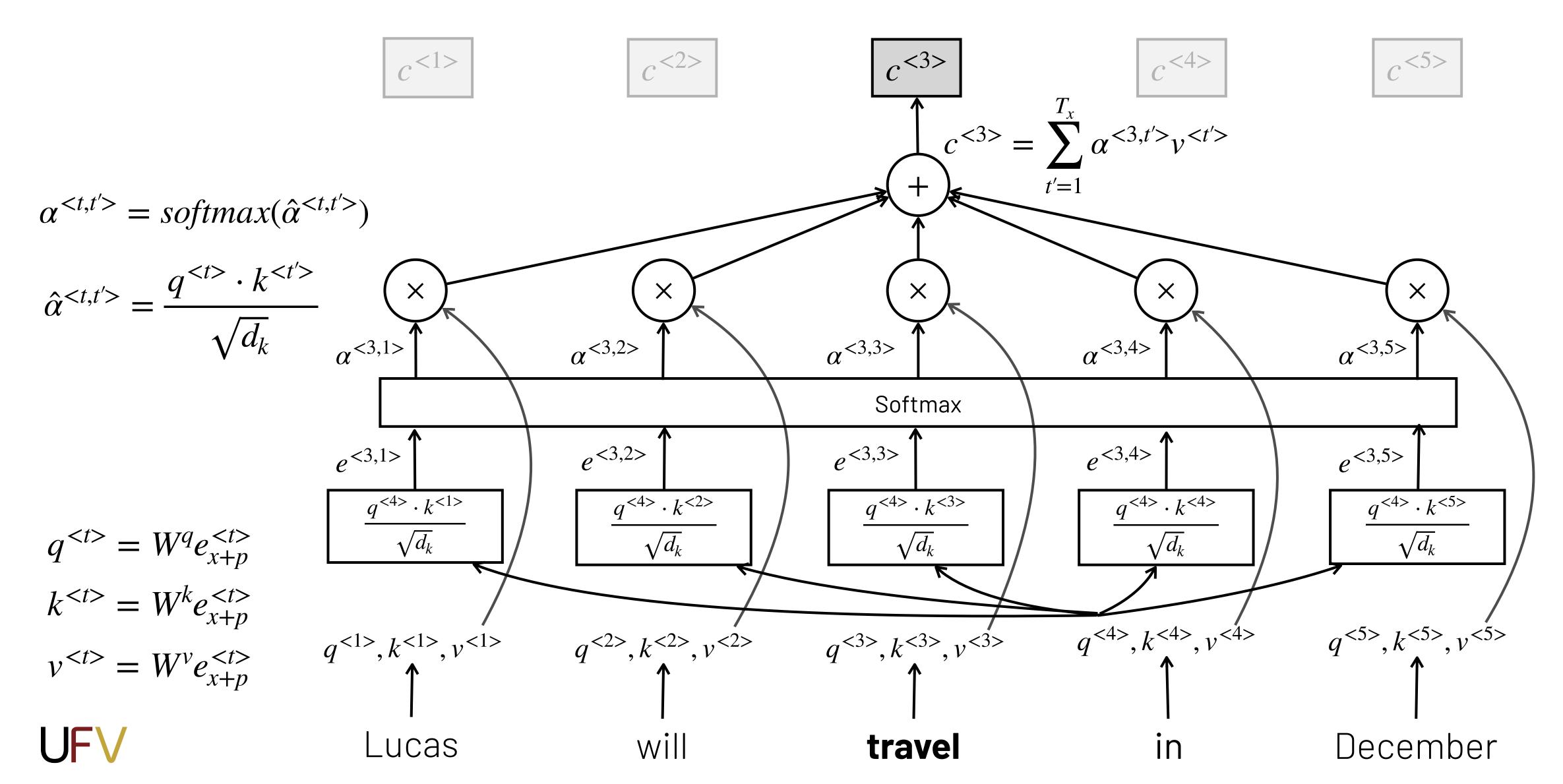


**Transformers** Scaled Dot-Product Attention



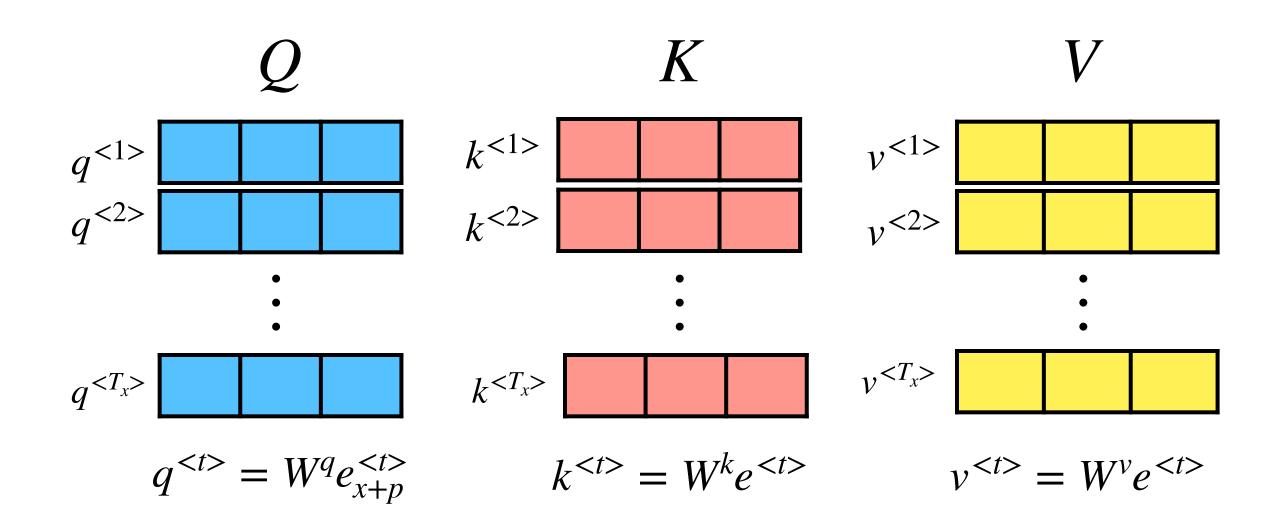
#### Self-Attention

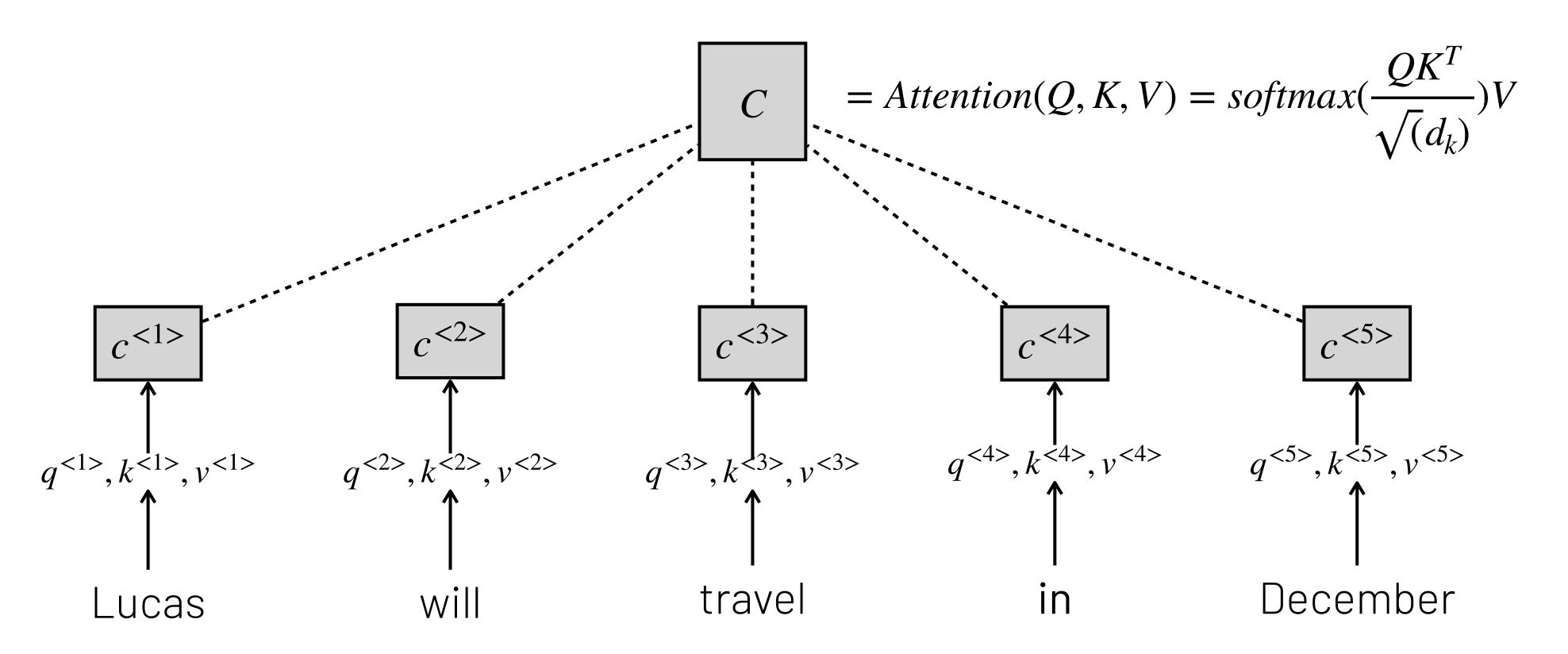
The key idea behing the Transformer is the **self-attention mechanism**, which learns a context vector  $c^{< t>}$  for each input element  $x^{< t>}$  based on the input sequence x itself.



#### Self-Attention

The contextal represention  $C = \{c^{<1>}, \ldots, c^{<T_x>}\}$  of the entire input sequence  $x = \{x^{<1>}, \ldots, x^{<T_x>}\}$  can be computed in a vectorized way combining vectors  $q^{<t>}$ ,  $k^{<t>}$ ,  $v^{<t>}$  in matrices Q,  $K \in V$ 

