Mestrado em Engenharia Informática

The 3D Rendering Problem

Visualização e Iluminação

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Global Illumination

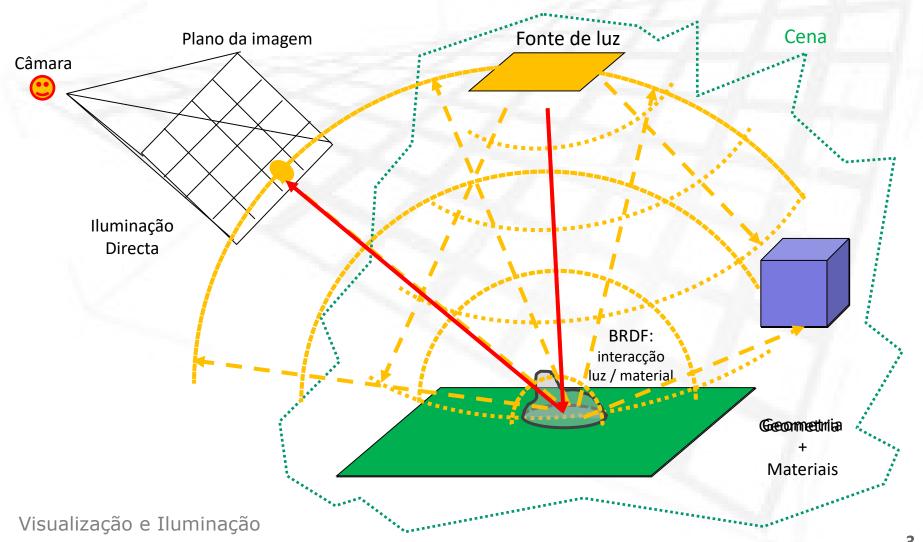




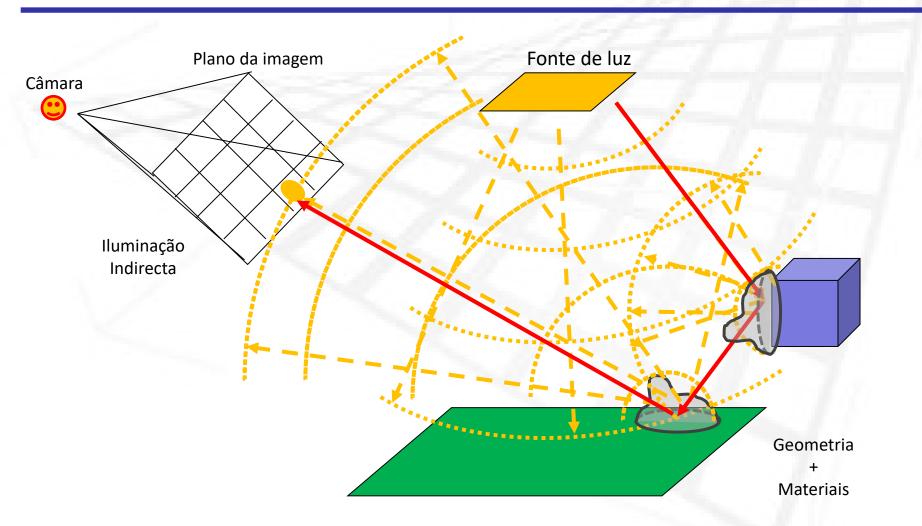


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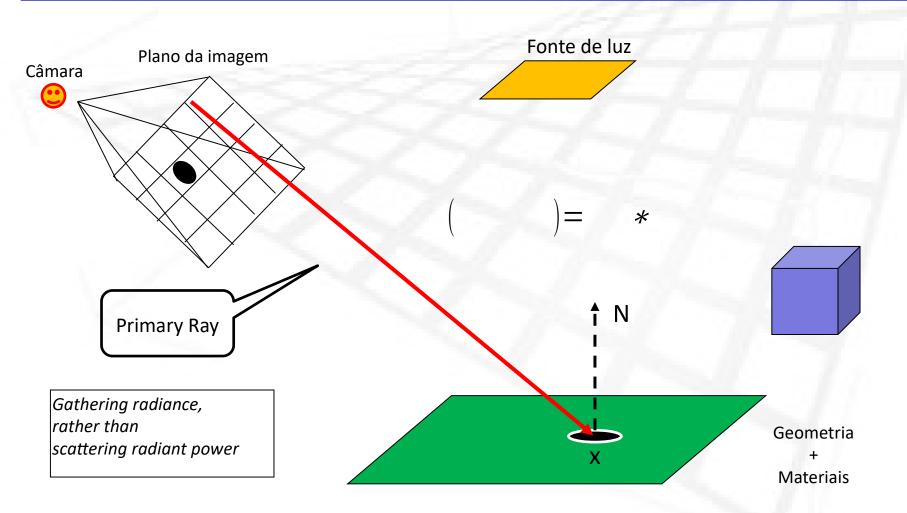
The 3D Rendering Problem