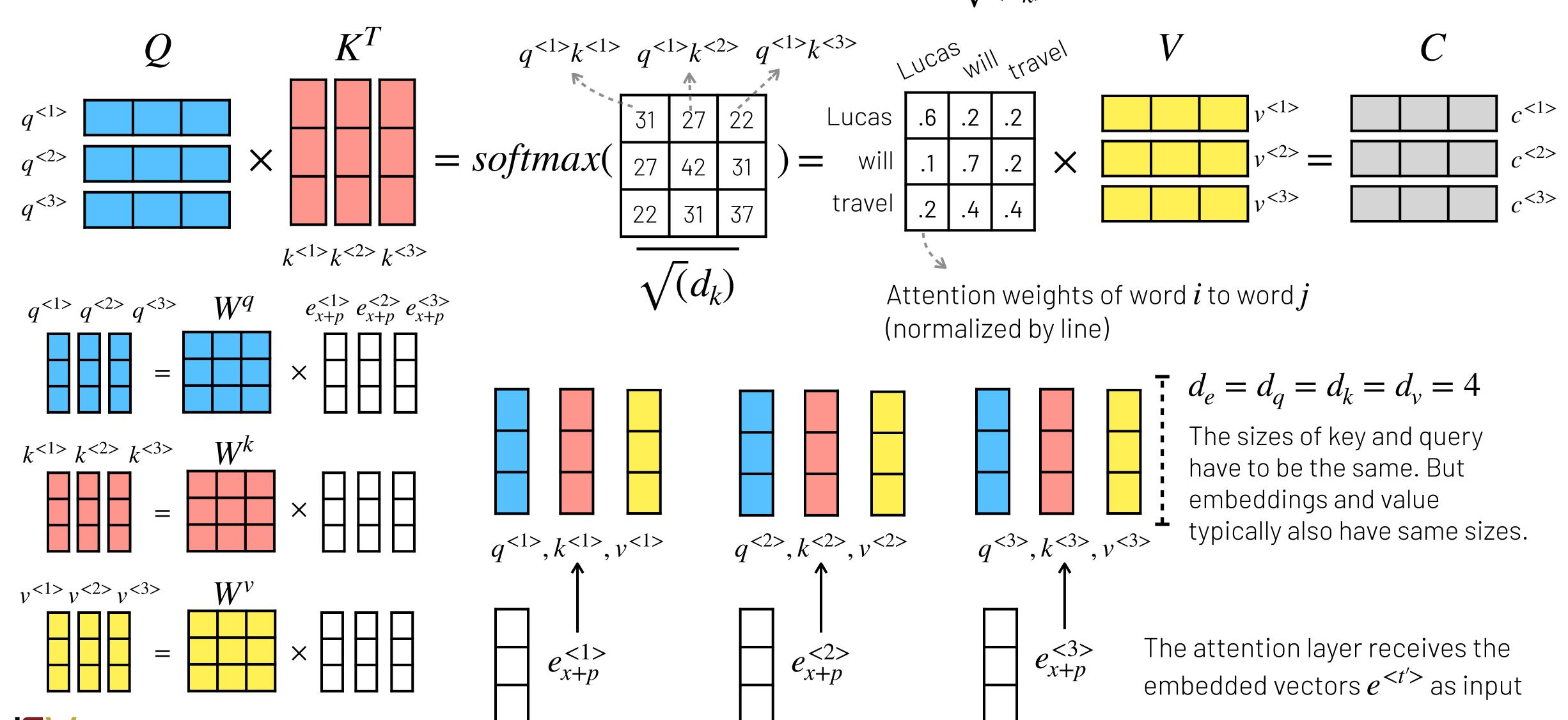






#### Self-Attention

$$C = Attention(Q, K, V) = softmax(\frac{QK^{T}}{\sqrt{(d_k)}})V$$



will

Lucas

travel

11

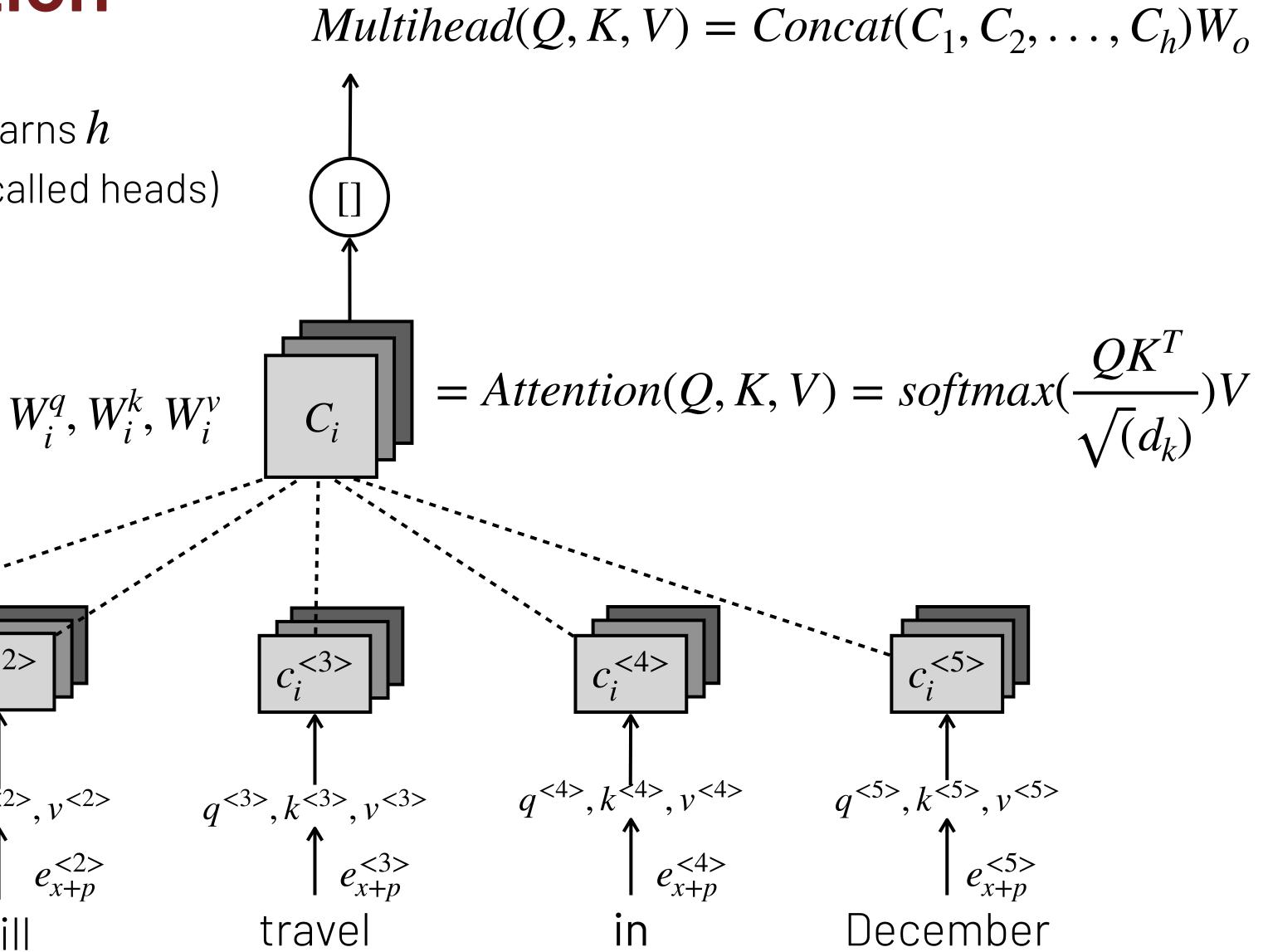
#### **Multi-Head Attention**

 $q^{<1>}, k^{<1>}, v^{<1>}$ 

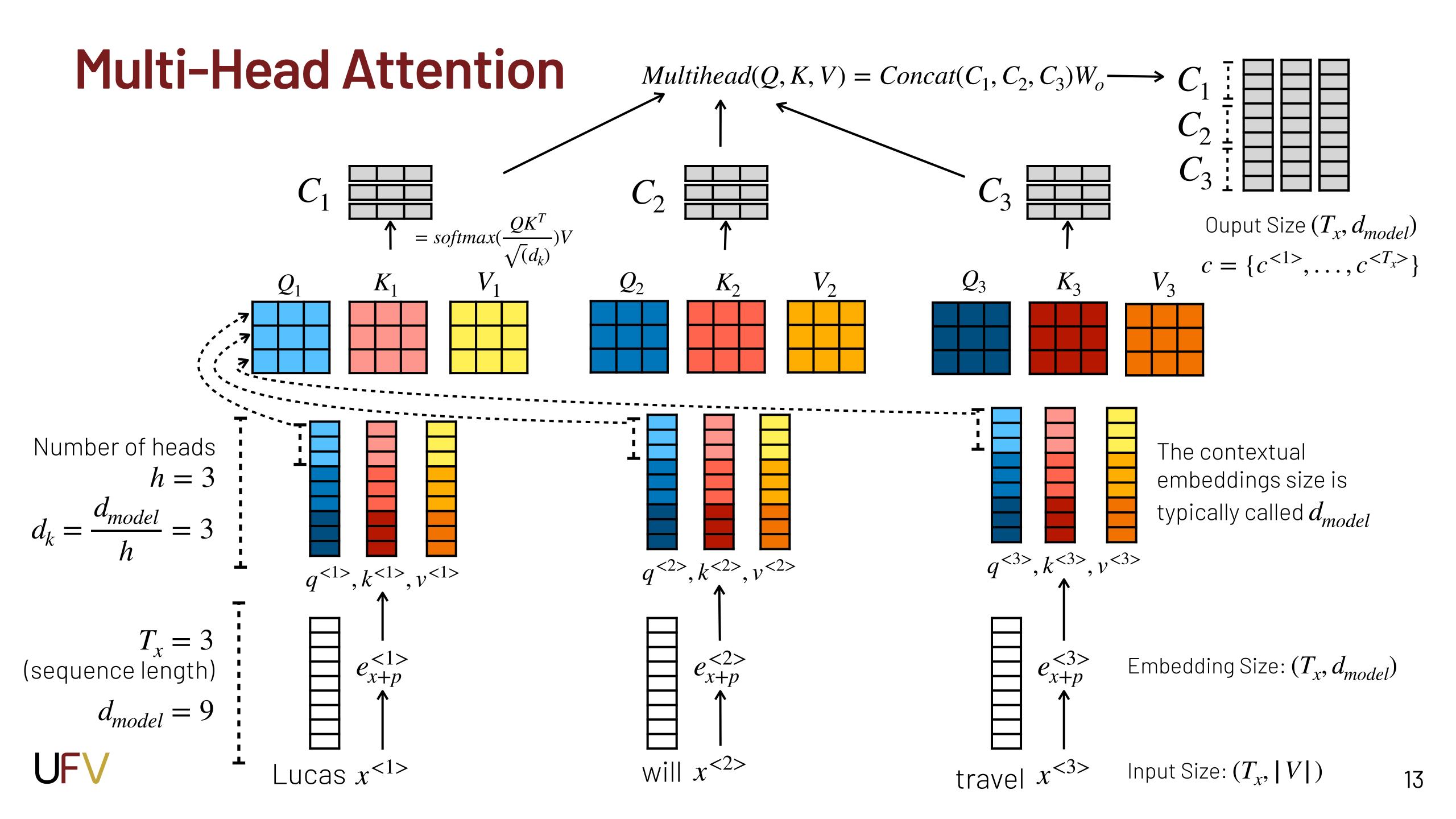
Lucas

will

The Multi-Head Attention layers learns h independent representations  $C_i$  (called heads) using Self-Attention







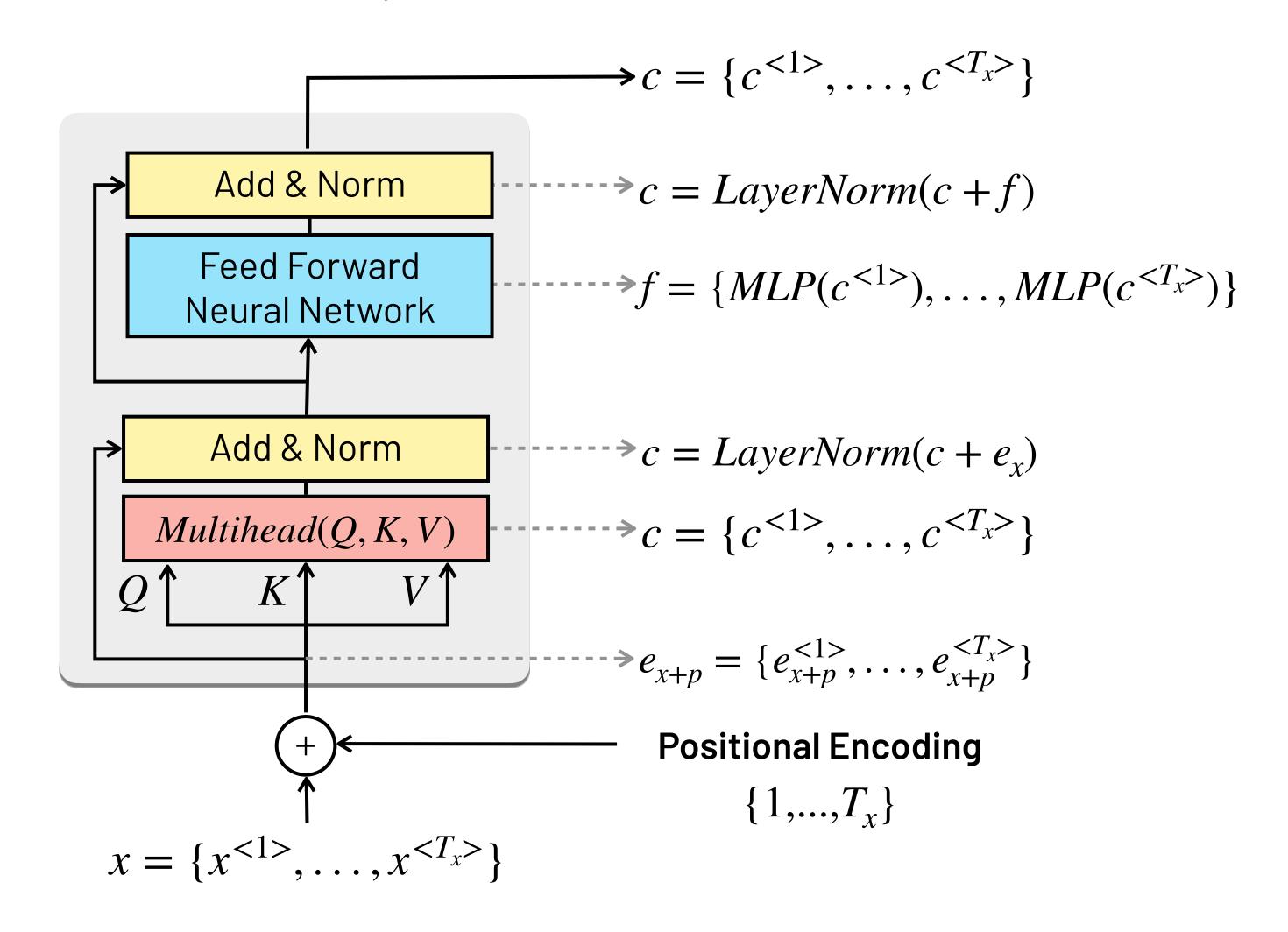
#### Encoder

**Input**: a sequence  $x = \{x^{<1>}, \dots, x^{< T_x>}\}$ 

**Ouput**: a contextual representation  $C = \{c^{<1>}, \dots, c^{<T_x>}\}$  of x

The encoder applies a Multihead Layer followed by a Feed Forward Neural Network (MLP).

Both are normalized with Layer Norm (*Norm*) and conneced with a residual connection (*Add*)