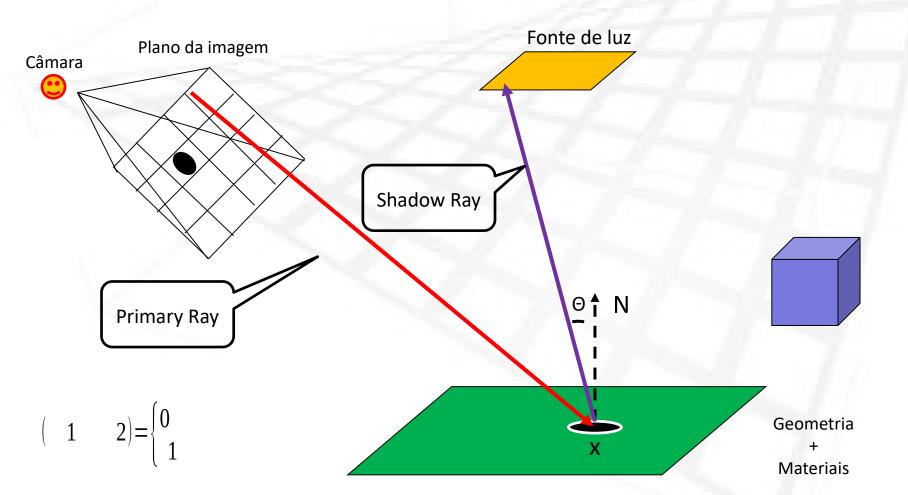
The 3D Rendering Problem



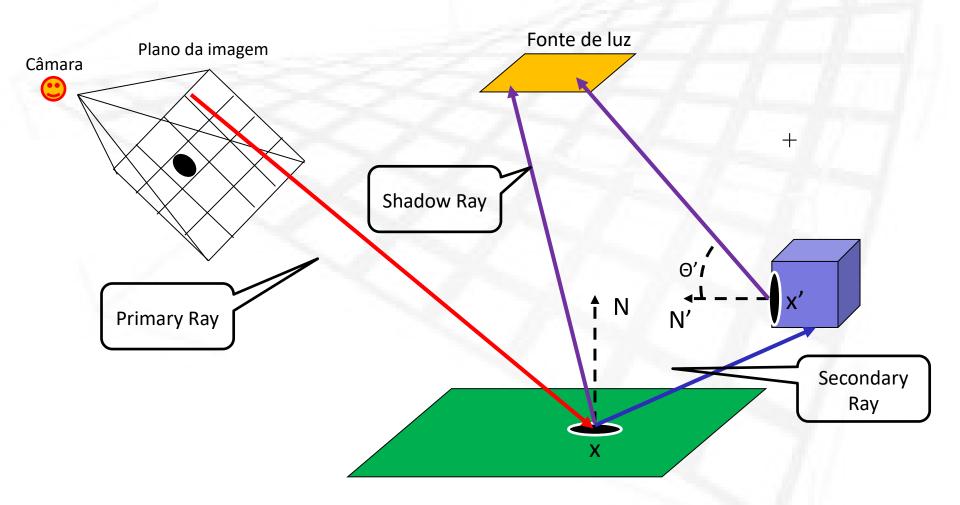
Backward Ray Tracing



Backward Ray Tracing



Backward Ray Tracing



Ray Tracing: Algoritmo

```
// main loop
computeImage (viewPoint) {
  para cada ponto p in plano imagem {
        ray = camera.GetRay (p)
        radiance[p] = rad (ray)
rad (ray) {
  primitive, x = scene.trace (ray)
  shade (x, ray, primitive)
```