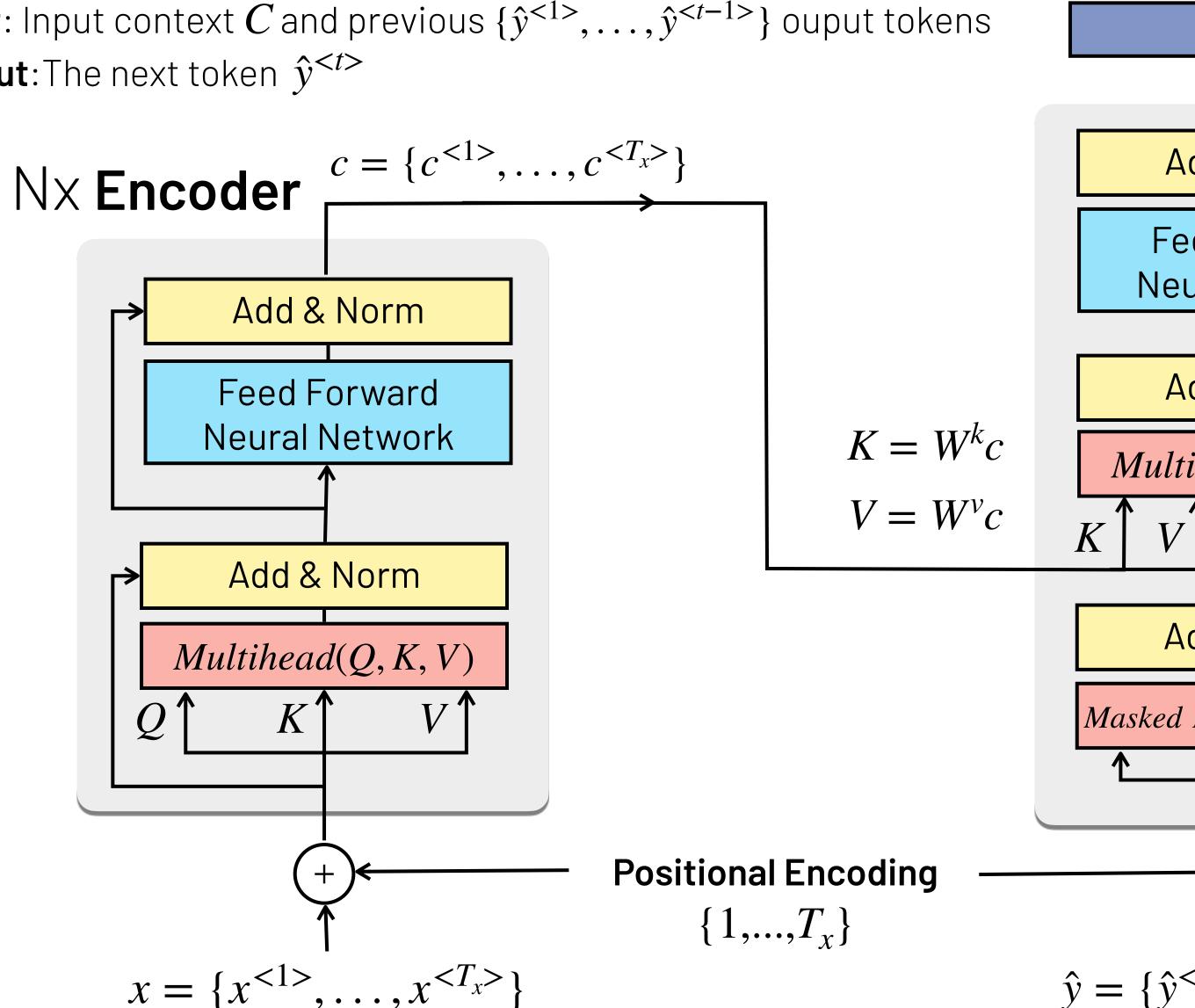


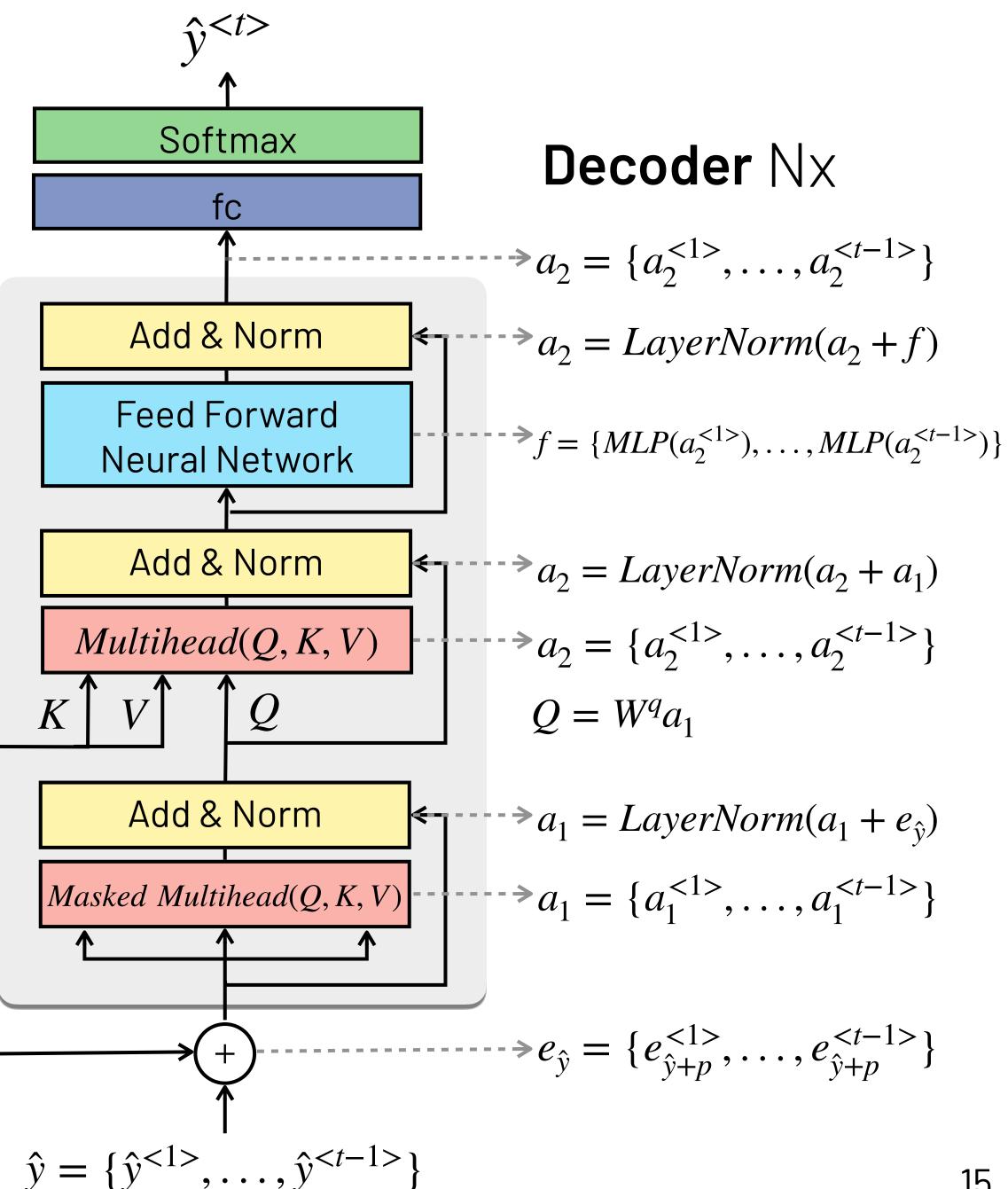


#### Decoder

**Input**: Input context C and previous  $\{\hat{y}^{<1>}, \dots, \hat{y}^{<t-1>}\}$  ouput tokens

**Output:** The next token  $\hat{y}^{< t>}$ 



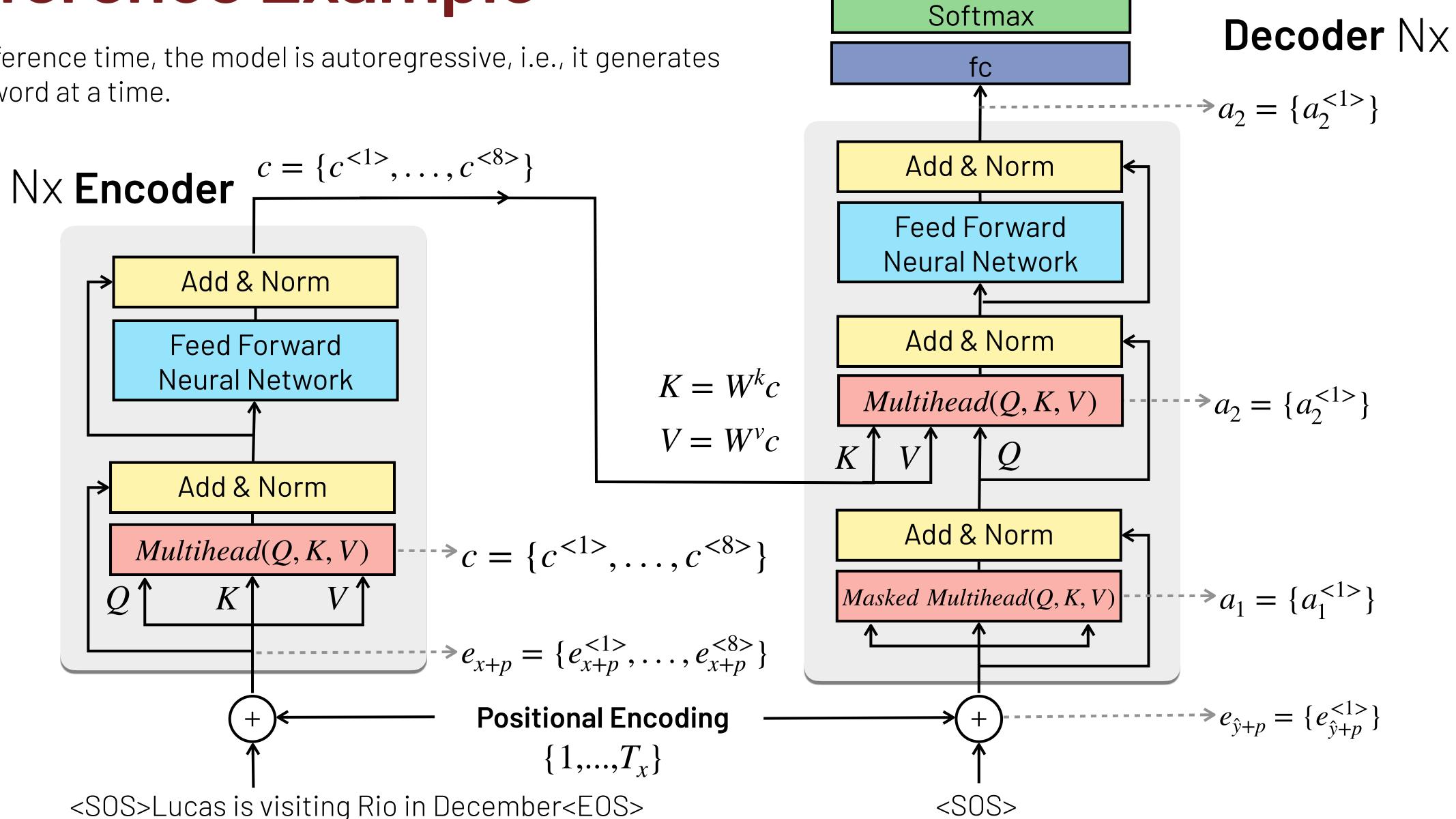




15

### Inference Example

At inference time, the model is autoregressive, i.e., it generates one word at a time.



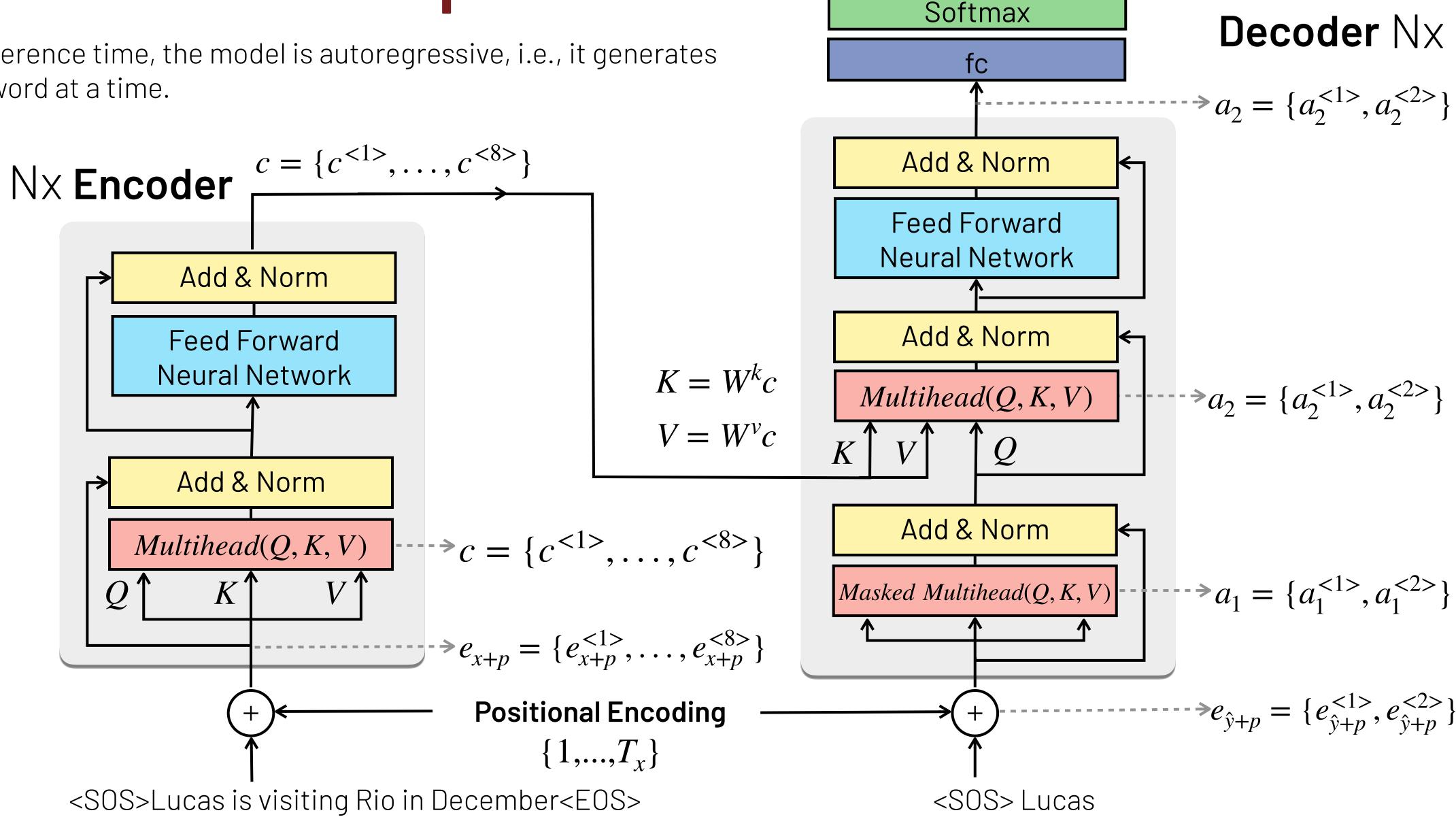
 $\hat{y}$  = Lucas



<SOS>Lucas is visiting Rio in December<EOS>

### Inference Example

At inference time, the model is autoregressive, i.e., it generates one word at a time.

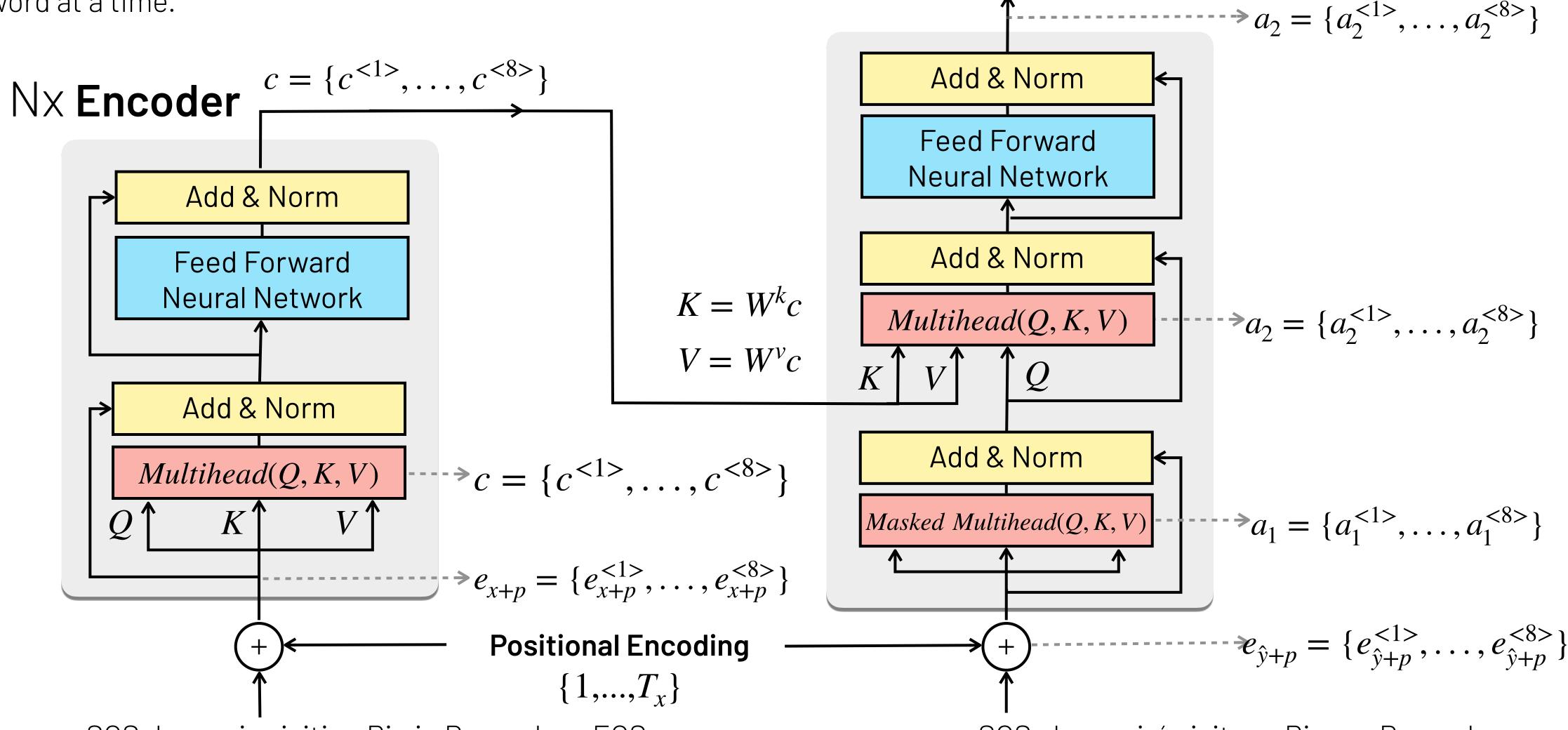


 $\hat{y}$  = Lucas irá



### Inference Example

At inference time, the model is autoregressive, i.e., it generates one word at a time.