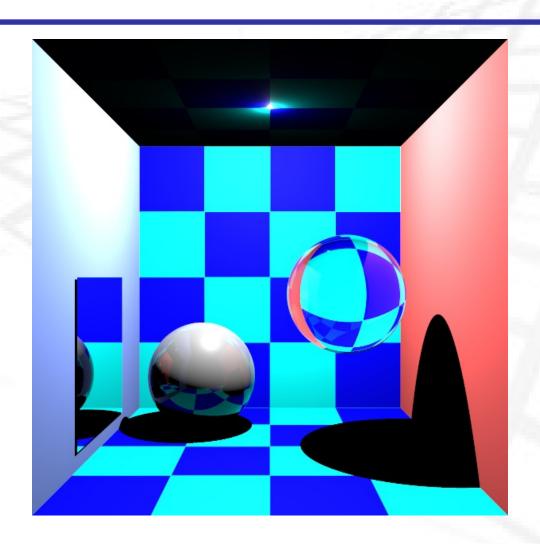
Ray Tracing: Algoritmo

```
// intersecção mais próxima da origem do raio
Scene::trace (ray) {
  tmin = Max dist
  while (primitive = scene.nextPrim())
        x = primitive.geom.intersect (ray)
        dist = x.distance (ray.origin)
        if (dist < tmin) {</pre>
              tmin = dist
              p = x
              prim = primitive
  return (prim, p)
```

Mestrado em

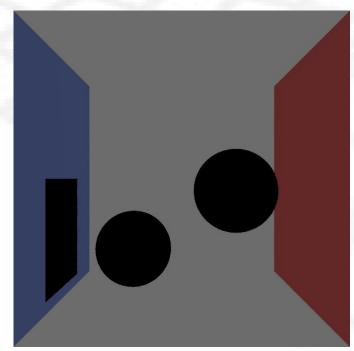
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Ray Tracing: Cornell Box



shading: diffuse BRDF

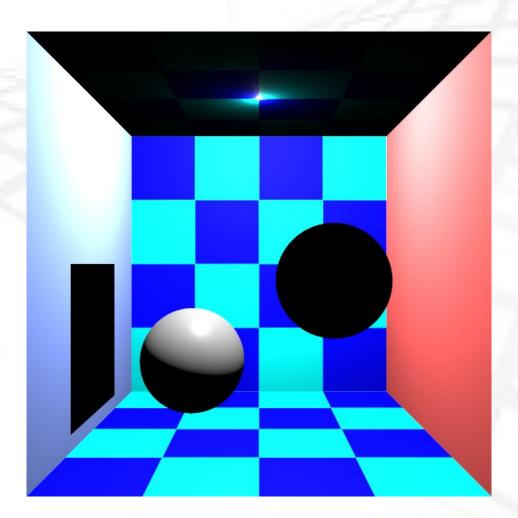
```
shade (x, ray, prim) {    // BRDF
    return (prim.BRDF(x, ray.dir))
}
```



- Se os shadow rays não forem disparados assume-se V(x,y)=1
- O algoritmo não calcula sombras (NÃO é fisicamente plausível)

```
shade (x, ray, prim) {
  radiance = directIllum_NoShadows (x, ray.dir, prim)
  return (radiance)
}

directIllum_NoShadows (x, dir, prim) {
  rad = 0;
  while (l = scene.nextLight()) {
    pl = l.Sample(); dir_l = x.vec2Point (pl);
    rad += prim.brdf (dir, dir_l)* l.L * cos (x.N, dir_l)
  }
  return (rad)
}
```



```
shade(x, ray, prim) {
  radiance = directIllum (x, ray.dir, prim)
  return (radiance)
directIllum (x, dir, prim) {
  rad = 0;
   while (l = scene.nextLight()) {
         pl = 1.Sample(); dir l = x.vec2Point (pl);
         ray = GenerateRay (x, 1, SHADOW)
         if (scene.visibility (ray, pl))
            rad += prim.brdf (dir, dir 1) * 1.L * cos (Nx,
  dir 1)
  return (rad)
```

```
// visibilidade da fonte de luz
                                      //V(x,y)
Scene::visibility (ray, pl)
  tmin = distance (ray.origin, pl)
  while (primitive = scene.nextPrim())
        x = primitive.geom.intersect (ray)
        dist = x.distance (ray.origin)
        if (dist < tmin) {</pre>
       return 0
  return 1
```