<SOS> Lucas irá visitar o Rio em Dezembro

 $\hat{y}$  = Lucas irá visitar o Rio em Dezembro<EOS>

Decoder Nx

Softmax

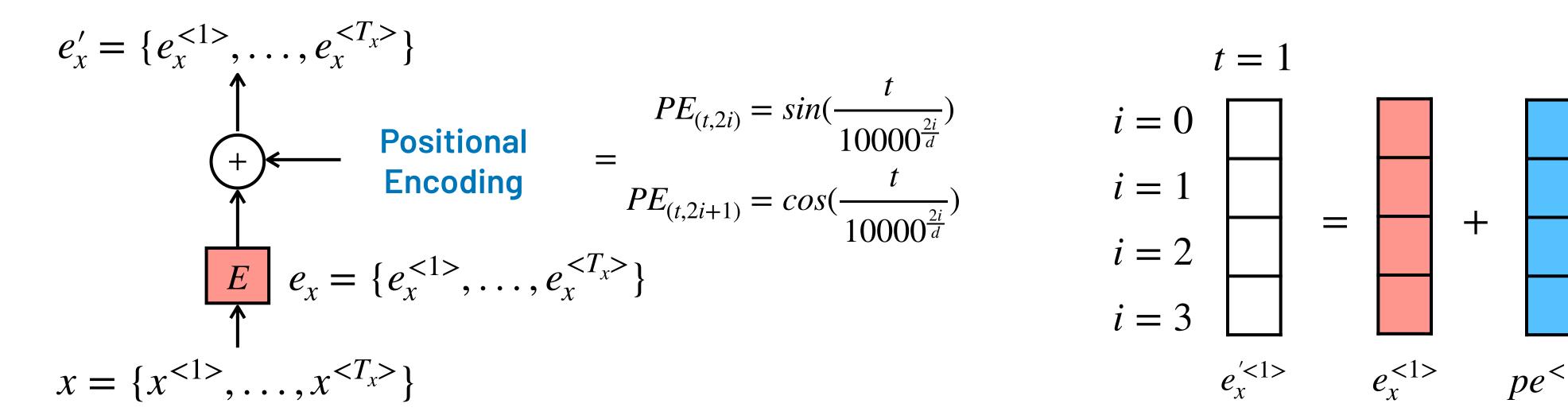
fc

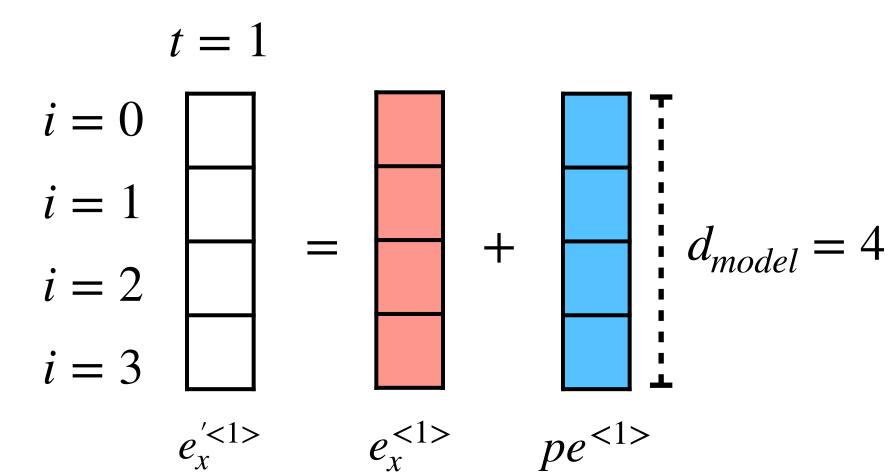
### Positional Encoding

The self-attention mechanism does not consider the position of the words.

$$C = Attention(Q, K, V) = softmax(\frac{QK^{T}}{\sqrt{(d_k)}})V$$

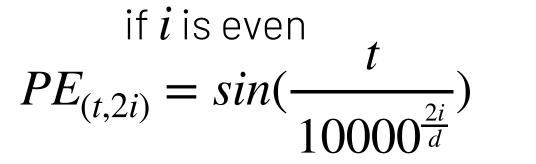
To add this information to the learned contextual representation  $oldsymbol{C}$ , both encoder and decoder add an positional information to each element  $x^{< t>}$  of the input  $x = \{x^{< 1>}, \dots, x^{< T_x>}\}$ 



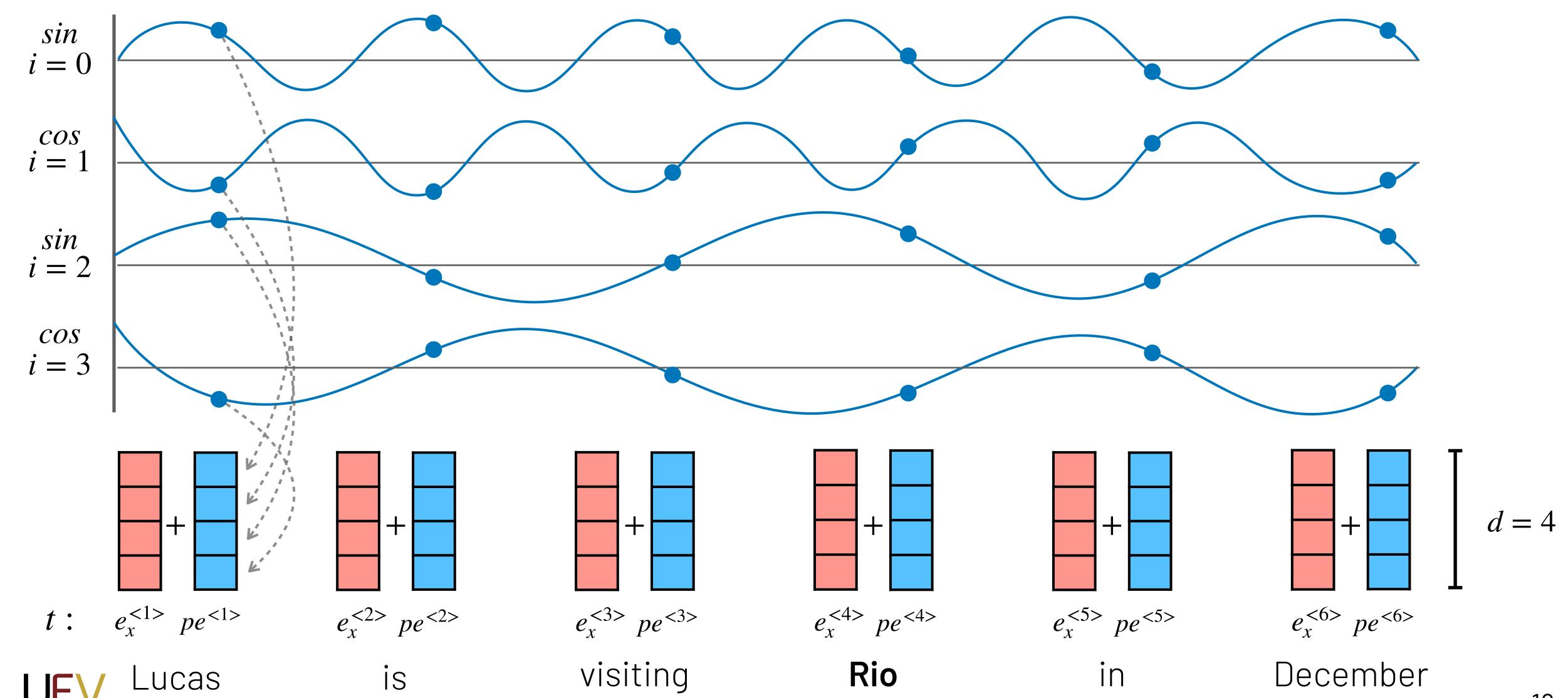




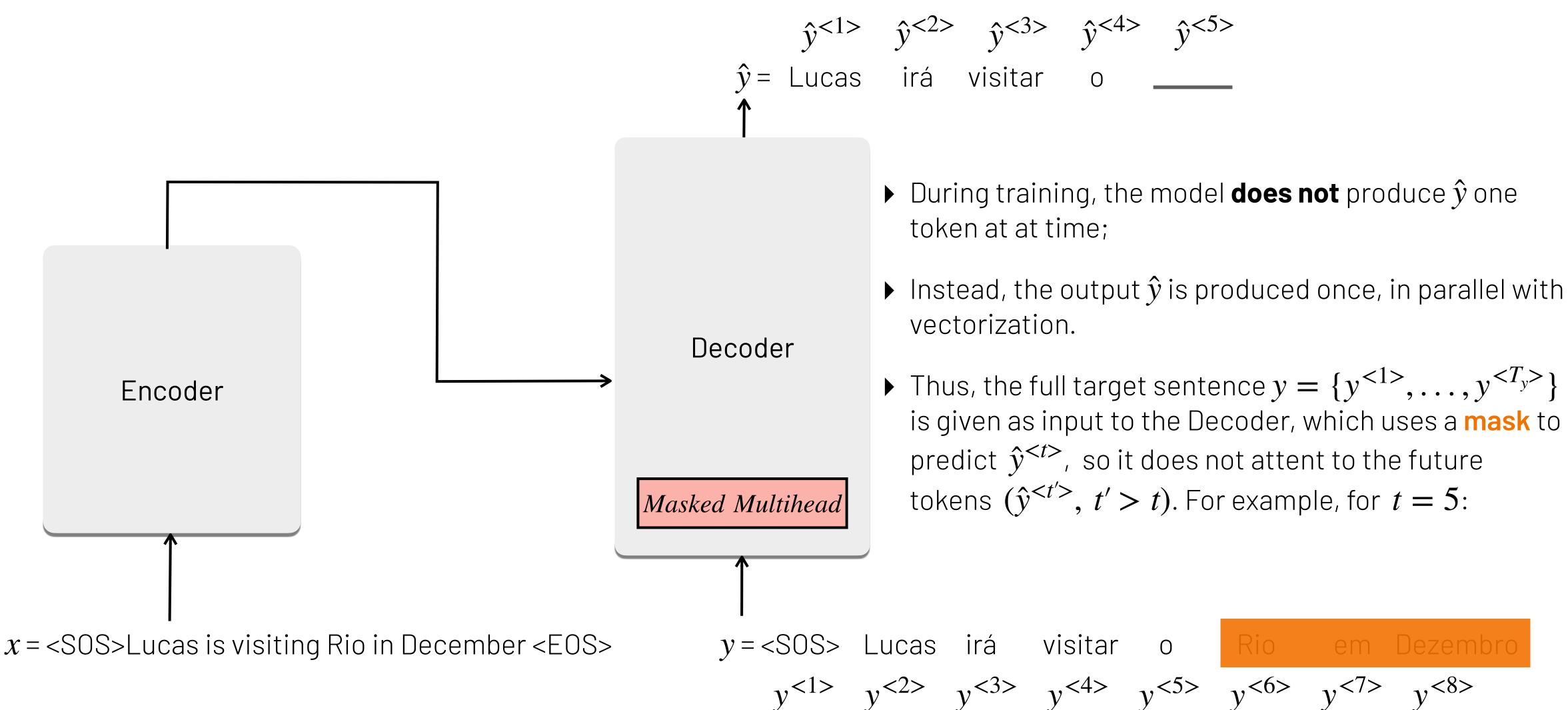
### Positional Encoding



if 
$$i$$
 is odd
$$PE_{(t,2i+1)} = cos(\frac{t}{10000^{\frac{2i}{d}}})$$

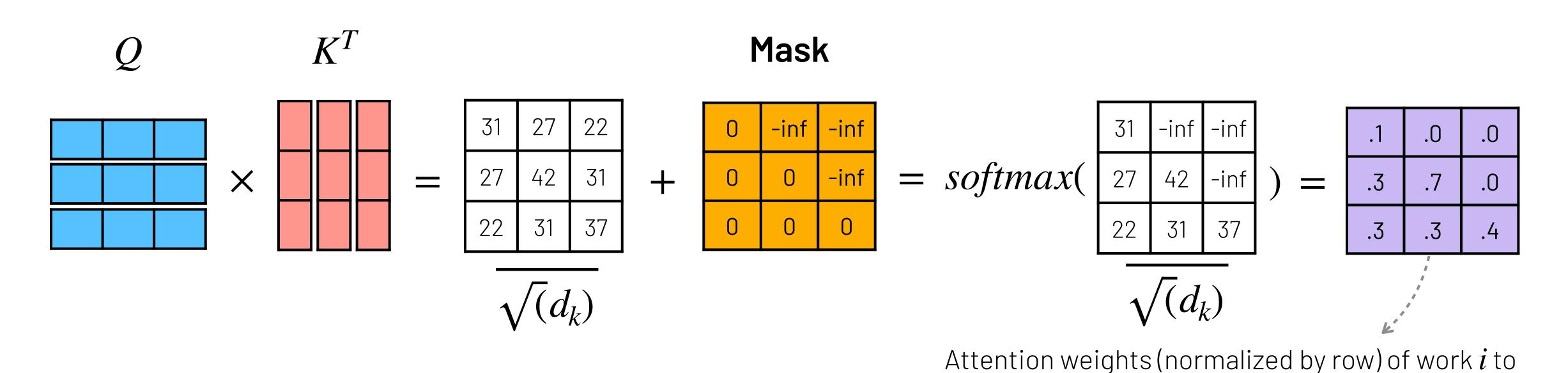


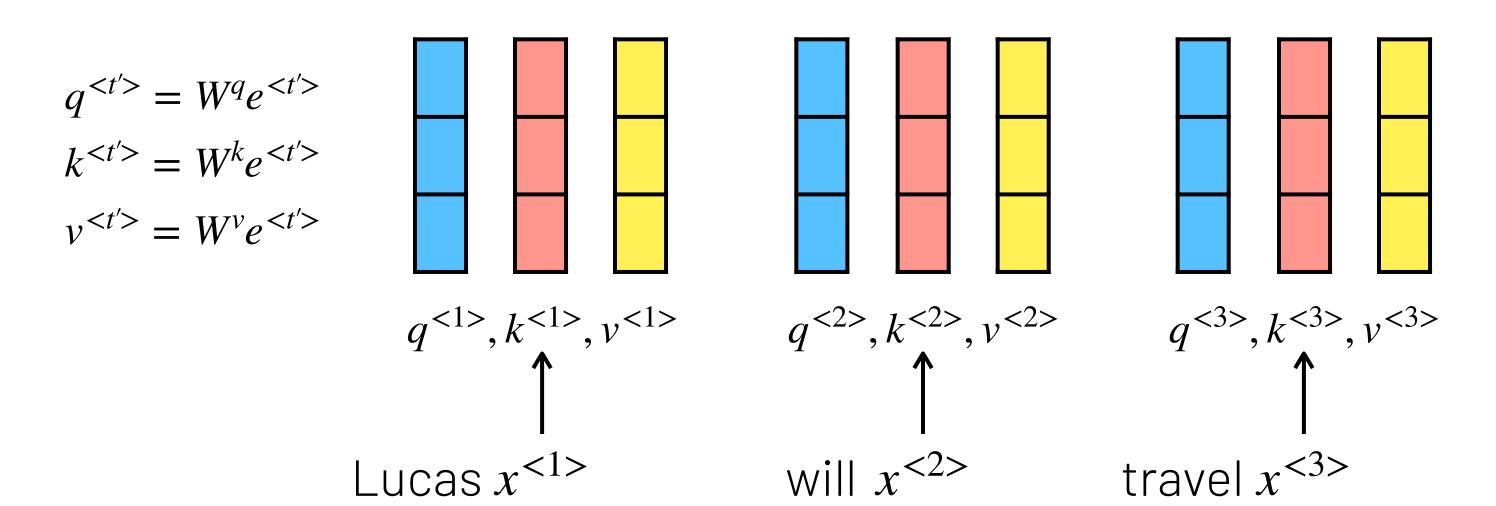
### Training with Masked Multi-head Attention





### Training with Masked Multi-head Attention







word j after mask application

#### Next Lecture

L17: Transformers (Part II)

Case studies of transformers: BERT and GPT

